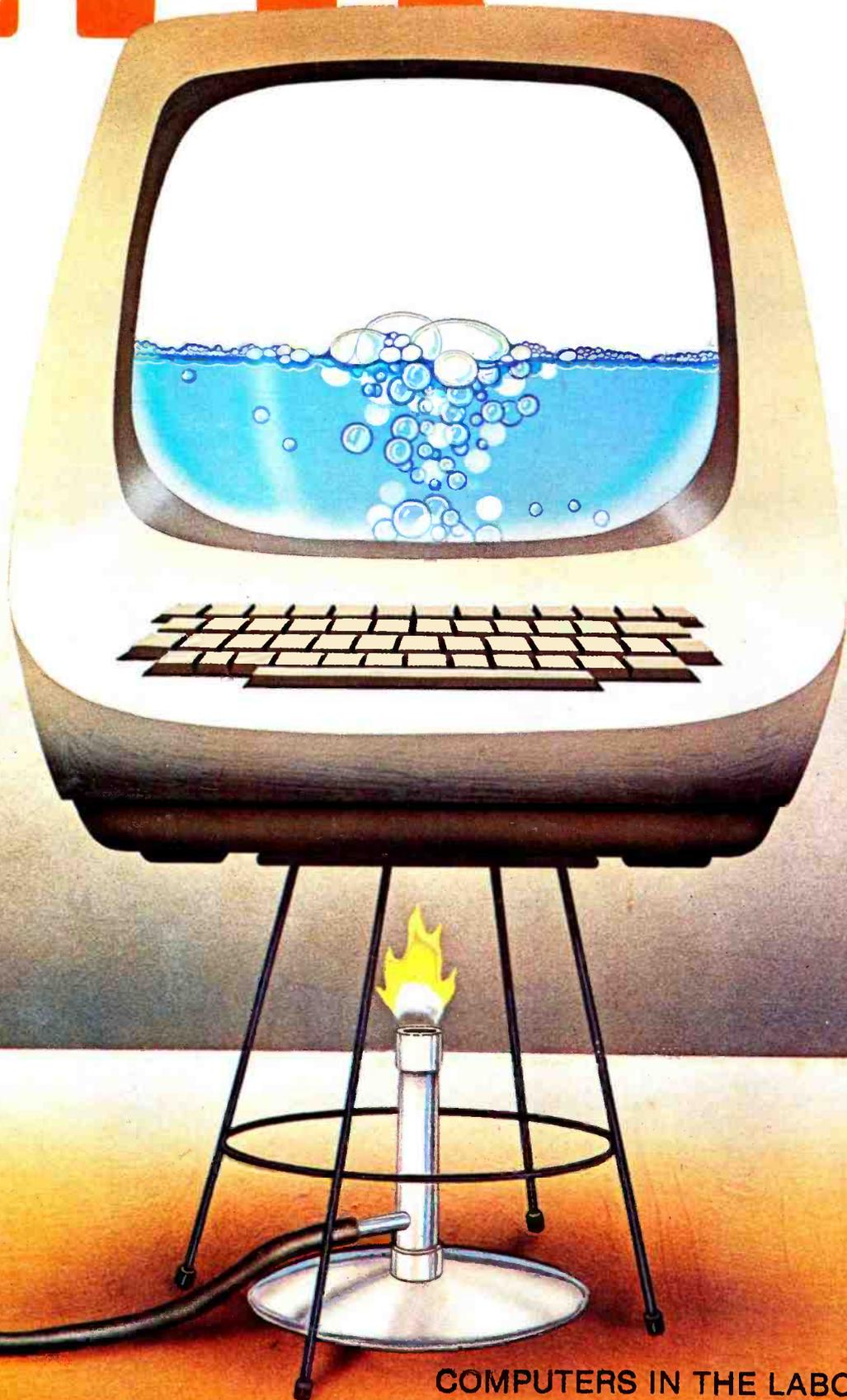


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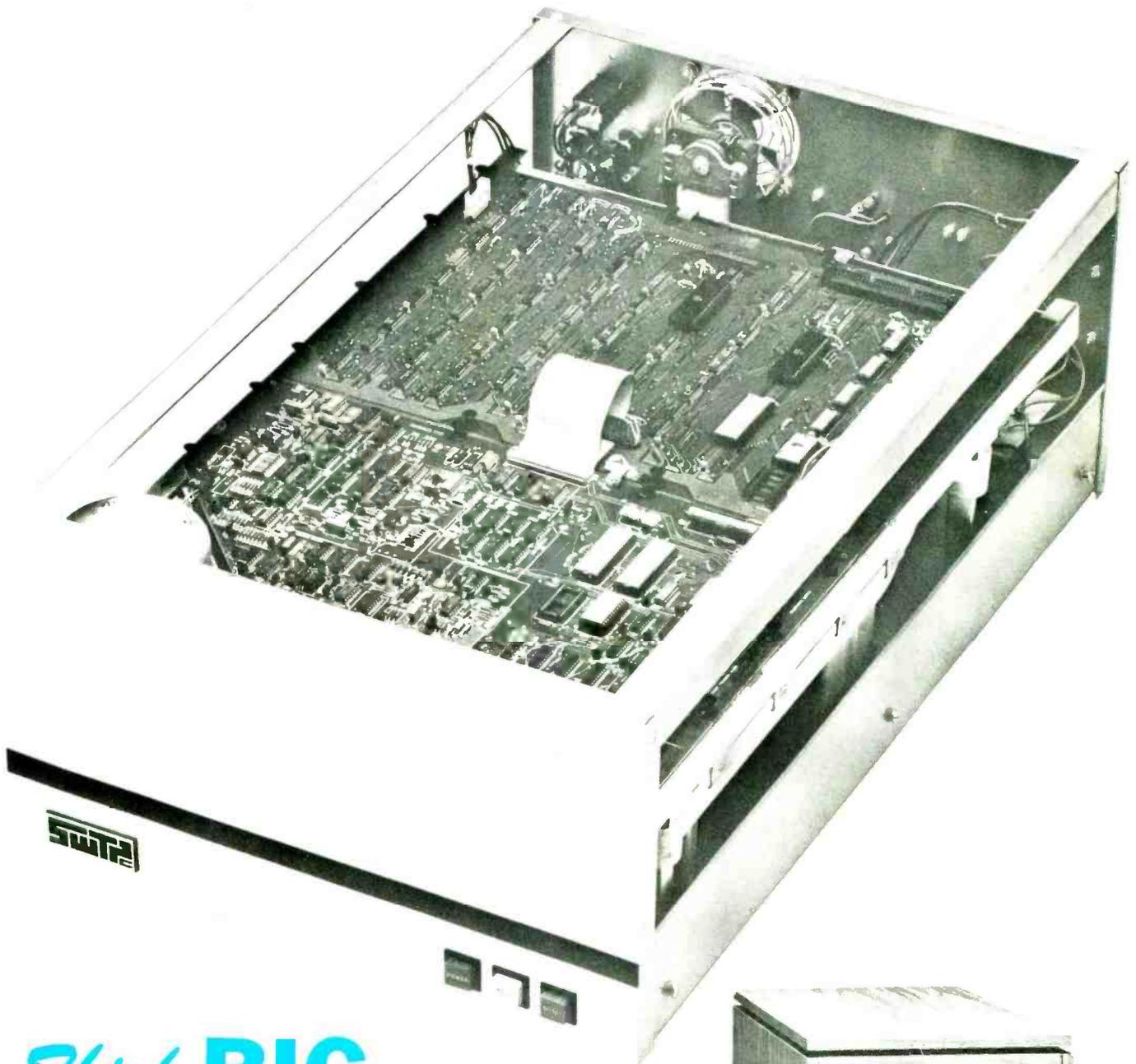
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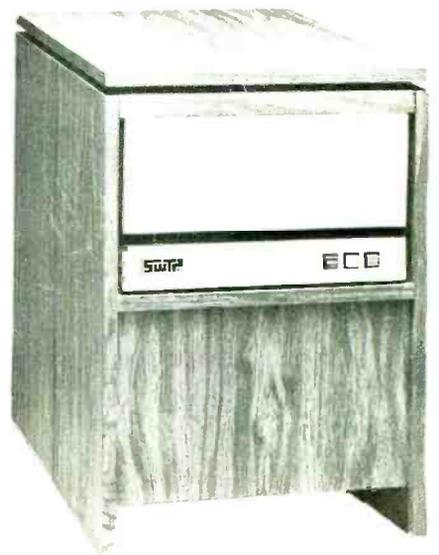
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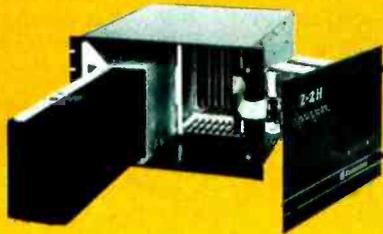
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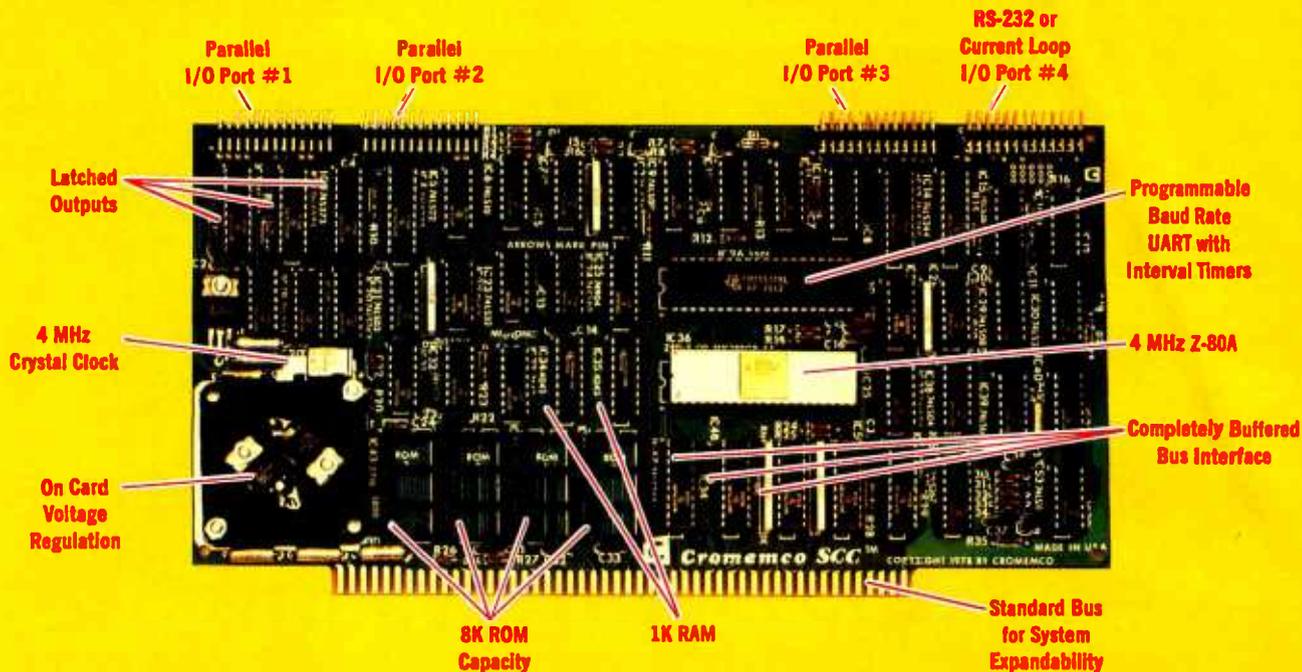
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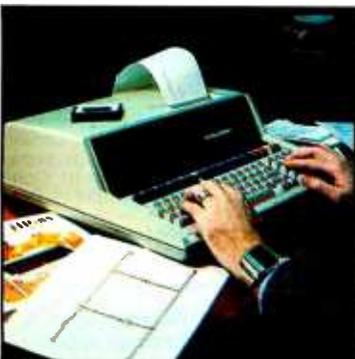
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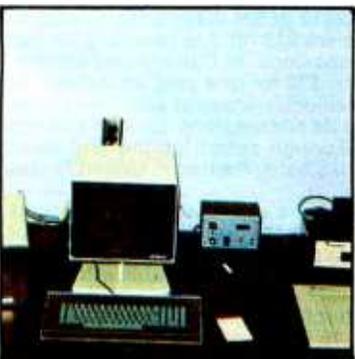
page 6



page 17



page 60



page 114

Foreground

17 EASE INTO 16-BIT COMPUTING: GET 16-BIT PERFORMANCE FROM AN 8-BIT COMPUTER *by Steve Ciarcia*

Steve tells you how the Intel 8088 is well-suited for building a minimum-configuration 16-bit computer.

34 ELECTRON BEHAVIOR IN A CHEMICAL BOND *by Michael Liebl*

Learn how to use a computer to explore the inner processes of a molecule by finding solutions to the Schrödinger wave equation.

74 SOLVING PROBLEMS INVOLVING VARIABLE TERRAIN, PART 2: SPECIAL CASES, INCLUDING HEXAGONAL GRIDS *by Scott T Jones*

After developing a general algorithm last month, Scott now explores several modifications that may be applied to typical conflict-simulation problems.

126 A POWER-LINE PROTECTION CIRCUIT *by Neil Schneider and Bror Erickson*

For hobby applications where an isolation transformer is too big and expensive, this relay-based circuit can provide some protection from power-line wiring errors.

130 LANDING MODULE SIMULATION WITH RANDOM SURFACE *by S J Houng*

This game uses the Motorola MEK6800 D2 kit. It can be interfaced to display the landing approach on an oscilloscope.

142 THE DIRT-CHEAP BOOTSTRAP, MORE NOTES ON BRINGING UP A MICROCOMPUTER *by Albert S Woodhull*

An inexpensive way to add front-panel functions to a minimal microcomputer system.

156 HYDROCARBON MOLECULE CONSTRUCTOR, *by Randall S Matthews*

The program presented here uses the high-resolution graphics ability of the Apple II to give a visual representation of molecular bonding.

232 SUPER TIC *by J Roehrig*

This is a three-dimensional, 4-by-4-by-4, tic-tac-toe game that can play against a human opponent. The program has ten levels of expertise, is written in BASIC, and can be modified to run in two dimensions.

Background

60 HEWLETT-PACKARD'S NEW PERSONAL COMPUTER, THE HP-85

by Christopher P Morgan

A first look at a personal computer from a company esteemed for its calculators and minicomputers.

84 TRS-80 PERFORMANCE, EVALUATION BY PROGRAM TIMING

by James R Lewis

James provides us with a direct comparison of the TRS-80 computer with an IBM System/370.

114 ELECTRONIC PLANIMETRY *by Peter A Santi, John Fryhofer and Gregory Hansen*

These authors describe a situation in which a specialized tool was replaced by a general-purpose minicomputer.

194 OPERATION CODES FOR 8080, 8085, AND Z80 PROCESSORS

by D Martin Harrell

The need to convert an assembler mnemonic to the hexadecimal object code often occurs when programming the 8080 microprocessor family. Here is a helpful summary of related information.

230 TO ERR IS HUMAN *by Roger A McGregor*

Techniques to enable your computer to detect and correct typographical errors in assembly-language programs.

Nucleus

6 Editorial: Hunting the Computerized Eclipse

14 Letters

68, 212, 240 Programming Quickies: Gear-Ratio Calculations for Bicycle Derailleurs; and many more

108 BYTE News

168 Book Reviews

174 BYTE's Bits

176 Clubs and Newsletters

180 BYTE's Bugs

184 Product Review: Lucidata P-6800 Pascal

186 Technical Forum: The Direct Impact of the Computer; Cutting the Gregorian Knot

208 Desktop Wonder: The Periodic Chart at Your Fingertips....

218 Event Queue

246 What's New?

287 Unclassified Ads

288 Reader Service, BOMB

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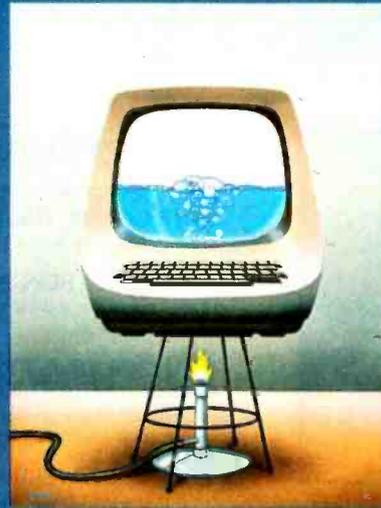
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ON THE COVER

This month's cover theme is "Computers in the Laboratory." Personal computers can be employed as a tool of analysis and control in scientific applications. We celebrate this theme with a fantasy suggestive of one area of scientific application: an advanced color-graphics-oriented personal computer is shown over a Bunsen burner on a beaker stand. On the terminal is a high-resolution image of some liquid boiling. This computer, without floppy-disk drives, certainly suggests a future direction: built-in, permanent mass storage with sufficient capacity to eliminate any need for removable media. We might even conjecture that a pattern is shown here being "boiled" into a bubble memory.

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Editorial

Hunting the Computerized Eclipse

by Carl Helmers

As noted last month, the subject of this editorial is completing some technical details of a project that has consumed all my spare time during the closing months of 1979. This project is the practical execution of what was really a pipe dream last March when the July 1979 editorial ("Computers and Eclipses") was written. The July editorial was inspired by my travels the previous February to see my first total solar eclipse from a roadside near Roundup, Montana. During that event, which took place in cold wintry weather, all my pictures were taken manually using the telephoto lens on my Nikon F2A camera. I knew there had to be a better way of controlling my camera during an eclipse event, and set about concocting a suitable first approximation of a computer-control method.

As a result of writing about the problem, I received a letter from and eventually met one of our readers, Norm Whyte, of Monte Rio, California. In the course of the ensuing correspondence and telephone calls, we developed a degree of friendship based on mutual interests in matters scientific and technological. The result was that since there were a couple of berths left in the travel plans for Norm's eclipse trip to Kenya during February 1980, I was able to become more serious about making a real version of the fantasy sketch outlined in last July's editorial.

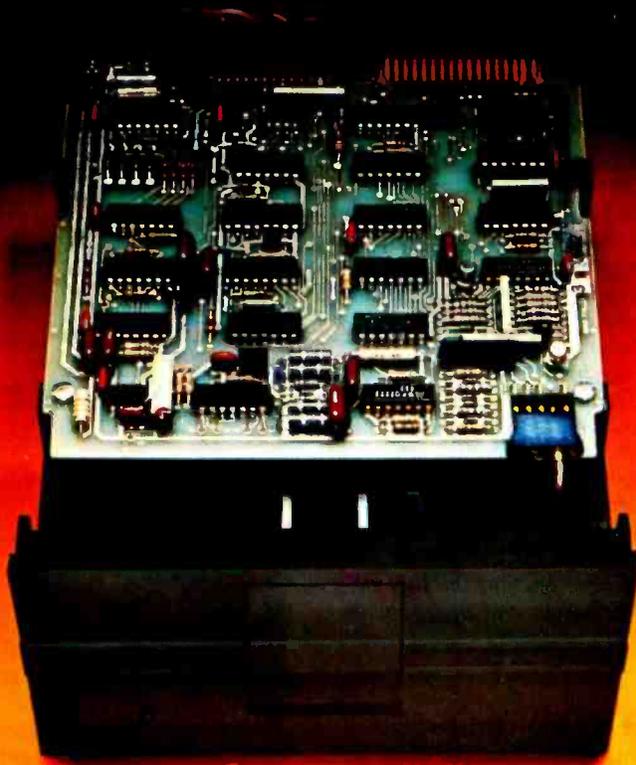
With the decision to go made, the next decision was how to implement the system. The number one step, of course, was to order a motor drive and a magazine back for the Nikon camera. I quickly came to the conclusion that if I were going to travel all the way to Kenya to watch 4 minutes of celestial follies, more than thirty-six exposures would be appropriate. The Peterborough Camera Shop did their job, so by September I had the motor drive, and I had the magazine-back and bulk-loading accessories by mid-October. The camera system and methods of developing a 250-frame roll in a small batch tank were debugged at the camera store in November, through the efforts of its owner Wayne Esty and lab technician Skip DeLiquori.

At about this time, I began testing my refined concept of electrical control for the motor-drive/shutter mechanism. It took about 15 minutes to verify what I wanted to know: applying an ohmmeter and a miniature Phillips screwdriver to the detachable control head of the motor drive, I was able to determine the proper wiring of the four-wire MC-1 remote-control cable I had purchased. In the normal use of a Nikon motor drive, this cable serves as the electrical equivalent of a mechanical cable release.

In my application, I simply cut off and set aside the extension socket for the control head. In its place I wired an electronic simulation of the control head. This electronic simulation is the circuit of figure 1 (see page 10), which acts like the push-button switch of the motor drive head. One silicon diode is required in the logic which distinguishes between single shot and continuous firing of the motor drive.

The relatively machine-independent, Pascal language interface to the machine-dependent absolute addresses of the annunciator output ANO is provided through a variant record technique. This technique works in UCSD Pascal implementations such as Apple Pascal, but may not work in all implementations since it definitely "bends" the formal definition of the language.

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Photo 1: The Camera. The camera equipment has slightly expanded since originally conceived. The method of interfacing has also been greatly simplified. The camera now has a 250-exposure magazine back, which will be loaded with ASA 64 Kodak Ektachrome slide film. It turns out that the Nikon MD-2 motor drive allows direct computer control of camera operation, through a single bit interface (see figure 1). When the shutter speed control is in the "bulb" position, this single bit out of the computer controls exposure time and motor drive action.

A transition from 0 to 1 opens the camera shutter after flipping the reflex mirror out of the way; a transition from 1 to 0 closes the shutter and causes the motor drive to advance the film to the next frame. The optically isolated two-transistor interface is wired to the four conductors in the Nikon MC-1 remote shutter extension cable. Readers should refer back to the July 1979 BYTE editorial for a much more elaborate and probably unworkable mechanical kludge suggestion.

All one needs to do is reference the appropriate address. One address, if referenced, sets the ANO output line; the second address, if referenced, resets the ANO line. I could have used the Apple-dependent, machine-language routine called TTLOUT, but decided instead to use the variant record escape of setting a pointer to an integer address value. The test program of listing 4 was used to verify the operation of the circuit in figure 1.

At the stage of this editorial's writing during December 1979, I had created a Pascal program shown in listing 1 (with execution shown in listings 2 and 3 photographed from my terminal). This program represents the most difficult part of the model, allocating the detail exposure times for all the shots of the eclipse.

The advantages of using this high-level language become obvious whenever such an elaborate program is even contemplated. I started out with a first version of the program that defined the application-specific data types of "seconds," "milliseconds," "absolute-time," "exposures," and "an-exposure-detail." The records "absolute-time" and "an-exposure-detail" give examples of how Pascal may be used to create conceptually oriented data types for specific purposes.

In this real-time simulation, I chose to use the millisecond as the basic unit of time, with actual time values on the order of seconds expressed as a two-part record with an integer value 0 thru 999 of milliseconds and an integer value of 0 thru 32,767 of seconds. I chose to express time in this manner as a part of my original intention to use a small, single-board computer programmed in

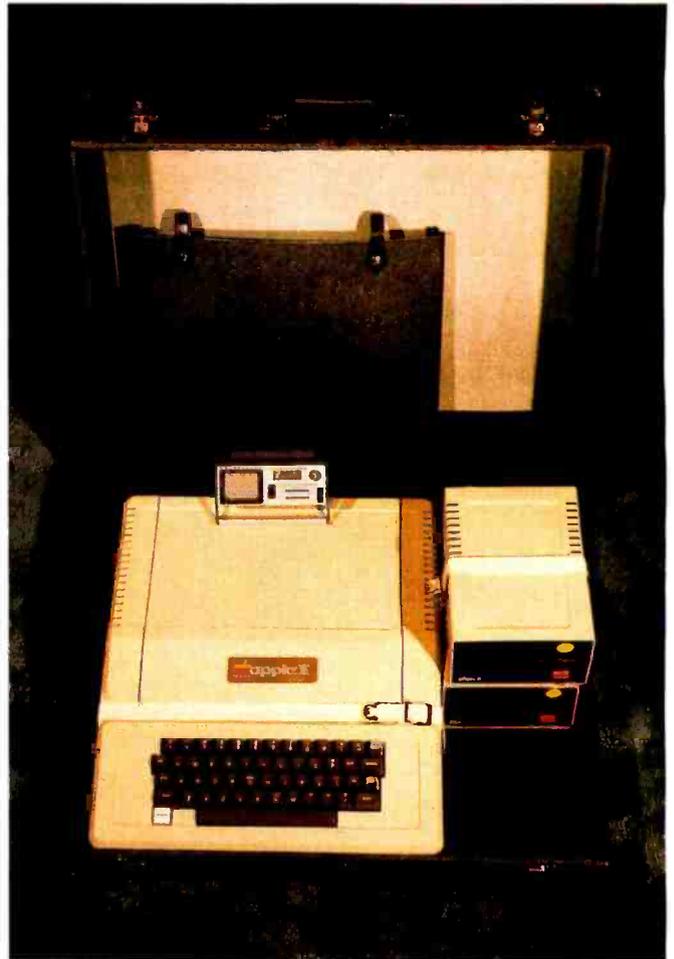


Photo 2: Field computer equipment. My original plan was to take a small, single board computer for use in the field. However, as the winter solstice of 1979 was fast approaching, it became obvious that it would be far easier to simply take along the Apple II Pascal machine which has the complete simulation of the event written in a high-level form. Thus, I went hunting at a local computer store, where I came upon a truly elegant Apple II traveling case. (Contact Bob McGuffie, Computerland of Nashua, New Hampshire, if you want one. I paid \$108 for this product.) The case will accept two floppy-disk drives, the Apple, and the Sanyo miniature television which will be used as my field display. (At the eclipse field site, we will have 110 V AC power provided by a small gasoline generator.)

assembly language. Such an expression of the data would have made it easy to translate the high-level language simulation into a hand-crafted small program.

(After time started growing short and I had not yet received the small computer I had intended to use, I started asking skeptical questions like: "Why should I flagellate myself with a macroassembly language expression of a perfectly good program written in Pascal?" After all, this "big machine" with its new suitcase is certainly portable and has the single-bit output needed.)

The variables needed by the program are declared with long, explanatory names immediately following the TYPE declarations. Thus, whenever I need a variable which is intended to be an "absolute-time" value, I declare it using the application-specific type of that name.

Text continued on page 12

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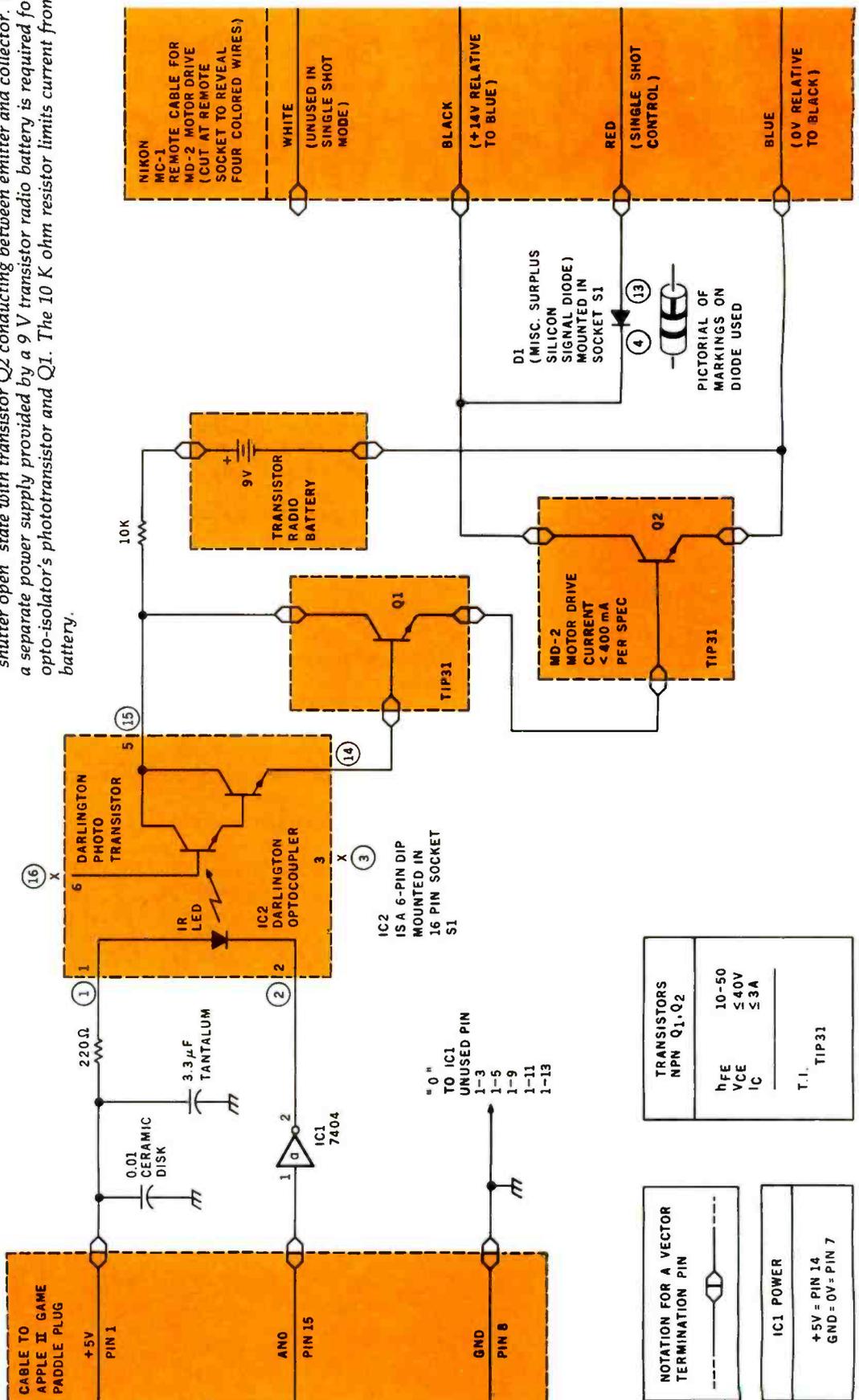
Figure 1: The schematic of the Apple II/Nikon interface. The two transistors (Q1 and Q2) and diode D1 simulate a switch and a diode found inside the original Nikon MD-2 motor drive shutter-control head. The colors noted at the right in this figure correspond to the colors found in the four-wire cable of the Nikon MC-1 remote shutter extension cable. An opto-isolator with Darlington phototransistor was required in order to isolate the Apple II from the noisy transients of the motor drive.

Before this final optically isolated version was devised after much frustration (and productive suggestions from Steve Ciarcia and Chris Bancroft), three different versions were tried in which switching transients propagated back to the Apple II via a common ground. The first unsuccessful version simply had a 7404 gate driving a reed relay. Then a 75450 peripheral driver was tried because the surplus relay proved to require a higher voltage (12 V) than the 5 V available from TTL. The peripheral driver made the relay

flip state. But at random times when operating the motor drive, the ANO output bit would refuse to stay in the state defined by my program. So, I then tried eliminating the relay entirely and using both output transistors of the 75450 in parallel.

The random state changes remained. The lack of a 100 MHz storage scope prevented me from seeing what had to be there: short (order of magnitude: nanoseconds) high voltage, inductive transients occurring during the time when the LS Schottky TTL latch in the Apple was having its state redefined by the program. After a trip to a Radio Shack store to buy two transistors and two packages of random assorted opto-isolators, the present circuit resulted.

The opto-isolator darlington phototransistor and transistor Q1 provide drive to an output transistor Q2. If all of the transistor collectors are wired to a common supply provided by the "black" lead of the MC-1 cable, then the circuit will latch into the "shutter open" state with transistor Q2 conducting between emitter and collector. Thus a separate power supply provided by a 9 V transistor radio battery is required for the opto-isolator's phototransistor and Q1. The 10 K ohm resistor limits current from the



New from SSM.



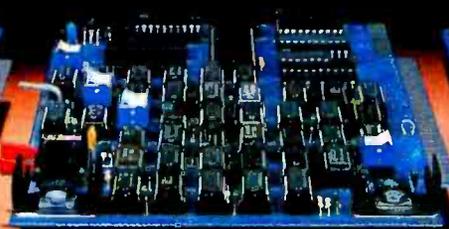
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It operates at 2MHZ or 4MHZ by DIP switch selection and includes two sockets for 2716/2732 EPROMs or TMS 4016 2K RAMs. Memory sockets can be disabled. Separate run/stop and single step switches allow system evaluation without the benefit of a front panel.

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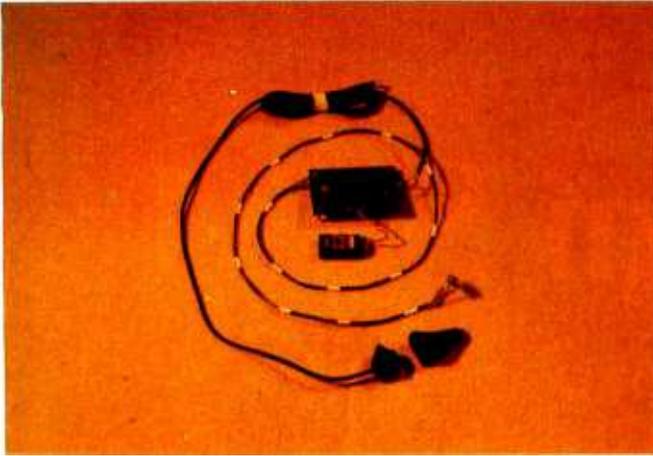


Photo 3: The Apple II/Nikon interface. The interface of figure 1 was wired on a framework of "P" pattern Vector perforated board. Vector terminal pins were used to provide anchorage for the Apple II cable (left edge), the cable from the Nikon MC-1 shutter extension (right edge), the connector for a 9 V transistor radio battery (bottom edge), and mountings for the two NPN transistors. Wiring was done using number 20 gauge copper wire for most connections; wire-wrap connections were used for one or two signal buses.

Text continued from page 8:

The model I am using for exposure control is a table-driven one, with two tables of the data type "an-exposure-detail." The table "ten-shot-grouping" is initialized (in procedure "initialize," naturally) with a set of ten exposures bracketing a range from 2 milliseconds to about 4 seconds. The second table "transient-shots" is used to specify the exposures that will be taken during the transient diamond ring events at the beginning and the end of the eclipse.

The exposure control details are provided by two numbers in my model: the number of milliseconds devoted to the open camera shutter state, and the number of milliseconds of waiting time which will be used to separate the shot from the next shot. This waiting time is initialized to an "overhead-duration" figure set by a Pascal constant of that name. The present value of "overhead-duration" is set at 200 milliseconds, corresponding to the motor drive's maximum speed of 5 frames per second. This initial value of the time required for each frame is used for the first pass through the procedure "sum-up-eclipse" in order to calculate the minimum time needed for all the exposures in the total phase.

The procedure "normalize-timing" is the main portion of the simulation program as it stands in listing 1. After some initialization dialog in listing 2, the procedure "alloc-exposures" is used to assign an equal number of exposures to each diamond ring sequence (second contact and third contact) given the number of exposures during totality and the total number of exposures available in the bulk film cassette.

Then the procedure "preliminary-allocation" is used to total up the time requirements of the diamond ring exposures, totality exposures, and an arbitrary amount of slack time entered to allow a hand-coordinated cuing of the third contact diamond ring sequence. The margin

Text continued on page 102

Listing 1: A Pascal eclipse interval-allocation program. This listing contains the first cut at a Pascal camera-control program for the 1980 solar eclipse. The program's name is "eclipse-monitor-simulation" in order to emphasize that the entire process is a conceptual simulation of an actual detailed sequence of events. At this stage in the design, most of the model details have been selected in order to produce a detailed time line specified by tables. The input parameters to the program are the number of exposures, the number of exposures during totality, the time expected for totality at the site of observation, and the time to be reserved at the end of totality for manual cuing of the second diamond ring/Baily's beads (so-called third contact) exposure sequence. Listings 2 and 3 were made photographically from the terminal during a run of the program. The program as shown here has the time allocation portion completed, with the details of the actual time line simulation represented by dummy procedures, which were written in late December 1979.

```
(
  ( NOTES ABOUT THE DESIGN PROCESS )
  (
  ( Step 1: High Level Description - begun November 22, 1979 )
  ( This is a first cut at a program to simulate the eclipse )
  ( photography process, and define some of the necessary global )
  ( data of the problem. )
  ( COMPLETED 11/24/79 )
  ( )
  ( Step 2: Fill in allocation details - )
  ( Achieve a complete allocation of the eclipse camera con- )
  ( trol function as evidenced by calculation of a detailed time )
  ( line for the eclipse event given various conditions: )
  ( Given: )
  ( n = number of totality exposures )
  ( m = number of diamond rings exposures )
  ( t = totality time )
  ( s = slack in allocated totality time )
  ( Then let us seek the followings... )
  ( # d2 = diamond rings time at 2nd contact )
  ( # d3 = diamond rings time at 3rd contact )
  ( # z = extra slack (one half of diamond rings total) )
  ( # p = anticipation time (half first diamond rings) )
  ( # A = required time for exposures during totality )
  ( # a = allocated totality time for exposures )
  ( # x = margin per frame in totality )
  ( Theorems: )
  ( d2,d3 derived from table of diamond ring frames )
  ( A derived from table of totality frames )
  ( z = (d2 + d3)/2 )
  ( p = d2 / 2 )
  ( a = t - s - z )
  ( x = (a - A) / n )
  ( )
  ( PROCEDURES Detailed Here Are... )
  ( initialize )
  ( normalize )
  ( COMPLETED 12/14/79 )
  ( )
  ( Step 3: Fill in the simulated details... )
  ( Create a program which uses the results of step 3 to )
  ( go through a detailed time line of the experiment on paper )
  ( or terminal screen). Each event (shutter transition )
  ( open->close or close->open will be marked by a report of )
  ( its nature and time of execution relative to <start> signal )
  ( )
  ( PROCEDURES Detailed Here Are... )
  ( wait_cue )
  ( diamond_rings_burst )
  ( totality )
  ( )
  ( Step 4: Adapt to real time control - )
  ( Put in adaptations of the software to actually demon- )
  ( strate operation with the Nikon F2A camera via a relay )
  ( plugged into the Apple II Game Paddle Socket )
  ( THIS IS THE FINAL FORM OF THE PROGRAM TO BE USED IN THE )
  ( FIELD CONTROLLING THE EXPERIMENT... )
  ( Necessary step: determines a method of measuring time )
  ( intervals from the CPU clock which is consistent with UCSD )
  ( Pascal. Possibly use assembly language subroutine. )
  ( )
  ( )
  )
```

```
PROGRAM eclipse_monitor_simulation;

CONST
  overhead_duration = 200 (milliseconds);

TYPE
  seconds = INTEGER;
  milliseconds = INTEGER;
  absolute_time =
    RECORD
      units : seconds;
      thousandths : milliseconds;
    END;
  exposures = INTEGER;
  an_exposure_detail =
    RECORD
      duration : milliseconds;
      wait_after : milliseconds;
    END;
  string_pointer = ^STRING;

VAR
  s : STRING(128);
  crash_ahead : BOOLEAN;
```

Listing 1 continued on page 96

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Letters

Needed: Software and/or Computers in Rhodesia

In the Faculty of Engineering at the University of Rhodesia, we have a critical shortage of computing facilities, and we do not have the foreign currency or the monies to purchase even simple systems like the Apple II or Cromemco. We are therefore obliged to build our own microcomputer systems. Unfortunately, we do not have the necessary expertise at the University or in the country to write the necessary BASIC interpreters, assemblers, and editors to make our systems useful or suitable for teaching purposes. I would appreciate it if one of your readers could put me on to someone who could possibly supply the BASIC interpreter and/or compiler; assembler, with loader if required; and a text editor for the Intel 8080 or 8085 microprocessors.

I have been through BYTE magazine, but no one seems to offer the above software in the form which we could adapt for our own homebrew computers, and, therefore, we would appreciate it if one of your readers could advise us of anyone who may be able to sell or donate such software to enable us to offer a more effective computer teaching facility.

W B Green
Projects Engineer
POB M P 167
Mount Pleasant
Salisbury
RHODESIA

The Bare Necessities

I enjoyed the article "Budget Building on a Bare Board" by Dan S Parker (October 1979 BYTE, page 206). As he points out, there are large savings in building up only the parts of a circuit board that are needed. For instance, I have built only one serial input/output (I/O) port (for my Teletype) from the two serial and four parallel ports available on the SSM IO-4 circuit board. I have also applied this technique to a Z80 processor board, an 8 K-byte memory board, an erasable programmable-read-only memory board, and a cassette interface board.

Mr Parker's article did not go on to

describe what you can do using these partially built-up boards. I am using the Integrand Research mainframe box, the SSM Monitor VI.0 (in the erasable programmable-read-only memory), and Palo Alto Tiny BASIC (Extended), which I typed into my system from the May 1976 and February 1977 issues of *Dr Dobb's Journal of Computer Calisthenics and Orthodontia*. This BASIC interpreter fits in only 2 K bytes of memory and is amazingly powerful.

I am writing a program to store a mailing list of 1000 names and addresses in main memory. The program should be able to add, delete, alphabetize, sort by ZIP code, and compress the list to free space from deleted entries. Just how far can one go without a floppy disk drive?

Readers of BYTE can obtain copies of the software I have written from me for either a small copying charge or in exchange for other software. I use the Intel hexadecimal checksum format on either paper tape or Kansas City cassette tape.

I have found that the Jade Serial/Parallel/Cassette I/O board is not software-compatible with the SSM monitor, but it can be made so through a process that involves cutting conductor etches on the board. You must reverse the port address bits 0 and 7, invert the transmitter-buffer-empty signal, invert the read-data-available signal and move to bit 7, and cut the control bits for the universal asynchronous receiver/transmitter (UART) from the data bus. Following this, you rewire these in the desired format.

Ralph Johnston
35 Groveland St
Newton MA 02166

Biological Rhythms and Biased Data

Regarding the editorial "... Pseudoscience Done ..." (November 1979 BYTE, page 6): I totally agree with Carl Helmers' comments on the "science of biorhythms." At many times I have also been curious about the apparent cyclical nature of my physical and mental processes — such as, a few occasional nights of especially weird dreams; or several days of running slower and more painfully than usual (I run for exercise); days of great mental energy filled with

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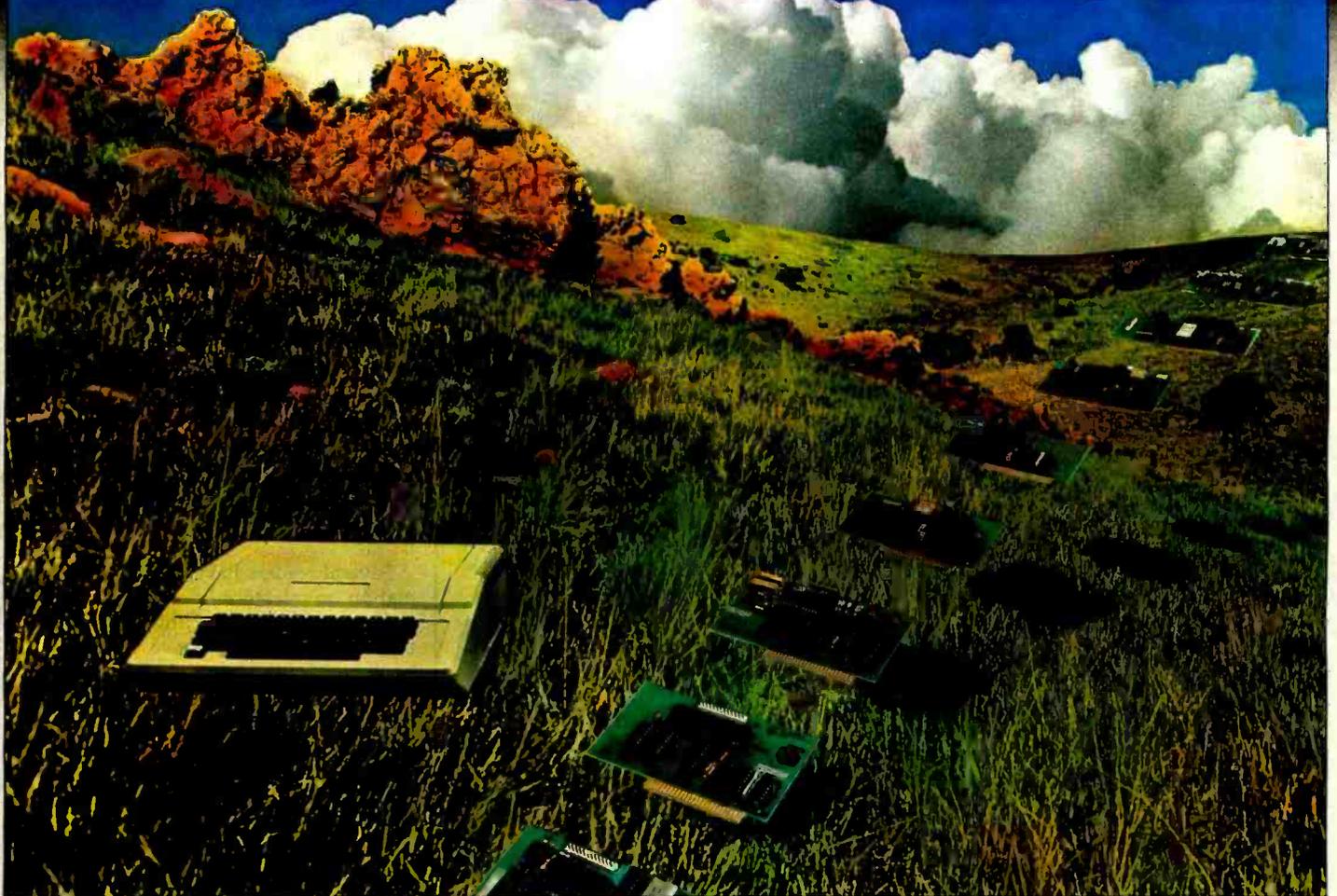
7016A 16K Dynamic Memory Add-On.

Watch this space for new CCS products for the Apple. We've got some real surprises in the works. To find out more about the CCS product line, visit your local computer retailer. The CCS product line is available at over 250 locations nationally, including most that carry the Apple. Or circle the reader service number on this ad.

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If you want to do business with an Apple, we've got tools to connect the Apple to standard business printers and terminals. Or to modems, for communications over telephone lines, with other computers, even with other Apples.

If you want to apply your Apple to engineering, scientific, or graphic projects, we've got tools for high-powered,

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And we have tools to connect the Apple to the outside world, including A/D converters and interval timers with external interface.

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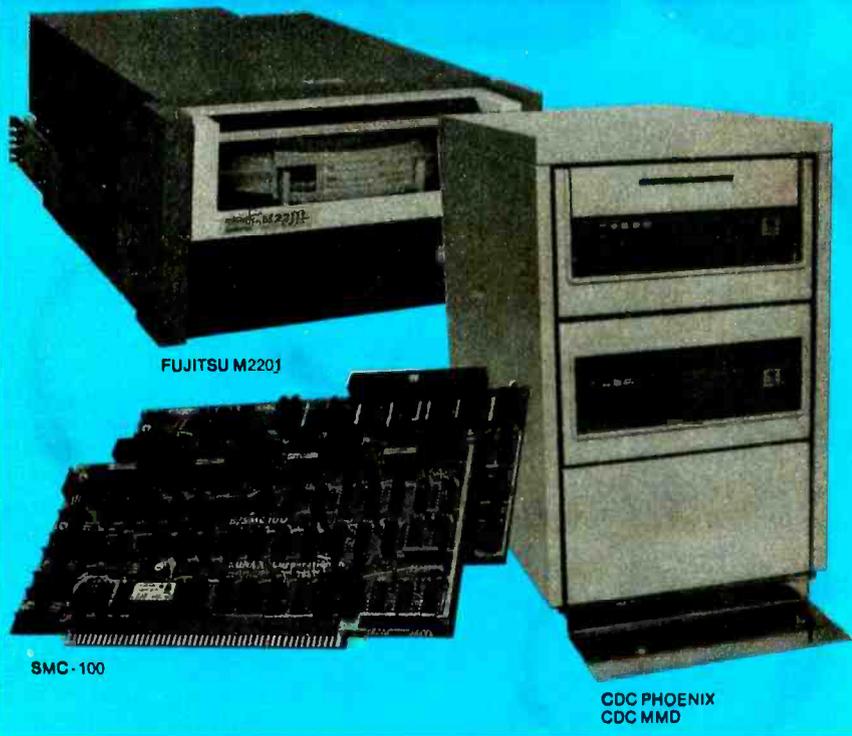
To find out how much computer your Apple II can be, see things our way. Because for serious users with serious uses for the Apple, we've got the tools.



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great plans, etc. . . . But each time I think about "taking data" on these phenomena, I realize the strong possibility that such data would be biased by my expecting that cycles do exist. We know how powerful our subconscious minds are. I feel my subconscious mind is easily capable of keeping track of days and thus creating (or at least influencing) the very cyclical data I am searching for.

If this is the case, perhaps the data gathering would only be valid for someone who had never heard of biorhythms. Or, maybe the human-behavior guys can figure a way around the bias.

Anyway, thanks for a good magazine.

Sid G Knox
4621 South G St
Oxnard CA 93030

Correspondence Regarding "Curve Fitting with Your Microcomputer"

"Curve Fitting with Your Microcomputer" (October 1979 BYTE, page 150) has resulted in interesting mail correspondence, some of which has enough general value to merit discussion in BYTE.

Several readers have requested information on reference books which relate to least-squares curve fitting in more than one dimension. I have yet to find a book which has a good, balanced discussion on this subject. Perhaps a reader has. One useful book is *Applied Regression Analysis*, by Norman Draper and Harry Smith (John Wiley and Sons, 1966). Another more detailed and complicated discussion appears in *Computational Geometry for Design and Manufacture*, by I D Faux and M J Pratt (John Wiley and Sons, 1979).

Dr Titus (of Tychon) has informed me of a convolution technique for least-squares smoothing of equally spaced data. The mechanics of the method are very similar to those involved in non-recursive digital filters, and reminiscent of Akima's approximation to the cubic spline fit. The reference Dr Titus supplied was "Smoothing and Differentiation of Data by Simplified Least-Squares Procedures," by A Savitsky and M J E Golay (*Analytical Chemistry*, volume 36, number 8, July 1964).

As a final note, it has been noted that program line 800 in listing 1 has an error in it. The correct statement is $S = S/(I-3)$, instead of $S = S/(I-1)$. This does not affect the curve fit or relative comparisons, but influences the printed value of the standard deviation by several percent.

F R Ruckdeschel
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Apple lets you get personal with Pascal.

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If you'd like to let the world know who speaks Pascal, here's how:

Follow the dotted line and cut out the transfer image above.

Preheat iron (dry-wool setting) for 3 minutes. Slip garment on ironing board over scrap material. Remove wrinkles. Position transfer face down and pin edges to ironing board cover. Iron transfer slowly for one minute. If paper browns, iron is too hot. Let transfer cool for one minute, then unpin and slowly pull transfer straight up. Results are best when t-shirt is at least 50% polyester.

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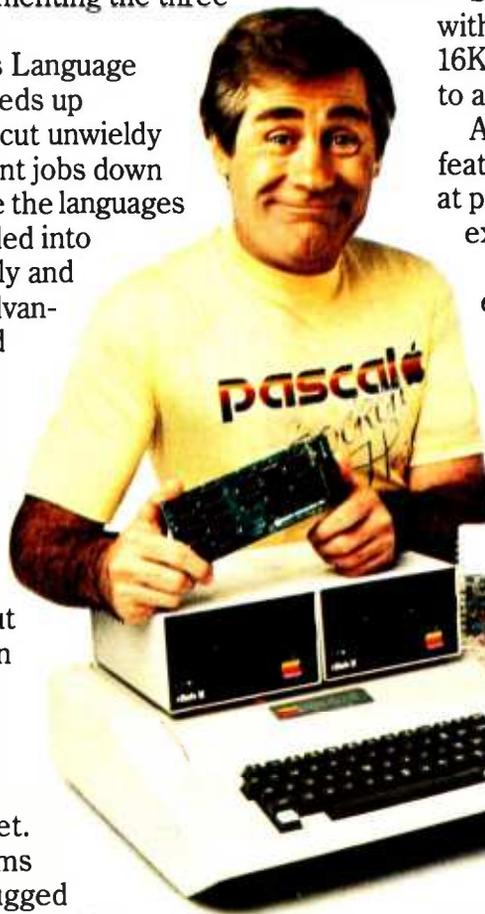
Apple's Pascal language takes full advantage of Apple high resolution and color graphics, analog input and sound generation capabilities. It turns the Apple into the lowest priced, highest powered Pascal system on the market. With Pascal, programs can be written, debugged and executed in just one-third the time required for equivalent BASIC programs. With just one-third the memory.

On top of that, Pascal is easy to understand, elegant and able to handle advanced applications. It allows one programmer to pick up where another left off with minimal chance of foul up.

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To be more specific.

The Apple II's specs are tempting enough without the Language System and Pascal. With them, they're downright irresistible.



The text screen, a 24x40-line window, can display an entire 80-column Pascal line, thanks to Apple's unique horizontal scrolling feature.

Characters are normal, inverse or flashing, 5x7, upper case. Full cursor control is standard.

Since Pascal runs on an Apple computer with 48K bytes of on-board RAM, the additional 16K bytes on the language card bring the total to a full 64K bytes.

And, Pascal runs on the new Apple II Plus. It features an Auto-Start ROM that boots the Disk II at power-on for turn-key operation. Applesoft extended BASIC is resident in ROM.

Standard color graphics (in the BASIC environment) offer 40h x 48v resolution, or 40h x 40v with 4 lines text, in fifteen colors.

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If you'd like more information on the advantages of owning an Apple personal computer, he can fill you in. Personally.



Ease into 16-Bit Computing: Get 16-Bit Performance from an 8-Bit Computer

Steve Ciarcia
POB 582
Glastonbury CT 06033

Stopping for coffee at the local doughnut shop has become a morning ritual. I am quite capable of making coffee at home, but I am not what you would call a "morning person." Even though I have culinary talents that include the preparation of eggs Benedict and strawberry crepes, it had better be evening when you request them around our house.

This morning started out like any other. I pulled my car into the doughnut shop's parking lot only after carefully examining all the potential hazards. I carefully avoided the broken glass, the beat-up 1962 Chevy and the large black van with a "Tax the Rich!" bumper sticker.

After entering the shop, I sat down and spread my reading material, the latest issue of BYTE, on the counter. As my coffee and bran muffin were delivered, I could not help but overhear the conversation of two other people at the counter.

"Dave, have you been reading any of the magazines lately? It looks like everyone is going 16-bit crazy."

"I've read a lot of descriptive articles, but I suppose it'll take a while before we see any real hardware."

"Actually, I'm a little hesitant to just jump on the bandwagon. My 8085 works just fine."

"I know what you mean, Ed. The Z80 system I built from scratch is still

cranking along. I'd like to do something with the 16-bit chips, but I sure don't want to throw out my 8-bit system."

"What about building a small system to experiment with? Didn't I see an article a few months ago on a single-board 8086?"

"Yeah, I remember. It was in BYTE. Wasn't it written by that guy who lives around here someplace, in his cellar or something?"

Upon hearing that last statement, I nearly choked on my muffin. I thought it would be prudent to remain anonymous until I learned whether or not they enjoyed the article. I carefully closed the magazine and placed it face down on the counter.

.....

One way to ease yourself into the world of 16-bit computers is with the Intel 8088. This micro-processor is an 8086 on the inside with an 8-bit data bus on the outside.

.....

"Maybe, but anyway, the article wasn't too bad," said Ed. I'm sure they didn't hear the sign of relief from across the counter. Then he continued, "But it just seemed like a

larger computer than I have time to build. It's obviously oriented toward guys who don't have any other development system. I'd prefer a minimal hardware configuration to start with. If I want large programs, I'll run a macroassembler on my 8085 system, write the object code into an EPROM, and then plug it into the test board."

"Eliminating all the keys and displays will help, but how small a computer can we end up with and still be 16-bit? You'll need 16-bit address and data buses, and what's 1 K words of memory—four chips? All the EPROMs I know are 8-bit output. That means at least two of them."

"Wait a minute," said Ed. "I didn't say I had all the answers. The minimal configuration may be twenty chips, but isn't this closer to something we could afford to experiment with?"

This was the perfect opportunity to express my point of view concerning the things that I write and consult about. "Excuse me," I said. "I couldn't help but overhear your conversation. Had you considered using an 8088?"

The two young men looked up at me, paused, and harmonized, "An 80 what?"

"I know a little about micro-processors. Have you considered using an Intel 8088?"

"Is it 16-bit?" asked Dave.

"Well, yes and no," I replied. "It uses an 8-bit data bus, but, internally it's an 8086. Essentially it's an 8-bit chip that's completely 8086-software-compatible."

Should they listen to this doughnut and coffee philosopher? "That sounds tremendous, but won't it still require quite a few chips to make an operational computer?"

I sensed that this was a good time for my exit. Staying any longer would involve my designing a computer for them on the back of a napkin. Ordinarily I probably would have stayed, but I had just completed a similar task in my latest article, so I decided to let them wait a few more weeks. I rose to leave, carefully rolling up the copy of *BYTE*, cover page inside, and stopped behind them on my way out. "My recollection is that while four chips is a possibility, a five-chip computer is quite a reality. I've even seen how a BASIC interpreter could be written to run on it. In case you're interested, the next issue of *BYTE* has an article all about it."

I excused myself to attend an

important meeting. As I opened the door I heard, "Thanks, I'll look forward to reading it." They watched me intently as I drove out. I could only speculate on their final conversation.

The 16-Bit Generation

The exciting items in microcomputing these days are the 16-bit microprocessors made by companies such as Intel (the 8086), Zilog (the Z8000) and Motorola (the M68000). All of these devices, although they differ in internal architectures, commonly claim to have compressed the power of a minicomputer within a single chip of silicon. Most notably are the 16-bit data bus and increased addressing space. A 20-bit address can directly address a megabyte of memory.

There seems to be little doubt in the minds of microcomputer-system designers that the 16-bit processors are the wave of the future. Already some major manufacturers are designing the new processors into intelligent terminals, word-processing systems, and other equipment. The day when this revolution within a

revolution will affect the personal and small-business computer marketplace is not too far away.

But if it is obvious that the 16-bit machines will be the trend of future product technology, it is equally obvious that it is relatively difficult for the designer to make a leap from the 8-bit world of the 8080, Z80, 6800 and 6502 to the emerging 16-bit world. The 16-bit instruction sets are more complex. The 8086, for instance, has a repertoire of some 133 instructions, as compared to seventy-eight for the 8080. Simply because of the larger range of memory that can be addressed and because of address segmentation, addressing of memory is more advanced. Also, the register set is more complicated, and the types of operands with which the processor can work are more extensive.

As complex as the 8086 or any other 16-bit microprocessor is from a software viewpoint, it is in the design of hardware circuits to work with the 16-bit processors where the real complexities arise. Peripheral interfaces and existing hardware systems are generally based on an 8-bit data bus. When your whole design is built to make efficient use of an 8-bit data bus, converting to a 16-bit architecture is not a simple matter of replacing the processor. This incompatibility dictates substantial design changes to take advantage of the new 16-bit microprocessor.

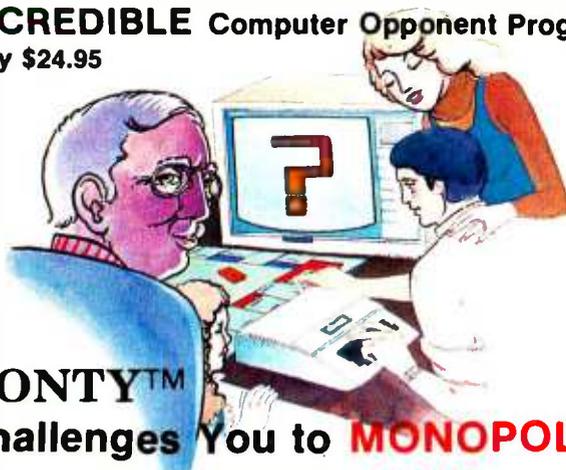
A Gradual Approach to 16-Bit Computing

There is an alternative to converting abruptly to 16-bit architecture. Look at photo 1 and observe the Intel 8088 microprocessor. This device uses an 8-bit data bus, so all of your present hardware system components will work with it from the standpoint of getting information between the processor and the peripheral-support devices or memory, but the 8088 features a common internal architecture and complete software compatibility with the 16-bit 8086 processor.

As a result, the 8088 provides an excellent way for designers, engineers, hobbyists, and students to ease into the world of 16-bit computing. Its 8-bit-compatible bus structure makes it the logical choice for upgrading 6800, 6502, Z80 and 8080 designs to 16-bit capability without

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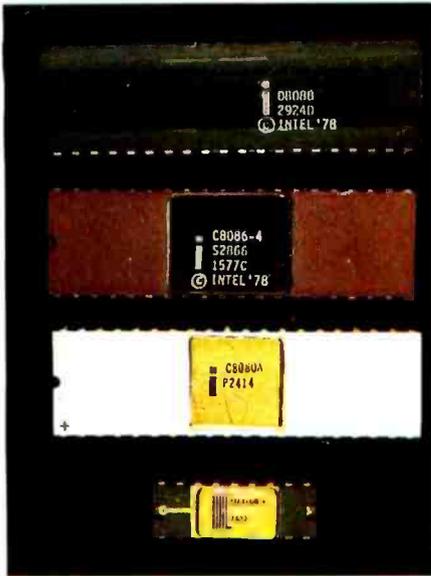


Photo 1: An exhibit of advancing microprocessor technology. Here are four integrated circuits produced by Intel Corporation. From bottom to top, we have the 8008, the first 8-bit general-purpose microprocessor; the 8080A, one of the breed of 8-bit devices that helped ignite the microcomputing boom; the 8086, the advanced 16-bit processor; and the 8088, the subject of this article—a component that contains 16-bit computing capability in a package that can communicate with the outside world through an 8-bit data bus.

alteration of existing 8-bit hardware.

The 8088 can be used in projects such as a low-cost system that employs multiplexed peripherals such as the 8155, 8755A and 8185. Or, fully expanded, it forms a system that allows a full megabyte of address space and compatibility with the 8086 family of coprocessors and multi-processors.

This two-part article is designed to give you a glimpse of the 8088. This month in Part 1, I shall attempt to familiarize you with the instruction set of the 8088 and the hardware of a microcomputer that is made from an 8088 and only four other integrated circuits. The power of this five-chip circuit will be emphasized by illustrating, among other examples, how it can be configured to support a multi-user Tiny BASIC.

Architecture of the 8088

Anyone comparing the internal architectures of the 8088 and the 8086 processors will realize that they are



Photo 2: An exhibit of advancing memory technology. The single black integrated circuit at the center can replace the entire board of components. The center component is the Intel 8185 1 K-byte static programmable memory. The board is a 1 K-byte memory board from a Scelbi 8B microcomputer system, which used the 8008 microprocessor (circa 1975).

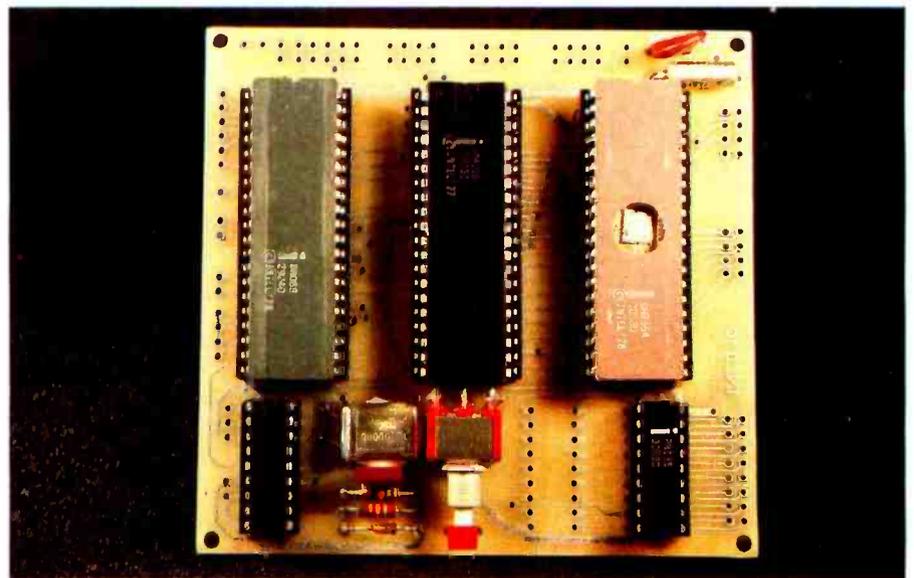


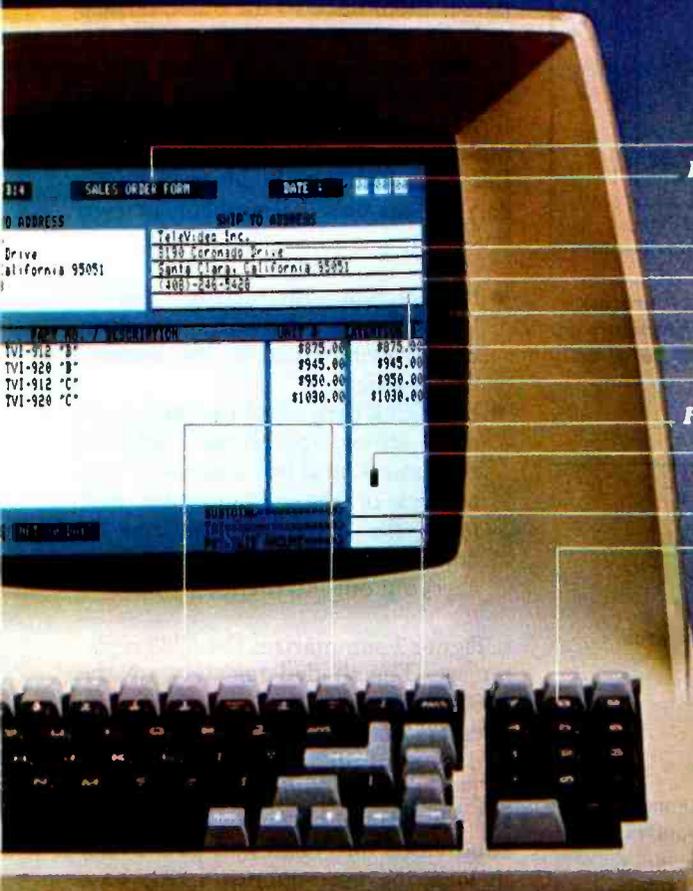
Photo 3: Using the 8088 and other components of kindred technology, it is possible to build a functional microcomputer system with only five integrated circuits. Part 2 of this article (in the April 1980 *BYTE*) will present more detailed information about this system.

identical. Even though I have previously discussed the 8086, a brief explanation of this architecture is necessary since the capabilities of our five-chip computer depend directly upon it. However, if you wish to read a more detailed description, you should refer to a previous Circuit

Cellar article, "The Intel 8086" (November 1979 *BYTE*, page 14).

A diagram of the internal structure of the 8088 is shown in figure 1. The 8088 contains two logical "units", the bus-interface unit (BIU) and the execution unit (EU), and a 4-byte instruction queue.

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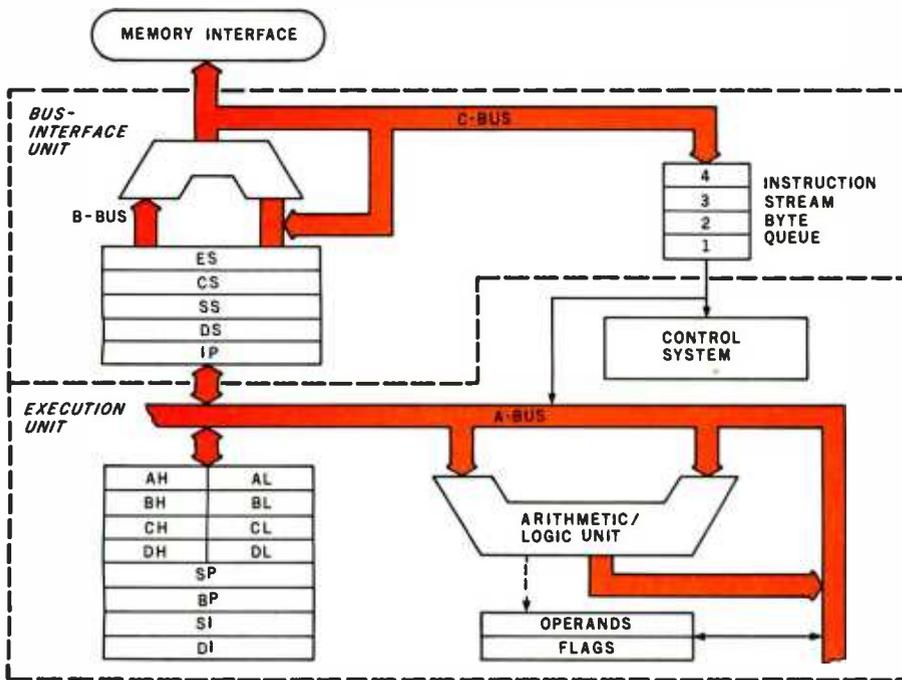


Figure 1: Diagram showing internal operational principles of the 8088 microprocessor. The 8088 (and the 8086) use a pipelined architecture that increases performance by overlapping instruction execution with memory-fetch operations. The 8088 can directly execute any 8086 software.

The *execution unit* is where the actual processing of data takes place inside the 8088. It is here that the familiar arithmetic logic unit (ALU) is located, along with the registers used to manipulate data, store intermediate results, and keep track of the stack. The execution unit accepts instructions that have been fetched by the bus-interface unit, processes the instructions, and returns operand addresses to the bus-interface unit. The EU also receives memory operands through the bus-interface unit, processes the operands, and then passes them back to the bus-interface unit for storage in memory.

The role of the *bus-interface unit* is to maximize bus-bandwidth utilization, (that is, to speed things up by making sure that the bus is used to its full capacity). The bus-interface unit carries out this assignment in two basic ways:

- by fetching instructions *before* they are needed by the execution unit, storing them in the instruction queue
- by taking care of all operand fetch and store operations, address relocation, and bus control (These actions of the bus-interface unit leave the execution unit free to concentrate on processing data and carrying out instructions.)

8088 REGISTER MODEL: (8080 REGISTERS SHADED)

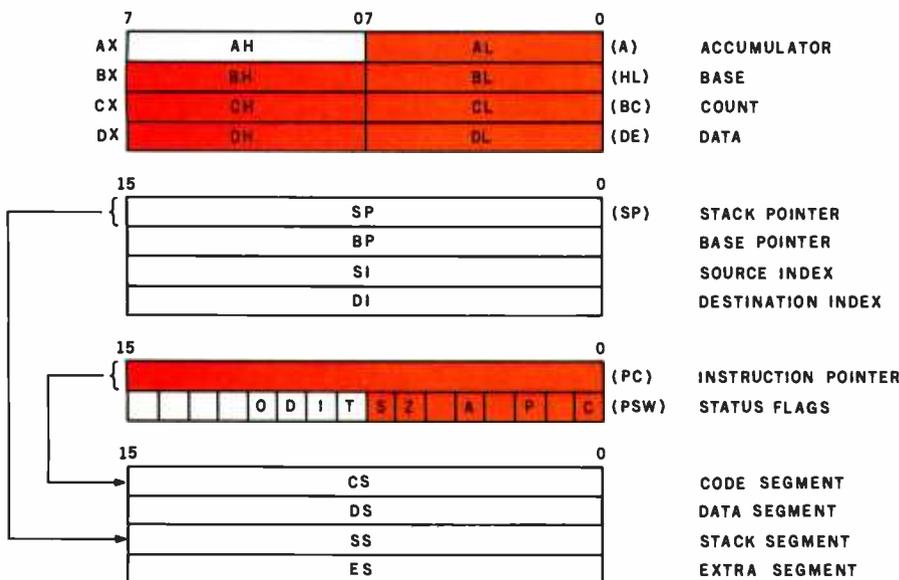


Figure 2: The 8088 contains fourteen 16-bit registers. The shaded registers are those common to the 8088 and the 8080.

Figure 2 summarizes the 8088 register set. The shaded registers are the 8080 register subset, that is, the registers that are common to the 8088 and its 8-bit predecessors.

The *general registers*, also called the HL group because they can be subdivided into *High* and *Low* bytes, include the accumulator (AX), base (BX), count (CX) and data (DX) registers. The AX register may be addressed as a 16-bit register, AX, or the high-order byte can be addressed as the register AH and the low-order byte as AL. The same holds true of the other three general registers (BX, CX, and DX).

Another group of registers is the *pointer and index* (or P and I) group. This set contains the stack pointer (SP), base pointer (BP), source index (SI), and destination index (DI)



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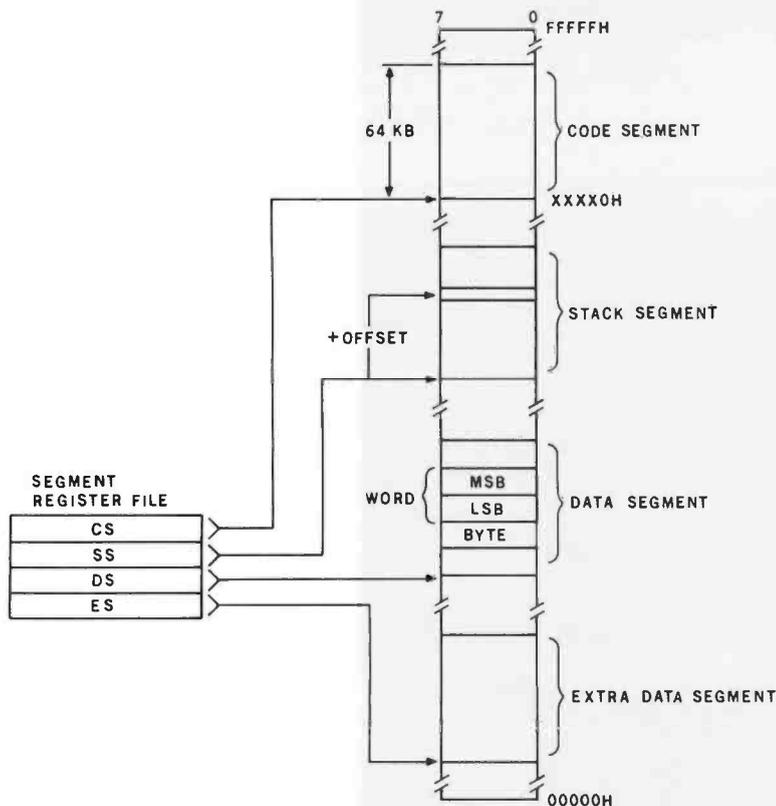


Figure 3: Memory organization. The 8088 uses a memory-segmentation technique to address up to 1,048,576 bytes (1 M byte) of memory. The user can use attributes of the memory-addressing system to dynamically relocate a program anywhere within the entire address space.

registers. Generally speaking, these registers hold offset addresses used for addressing within a segment of memory. They can also participate, along with the general register group, in arithmetic and logical operations of the 8088.

The 8088 uses memory segmentation to address this large memory space efficiently. At any one time, the 8088 can deal with memory as a set of four 64 K-byte segments. The total memory is organized as a linear array of 1,048,576 bytes, addressed as hexadecimal 00000 to hexadecimal FFFFF. The 8088 creates a 20-bit address by combining a 16-bit offset and a segment boundary value stored in one of the segment registers. Figure 3 demonstrates how this works.

Each of the 16-bit-segment registers, the code segment (CS) register, the stack segment (SS) register, the data segment (DS) register, and the extra data segment (ES) register, contains a value that is added to a 16-bit

offset address, forming a 20-bit address. The memory is thus divided into a maximum of four 64 K-byte segments that are active at any single time. The *code segment* of memory is where instructions are stored, the *stack segment* of memory is where the pushdown stack is located, the *data segment* is where data to be operated on is found in memory, and the *extra segment* is an additional 64 K-byte data area.

When fetching an instruction from memory, the location accessed is given by a 20-bit address that is the sum of two numbers. The first number is the value of the 16-bit instruction pointer. The second number is a 20-bit value that is the 16-bit code-segment register with four low-order zero bits appended. This forms the 20-bit address required to specify any location in the megabyte-sized address space.

In the case of a memory-reference operation for a transfer of data, the

absolute memory address referenced by a given memory-access instruction is calculated by adding the given 16-bit address to the base address. The base address is given by the contents of the data-segment or extra-segment register and is followed by four low-order zero bits.

In the case of a stack operation, the memory location referenced is similarly offset from the value contained in the stack-segment register.

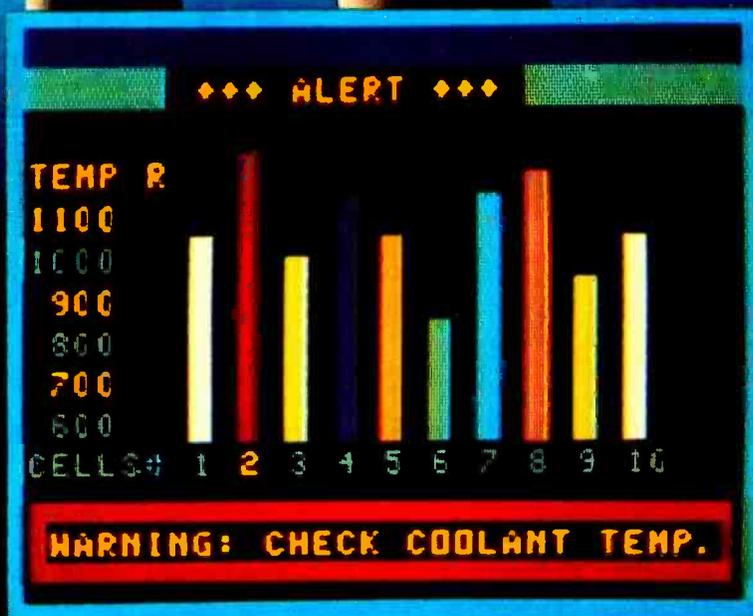
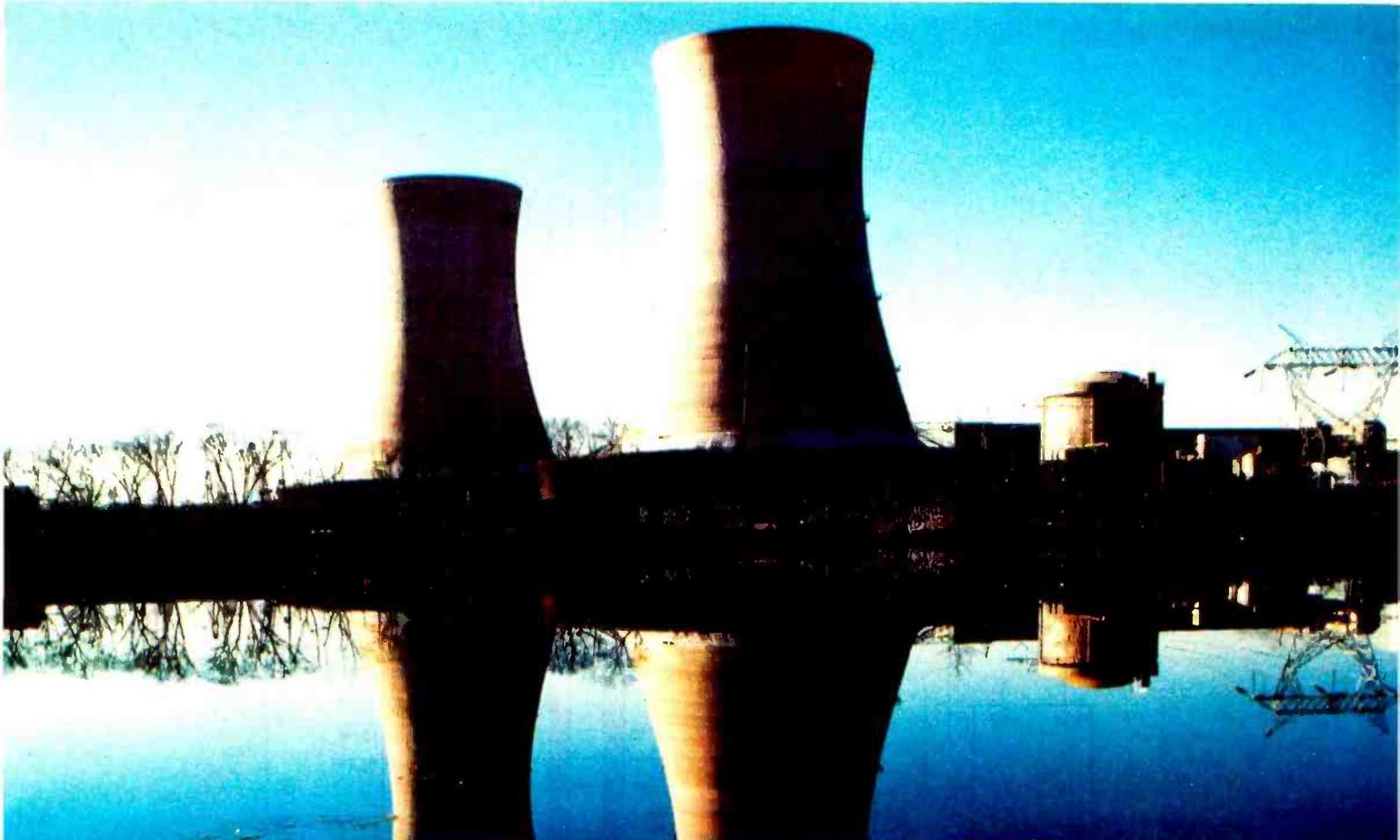
The 8088 has both relative and absolute branch instructions. When all branch instructions within a given segment of memory are specified in relation to the instruction pointer and the program segment does not modify the value of the code-segment register, the program segment can be relocated dynamically anywhere within the megabyte address space. A program is relocated in the 8088 simply by moving the code, updating the value of the code-segment register, and resuming execution.

Small System Applications

The 8088 can be used in a broad range of applications, from systems requiring use of a minimum number of components to systems requiring maximum performance. The component-count-sensitive applications include point-of-sale terminals and simple controllers, which require that system cost be kept low, but need substantial processing power. A big reason for this design flexibility is the ability of the 8088 to operate in a minimum-hardware mode.

The minimum-mode, multiplexed configuration, as shown in figure 4, is an effective way of building a powerful system around the 8088, while using the smallest number of parts. The processor is connected in the minimum mode by wiring its Mn/Mx pin in the high-logic state (at V_{cc} potential). The multiplexed bus is directly compatible with the Intel 8085A-family peripheral components (8155, 8355, 8755A, and the new 8185).

A four-chip system can be designed using the following components: an 8088 microprocessor; an 8284 clock generator; an 8155 memory, input/output (I/O), and timer device; and an 8755A EPROM and I/O device. A fifth component, the 8185, is a simple



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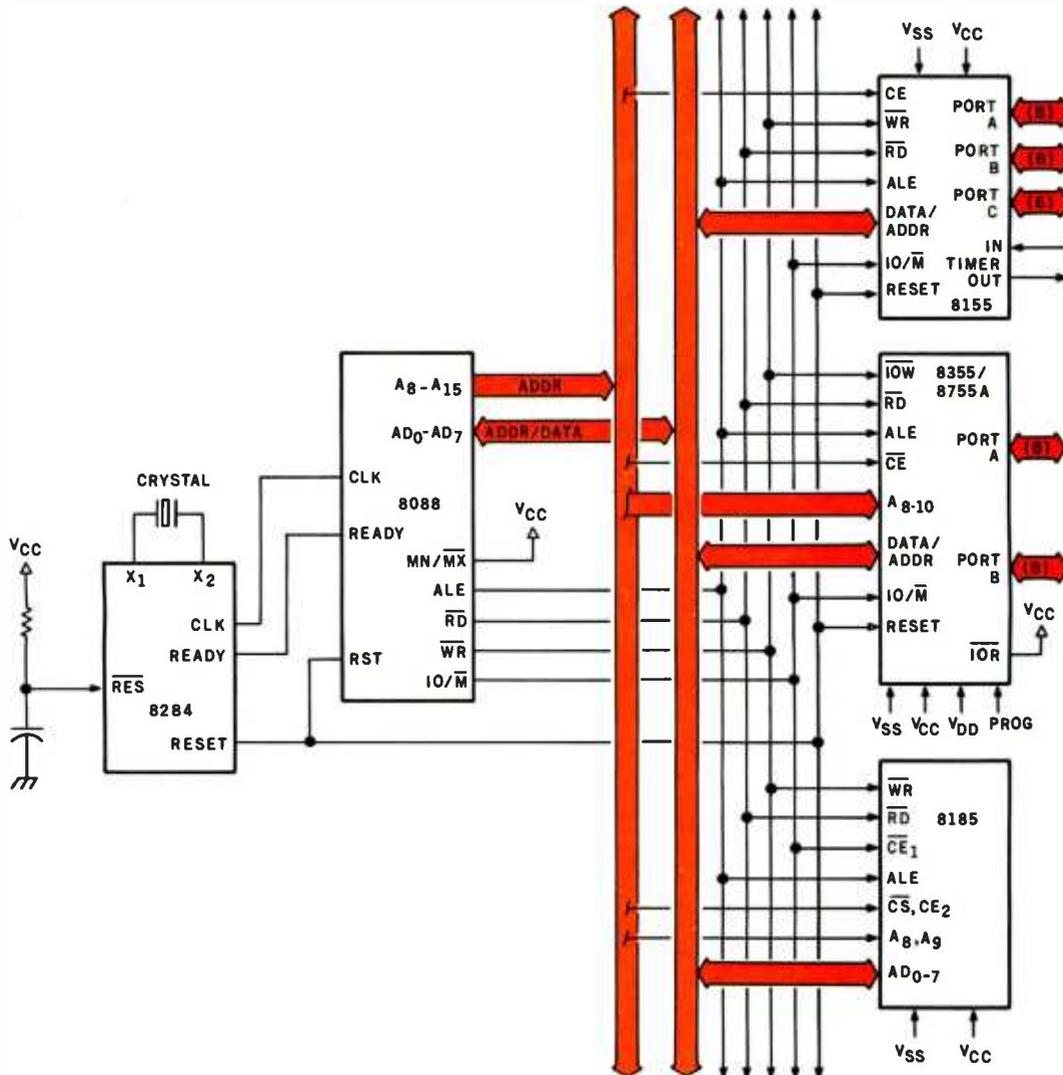


Figure 4: When used in the minimum mode ($\overline{MN}/\overline{MX}$ line held high), the 8088 interfaces directly with the multiplexed address and data components in the 8085A-support family to form a functional microcomputer system using only five integrated circuits. Detailed information concerning this circuit will be given in Part 2.

addition to the system and provides an extra 1 K bytes of user memory.

In the minimum-mode configuration, the 8088 provides all necessary bus-control signals, including \overline{RD} , \overline{WR} , $\overline{IO}/\overline{M}$ and ALE. It further provides HOLD and HLDA (hold-acknowledge) signals to allow direct-memory-access (DMA) data transfer, INT and \overline{INTA} to interface the 8259A interrupt controller, and \overline{DEN} and $\overline{DT}/\overline{R}$ to control transceivers on the data bus.

The power of the 8088 can be extended in large-system applications by wiring it into the maximum-mode configuration. However, a discussion

of maximum-mode features is beyond the scope of this article.

The 8088 Instruction Set

A complete discussion of the 8088's instruction set is also beyond the scope of this article. Rather than attempt it, I shall concentrate on some specific features of the 8088 instruction set that facilitate the specific application discussed next month in Part 2 of this article. These features include extended arithmetic instructions, direct use of ASCII-encoded data, multiprocessing features, string-manipulation instructions, and table-translating aids. The

8088 instruction set includes single-instruction multiplication and division instructions, along with five different types of addition and seven types of subtraction operations.

These multiply and divide instructions greatly facilitate "number crunching." This numerical ability saves much time in such applications as data sampling, signal processing, and scientific calculation. Not only are fewer machine instructions needed to perform a given task, with corresponding savings in memory usage and execution time, but the versatility of the instructions and the

Text continued on page 30

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Listing 1: An example of the efficiency of the 8088 and 8086 instruction set. This short routine accepts input of five values from an input port, and then calculates and sends a running-average value to an output port. Compare this listing with listing 2.

```

XOR    BX, BX           ;CLR BX
MOV    CX, 5           ; Set loop counter

Average INC    BL           ;Increment data counter
IN     AL, Port #     ;Input data
ADD    BH, AL         ;Update running total
MOV    AL, BH
DIV    BL             ;Divide running total by
                           ;data counter.

OUT    Port #, AL     ;Output running average.

LOOP   Average       ;Return unless fifth pass
                           ;is completed.

HLT

```

Listing 2: A routine that performs the same task as the routine given in listing 1. This code, however, was written for the older 8080 processor. As you can see, it is longer and more tedious to write.

```

MVI    H,00           ;Clear H register
MVI    E,00           ;Clear E register

Average INR    E           ;Increment data counter

MOV    C, H
IN     A, Port #     ;Input data
ADD    H             ;Add data to running total

Divide XRA    A           ;Clear accumulator
MOV    B, A           ;Clear B register
MOV    L, A           ;Clear L register
MVI    C, 80         ;Initialize bit counter

Loop   MOV    A, C     ;Shift B and C as
RAL                    ;a 16-bit unit—
MOV    C, A           ;one bit left
MOV    A, B
RAL
MOV    B, A

CMP    E             ;Compare data
JC     Next          ;counter (divisor) with
                           ;dividend; if divisor is larger,
                           ;bypass subtract.
SUB    E             ;Divisor is smaller; subtract.
MOV    B, A
MOV    A, D
ORA    L
MOV    L, A

Next   MOV    A, D     ;Shift D right and check carry
RRC
INC    Loop          ;If no carry, return for next bit.

MOV    A, L           ;Outport running average
OUT    Output #

MVI    A, 05         ;Return unless fifth pass is
CMP    E             ;completed.
JNZ    Average

HLT

```

Text continued from page 26

ability of the 8088 to deal with several types of data remove the usual necessity of handling messy conversions from one type of data representation to another and back again.

Two program listings demonstrate the saving of effort. Listing 1 gives the 8088 code for the skeleton of a subroutine that accepts data from a specified input port and calculates a running average of the values entered. The same subroutine section coded for the older 8080 microprocessor is shown in listing 2.

Direct Use of ASCII and Decimal Data

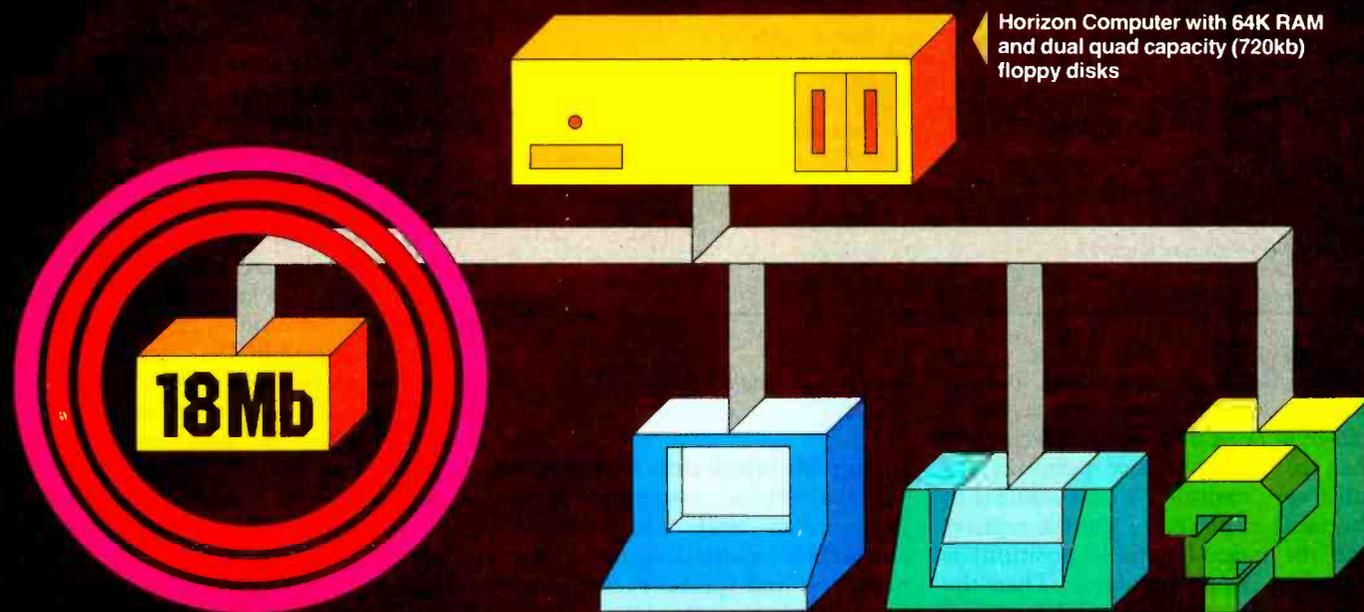
The direct use of unpacked binary-coded decimal (BCD) or ASCII-encoded data in a microcomputer has a number of obvious advantages. Since many I/O devices present data to the processor in American Standard Code for Information Interchange (ASCII) format and expect responses in the same format, microcomputer-system designers have for years faced the necessity of putting their input and output through a translation process (usually involving a table look-up operation) before processing the input or responding with output.

With the 8088's instruction set, such manipulation is no longer necessary. All four mathematical instruction types (add, subtract, multiply, and divide) provide for ASCII adjustment of the accumulator contents by a single instruction. This feature is obviously of great use in everyday microprocessor applications. Equally interesting (and useful) are the two instructions that adjust the results of addition and subtraction to packed decimal form.

Table-Translating Aid

Despite the availability of single instructions to convert accumulator contents from one type of data representation to another, it may still be necessary from time to time to translate data by means of the traditional look-up table. This might, for example, be necessary if the data is being received or transmitted in EBCDIC (Extended Binary-Coded-Decimal Interchange Code) rather than in ASCII form.

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Listing 3: A segment of 8088 code that translates characters from Extended Binary-Coded-Decimal Interchange Code (EBCDIC) to American Standard Code for Information Interchange (ASCII) form. The 8088 instructions for manipulating and translating strings of characters are put to good use.

```

MOV     SI, FFFE      ; Source index register contains start of EBCDIC Buffer
MOV     BX, 0100     ; B register points to translate table
MOV     DI, ASCBUF   ; Destination index points to ASCII buffer
MOV     CX, 528      ; C register contains length of buffer
CLD
JCXZ   EMPTY        ; Skip if input buffer empty
NEXT:  LODS          ; Get next EBCDIC character
       XLAT         ; Translate to ASCII
       STOS         ; Transfer ASCII character to buffer
       CMP         AL, EOT ; Test for EOT character
       LOOPNE      NEXT ; Continue if no EOT received (CX decrements first)

```

EMPTY: (Program continues)

incrementing or decrementing of a predetermined count.

Putting Some Things Together

Let's take a quick look at a small but powerful example that employs both the string manipulation and the XLAT instructions to solve a very practical problem.

You are designing an input routine that must translate a buffer filled with EBCDIC characters into ASCII form, continuing the transfer until one of several possible EBCDIC characters is received. The transferred ASCII string should be terminated with an EOT (end-of-transmission, hexadecimal value 04) character. Assume that the buffer starts at hexadecimal memory location FFFE, the table to translate the EBCDIC form to ASCII begins at hexadecimal location 0100 and the CX register is to contain a value giving the length of the buffer containing EBCDIC characters. The buffer may, of course, be empty.

The small 8088 program segment shown in listing 3 accomplishes this task in a small number of instructions and handles a great deal of overhead work with little effort or concern on the part of the system designer and programmer.

By now you should have an understanding of the power of the 8088 microprocessor. Even in a minimal-mode, five-component circuit, our little computer will have the following attributes:

- 5 MHz 8088 8-bit processor (completely 8086 software-compatible)
- 1280 bytes of static user memory
- 2048 bytes of erasable, programmable read-only memory (EPROM)
- 38 parallel I/O lines
- a 14-bit counter/timer
- power-on reset and nonmaskable interrupt.

Next month, in Part 2, we will deal with some key features of the 8088 which make it particularly suited to multiprocessing situations. We will investigate the operating system of a multi-user, Tiny BASIC language system on our minimal-configuration computer. ■

These figures are provided through the courtesy of Intel Corporation.

The XLAT (ie: translate) instruction allows the user to define a 256-byte table of correspondence and then to reference any point in the table very easily. The base address of the table is placed in the BX register and the index (ie: table position) is stored in the accumulator. Then the single instruction code XLAT is used to refer to the proper point in the table, pick out the translation, and store the result in the accumulator.

This is useful particularly when data that has been entered from a port comes into the accumulator for disposition or transfer. If you are dealing with a stream of incoming characters in EBCDIC format, for example, the translation proceeds thusly. You begin by storing the beginning memory address of your 256-byte translation table in the BX register. If you set up the table so that the base address of the table corresponds to an incoming EBCDIC value of 00, the next address to an incoming value of 01, etc, all you must do is simply accept a byte of data and execute the XLAT instruction.

This simple procedure lets us obtain the correct translation of that byte into the proper format for handling by the 8088 or some other processor. A MOV instruction will then store the result of translation until it is needed; the translation process can then be repeated with the next incoming byte. Setting up the necessary instruction sequence requires one instruction: a MOV to the BX register of the base address of the table. The loop for handling the translation requires only three basic instructions:

the input instruction, XLAT, and MOV.

String-Manipulation Instructions

Since typical computer applications often deal with strings of characters consisting of letters, numbers, and special symbols, easy-to-use string-manipulation instructions are a welcome enhancement to 8-bit processors. The 8088 addresses this need by providing five powerful primitive string operators that may be preceded by a single-byte repetition prefix.

For a byte-for-byte or word-for-word comparison of two data strings (as you might use in verifying the accuracy of data loaded into memory from a mass-storage device, for example), the 8088 offers the CMPS instruction. This also allows termination of a program segment upon occurrence of a predetermined equality or inequality condition, as well as automatic incrementing or decrementing.

You can scan through a string of data for an occurrence or for an absence of occurrence of a specific string or character by using the SCAS instruction. This operation subtracts the byte or word operand in memory (or elsewhere) from the accumulator and changes the logic state of the flags; it does not, however, return a result. Again, decrementing or incrementing is automatic.

The STOS instruction allows you to fill a string of arbitrary length with a single value (eg: a string of zeros or nulls for a floppy disk initialization routine), once more with automatic

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Electron Behavior in a Chemical Bond

Michael Liebl, OSB
Mount Michael High School
Elkhorn NB 68022

Years spent subconsciously gathering and sifting data in our daily lives gives each of us a common sense intuition for the laws of nature. But our intuitive understanding of how nature works often fails when we explore worlds beyond the realm of common experience. In the sub-microscopic world of atoms and molecules, matter exhibits unexpected behavior attributable to its dual nature as particle and wave. Scientists interpret this world with the aid of quantum mechanics, a discipline that more often than not involves long and complicated mathematical operations.

The computer, by virtue of the ease and speed with which it handles such operations, has become an invaluable tool in the quantum-mechanical study of atoms and molecules. This article describes a program written in BASIC which allows anyone with an elementary understanding of quantum mechanics to investigate the behavior of an electron in the bond formed between two atoms in a diatomic molecule.

Electronic Potential Well

A chemical bond is the result of attractive, electric interaction between the atoms' electrons which are negatively charged and the nuclei which are positively charged. Opposite charges attract; like charges repel. In the vicinity of the nucleus of an atom, an electron feels an attractive force. The environment in which the electron is subject to this force is

described as a *potential*. A rectangular *potential well*, as shown in figure 1, is an approximate model of the relation between an electron and its nucleus. The depth of this rectangular well determines the extent to which the electron is confined to the region about the nucleus. If the well is deep, it is difficult for the electron to cross the boundaries of the high walls. If, on the other hand, the well is shallow, then it is relatively easy for the electron to escape the nucleus.

A molecular bond can form when two atoms exchange or share an electron. For example, table salt is composed of two elements, sodium, an alkali metal, and chlorine, a halogen. Sodium, like all alkalis, can arrive at a stable electronic configuration by giving away one of its electrons to form a positively charged sodium ion. This element has a *shallow*

potential well. Chlorine, like all halogens, can arrive at a stable electronic configuration by accepting an extra electron to form a negatively charged chloride ion. Chlorine has a *deep* potential well.

A bond can form between a sodium atom and a chlorine atom, and between any alkali and any halogen, when the former donates an electron to the latter. The result is a molecule, the positively charged sodium ion bound to the negatively charged chloride ion. We will use the potential well model to study different elements and the bonds that they make.

No two elements are exactly alike either in their ability to receive or in their ability to donate an electron. Thus the behavior of the electron in a chemical bond depends upon certain properties of the two elements involved. To determine the depth of the rectangular potential well for a given element, we will refer to two characteristic properties of the elements: ionization potential and electron affinity.

Ionization potential is a measure of the amount of energy required to remove an electron from a neutral atom of some element X: $X \rightarrow X^+ + e^-$. For alkalis this number is small, for halogens large. *Electron affinity* is a measure of the amount of energy released when a neutral atom acquires an extra electron: $X + e^- \rightarrow X^-$. For alkalis this number is 0, for halogens the number is large. (For values of ionization potentials and

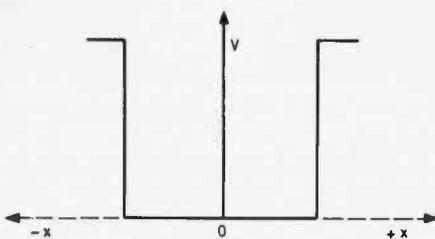


Figure 1: Rectangular potential well model that approximates the relation of an electron to the nucleus of an atom. The depth of the well indicates the extent to which the electron is confined to the region about the nucleus.

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electron affinities see the *Handbook of Chemistry and Physics* published by the Chemical Rubber Company.) The depth of the potential well of any element, that is, its ability to hold on to an electron, can be estimated by averaging the element's ionization potential and electron affinity.

Composite Potential Model

When two atoms form a *diatomic* molecule, each of the atoms brings its potential well to the bond. The electron exchanged or shared by the two atoms can be pictured as being confined to a composite rectangular well that consists of the two potential wells placed side by side, as shown in figure 2. Unless the two atoms are of the same element, one side of the composite well will be deeper than the other. The difference in height between the two levels of the well is the essential feature of the bond which determines how much time the electron spends in the vicinity of one atom's nucleus as compared to the other.

Because the *difference* in height is the crucial factor, the lower level of the potential well can always be

assigned as the origin on the potential axis of a Cartesian coordinate system. The upper level of the well is located at the point that represents the difference between the averages of the ionization energies and electron affinities of the two elements. Finally, it is also convenient to assume that the walls of the potential well at the endpoints of the bond are infinitely high. Given this assumption, it is impossible for the electron to escape the confines of the molecule. This potential model of the bond in a diatomic molecule simplifies the equations that describe the behavior of the electron in the bond.

Schrödinger Wave Equation

In 1926, Erwin Schrödinger formulated a differential equation to describe the behavior of a submicroscopic particle such as an electron. This equation incorporates both the particle and wave nature of the electron. Fundamentally, Schrödinger's equation is a restatement of the basic energy relation; the kinetic energy, $p^2/2m$ (derived from momentum and mass), plus the potential energy, V , yields the total energy, E ,

of any particle:

$$p^2/2m + V = E$$

Schrödinger's equation takes the form:

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} + V\psi = E\psi$$

for a single-dimension model.

In the equation, \hbar is read as "h-bar," and stands for a value equal to Planck's constant divided by 2π . Planck's constant, h , is an empirically determined value equal to 6.6256×10^{-34} Joule-seconds. The mass of the particle is shown as m . The Greek psi (ψ) is the notation for the wave function. In Schrödinger's formulation, the energy equation has been multiplied by a wave function, ψ , to account for the wave-like behavior of submicroscopic particles, and the square of the momentum has been replaced by the differential operator, $-\hbar^2 d^2/dx^2$.

When the Schrödinger equation is solved for a particular set of circumstances, called *boundary conditions*, it yields as a solution the form of ψ , the wave equation. ψ^2 gives the relative probability, for the conditions assumed, of finding the particle it describes at some point in space. It is known as the *probability distribution function*.

In our model, the depth of the rectangular potential well is a measure of the magnitude of the potential energy, V , which acts on the electron and affects its location. In a split-level well the deeper side exerts a greater force on the electron. Therefore we

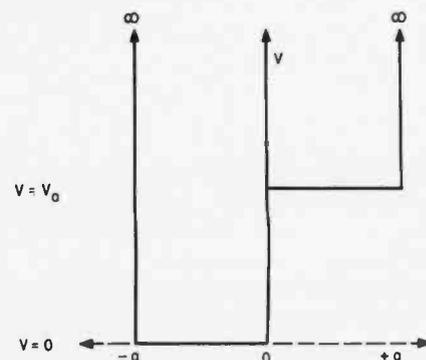


Figure 2: When a diatomic molecule is formed, the relationship between the two atoms may be considered as a combination of two potential wells.

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m	mass of an electron; 9.109×10^{-31} kilograms
q	charge on an electron; 1.602×10^{-19} Coulombs
\hbar	Planck's constant divided by 2π ; 0.658×10^{-15} electron-volt-seconds
p	momentum of the electron
a	length of chemical bond
V_0	potential difference between elements
E	total energy of the electron
A	coefficient of the wave equation, ψ_L , for the left side of the potential well
B	coefficient of the wave equation, $\psi_{R,1}$, for the right side of the potential well when $E > V_0$
C, D	coefficients of the wave equation, $\psi_{R,II}$, for the right side of the potential well when $E < V_0$

Table 1: Symbols and constants that are used throughout this article.

would expect the probability distribution function, ψ^2 , to be skewed toward the deeper side of the well.

Two-Part Equation Solution

For the potential well pictured in figure 2, the Schrödinger equation is solved in two parts, corresponding to the lower or left side and to the upper or right side of the well. The potential in the left side of the well is equal to zero. The potential in the right side of the well is equal to the difference between the potentials of the two elements, V_0 .

The wave-equation solution, ψ , must meet four requirements:

- At the left boundary of the well, the potential wall is infinitely high. There is no possibility for the electron to pass beyond this point. Therefore at $x = -a$, the value of the function ψ_L must be zero.
- Similarly, the wall at the right boundary is infinitely high. There is no possibility for the electron to pass beyond this point. Consequently at $x = +a$, ψ_R must also be equal to zero.
- We are studying a single electron. Although we attack the solution in two parts that correspond to the two sides of the potential well, a

Text continued on page 44

Listing 1: BASIC program that solves the Schrödinger equation to simulate the behavior of an electron in a diatomic chemical bond. The program finds αa , βa , and γa in terms of V_0 .

The correspondence of variables in the program to terms in the equations is as follows: A1 stands for αa ; B1 stands for βa ; G1 stands for γa ; V0 stands for V_0 .

```

10 REM PROFILE OF A CHEMICAL BOND IN A DIATOMIC MOLECULE
20 REM WRITTEN BY MICHAEL LIEBL
30 REM CALCULATION OF N AND V0
40 REM PROGRAM LINES 10-1000
50 PRINT : PRINT : PRINT
60 DIM S$(10),R(10),IP(10),EA(10)
70 PRINT TAB(20);"--PROFILE OF A CHEMICAL BOND--"
80 PRINT
90 PRINT"    THE ELECTRON DENSITY IN THE CHEMICAL BOND OF A DIATOMIC MOLECULE"
100 PRINT"DEPENDS UPON THE POTENTIAL DIFFERENCE (V0) BETWEEN THE TWO ELEMENTS"
110 PRINT"WHICH ARE BOUND TOGETHER AND UPON THE LENGTH OF THE BOND (A).  THE"
120 PRINT"AVERAGE OF THE IONIZATION ENERGY AND THE ELECTRON AFFINITY OF AN"
130 PRINT"ELEMENT OFFERS A MEASURE OF THE POTENTIAL OF THE ELEMENT."
140 PRINT
150 PRINT"    THIS PROGRAM CALCULATES A PROFILE OF A CHEMICAL BOND BASED"
160 PRINT"UPON THIS INFORMATION.  FROM THE LIST OF ELEMENTS BELOW, SELECT TWO"
170 PRINT"WHICH WILL MAKE UP THE MOLECULE.  ENTER THE SYMBOLS FOR THESE"
180 PRINT"ELEMENTS AT THE REQUEST OF THE PROGRAM."
190 PRINT : PRINT
195 F=0
200 PRINT TAB(10)"HYDROGEN    -  H"
210 PRINT TAB(10)"LITHIUM     -  Li";TAB(40)"FLUORINE    -  F"
220 PRINT TAB(10)"SODIUM      -  Na";TAB(40)"CHLORINE   -  Cl"
230 PRINT TAB(10)"POTASSIUM   -  K";TAB(40)"BROMINE    -  Br"
240 PRINT TAB(10)"RUBIDIUM    -  Rb";TAB(40)"IODINE     -  I"
250 PRINT TAB(10)"CESIUM     -  Cs"
260 PRINT
270 PRINT
280 INPUT"ENTER ELEMENT NUMBER ONE - ";A$
290 FOR I=1 TO 10
300 READ S$(I),R(I),IP(I),EA(I)
310 IF S$(I) <> A$ THEN NEXT I
320 IF I > 11 THEN 350
330 GOSUB 800
340 GOTO 280
350 RESTORE
360 INPUT"ENTER ELEMENT NUMBER TWO - ";A$
370 FOR J=1 TO 10
380 READ S$(J),R(J),IP(J),EA(J)
390 IF S$(J) <> A$ THEN NEXT J
400 IF J > 11 THEN 430

```

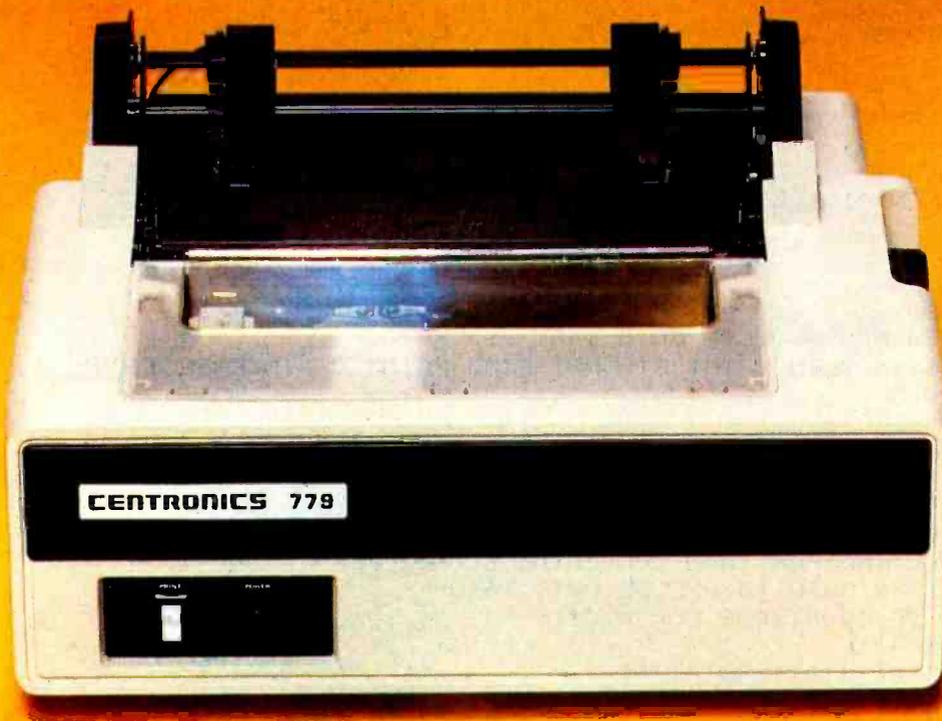
Listing 1 continued on page 38

Listing 1 continued:

```
410 GOSUB 800
420 GOTO 360
430 RESTORE
440 PRINT : PRINT : PRINT
450 M=9.109E-31
460 Q9=1.602E-19
470 H=0.658E-15
480 A=(R(I)+R(J))*1E-10
490 V1=(IP(I)+EA(I))/2
500 V2=(IP(J)+EA(J))/2
510 V0=V2-V1
520 IF V0<0 THEN V0=-V0
530 N=SQR(2*M*V0/Q9)*A/H
540 N2=N^2
550 PRINT"V0 = ";
560 PRINT USING"###.###";V0
570 PRINT" N = ";
580 PRINT USING"###.###";N
590 PRINT : PRINT : PRINT
600 INPUT"WHEN READY TO CONTINUE TYPE A CARRIAGE RETURN. ";A$
610 GOTO 1010
800 REM SYMBOL ENTRY ERROR
810 PRINT
820 PRINT"THE CHEMICAL SYMBOL ENTERED DOES NOT MATCH ANY IN THE FILE. CHECK"
830 PRINT"THE LIST AND TRY AGAIN."
840 PRINT
850 RESTORE
860 RETURN
900 REM DATA FILE
910 DATA H, 1.54, 13.595, 0.80
920 DATA Li, 0.68, 5.39, 0
930 DATA Na, 0.97, 5.138, 0
940 DATA K, 1.33, 4.339, 0
950 DATA Rb, 1.47, 4.176, 0
960 DATA Cs, 1.67, 3.893, 0
970 DATA F, 1.33, 17.418, 3.448
980 DATA Cl, 1.81, 13.01, 3.613
990 DATA Br, 1.96, 11.84, 3.363
1000 DATA I, 2.20, 10.454, 3.063
1010 REM CALCULATION OF A1 AND B1 OR G1, LINES 1010-1780
1020 PRINT
1030 PRINT"GRAPHICAL SOLUTION OF"
1040 PRINT"TRANSCENDENTAL EQUATION"
1050 PRINT
1060 PRINT TAB(6);"-30";TAB(36);"0";TAB(64);"+30"
1070 FOR A=1 TO 60
1080 PRINT TAB(A+6);"-";
1090 NEXT A
1100 PRINT
1110 PRINT " -A1-";TAB(36);"!"
1120 FOR A1=.1 TO 3.2 STEP .1
1130 PRINT USING " #.###";A1;
1140 PRINT"--1";
1150 A2=A1^2
1160 GOSUB 1530
1170 IF INT(Y1)=INT(Y2) THEN GOTO 1290
1180 IF Y2<Y1 THEN GOTO 1240
1190 IF ABS(Y1)<=30 THEN PRINT TAB(36+Y1);"+";
1200 IF ABS(Y2)<=30 THEN PRINT TAB(36+Y2);"*" ELSE GOTO 1220
1210 GOTO 1300
1220 PRINT""
1230 GOTO 1300
1240 IF ABS(Y2)<=30 THEN PRINT TAB(36+Y2);"*";
1250 IF ABS(Y1)<=30 THEN PRINT TAB(36+Y1);"+" ELSE GOTO 1270
1260 GOTO 1300
```

Listing 1 continued on page 40

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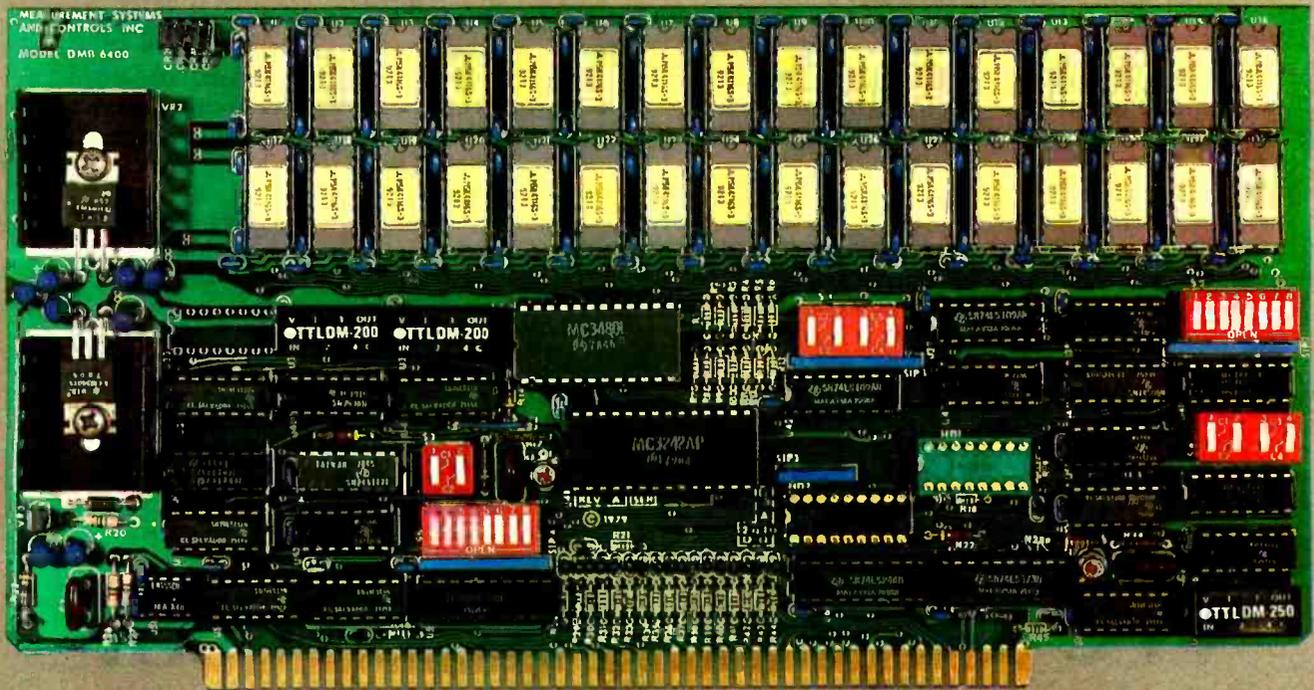
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Listing 1 continued:

```
1270 PRINT""
1280 GOTO 1300
1290 PRINT TAB(36+Y1);"x"
1300 NEXT A1
1310 FOR A=1 TO 60
1320 PRINT TAB(6+A);"-";
1330 NEXT A
1340 FOR A=1 TO 3
1350 PRINT
1360 NEXT
1370 PRINT"AT WHAT VALUE OF A1 DO THE LINES SEEM TO INTERSECT?"
1380 PRINT"A1= ";
1390 INPUT A1
1400 IF N=0 THEN A1=1.57079
1410 G9=1000
1420 A1=A1+.0004
1430 A2=A1^2
1440 GOSUB 1530
1450 IF S<G9 THEN G9=S ELSE GOTO 1480
1460 IF A1=3.1416 THEN PRINT"DID NOT FIND POINT OF INTERSECTION"
1470 GOTO 1420
1480 PRINT
1490 PRINT"THE POINT OF INTERSECTION IS:"
1500 PRINT"A1= ";
1510 PRINT USING "##.###"; (A1-.0004)
1520 GOTO 1670
1530 REM SUBROUTINE FOR TRANSCENDENTAL EQUATION
1540 IF N>A1 THEN GOTO 1560 ELSE GOTO 1610
1550 REM PAIR OF EQUATIONS FOR N>A1
1560 Q1=SQR(N2-A2)
1570 Y1=Q1*SIN(A1)/(A1*COS(A1))
1580 Y2=- (EXP(Q1)-EXP(-Q1))/(EXP(Q1)+EXP(-Q1))
1590 S=(Y1-Y2)^2
1600 RETURN
1610 REM PAIR OF EQUATIONS FOR N<A1
1620 Q2=SQR(A2-N2)
1630 Y1=Q2*SIN(A1)/(A1*COS(A1))
1640 Y2=-SIN(Q2)/COS(Q2)
1650 S=(Y1-Y2)^2
1660 RETURN
1670 REM END SEARCH
1680 A2=A1^2
1690 IF N>A1 THEN G2=N2-A2 ELSE B2=A2-N2
1700 G1=SQR(G2)
1710 B1=SQR(B2)
1720 IF N<A1 THEN GOTO 1760
1730 PRINT"G1= ";
1740 PRINT USING "##.###";G1
1750 GOTO 1780
1760 PRINT"B1= ";
1770 PRINT USING "##.###";B1
1780 PRINT
2000 REM CALCULATION OF PSI
2010 PRINT"--CALCULATION OF PSI--"
2020 PRINT
2030 REM CHOICE OF OUTPUT
2040 PRINT"DO YOU WANT OUTPUT AS TABLE OF VALUES (1) OR IN GRAPHICAL FORM (2)?"
2050 PRINT"ENTER A 1 OR 2"
2060 INPUT Z9
2070 IF Z9=1 THEN GOTO 2090
2080 IF Z9=2 THEN GOTO 2310 ELSE GOTO 2050
2090 REM TABLE OF VALUES
2100 PRINT TAB(9);"TABLE OF VALUES"
2110 PRINT TAB(8);"-----"
2120 PRINT
```

Listing 1 continued on page 43



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Listing 1 continued:

```

2130 PRINT TAB(4);"A";TAB(17);"PSI";TAB(26);"(PSI)^2"
2140 FOR P=-16 TO 0
2150 GOSUB 2610
2160 GOSUB 2830
2170 NEXT P
2180 FOR F=1 TO 16
2190 GOSUB 2680
2200 GOSUB 2830
2210 NEXT F
2220 PRINT
2230 IF F=1 THEN 3000
2240 PRINT"WOULD YOU LIKE TO SEE THE GRAPHICAL FORM?"
2250 PRINT"ENTER A YES OR NO"
2260 F=1
2270 INPUT A$
2280 IF A$="YES" THEN GOTO 2310
2290 IF A$="NO" THEN 3000
2300 GOTO 2250
2310 REM GRAPHICAL FORM
2320 PRINT
2330 PRINT TAB(9);"GRAPHICAL FORM"
2340 PRINT TAB(8);"-----"
2350 PRINT
2360 PRINT TAB(10);"(PSI)^2"
2370 PRINT
2380 FOR A=1 TO 50
2390 PRINT TAB(12+A);"_"
2400 NEXT A
2410 PRINT
2420 FOR P=-16 TO 0
2430 GOSUB 2610
2440 GOSUB 2900
2450 NEXT P
2460 FOR F=1 TO 16
2470 GOSUB 2680
2480 GOSUB 2900
2490 NEXT F
2500 IF F=1 THEN 3000
2510 PRINT
2520 PRINT"WOULD YOU LIKE TO SEE THE TABLE OF VALUES?"
2530 PRINT"ENTER A YES OR NO"
2540 F=1
2550 INPUT A$
2560 IF A$="YES" THEN GOTO 2090
2570 IF A$="NO" THEN 3000
2580 GOTO 2530
2590 PRINT
2600 GOTO 3000
2610 REM SUBROUTINE FOR PSI FROM -16 TO 0
2620 W=P/16
2630 X=W*A
2640 A9=1
2650 P1=A9*SIN(A1*(X+A)/A)
2660 P2=P1^2
2670 RETURN
2680 REM SUBROUTINE FOR PSI FROM 0 TO 16
2690 W=P/16
2700 X=W*A
2710 IF N>A1 THEN GOTO 2720 ELSE GOTO 2790
2720 D=A9*SIN(A1)
2730 C=-D*(EXP(G1)+EXP(-G1))/(EXP(G1)-EXP(-G1))
2740 E5=EXP(G1*X/A)
2750 E6=EXP(-G1*X/A)
2760 P1=C*(E5-E6)/2+D*(E5+E6)/2
2770 P2=P1^2

```

Listing 1 continued on page 44

Listing 1 continued:

```
2780 GOTO 2820
2790 B=A9*SIN(A1)/SIN(B1)
2800 P1=B*SIN(B1*(A-X)/A)
2810 P2=P1^2
2820 RETURN
2830 REM SUBROUTINE FOR TABLE OF VALUES
2840 PRINT USING "##.###";W;
2850 PRINT TAB(14);
2860 PRINT USING " #.###";P1;
2870 PRINT TAB(26);
2880 PRINT USING " #.###";P2
2890 RETURN
2900 REM SUBROUTINE FOR GRAPHICAL FORM
2910 P9=INT(50*P2)
2920 PRINT TAB(5);
2930 PRINT USING"##.###";W;
2940 PRINT "1";
2950 FOR F9=0 TO P9
2960 IF F9+13<>13 THEN PRINT TAB(F9+13);"=";
2970 NEXT F9
2980 PRINT
2990 RETURN
3000 REM CONTINUE OR FINISH
3010 PRINT : PRINT
3020 PRINT"WOULD YOU LIKE TO STUDY ANOTHER PAIR OF ELEMENTS?"
3030 PRINT"ENTER A YES OR NO"
3040 INPUT A$
3050 IF A$="YES" THEN 190
3060 IF A$<>"NO" THEN 3030
3070 END
```

Text continued from page 37:

single function, ψ , must describe a single particle. Thus at the junction of the two sides of the well, the solution for the left side must take on the same value as the solution for the right side:

$$\psi_L = \psi_R \text{ at } x = 0$$

- In addition, the solutions for the left and the right sides must fit together smoothly at the junction of the two sides.

Mathematically, this fourth requirement is met if the first derivatives of the solutions for the left and the right sides of the well take on the same value at the junction:

$$\frac{d\psi_L}{dx} = \frac{d\psi_R}{dx}$$

at $x = 0$.

There is a further complication in the solution for the right side of the potential well. Two cases must be distinguished. The total energy of the

electron, E , may be greater than the potential difference between the elements, V_0 , or E may be less than V_0 . According to classical theory, if E were less than V_0 , the electron would never be able to pass into the region of the bond that is represented by the upper level of the potential well. But such is not the case in quantum mechanics.

Because of the wave-like nature exhibited by submicroscopic particles, it is possible for an electron to enter an area where its total energy is less than the potential of that area. If $E > V_0$, ψ_R is a sine function designated $\psi_{R,i}$ similar in form to the solution for the left side of the potential well. But if $E < V_0$, then ψ_R is a linear combination of hyperbolic functions designated $\psi_{R,ii}$. The Schrödinger equation and these boundary conditions lead to the equations listed in table 2. The program in listing 1 portrays electron behavior in a chemical bond based on these equations.

Algorithm for Simulation

To simulate the behavior of the

electron in a chemical bond, the program executes the following steps:

1. determine the potential difference, V_0 , between the two elements that make up the molecule
2. determine the bond length, a
3. determine the parameter, n , which is a function of V_0 and a
4. determine αa (where α is equal to the momentum of the particle divided by \hbar when the particle is in the left, low side of the well) by solving the appropriate transcendental equation depending upon whether $E > V_0$ or $E < V_0$
5. determine βa or γa (where β and γ correspond to α , but for the right, high side of the well) depending upon whether $E > V_0$ or $E < V_0$
6. determine the coefficients B or C and D in terms of A depending upon whether $E > V_0$ or $E < V_0$
7. evaluate ψ_L and, depending upon whether $E > V_0$ or $E < V_0$, evaluate either $\psi_{R,i}$ or $\psi_{R,ii}$
8. list the values of ψ and ψ^2 in tabular form or display ψ^2 in graphical form



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Table 2: Equations and definitions for solving Schrödinger's equation. The author is indebted to Lars Melander for the potential-well model described in this article and the equations listed in this table. For a complete description of the problem and its solution see Melander's article "Rectangular Box Model of the Polar Bond" in the Journal of Chemical Education, October 1972, pages 686 thru 688. Melander's article was the inspiration for the program of listing 1.

$$\mathbf{A} \quad \frac{d^2\psi}{dx^2} = \frac{-2mE\psi}{\hbar^2} = -\alpha^2\psi; \psi_L = A \sin(\alpha(x+a))$$

The Schrödinger equation and its solution for the left side of the potential well. The solution can be verified by differentiating ψ_L twice.

$$\mathbf{B} \quad \text{i) } \frac{d^2\psi}{dx^2} = \frac{-2m(E - V_0)\psi}{\hbar^2} = -\beta^2\psi; \psi_{R,i} = B \sin(\beta(a - x)) \text{ for } E > V_0$$

$$\text{ii) } \frac{d^2\psi}{dx^2} = \frac{2m(V_0 - E)\psi}{\hbar^2} = \gamma^2\psi; \psi_{R,ii} = C \sinh(\gamma x) + D \cosh(\gamma x) \text{ for } E < V_0$$

The Schrödinger equations and their solutions for the right side of the potential well. There are two possible solutions depending upon whether E is greater than or less than V_0 . The solutions can be verified by differentiating ψ_R twice.

$$\mathbf{C} \quad n^2 = \frac{2mV_0a^2}{\hbar^2}$$

Definition of n , a parameter which is a function of V_0 and a . It is introduced for reasons of convenience.

$$\mathbf{D} \quad \text{i) } \beta^2a^2 = \alpha^2a^2 - n^2 \text{ for } E > V_0$$

$$\text{ii) } \gamma^2a^2 = n^2 - \alpha^2a^2 \text{ for } E < V_0$$

Identities that can be verified by combining the appropriate definitions from A, B and C.

$$\mathbf{E} \quad \text{i) } \sqrt{\frac{\alpha^2a^2 - n^2}{\alpha a}} \tan(\alpha a) = -\tan(\sqrt{\alpha^2a^2 - n^2}) \text{ for } E > V_0$$

$$\text{ii) } \sqrt{\frac{n^2 - \alpha^2a^2}{\alpha a}} \tan(\alpha a) = -\tanh(\sqrt{n^2 - \alpha^2a^2}) \text{ for } E < V_0$$

Pair of transcendental equations that derive from the boundary conditions. They determine the value of αa given n . The equation used depends upon whether E is greater than or less than V_0 .

$$\mathbf{F} \quad \text{i) } B = A \sin(\alpha a) / \sin(\beta a) \text{ for } E > V_0$$

$$\text{ii) } C = -D / \tanh(\gamma a) \text{ for } E < V_0$$

$$D = A \sin(\alpha a)$$

Equations which define the coefficients of the solutions for the right side of the potential well in terms of the coefficient (amplitude), A , of the solution for the left side of the potential well. These equations also derive from the boundary conditions.

A small data file is created. The file contains a list of elements capable of forming a diatomic molecule by exchanging or sharing a single electron with another element. The file contains the following information: the chemical symbol of the element, its ionic radius, ionization potential, and electron affinity. [Note: The ionic radius of an element depends upon whether the molecule is a single unit, as in the gas phase, or whether it belongs to a larger group as in the crystalline or solid phase. The crystalline ionic radii used in this program may be found in the Handbook of Chemistry and Physics, Chemical Rubber Company, 18901 Cranwood Parkway, Cleveland OH 44128.]

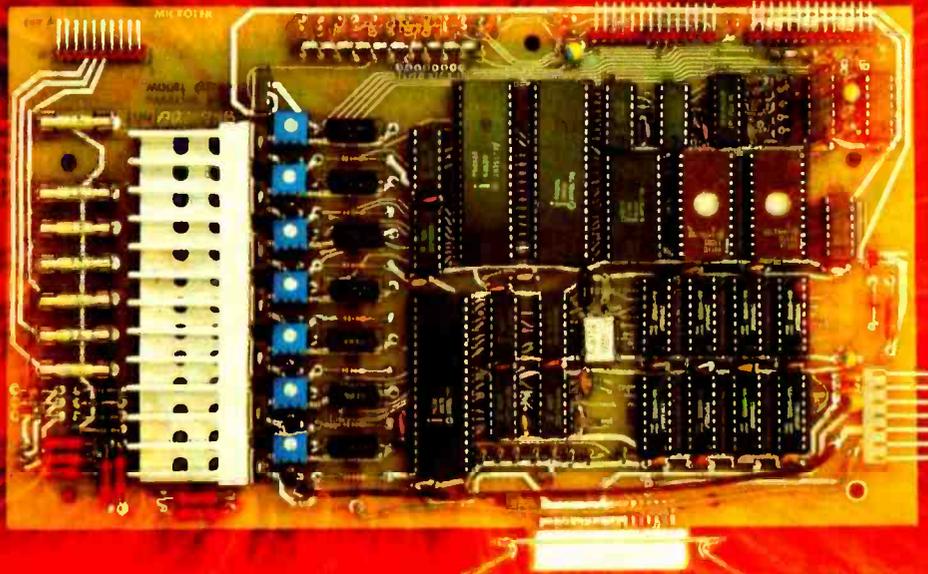
The program lists the elements by

name and symbol after a short introduction. The operator enters the symbols for the two elements to be involved in the bond. The program determines potential energy, V_0 , and the bond length, a , then solves for and prints out the parameter, n . Then the product of the momentum and the bond length, αa , must be determined. If the diatomic molecule is in a state of lowest energy, the ground state, then αa must lie in the interval between 0 and π .

Theoretically, the best method of solving the appropriate transcendental equation for αa would be to evaluate each side of the equation separately for all values of αa between 0 and π , and find the point at which the two sides of the equation

are equivalent. It is possible for a computer to find the correct value of αa by stepping αa from 0 to π in very small increments. In practice, this is far too time-consuming, especially on a small computer.

The program of listing 1 determines the value of αa in two stages. In the first stage, αa is increased from 0 to π by steps of 0.1. A graph of each side of the transcendental equation is plotted on the same axis. The point where the two lines generated by the two halves of the equation intersect gives a rough approximation to the proper value of αa . The operator then enters the value of αa immediately before the point of intersection. The program begins with this value of αa and increments it in steps of 0.0004. When



IT'S THE THOUGHT THAT COUNTS

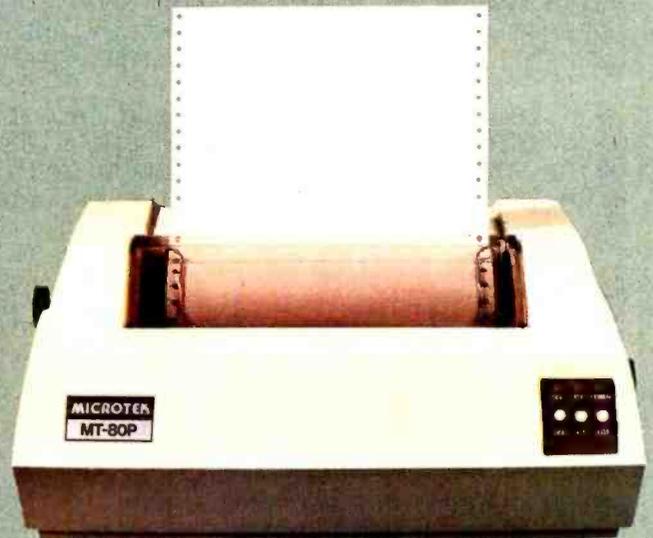
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the difference between the two sides of the transcendental equation (squared so that negative numbers are inconsequential) is a minimum, the program prints out the value of αa . Depending upon the relative size of αa and n , the program then evaluates and prints out either βa or γa .

Next the coefficients of the equations for the right side of the potential well are determined in terms of A , the amplitude of the wave equation for the left side of the potential well. The value of the coefficient A could be determined by normalization, making the probability that the electron is at some point between $-a$ and $+a$ equal to 1. In this program, the wave equation is left unnormalized.

The equations defining the relationship among these coefficients are

the result of application of the boundary conditions. Finally, numerical values of ψ and ψ^2 can be determined. The program evaluates ψ for each side of the potential well at fractional intervals along the bond length according to the appropriate equation. The data is available to the operator either in tabular or in graphical form. As might be expected, the graphical form gives a better impression of how the electron behaves in the bond.

Characteristics of the Program

The program of listing 1 was written in AlphaBASIC to run on an AlphaMicro Systems AM-100 computer. The hyperbolic trigonometric functions, $\sinh(x)$ and $\cosh(x)$, do not appear in AlphaBASIC. But these functions can be defined in terms of

the natural exponential function, which appears in most versions of BASIC:

$$\sinh(x) = \frac{e^x - e^{-x}}{2}$$

$$\cosh(x) = \frac{e^x + e^{-x}}{2}$$

In these equations, e is the base of the Napierian natural logarithm and has a value of approximately 2.71828. Otherwise there are no unusual statements or functions in the program. The processing of mathematical variables is carried out in floating-point notation with eleven-digit accuracy.

The formatted output rounds off all results at the third decimal place.

Text continued on page 56

Listing 2: A sample execution of the program of listing 1.

RUM CHMBND

-PROFILE OF A CHEMICAL BOND-

THE ELECTRON DENSITY IN THE CHEMICAL BOND OF A DIATOMIC MOLECULE DEPENDS UPON THE POTENTIAL DIFFERENCE (V_0) BETWEEN THE TWO ELEMENTS WHICH ARE BOUND TOGETHER AND UPON THE LENGTH OF THE BOND (A). THE AVERAGE OF THE IONIZATION ENERGY AND THE ELECTRON AFFINITY OF AN ELEMENT OFFERS A MEASURE OF THE POTENTIAL OF THE ELEMENT.

THIS PROGRAM CALCULATES A PROFILE OF A CHEMICAL BOND BASED UPON THIS INFORMATION. FROM THE LIST OF ELEMENTS BELOW, SELECT TWO WHICH WILL MAKE UP THE MOLECULE. ENTER THE SYMBOLS FOR THESE ELEMENTS AT THE REQUEST OF THE PROGRAM.

HYDROGEN	-	H			
LITHIUM	-	Li	FLOURINE	--	F
SODIUM	-	Na	CHLORINE	-	Cl
POTASSIUM	-	K	BROMINE	-	Br
RUBIDIUM	-	Rb	IODINE	-	I
CESIUM	-	Cs			

ENTER ELEMENT NUMBER ONE - Na
 ENTER ELEMENT NUMBER TWO - Cl

$V_0 = 5.743$
 $N = 3.414$

WHEN READY TO CONTINUE TYPE A CARRIAGE RETURN.

GRAPHICAL SOLUTION OF
 TRANSCENDENTAL EQUATION

Listing 2 continued on page 50

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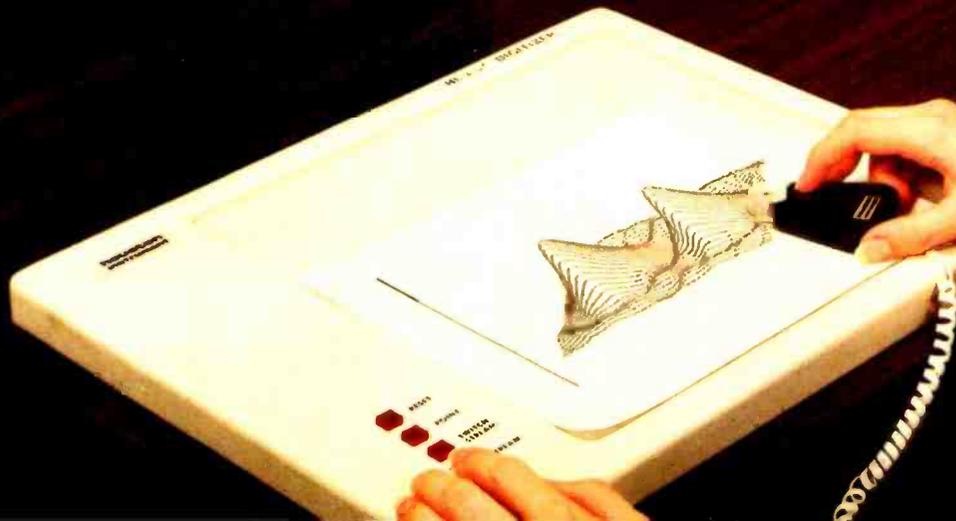
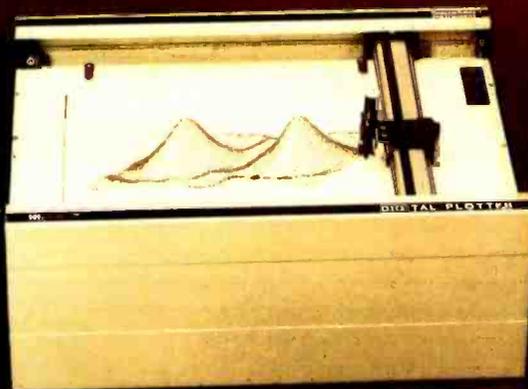
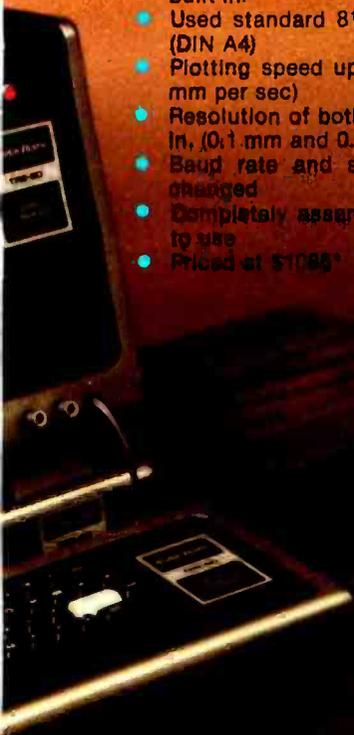
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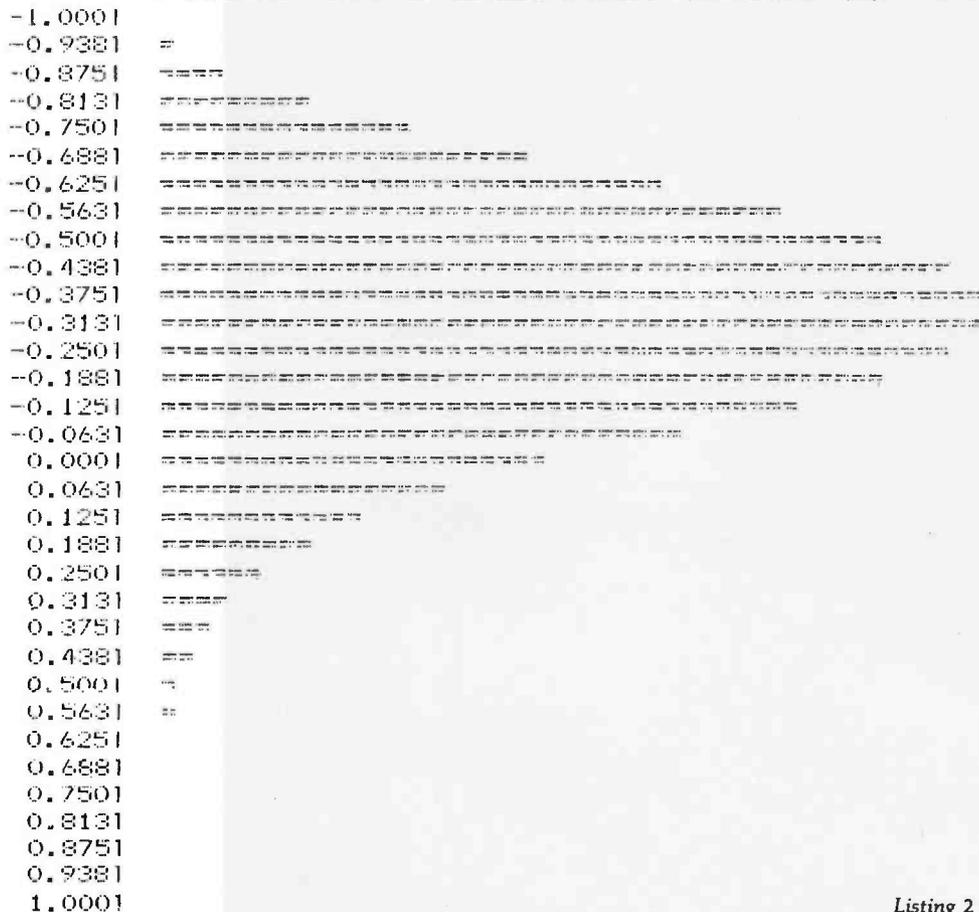
Listing 2 continued:

-0.438	0.973	0.947
-0.375	0.996	0.993
-0.313	0.998	0.996
-0.250	0.977	0.955
-0.188	0.935	0.875
-0.125	0.872	0.761
-0.063	0.790	0.625
0.000	0.691	0.477
0.063	0.591	0.350
0.125	0.506	0.256
0.188	0.432	0.186
0.250	0.368	0.135
0.313	0.313	0.098
0.375	0.265	0.070
0.438	0.223	0.050
0.500	0.187	0.035
0.563	0.155	0.024
0.625	0.127	0.016
0.688	0.101	0.010
0.750	0.078	0.006
0.813	0.057	0.003
0.875	0.037	0.001
0.938	0.018	0.000
1.000	0.000	0.000

WOULD YOU LIKE TO SEE THE GRAPHICAL FORM?
 ENTER A YES OR NO
 ? YES

GRAPHICAL FORM

(PSI)^2



Listing 2 continued on page 54

Chief Relief

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Listing 2 continued:

WOULD YOU LIKE TO STUDY ANOTHER PAIR OF ELEMENTS?
ENTER A YES OR NO
? YES

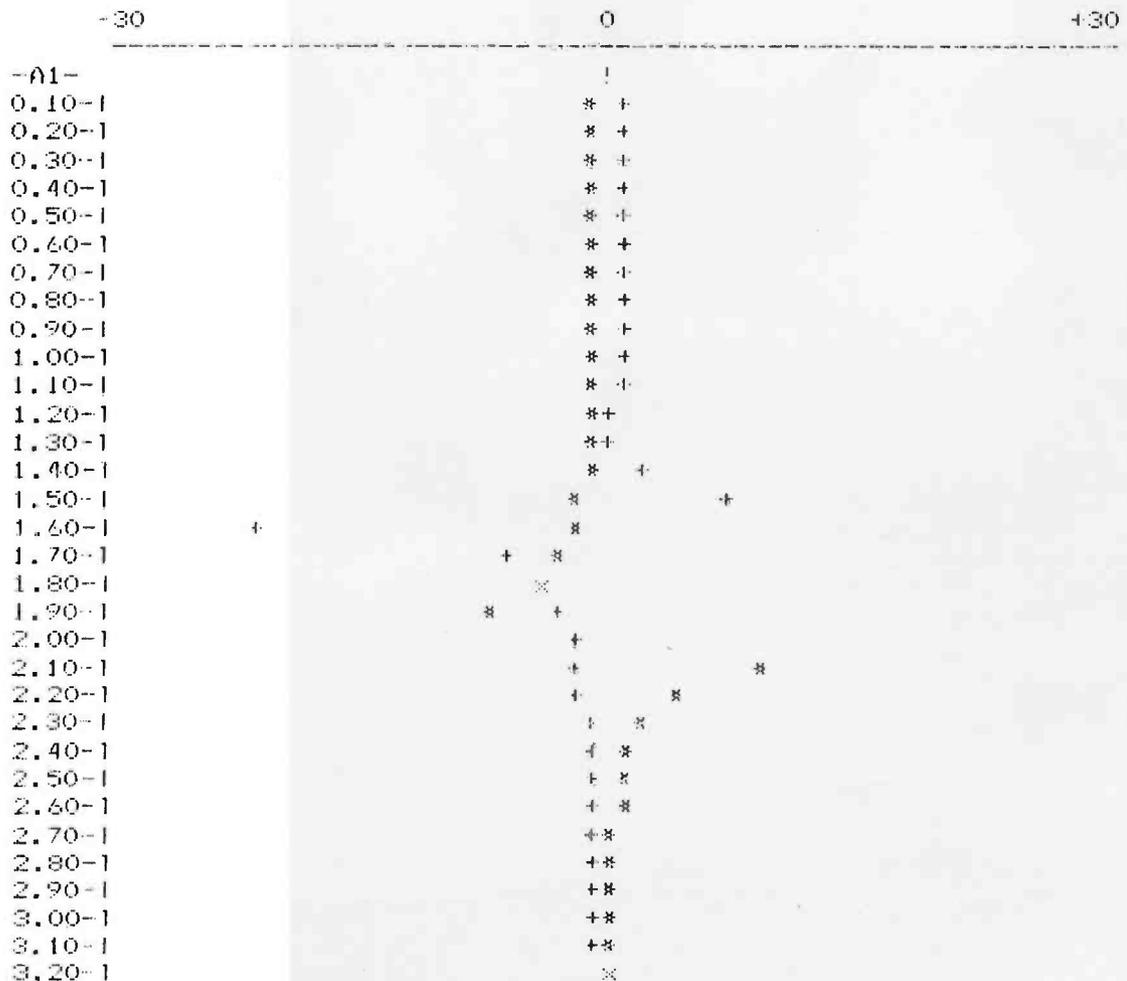
HYDROGEN	-	H	FLOURINE	-	F
LITHIUM	-	Li	CHLORINE	-	Cl
SODIUM	-	Na	BROMINE	-	Br
POTASSIUM	-	K	IODINE	-	I
RUBIDIUM	-	Rb			
CESIUM	-	Cs			

ENTER ELEMENT NUMBER ONE - H
ENTER ELEMENT NUMBER TWO - I

VO = 0.439
N = 1.270

WHEN READY TO CONTINUE TYPE A CARRIAGE RETURN.

GRAPHICAL SOLUTION OF
TRANSCENDENTAL EQUATION



Listing 2 continued on page 56

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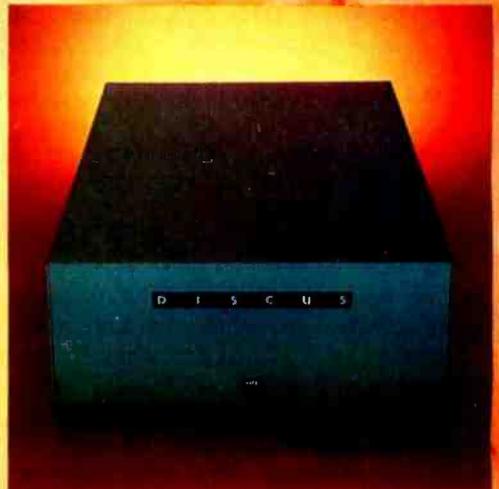
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Listing 2 continued:

AT WHAT VALUE OF A1 DO THE LINES SEEM TO INTERSECT?

A1 = ? 1.70

THE POINT OF INTERSECTION IS:

A1 = 1.791

B1 = 1.264

-CALCULATION OF PSI-

DO YOU WANT OUTPUT AS TABLE OF VALUES (1) OR IN GRAPHICAL FORM (2)?

ENTER A 1 OR 2

? 1

TABLE OF VALUES

A	PSI	(PSI)^2
-1.000	0.000	0.000
-0.938	0.112	0.012
-0.875	0.222	0.049
-0.813	0.330	0.109
-0.750	0.433	0.188
-0.688	0.531	0.282
-0.625	0.622	0.387
-0.563	0.706	0.498
-0.500	0.781	0.610
-0.438	0.846	0.715
-0.375	0.900	0.810
-0.313	0.943	0.889
-0.250	0.974	0.949
-0.188	0.993	0.987
-0.125	1.000	1.000
-0.063	0.994	0.988
0.000	0.976	0.952
0.063	0.948	0.899
0.125	0.915	0.837
0.188	0.876	0.767
0.250	0.831	0.691
0.313	0.782	0.611
0.375	0.727	0.529
0.438	0.668	0.446
0.500	0.605	0.366
0.563	0.538	0.289
0.625	0.467	0.218
0.688	0.394	0.155
0.750	0.318	0.101
0.813	0.240	0.058
0.875	0.161	0.026
0.938	0.081	0.007
1.000	0.000	0.000

WOULD YOU LIKE TO SEE THE GRAPHICAL FORM?

ENTER A YES OR NO

? YES

Listing 2 continued on page 58

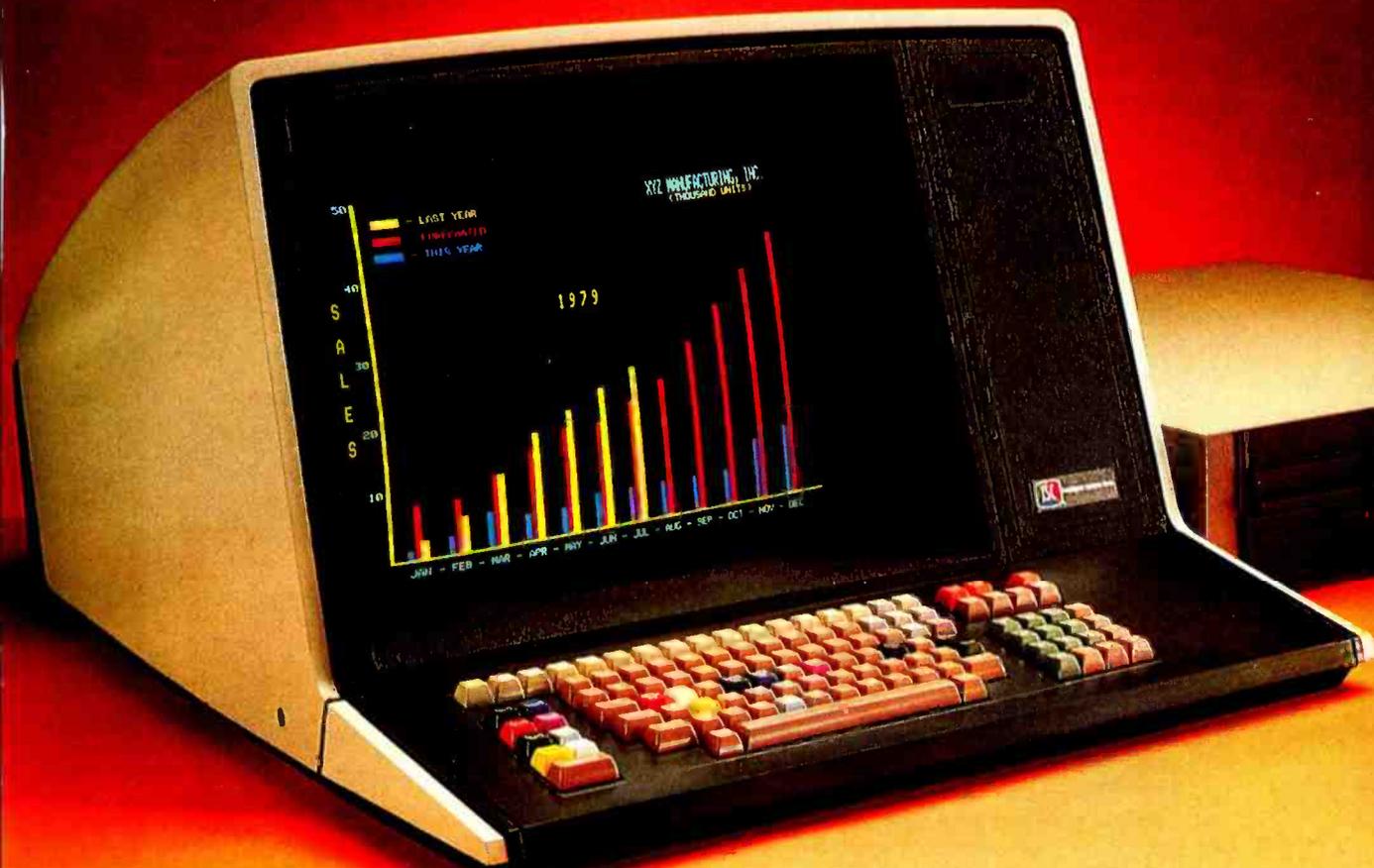
Text continued from page 48:

The format (PRINT USING) statements are somewhat rare and may have to be modified according to the particular version of BASIC with which you happen to be working. The program requires no special graphics systems. All graphic features are generated by using terminal keyboard symbols (such as the asterisk).

Uses of the Program

The program can be easily adapted for further study of chemical bonds in diatomic molecules. You can study the electron distribution for different bond lengths at a constant potential difference. Alternately, you could study the electron distribution for varying potential differences at a constant bond length.

It is also possible to estimate the ionic character of the bond. If the potential difference between two elements was infinitely large, the electron would be confined indefinitely to the lower side of the potential well. The most probable electron location in a symmetrical well would be at the center of the well, in this case at $x = -0.5a$. Since one nucleus would



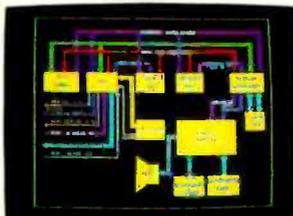
Color communicates better. That's the *obvious* benefit of ISC's new CP/M[®]2 compatible desktop computer.

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Circle 26 on inquiry card.

Listing 2 continued:

(PS1)^2

```
-----  
-1.0001  
-0.9381  
-0.8751 ==  
-0.8131 =====  
-0.7501 =====  
-0.6881 =====  
-0.6251 =====  
-0.5631 =====  
-0.5001 =====  
-0.4381 =====  
-0.3751 =====  
-0.3131 =====  
-0.2501 =====  
-0.1881 =====  
-0.1251 =====  
-0.0631 =====  
0.0001 =====  
0.0631 =====  
0.1251 =====  
0.1881 =====  
0.2501 =====  
0.3131 =====  
0.3751 =====  
0.4381 =====  
0.5001 =====  
0.5631 =====  
0.6251 =====  
0.6881 =====  
0.7501 =====  
0.8131 ==  
0.8751 =  
0.9381  
1.0001
```

WOULD YOU LIKE TO STUDY ANOTHER PAIR OF ELEMENTS?
ENTER A YES OR NO
? NO

have exclusive possession of the electron, such a bond would be 100% ionic.

If there was *no* potential difference between the two elements, the most probable location in the symmetrical well would again be the center of the well, but this time at $x = 0$. The bond has 0% ionic character.

All real molecular bonds lie between these two extremes. To estimate the ionic character of a bond, search for the fractional value of the bond length at which the probability distribution curve has maximum amplitude. Multiply this number by two, make it positive, and convert it to a percentage form. The result is a model estimate of the ionic

character of the bond.

This program represents a mere peek at the quantum mechanical world of atoms and molecules. Much has been discovered and much remains to be discovered. The computer facilitates investigation of this world. Moreover, the computer can be a spur to our imagination beckoning us to new vistas in the microscopic world and beyond. ■

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Hewlett-Packard's New Personal Computer The HP-85

Christopher P Morgan
Editor-in-Chief

Photos by Ed Crabtree

A question often heard in personal computer circles is, "When is Hewlett-Packard going to bring out a personal computer?" The question has been answered, and the new HP-85 computer is quite a system.

Hewlett-Packard (HP) has long been a respected manufacturer of minicomputers, desktop calculators, and handheld calculators; the high quality of their electronic test equipment is well known to the engineering

community. Hewlett-Packard also has the reputation for being a careful, conservative company, and the HP-85 is, not surprisingly, a logical outgrowth of their desktop and handheld calculators.

We recently had the opportunity to audition the HP-85. Our preliminary findings are listed below.

System Features

The basic HP-85, shown in photo

1, costs \$3250 and consists of a micro-computer with a custom 8-bit processor and several other custom integrated circuits, data cartridge drive for DC-100 tape cartridges, a high-resolution video display with a 5-inch screen (measured diagonally) with resolution of 256 by 192 dots (individually addressable) for graphics, 16 lines by 32 characters of text, keyboard, and thermal printer. The unit comes with 16 K bytes of program-

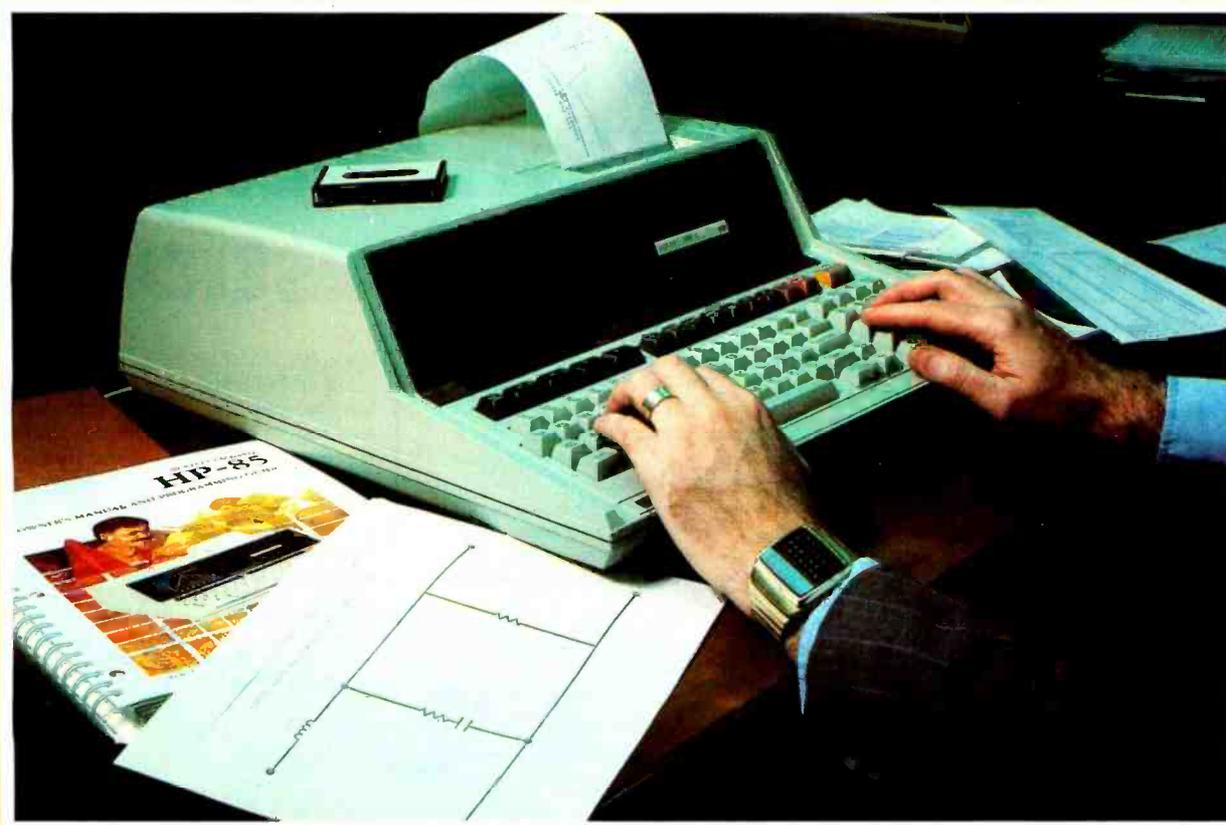


Photo 1: Hewlett-Packard's new entry into the personal computer market: the HP-85. The \$3250 unit features a 5-inch video display, data cartridge drive, keyboard with user-programmable keys, and thermal printer. The HP-85 also offers interesting graphics capabilities. Every point on the 256 by 192 dot array can be individually addressed by the programmer. The built-in thermal printer can make a copy of any graphic design on the screen or any alphanumeric data. Sophisticated features included in this unit are a hardware and software self-test key; four levels of security protection for files on data cartridges; plug-in memory expansion to the basic package of 16 K bytes of programmable memory and 32 K bytes of read-only memory; ANSI standard Enhanced BASIC with the ability to chain programs together; and line editing.

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sembler and debugger. And, with SuperBrain's S-100 bus adapter, you can even add a 10 megabyte disk!

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Your operators will praise the SuperBrain's good looks. A full ASCII keyboard with a numeric keypad and function keys. A non-glare, dynamically focused, twelve inch screen. All in an attractive desktop unit weighing less than a standard

office typewriter. Sophisticated users will acclaim SuperBrain's twin Z-80 processors which transfer data to the screen at 38 kilobaud! Interfacing a printer or modem is no problem using SuperBrain's RS-232C communications port. But best of all, you won't need a PhD in computer repair to maintain the SuperBrain. Its single board design makes servicing a snap!

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mable memory (14,500 of which are available to the user) expandable to 32 K bytes, and 32 K bytes of read-only memory. The latter contains the operating system and the Enhanced BASIC package.

Data Cartridges

One of the main differences between the HP-85 and most other small systems on the market is its use of data cartridges for reading and writing programs and data. This is not surprising, since the company expects to sell the unit in large quantities to professionals, and the data cartridge is one of the most reliable forms of mass storage available today. The cartridge-drive slot is located on the front of the machine (see photo 1).

Each cartridge can hold 780 program records consisting of 192 K bytes each, or 850 data records of 210 K bytes. There can be a maximum of forty-two named files per cartridge.

Cartridge rewind time is 29

seconds; search speed is 152 cm (60 inches) per second; data transfer speed is 25.4 cm (10 inches) per second; and tape length is 43 meters (141 feet). With the data cartridge system the user can create data files, input arrays into the computer with a single program statement, store an "autostart" program that is automatically loaded and executed at power-on, and secure programs from unauthorized access.

Keyboard

The keyboard is divided by function: the typewriter keyboard for entering alphanumeric data, the numeric pad for entering numeric information, and eight user-definable keys. (These keys are located directly under the video screen. Labels for the keys can be entered by the user and will appear at the bottom of the screen). Display, editing, and system-control keys permit the user to control the video display. The keyboard is hinged and can be easily swung out

of the way after the cover is removed to service the processor board (see photo 3).

Video Display

One of the HP-85's strong points is its graphics and alphanumeric display capability. Sixteen lines of text can be displayed at a time on the screen, but a buffer holds up to sixty-four lines, so the user can back up and see a part of a listing that has scrolled off the screen—a decided convenience in writing or debugging programs. If you come to the end of the sixty-four-line section in the buffer, the display wraps around to the beginning again. Characters are formed in a 5 by 7 dot matrix.

In the graphics mode, the display consists of a 256 (wide) by 192 (high) dot field, giving a total of 49,152 individual dots available for high-resolution plotting. The HP-85 also stores the last alphanumeric display and the last graphics display in separate buffers so the user can switch more freely

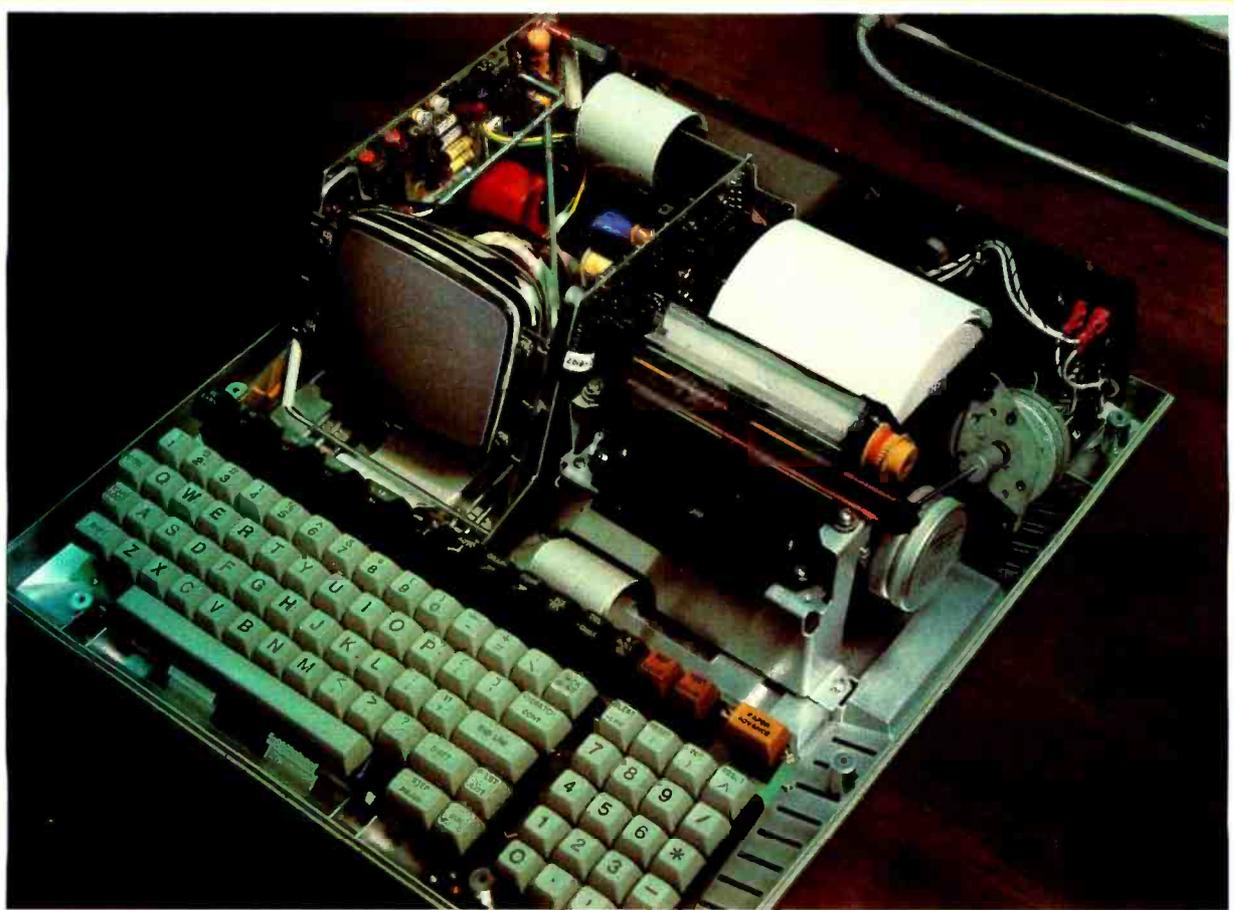


Photo 2: Inside the HP-85, showing the 5-inch video display cathode-ray tube, thermal printer, and data cartridge drive. The processor board is located under the keyboard (see photo 4). Note the set of user-definable keys at upper left of the keyboard. Labels for these keys are displayed at the bottom of the video screen.

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service in most major cities (see below) and a reduced phone charge in over a hundred others.

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"... but the really impressive stuff is in the back room."

from one mode to the other without losing data.

Readers familiar with the company's desktop calculators will be immediately at home with the HP-85's graphics-handling routines. There are sixteen graphics commands for setting up graphs, locating the origin, and scaling and labeling the axes quickly.

Anything that appears on the screen can be printed on the thermal printer by simply pressing the GRAPH and COPY keys in that order. You may also enter commands from the keyboard while in graphics mode. Inverse video is also available, as well as a B PLOT routine for user-defined graphics.

The alphanumeric characters are on the small side compared to the average personal computer display because of the screen size. However, they are quite readable— not unlike the IBM 5100 display. Screen editing is convenient. There are five cursor-

control keys, plus keys for clearing the screen, a line, or a single character. The ability to edit within a program line is a great time saver.

Security

The HP-85 offers unprecedented versatility when it comes to securing data and programs. The SECURE command is used to prevent specific program files from being listed, edited, or stored; to prevent any file's name from appearing in the directory listing; and to protect the user from writing over a file. The UNSECURE command removes security on secured programs or data files. The file name to be secured must already appear in the directory (ie: it must already exist on tape).

The file name may be any string of characters except the null string. The system takes the first two characters of the string and stores them as the security code. There are four levels of security.

At level 0, the program may not be listed or edited. Level 1 further prevents the program from being duplicated. At level 2, the program may also not be overwritten. Level 3 removes the name of the file from the catalog and replaces it with blank.

Printer

The thermal printer operates in both alphanumeric and graphics modes. In the alphanumeric mode, it can print the full 128-character ASCII character set, which includes uppercase and lowercase letters, numerals, and special symbols. The full character set can be underlined. Printer speed is 2 lines per second.

Enhanced BASIC

The HP-85's Enhanced BASIC interpreter meets and exceeds the most recent ANSI standard. Its features include: 12-digit accuracy and exponents up to ± 499 for calculations; extremely versatile

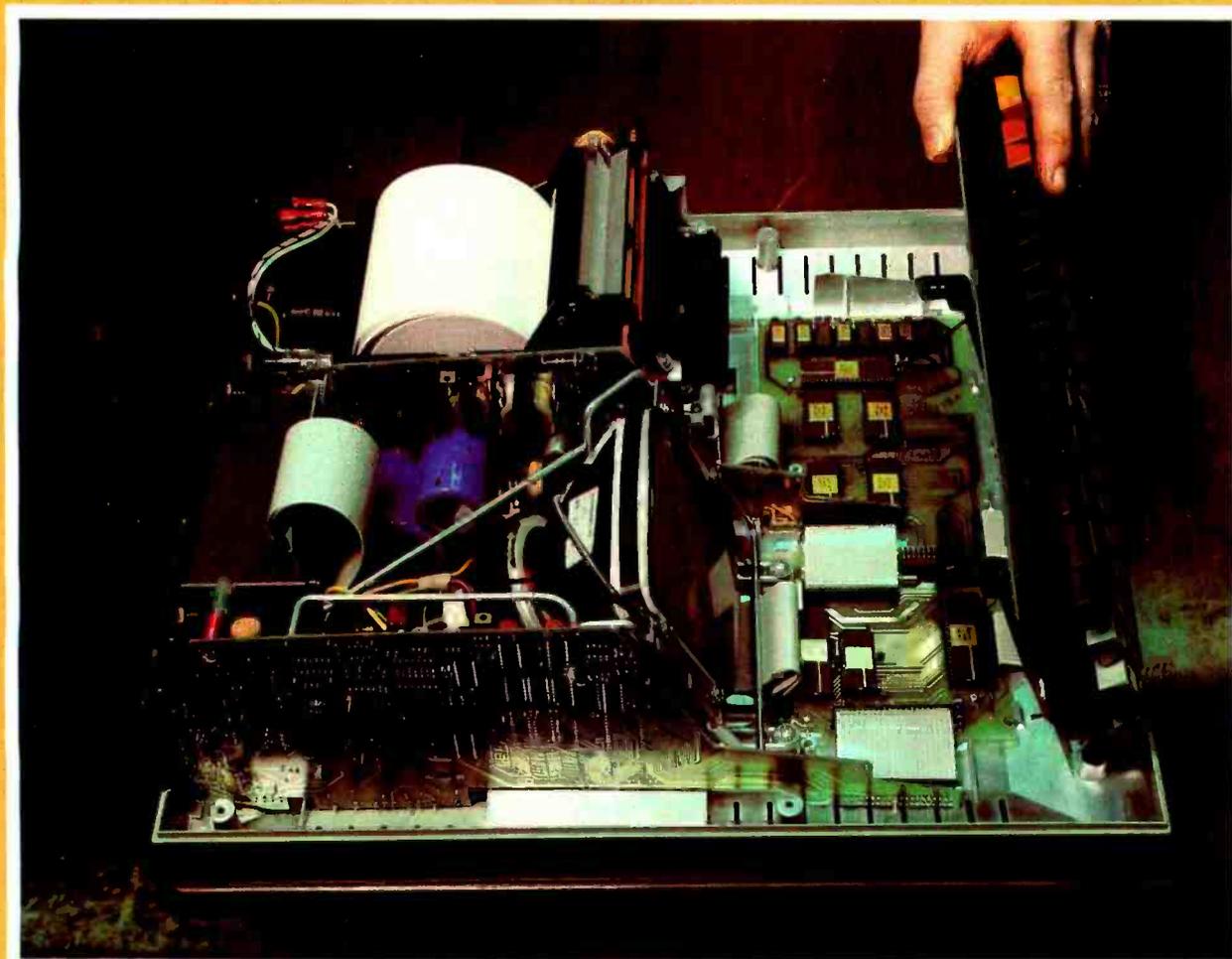
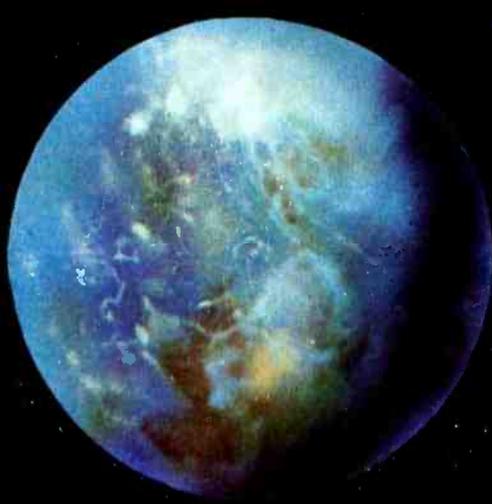


Photo 3: Internal view of the HP-85, showing the processor board under the hinged keyboard. The 8-bit processor is a custom Hewlett-Packard design, as are most of the integrated circuits in the computer.

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string-handling capability (a string in HP-85 Enhanced BASIC can theoretically be up to 32 K bytes long) compatible with string handling on other HP computers; 42 predefined functions; formatted output; the ability to chain BASIC programs together; multistatement lines; a programmable sound generator that can play single-voice lines of melody through the built-in speaker or make audible beeps at predetermined times during the execution of a program; and calculator capability. For debugging, the user can single-step through BASIC programs, branch ON ERROR, or have the program provide a default value with DEFAULT ON to enable a program to continue executing. In particular, the formatted-output capability is useful for generating headings, columns, and spaces for program output.

Self-Test

A unique feature of the HP-85 is the built-in self-test routine. When the TEST key is pressed, the computer runs through an electronic check of all internal components—a

feature common to many Hewlett-Packard electronic instruments. If everything checks out correctly, a particular set of characters is displayed on the screen. (The graphics display will be cleared, but programs and variables in memory will remain intact.) If the system is not operating correctly, the system displays "Error 23 SELF TEST."

Input/Output

Photo 4 shows the back of the HP-85 and the four input/output (I/O) ports. Additional memory can be added via the ports. The company will be introducing a variety of peripherals for the unit, including dual 5-inch floppy-disk drives, external printers, plotters, and so on. An extra 16 K bytes of memory costs \$395.

Software

Software currently available on data cartridges for the HP-85 includes BASIC training, general statistics, mathematics, electrical engineering, finance, linear programming, and regression analysis. Each package costs \$95. More packages are under

development. BASIC program developed for Hewlett-Packard's desktop computers can be adapted for use on the HP-85, as can most programs written in ANSI BASIC. The unit also comes with a well-written, 350-page owner's manual and a standard application software package. Hewlett-Packard is quoting immediate delivery on the HP-85.

Evaluation

We were impressed with the performance of the HP-85 computer. The graphics alone make this an attractive, albeit not inexpensive, alternate to existing small systems on the market. And many of its features are unique. Although Hewlett-Packard is pinning its hopes on heavy sales to the professional marketplace, it is our guess that many personal computer experimenters and hackers will want this machine.

In future issues of BYTE we will evaluate the HP-85 in greater depth.

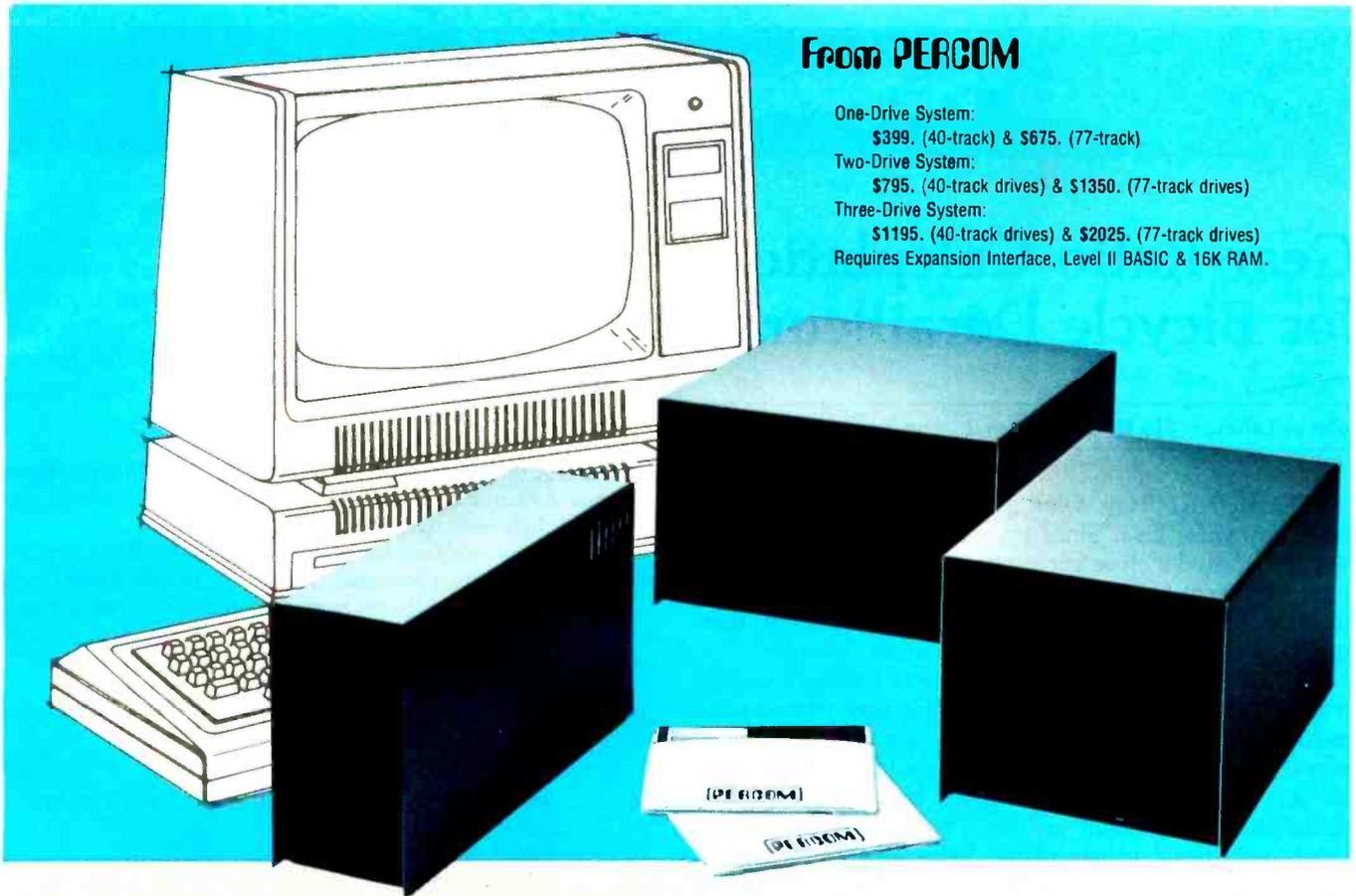
For further information about the HP-85, contact: Inquiries Manager, Hewlett-Packard Co, 1507 Page Mill Rd, Palo Alto CA 94303. ■



Photo 4: Rear view, showing the four I/O ports and their removable covers.

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Gear-Ratio Calculation for Bicycle Derailleurs

John A Lehman, 716 Hutchins, Apt 2, Ann Arbor MI 48103

KERCHUNK! "Hey, what gear is next on this thing?" asked my wife, Lisa. Since my old, reliable three-speed bicycle suffered a close encounter of the worst kind with a car impatient to turn right on a red light, we had both decided to buy used ten-speed bikes. Unfortunately, that meant having to worry about seven more "speeds."

"Why don't you use your computer to figure out what order to do things in?" she asked. This was a good suggestion, especially since one of our neighbors had been wanting me to figure out whether it would be worthwhile for him to change from a five-speed to a ten-speed shift mechanism. The result is this Programming Quickie which describes a program that helps answer these and other questions.

The most popular gear shift mechanism on bicycles these days is the *derailleur*. This mechanism uses one, two, or three front gear sprockets (ie: chain wheels) and either five or six rear gear sprockets. This means that one can have a five-, six-, ten-, twelve-, fifteen-, or eighteen-speed shift mechanism. The derailleur device moves the chain between the different gear sprockets, as shown in figure 1 on page 70. This means that, unlike two- and three-speed bikes, the shift mechanism cannot go directly from low to high gear. Rather, there are as many separate sequences of gear combinations as there are front chain wheels; the rider has to combine these different sequences into one overall shift pattern.

To make things more complicated, there are fairly wide variations in the number of gear teeth on the front and rear sprockets. Differently configured gear-tooth combinations are used for different riding conditions. For example, racers who ride mostly on level ground have a narrower gear-ratio range than bike tourists who have to manage both long, level stretches and steep hills. It would be nice to be able to tell what difference it would make riding up that long hill if you changed to a given front and rear sprocket combination.

The program given in listing 1 addresses both of these problems. It will analyze any combination of between five and eighteen speeds; it will produce a shift chart to indicate the order in which to use different combinations of front and rear gear sprockets and a chart of gear range so that comparisons can be made between different combinations of sprockets with variations in the number of gear teeth.

The unit of measure used here for gear range is the traditional one of wheel size. This is the size of the front wheel that would be necessary to produce the same drive

ratio on one of the old high-wheel (ie: penny-farthing) bikes of the nineteenth century. The program is written in TDL 12 K BASIC, but should run unaltered on any computer that uses Microsoft or a similar BASIC system such as the TRS-80, PET, Apple II, or Ohio Scientific. Happy cycling, and wear a helmet!

Listing 1: A program written in TDL 12 K BASIC that calculates the gear ratios available from combinations of front and rear gear sprockets with varying numbers of teeth.

Special language features are as follows. A PRINT USING statement provides formatted output. A simple PRINT will work, but will be slightly less neat. If your BASIC does not have the EXCHANGE statement used in lines 310 thru 314, you can substitute a simple swap routine such as:

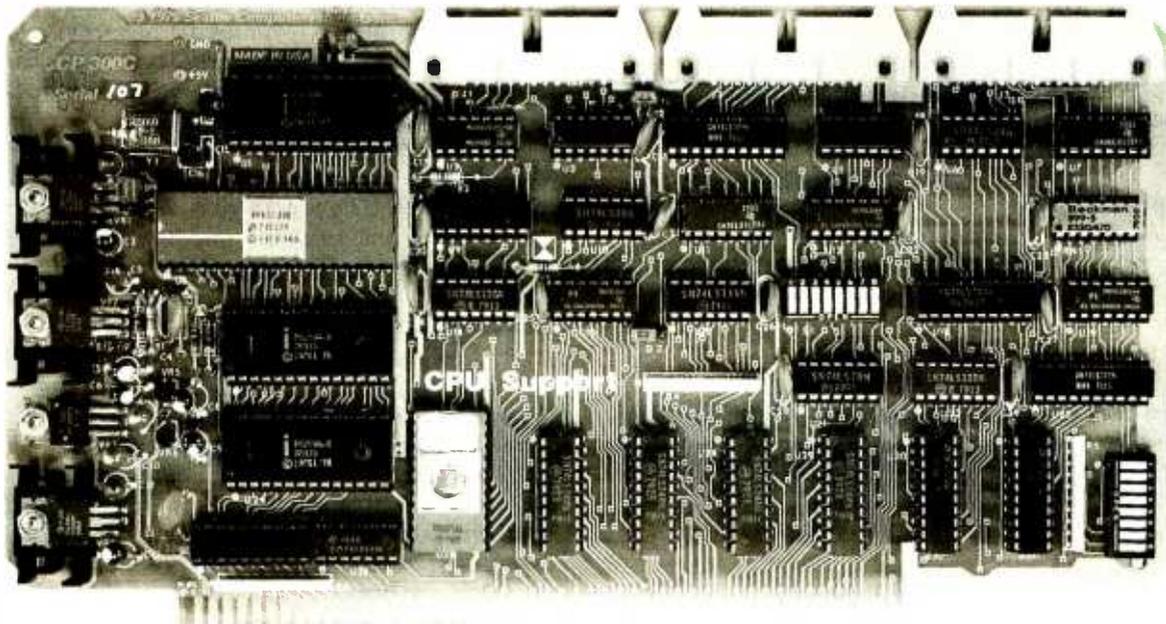
$$T1 = P(J+1, 1) : P(J+1, 1) = P(J, 1) : P(J, 1) = T1$$

to perform the exchange. A question mark is an abbreviation for PRINT.

```

10 'PROGRAM TO CALCULATE 10 SPEED OR 15 SPEED
   GEAR RATIOS
20 DIM W(16),P(16,3)
30 INPUT "NUMBER OF FRONT GEARS";F1
40 INPUT "NUMBER OF GEARS ON REAR
   FREEWHEEL";R1
50 IF F1=0 THEN F1=2
60 IF R1=0 THEN R1=5
70 N=R1*F1
80 INPUT "REAR WHEEL DIAMETER";W1
90 IF F1=3 THEN 120
100 F$(1)="INNER ":F$(2)="OUTER "
110 GO TO 130
120 F$(1)="INNER ":F$(2)="MIDDLE ":F$(3)="OUTER "
130 FOR I=1 TO F1
140 PRINT "NUMBER OF TEETH ON ";F$(I); "GEAR";
150 INPUT T(I)
160 NEXT I
170 FOR I=1 TO R1
180 PRINT "NUMBER OF TEETH ON ";I;" REAR GEAR";
190 INPUT S(I)
200 NEXT I
210 FOR I=1 TO F1
220 FOR J=1 TO R1
225 X=(I-1)*R1+J
230 W(X)=T(I)/S(J)*W1
235 P(X,1)=X:P(X,2)=I:P(X,3)=J
240 NEXT J
250 NEXT I
260 FOR I=1 TO N:P(I,1)=I:NEXT I
270 'START SORT
280 FOR I=1 TO N
290 FOR J=1 TO N-1
300 IF W(P(J,1))<W(P(J+1,1)) THEN 320
310 EXCHANGE P(J,1),P(J+1,1)
312 EXCHANGE P(J,2),P(J+1,2)
314 EXCHANGE P(J,3),P(J+1,3)
320 NEXT J
330 NEXT I
340 ??:?
350 ?"WHEEL";TAB(10);"FRONT";TAB(20);"REAR"
360 FOR I=1 TO N
370 PRINT USING "###.##"; W(P(I,1));
375 PRINT TAB(10);F$(P(I,2));TAB(20);P(I,3)
380 NEXT
390 END

```



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Notes on Gear Ratios

Contrary to popular belief, on most ten-speed bicycles the first five gear ratios are not all produced using the small front sprocket, with the top five gear ratios correspondingly produced using the large front sprocket. The actual case is more complicated, as can be seen from listing 2.

On many bikes, the setup is as follows. The first and

lowest gear ratio is produced using the small front sprocket and the largest rear sprocket. The second gear ratio is produced using the small front sprocket and the next-to-largest rear sprocket.

Now for the anomaly. The third gear ratio is produced using the large front sprocket and the largest rear sprocket. The fourth gear ratio is obtained using the small front sprocket and the third-largest rear sprocket. For the fifth gear ratio, we move the chain back onto the large front sprocket and onto the second-largest rear sprocket.

At this point, we may become perplexed. Is there not one pattern in the sprocket use that we can remember? Well, there is some regularity. Using the small front sprocket and all the rear sprockets in order from largest to smallest, we obtain gear numbers 1, 2, 4, 6, and 8. Using the large front sprocket and all the rear sprockets in order from largest to smallest, we obtain gear numbers 3, 5, 7, 9, and 10. So really, only the very top and bottom gears fall out of the easily remembered even/odd sequence.

Now you may object, "How am I supposed to follow such a complex shifting sequence while I am dodging traffic, pot holes, and vicious dogs?" Well, you don't have to follow the sequence strictly.

Most bike riders, in fact, rarely use gears three and eight. These are the extreme combinations of large front sprocket with largest rear sprocket, and of small front sprocket with smallest rear sprocket. Since the chain has to bend rather sharply when it is set up in these combinations, mechanical stress and wear are increased.

In my own riding around hilly Peterborough, New Hampshire, I typically leave the chain on the large front sprocket and shift up and down through the range made available by moving the chain to the various rear sprockets. I move the chain to the small front sprocket when I need the bottom two gears, such as when I ride up the steep hill that leads to my home. . . . **RSS ■**

Listing 2: Sample execution of the program of listing 1. The gear ratios are measured in terms of the equivalent size of the front wheel of a high-wheel (ie: penny-farthing) bicycle needed to produce the same final drive ratio.

```

RUN
NUMBER OF FRONT GEARS? 2
NUMBER OF GEARS ON REAR FREEWHEEL? 5
REAR WHEEL DIAMETER? 27
NUMBER OF TEETH ON INNER GEAR? 44
NUMBER OF TEETH ON OUTER GEAR? 52
NUMBER OF TEETH ON 1 REAR GEAR? 14
NUMBER OF TEETH ON 2 REAR GEAR? 16
NUMBER OF TEETH ON 3 REAR GEAR? 18
NUMBER OF TEETH ON 4 REAR GEAR? 20
NUMBER OF TEETH ON 5 REAR GEAR? 22
    
```

WHEEL	FRONT	REAR
54.00	INNER	5
59.40	INNER	4
63.82	OUTER	5
66.00	INNER	3
70.20	OUTER	4
74.25	INNER	2
78.00	OUTER	3
84.86	INNER	1
87.75	OUTER	2
100.29	OUTER	1

READY:

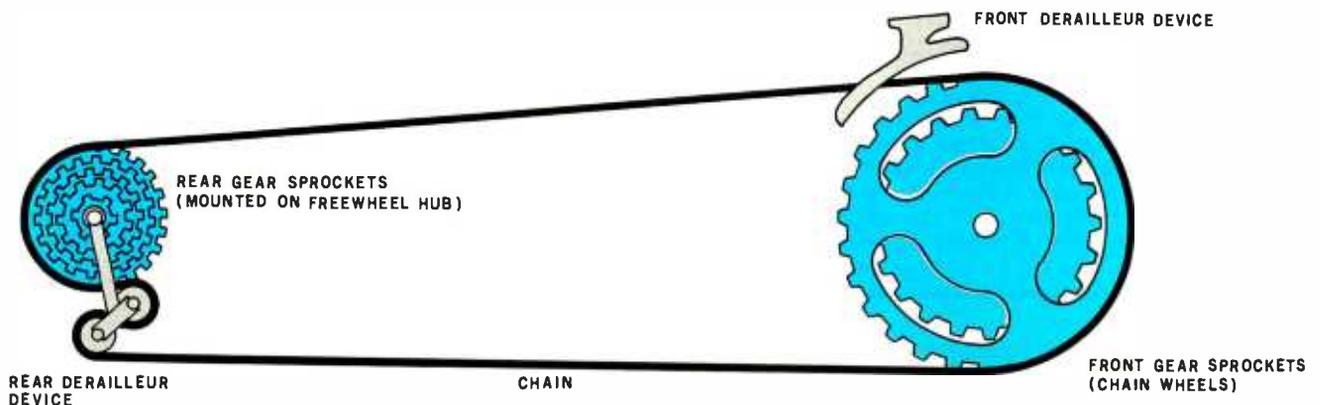
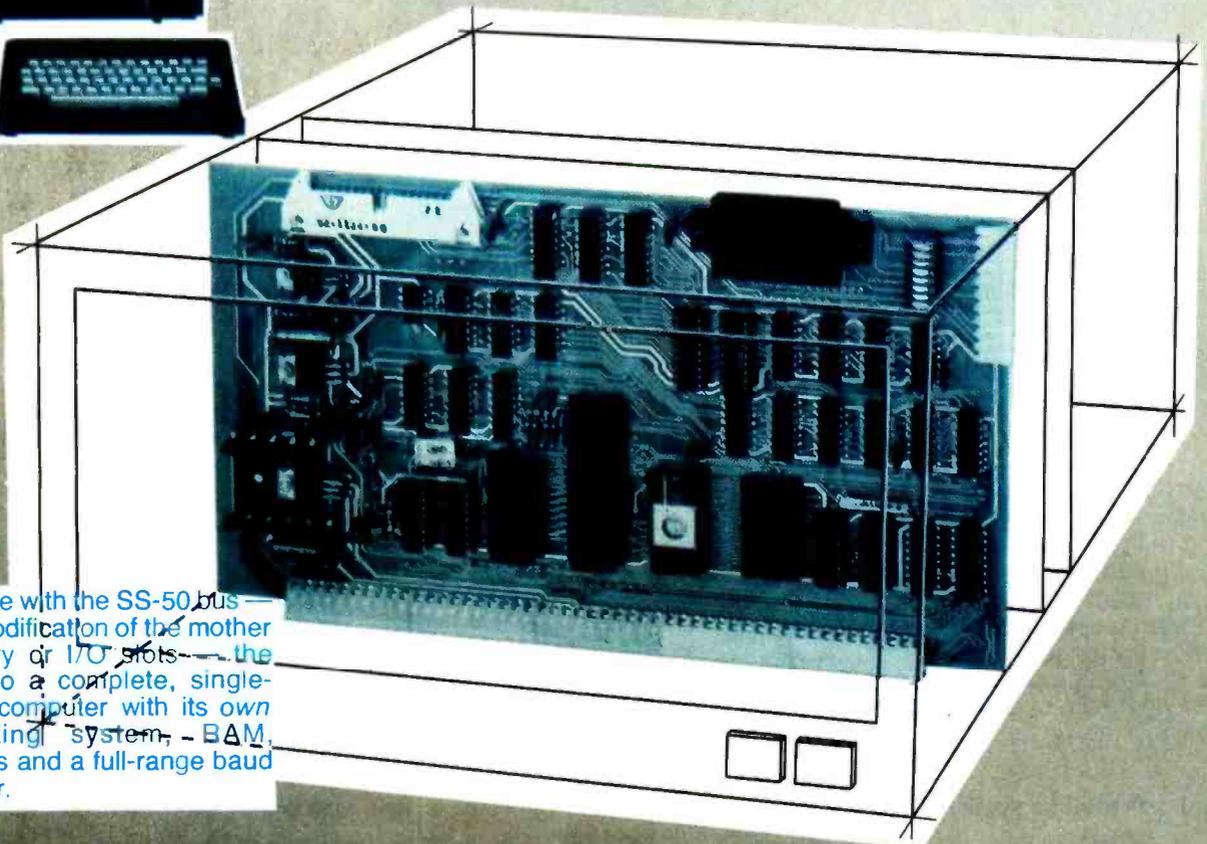


Figure 1: Diagram of the drive mechanism of a ten-speed, derailleur-equipped bicycle. The pedal cranks (not shown) are attached to the front gear sprockets (ie: chain wheels) through the crank axle. The front derailleur device can shift the chain between the large front sprocket and the small front sprocket.

The rear gear sprockets are attached to the rear axle by means of a freewheel hub that allows the rider to stop pedaling while the bicycle remains in motion. The rear derailleur device can shift the chain between any of the five rear gear sprockets. Different front and rear sprocket combinations produce the ten gear ratios.

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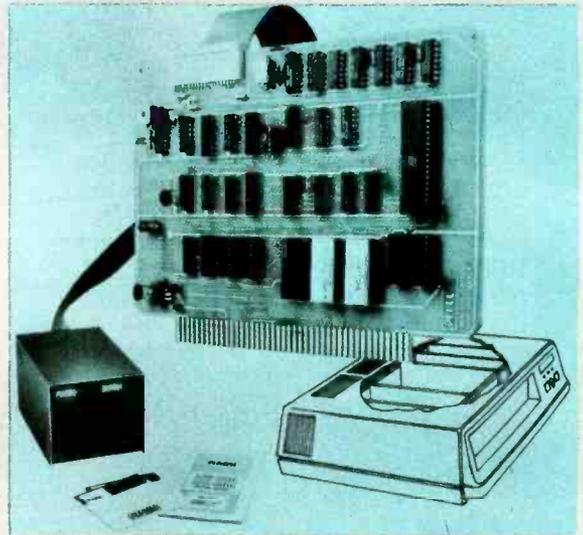
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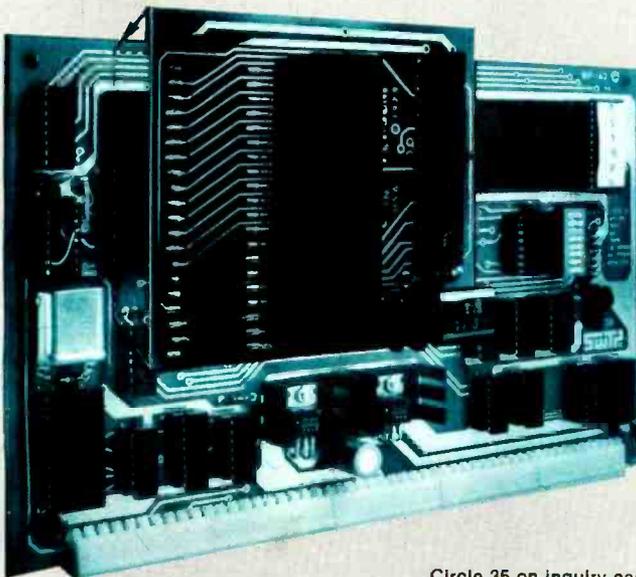
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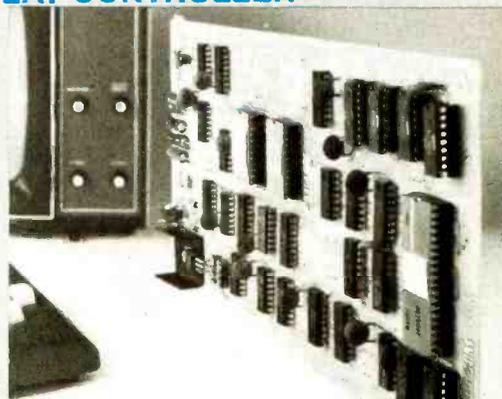
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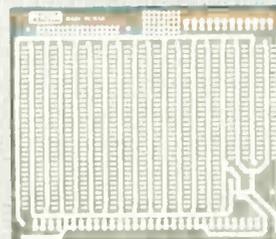
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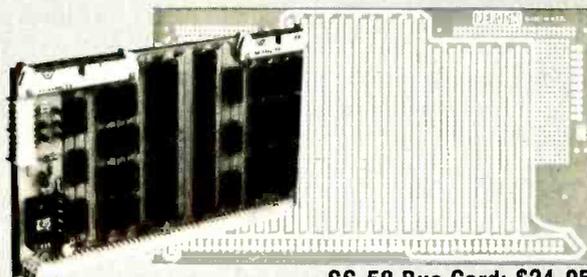
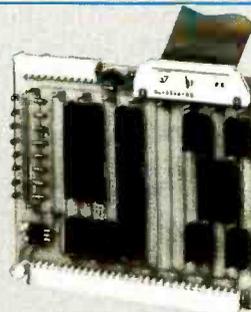
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Solving Problems Involving Variable Terrain

Part 2: Special Cases, Including Hexagonal Grids

Scott T Jones
271 NW 28th St
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In part 1 some general terrain problems were defined. These were problems that could be expressed in terms of movement on a map, with terrain defined as any map feature affecting movement. By superimposing a rectangular grid and coordinate system on these maps, we were then able to represent the terrain with a set of boolean arrays or terrain masks. Movement, distance, and the concept of movement cost for different types of terrain were also defined. A scatter function was then defined to generate scatter maps representing all possible movement within the limits imposed by the terrain.

Finally, we demonstrated the use of these scatter maps to solve such problems as the feasibility of road construction within cost restraints and the determination of an optimal path between two points on a map, across variable terrain.

Part 2 is concerned with the application of these techniques to the problems encountered in conflict simulations.

Conflict Simulations and the Hexagonal Grid

The most common type of conflict simulation is the war game. In a war game, playing pieces that represent military units are moved on a terrain map to simulate a battle. The map has been overlaid with a grid; each unit has an inherent movement factor; and each type of terrain has a movement cost. The ideas presented in this article were developed when I was trying to solve the problems of writing programs to play conflict simulations.

The most common grid used today is the hexagonal grid. Instead of an array of squares, the map is divided into hexagons or "hexes" to form a honeycomb pattern. Each hexagon has six adjacent hexagons. We can easily define the distance between a hexagon and any adjacent hexagon to be equal to 1 without worrying about the am-

biguous, diagonally adjacent squares that we encountered with rectangular grids. The problem is in defining a coordinate system and a distance function or metric.

Most games use an *offset* coordinate system. The hexagonal grid is treated as a rectangular grid in which every even-numbered column is offset by one-half the size of the squares. (See figure 9.) The trouble with this system is that there is no uniform relationship between these coordinates and a metric. Note the relationships of the coordinates of those hexagons adjacent to (2,2) as opposed to (3,2). Separate metrics must be used for the even and odd values of the first coordinate. Clearly, another system is required.

The solution is the *slant* coordinate system (X,Y) where the second coordinate is constant along a slanting, diagonal line from upper right to lower left, or vice-versa. (See figure 10.) The relationships of the coordinates are now consistent throughout the array.

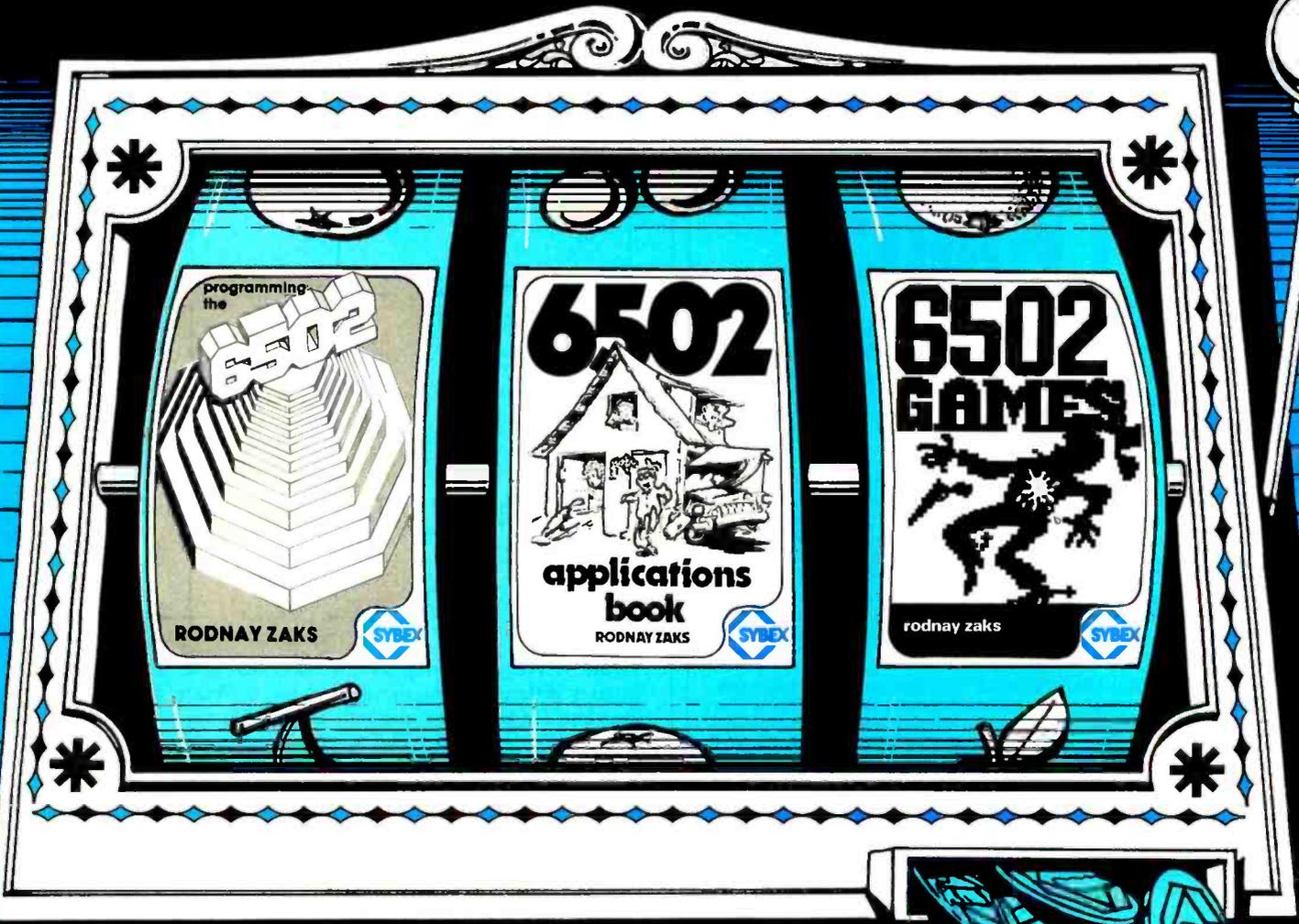
By defining a third, dependent coordinate Z to be $X - Y + C$, where C is any integer constant, our slant metric (ie: distance function) is simply the maximum of the absolute values of the differences of the three coordinates. That is, for (a,b,c) and (d,e,f), the distance is defined as:

$$\max(|a-d|, |b-e|, |c-f|)$$

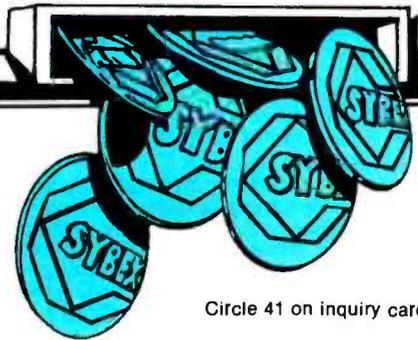
The Z coordinate is constant along the other slanting line from upper left to lower right. It will be left for the reader to prove both of these statements by working examples with figure 10.

Using these slant coordinates, we can now assign any hexagon to a square in a standard, rectangular scatter

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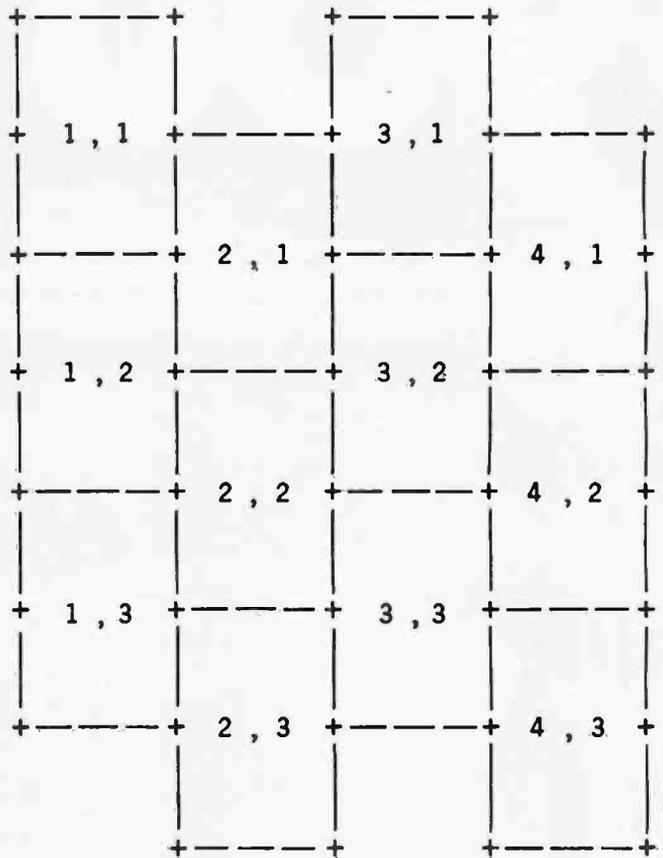


Figure 9: When working with a hexagonal grid, a set of coordinates different from those used for a square grid must be developed. One such coordinate system, shown here, is the offset coordinate system. This system produces difficulties when the distance between two coordinates must be determined. (Numbering of figures is continued from Part 1.)

mapping. Each hexagon (X,Y) is assigned to the square or element in row X and column Y of the two-dimensional matrix. The hexagonal scatter function HSC will assign to each element in array B the value:

$$B(I,J) = \text{HSC}(A(I,J)) = A(I,J) \text{ OR } A(I-1,J-1) \text{ OR } A(I-1,J) \\ \text{OR } A(I,J-1) \text{ OR } A(I,J+1) \\ \text{OR } A(I+1,J) \text{ OR } A(I+1,J+1)$$

Figure 11 demonstrates the scatter mappings that are generated from the same initial position used with the square and city scatter functions in a previous example. (See part 1, figure 4.)

If we are working with a map that already has offset coordinates printed on it, in a case where we would prefer to use slant coordinates, the following relations allow an easy transformation from one system to the other:

$$X(\text{slant}) = X(\text{offset})$$

and

$$Y(\text{slant}) = Y(\text{offset}) + \text{INT}(X/2)$$

where INT is the greatest-integer function.

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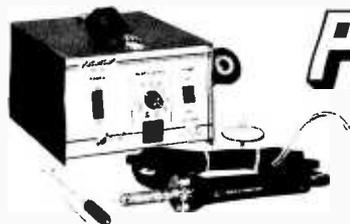
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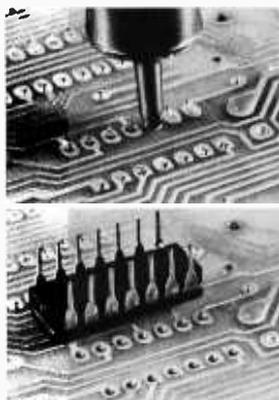
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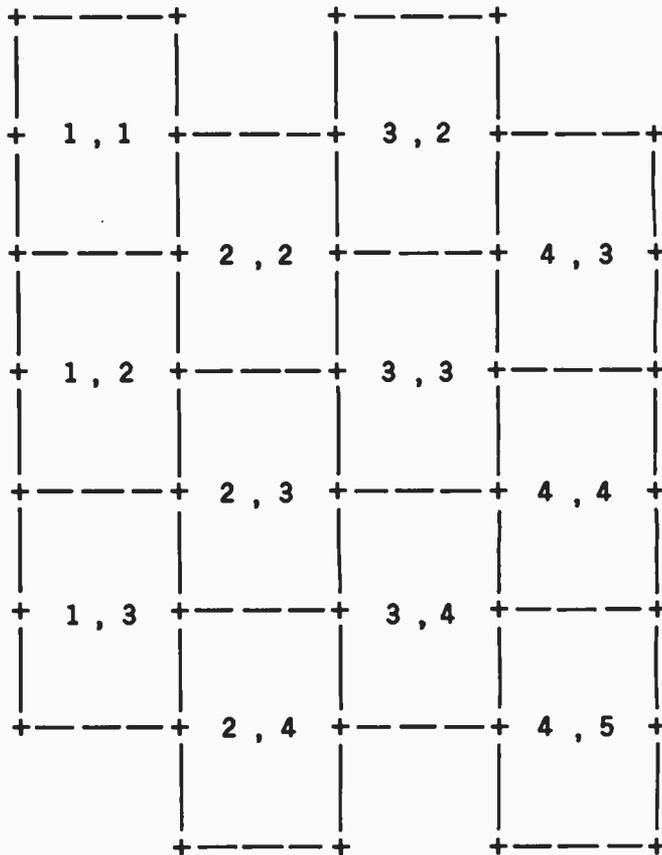


Figure 10: A coordinate system that solves the distance problems found in the offset coordinate system is the slant coordinate system. In this system, one of the coordinates is constant along a diagonal (ie: slanted) axis.

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Specific Game Applications

It should now be obvious how to determine movement in a game environment when fixed terrain is the only constraint. However, in many war games, the concept of a zone of control introduces a new type of terrain. The unit may enter this zone at the normal movement cost but may not leave until the opposing unit that imposed the zone of control is removed, usually by combat of some form.

A unit's zone of control is usually defined as all positions (ie: squares or hexagons) that are adjacent to the unit's own position. In other words, a unit's zone of control is simply the first scatter mapping of its position. Thus, when moving with the constraints of zones of control, a new terrain map Z must be defined where Z(I,J) is 0 if (I,J) is 1 in the first scatter mapping of any opposing unit, and Z(I,J) = 1, otherwise.

This terrain map is then used to mask out starting positions that will be used on the next scatter. This gives us the relation:

$$M_n = M_{n-1} \text{ OR } (T_1 \text{ AND } XSC(Z \text{ AND } M_{n-1}))$$

$$\text{OR } (T_2 \text{ AND } XSC(Z \text{ AND } M_{n-2}))$$

$$\text{OR } (T_k \text{ AND } XSC(Z \text{ AND } M_{n-k}))$$

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0 0 1 0 0	0 1 1 1 0	1 1 1 1 1
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0 0 0 0 0	0 0 0 0 0	0 0 1 1 1
a. A	b. HSC(A)	c. HSC(HSC(A))

Figure 11: An example of the hexagonal scatter-function mappings that develop from a central starting point, assuming that the movement cost of all terrain is equal.

This relation now shows how we can "premask" our scatter mappings to include the effects of zones of control or other types of no-exit terrain found on our terrain map

while we postmask to include the effects of movement costs.

This relation is the basis for our movement algorithm in most conflict simulations. With it, we can easily determine not only if a unit can reach a position, but also if the unit is inhibited by opposing units or if it is surrounded. By operating with sets of these scatter mappings, we can even coordinate the moves of a group of units. Scatter mappings can be weighted by the relative combat strengths of the corresponding units so that sums of these weighted mappings represent the total strength that can be applied to any position on the map.

The metrics (ie: distance functions) work well as range functions for game features that are unaffected by terrain,

such as determining the range to a target in the simulation of naval battles. Line-of-sight rules that govern the use of projectile weapons in land-battle simulations pose new problems which we will not attempt to resolve at this time.

Directional Terrain Features

In a game environment, concessions are often made to the scale of the terrain map. This means that prohibited terrain, like rivers, or ideal terrain, such as roads, must be represented in a nonstandard way. In situations where you are not fixed by the terrain map provided with the game, you may either increase the scale so that terrain types can be easily isolated, or reduce the scale so that single locations contain many types of terrain, but the effects are dominated by only one type.

With a fixed scale, however, our algorithm must be modified. For example, when we have roads that lower the movement cost for units following the road, we must first adjust our cost scale so that this cheaper, road-movement cost is our unit cost.

Next we must define a set of directional terrain masks which function like the zone-of-control masks to premask invalid starting positions for the direction being considered. In the mask for a given direction, the locations contain values of 1 if movement is allowed from the current position in that given direction. Otherwise, the locations contain 0.

The number of directional terrain masks required equals the number of possible movement direction

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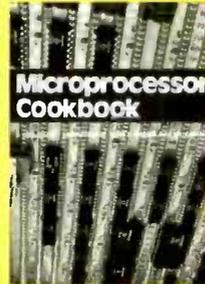
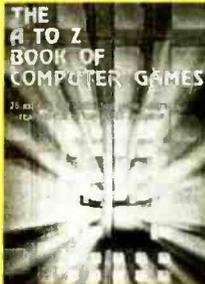
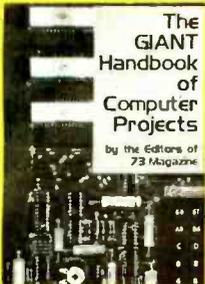
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multiplied by the number of different movement costs of directional terrain. For example, if trails reduce the movement cost to one-half, and roads reduce the movement cost to one-third, on a map using the city metric scatter function, eight directional terrain masks would be required and the unit movement cost would have to be reduced to one-sixth of its original value. This reduced value must be divisible by the least-common multiple of the reduction factors.

Prohibited terrain, such as a river that occupies only the edges of a position and can be crossed only via a bridge, poses yet another problem. A bridge is an example of directional terrain that does not affect the movement cost. To include the effects of bridges, you must define a set of directional terrain premasks to be used in conjunction with all other terrain masks. To represent the effects of directional terrain that adds a constant factor to the movement costs, yet another set of premasks must be defined.

The most effective way to use these directional terrain masks is by modification of the basic scatter function. Consider a game situation where we have clear terrain (one movement factor), rough terrain (two movement factors), roads (one-half movement factor in the direction that the road travels), and bridges over rivers (restricted movement that does not alter movement cost). Let us also use the city metric.

First, we must scale all of our movement costs to reflect the lower cost for the ideal terrain. Thus, we have roads

(1), clear (2) and rough (4). Note that bridges are unaffected. Let T2 and T4 be the terrain masks for clear and rough terrain as described in part 1 of this article. Let I_d be the terrain mask for the ideal terrain in the d direction and let P_d be the terrain mask for the prohibitive terrain (eg: rivers without bridges) in the d direction, where $d=1, 2, 3, 4$. Both I_d and P_d will be 1 only if movement is allowed from that location in direction d for each position on the map. Note that $I_d(I,J)=I_d(I,J)$ AND $P_d(I,J)$ for all I and J .

Let us now define our modified scatter functions CSC' and CSC'' as follows:

$$\begin{aligned} CSC'(A(I,J)) = & A(I,J) \text{ OR } (I1(I,J+1) \text{ AND } A(I,J+1)) \\ & \text{OR } (I2(I,J-1) \text{ AND } A(I,J-1)) \\ & \text{OR } (I3(I+1,J) \text{ AND } A(I+1,J)) \\ & \text{OR } (I4(I-1,J) \text{ AND } A(I-1,J)) \end{aligned}$$

Similarly:

$$\begin{aligned} CSC''(A(I,J)) = & (I,J) \text{ OR } (P1(I,J+1) \text{ AND } A(I,J+1)) \\ & \text{OR } (P2(I,J-1) \text{ AND } A(I,J-1)) \\ & \text{OR } (P3(I+1,J) \text{ AND } A(I+1,J)) \\ & \text{OR } (P4(I-1,J) \text{ AND } A(I-1,J)) \end{aligned}$$

Finally, by replacing CSC in the mapping relation developed in part 1 with CSC' and CSC'' we get:

$$\begin{aligned} M_n = & M_{n-1} \text{ OR } CSC'(M_{n-1}) \\ & \text{OR } (T2 \text{ AND } CSC''(M_{n-2})) \\ & \text{OR } (T4 \text{ AND } CSC''(M_{n-4})) \end{aligned}$$

Summary

We have seen that many problems involving variable terrain may be solved through the use of scatter mappings, scatter sums, premasking, and postmasking. Fixed, prohibited, and ideal terrain, as well as no-exit conditions, have been discussed in reference to our general algorithm of successive scatter mappings. Three different scatter functions and distance-function metrics have been demonstrated for use with two different grids. Two different coordinate systems have also been presented for hexagonal-grid problems.

Since you will most likely want to code it in your favorite language, I have not tried to write this algorithm as a program. I will, however, make a few suggestions. Perform logical functions on groups of elements simultaneously. The rows and columns of the arrays used in the island problem lend themselves nicely to implementation as 8-bit bytes of data. By using a little judicious shifting of these bytes, entire arrays can be scattered with only a few operations.

Do not be afraid to waste a few bits of storage or perform a few unnecessary logical operations to gain a more general representation of your map. It is easier to employ a buffer of unused elements around your arrays than to check for array subscripts that are out of range. Notice how the water terrain provided just such a buffer in the island problem.

In conclusion, this graphical approach to terrain problems provides a viable solution for a wide range of applications, not the least of which is conflict simulation. ■



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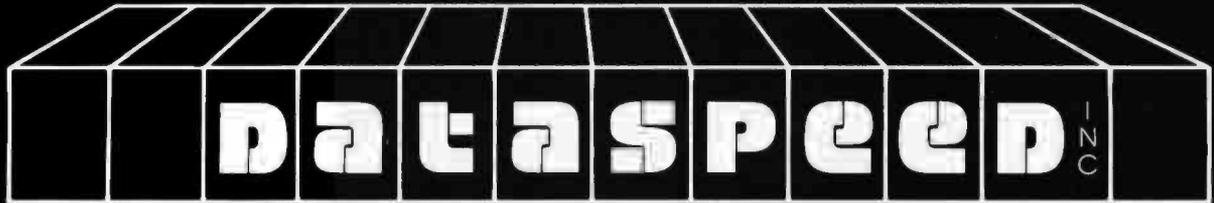
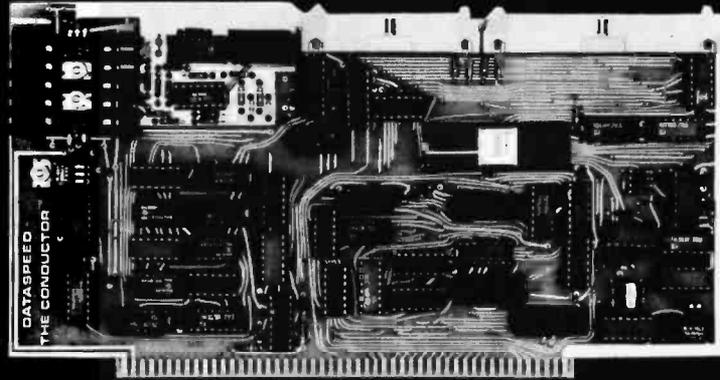
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TRS-80 Performance Evaluation by Program Timing

James R Lewis
4051 Mountain Dr
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I have been asked to evaluate the performance characteristics of numerous hardware and software computer products in my capacity as a systems programmer. In late 1978 I acquired a Radio Shack TRS-80 personal computer system with Level I BASIC and 4 K bytes of memory. I did not consider a performance evaluation; after all, this was my own toy. I did not have to respond to any requests for performance improvements or evaluations. Only my personal satisfaction was important.

As it turned out, I was satisfied, but my friends and colleagues were not. They were continually asking,

Listing 1: Prime-number generator written in Level I BASIC for the TRS-80. No attempt was made here to optimize the speed of execution.

```
30 PRINT " LIST OF PRIME NUMBERS"
40 PRINT
50 PRINT 1;2;3;
55 C=0
70 M = 3
80 M = M + 2
90 FOR K = 3 TO M/2 STEP K - 1
100 IF INT(M/K)*K - M = 0 THEN 190
110 NEXT K
121 PRINT M;
122 C=C+1
190 IF M < 10000 THEN 80
195 PRINT "C = ";C
200 END
```

Listing 2: Level I BASIC version of the prime-number generator in which abbreviations were used and explanatory material omitted to increase speed. Such practices are termed "optimization."

```
80 F.M = 5TO10000S.2
90 F.K = 3TOM/2S.2
100 IFI.(M/K)*K = MT.N.M
110 N.K
120 P.M;
190 N.M
```

"How fast does your toy run?" or "What new tricks have you taught it now?" It seemed that a comprehensive performance testing and evaluation plan was called for. I decided to compare my TRS-80 personal computer with one of the IBM computers (a System/370-148) at work. Since I was also in the process of converting from Level I to Level II BASIC and acquiring more hardware, I wanted to see if I could verify the performance improvements claimed by Radio Shack.

Test Problem

The test problem to be solved was one familiar to computer science students: calculation of prime-number integers from 5 to 10,000. This problem was chosen for several reasons. First, it is a problem that many computer programmers can relate to; second, it uses two program loops; and third, it requires calculations more complex than simple addition. The number of microseconds or nanoseconds required to perform a single function like addition does not adequately describe the performance characteristics of an individual computer, nor does comparison of timing determine the difference between two machines. What is needed is a comparison of a group of instructions or the use of a program representative of those which will be used extensively on that computer as the comparison base. The problem used here performs loops, does moderately complex arithmetic calculations, and performs some input/output (I/O) operations.

Test Problem and the TRS-80 Level I

Listing 1 gives the BASIC statements from my first coding of

the test problem. Note that each keyword of the program was completely entered and spelled out in full, without regard to the abbreviations allowed in Level I. This code took 8 hours and 12 minutes to run to completion (see table 1 for a complete comparison of the results). By simply using the keyword abbreviations (ie: F. instead of FOR and N. instead of NEXT, shown in listing 2), the run time was cut to 7 hours and 12 minutes. The extra N.M (NEXT M) statement was used to speed up the loops, but at the completion of the problem run, a FOR-NEXT error results. This is okay because the problem has been completed.

Listing 3: Level II BASIC version of test program. Keywords must be spelled out in Level II, but the use of integer variables makes it faster than the optimized Level I program. Level II BASIC is also an interpretive system.

```
10 DEFINTM,K
80 FORM = 5TO10000STEP2
90 FORK = 3TOM/2STEP2
100 IFINT(M/K)*M = MTHENNEXTM
110 NEXTK
120 PRINTM;
190 NEXTM
```

The first performance conclusion has been reached; abbreviated syntax cut an 8-hour program by 1 hour. This gave me a 12% improvement in throughput, the magic measure of system performance. Now the problem solution can be accelerated with faster software. For \$99 you can go back to fully spelled out keywords and still gain speed. [Although Level II BASIC requires that keywords be entered in the fully spelled out form, and displays them in that way, the keywords are stored in memory in the

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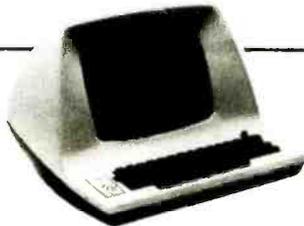


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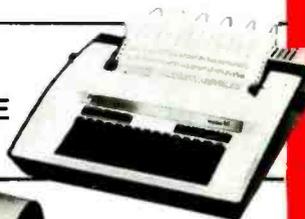
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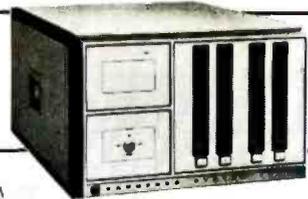
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form of single-byte codes. A translation routine is used to spell out the meaning of these codes when the LIST command is given.... RSS]

Test Problem and Level II BASIC

I sent back my TRS-80 Level I 4 K computer. A short time later it came back with Level II BASIC and an expanded 16 K bytes user memory. The original test problem now ran in 6 hours and 31 minutes. This improvement was approximately 9%; there was an \$11 investment for each percent of performance gained.

Test	Listing	Run Time			Description
		hours	minutes	seconds	
1	1	8	12	13	TRS-80 Level I Nonoptimized BASIC
2	2	7	12	27	TRS-80 Level I Optimized BASIC
3	3	6	31	10	TRS-80 Level II BASIC
4	4		21	55	Z80 Assembler Language
5	4		22	50	Z80 Assembler Language under TRSDOS Disk Operating System
6	5	1		19	PL/I for IBM 370-148 using Optimizing Compiler
7	6			56	370-148 Assembly Language IBM 370-148 Assembly Language

Table 1: Summary of tests in our performance evaluation. In each case the program found integer prime numbers from 5 to 10,000.

Test Problem and Z80 Assembly Language

Several years ago I became proficient in Datapoint 2200 assembly language, which is very similar to Z80 assembly language. I thought that several hours of coding and testing would be required to implement the test problem in Z80 assembly instructions. After several days of relearning the microinstruction format and developing the conversion and division subroutines, I finally ran my assembly test. To my surprise, it now ran in just under 22 minutes, an improvement of over 6

hours. Note that in the assembly-language program multiplication was not required, because all that is needed for prime number detection is division and determination of the remainder. The quotient proved useful in controlling the inner loop.

My next expansion of the system added a floppy-disk drive and more memory to a 32 K bytes total. There was an apparent five-second reduction in run time when the prime number output conversion was eliminated. However, I observed no noticeable performance change when the program ran in either the first 16 K bytes of memory or in the second 16 K bytes. Now that I had a disk and the TRSDOS disk operating system, I thought of the real-time CLOCK function now activated and wondered about its effect on performance.

Test Problem and the TRSDOS Disk Operating System

I relocated my assembly-language program to hexadecimal location

Text continued on page 92

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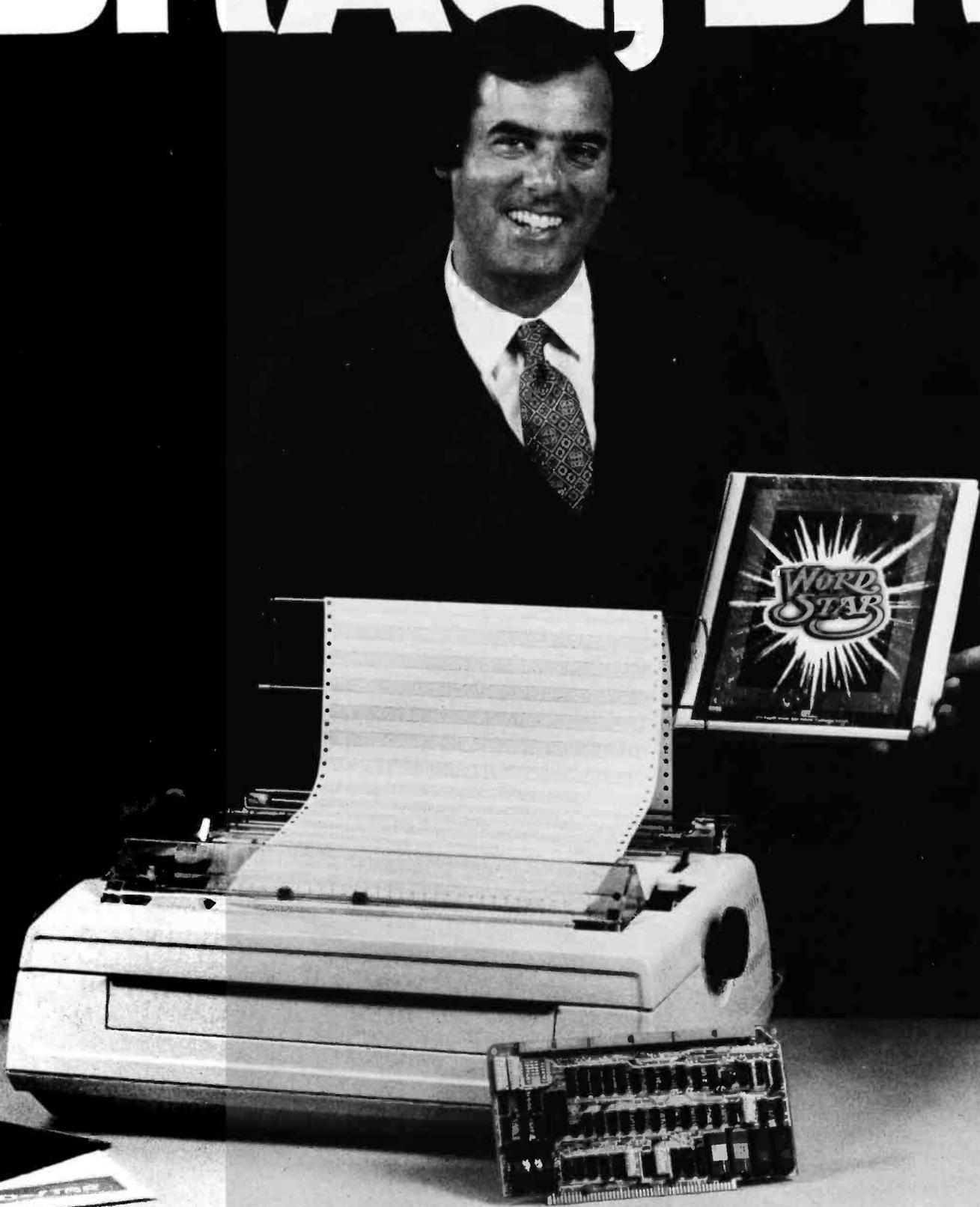
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```

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  X = -A,
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  X = 0

Enter ? TAN (X) * COS (X) + 1/CSC (X);
Response
  2 * SIN (X)

Symbolic Integration!
  ? INT (X * COS(A * X^2), X);
  SIN (X^2 * A) / (2 * A)

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  ? [1, X]
  [0, A] + -1;
  [1, -X/A],
  [0, 1/A],

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  ? 991 * 3 + (1/2) / 40 + 35;
  296438922463401814427834889493
  2562055695871443300411356128843
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```

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Listing 4: Prime-number generator coded in Z80 assembler for the TRS-80. The Radio Shack Editor and Assembler package was used. The efficiency of assembler coding is clearly shown in the greatly reduced execution time. No interpretation is required; we are speaking in the "native language" of the machine.

```

START   ORG     7000H
        LD     HL,(NUM)           ;GET NUMBER
        INC   HL                 ;BUMP NUMBER
        INC   HL                 ;BY TWO TO INSURE ODD VALUE
        LD   (NUM),HL           ;SAVE FOR NEXT TIME
        LD   A,10000<8<-8      ;LSB OF 10000
        SUB  L                   ;DOUBLE PRECISION COMPARE
        LD   A,10000<-8        ;MSB OF 10000
        SBC  A,H                 ;CHECK HIGH BYTE
        JR   C,DONE             ;END OF RUN
        LD   DE,1               ;START VALUE
        LD   (NUM2),DE         ;SAVE IT

;
DLOOP   LD     DE,(NUM2)         ;DIVISOR
        INC   DE                 ;BUMP IT
        INC   DE                 ;TWICE TO KEEP ODD
        LD   (NUM2),DE         ;SAVE FOR NEXT TIME
        LD   BC,(NUM)          ;TARGET
        LD   HL,0               ;CLEAR HIGH HALF OF DIVIDEND
        CALL DIV16              ;PERFORM 16 BIT DIVIDE
        LD   A,H                ;CHECK REMAINDER
        OR   L                   ;IF ZERO WAS DIVISIBLE
        JR   Z,START           ;AND NOT PRIME
        DEC  BC                 ;CHECK FOR ONE
        LD   A,B                ;AS THIS MEANS WE
        OR   C                   ;HAVE GONE HALFWAY
        JR   NZ,DLOOP          ;NO, LOOP
        LD   HL,(NUM)          ;DISPLAY THIS NUMBER
        LD   IX,WORK            ;WORK AREA
        CALL DCONV              ;CONVERT TO ASCII
        LD   HL,WORK           ;AREA FOR DISPLAY
        CALL DSPLY              ;TO SCREEN
        LD   HL,(COUNT)       ;COUNT PRIME NUMBERS
        INC  HL                 ;BY ONE
        LD   (COUNT),HL
        JR   START

;
DONE    LD     HL,(COUNT)       ;DISPLAY TOTAL COUNT
        LD   IX,WORK            ;CONVERT TO ASCII
        CALL DCONV              ;DISPLAY STRING
        LD   HL,TOTAL
        CALL DSPLY              ;LOOP
        JR   $

;
TOTAL   DEFM   'TOTAL ='
WORK    DEFM   '12345 '
        DEFB   3

NUM     DEFW   1                 ;NUMBER TO BE TESTED
NUM2    DEFW   0                 ;TESTING NUMBER
COUNT  DEFW   0                 ;COUNT OF PRIME NUMBERS
;
        DISPLAY STRING TO SCREEN
DCHAR   EQU    33H              ;LEVEL II CHAR DISPLAY
DSPLY   LD     A,(HL)           ;GET CHARACTER
        CP     3                 ;END OF STRING?
        RET   Z                  ;YES, DONE
        CALL  DCHAR             ;LET LEVEL II MANAGE SCREEN
        INC   HL                 ;BUMP MEMORY POINTER
        JR   DSPLY

;
        CONVERT HL TO 5 DIGIT AREA POINTED TO BY IX
DCONV   LD     C,' '            ;TRIGGER AND ASCII CHARACTER
        LD   B,5                 ;COUNT OF CONVERSION
        LD   IY,CTBL            ;CONVERSION TABLE
DCONV1  LD     E,(IY)           ;LSB OF FACTOR
        INC  IY
        LD   D,(IY)            ;MSB OF FACTOR
        INC  IY
        SUB  A                   ;CLEAR C FLAG AND DIGIT COUNTER
DCONV2  SBC  HL,DE              ;16 BIT SUBTRACT
    
```

Listing 4 continued on page 92

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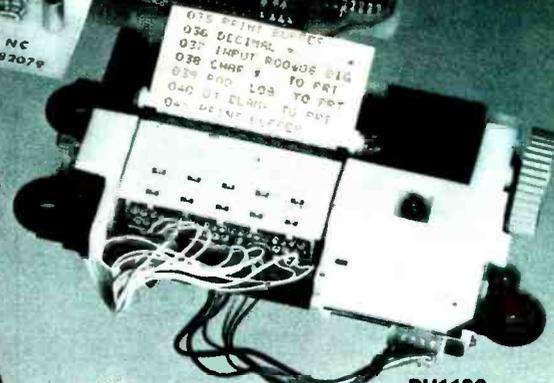
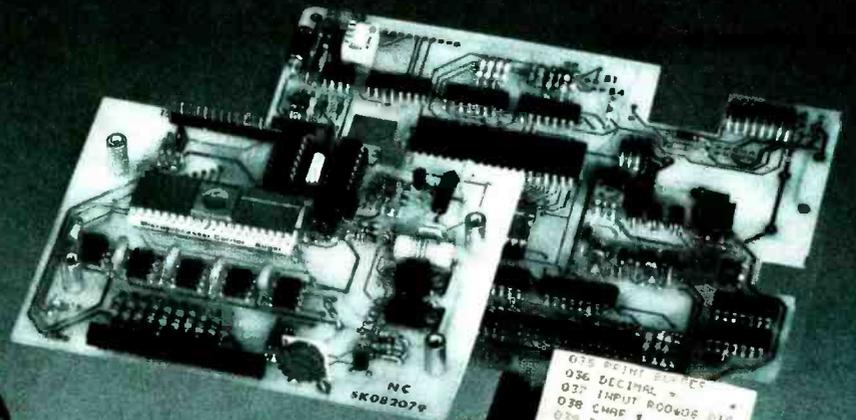
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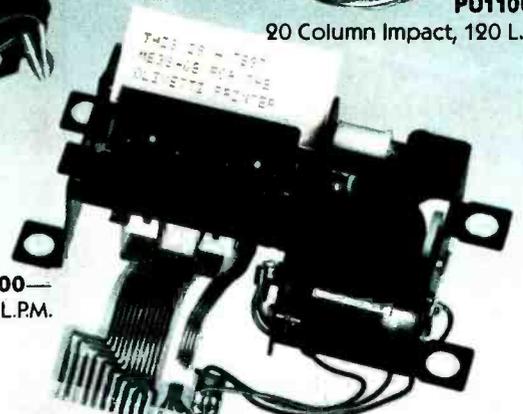
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Listing 4 continued:

```

JR          C,DCONV3          ;UNDERFLOW
INC         A                ;BUMP DIGIT
JR          DCONV2          ;CONTINUE BUILDUP
DCONV3     ADD              HL,DE ;COMPENSATE FOR UNDERFLOW
OR          A                ;NON-ZERO DIGIT?
JR          Z,DCONV4        ;NO, ZERO, DO NOT RESET TRIGGER
LD         C,'0'            ;ASCII TRIGGER
DCONV4     OR          C      ;TURN INTO ASCII (OR BLANK)
LD         (IX),A           ;STORE DIGIT
INC         IX
DJNZ       DCONV1          ;COUNT DOWN
OR         A,(IX-1)         ;MUST SHOW A ZERO DIGIT
OR         '0'              ;IF ZERO
LD         (IX-1),A
RET

;
CTBL       DEFW             10000
           DEFW             1000
           DEFW             100
           DEFW             10
           DEFW             1
; 16 BIT DIVISION
; DIVIDEND = HLBC
; DIVISOR = DE
; QUOTIENT = BC
; REMAINDER = HL
DIV16     LD          A,16
DIV161    SLA         C
           RL          B
           ADC         HL,HL
           SBC         HL,DE
           JR          NC,DIV162
           ADD         HL,DE
           JR          DIV163
DIV162    INC         C
DIV163    DEC         A
           JR          NZ,DIV161
           RET
;
           END          START

```

Listing 5: Test program coded in the PL/I language for the IBM System/370-148. An optimizing compiler was used to run this version. Compilation is more efficient than interpretation in reducing execution time. This program also finds prime numbers.

```

PRIME: PROC OPTIONS(MAIN) REORDER;
      DECLARE (C, D, M) FIXED BINARY(31) INIT(0);
      DO M = 3 TO 10000 BY 2;
        DO D = 3 TO M/2 BY 2;
          IF MOD(M, D) = 0 THEN GOTO NOT__PRIME;
        END;
        C = C + 1;
        PUT LIST(M);
      NOT__PRIME:
      END;
      END PRIME;

```

Text continued:

7000 and constructed a disk operating system command (CMD) file. When run under the disk operating system, the test problem execution time was extended by 55 seconds. I attributed this delay to the 25 ms interrupt from the expansion interface and the processing required to service the interrupt and update the clock. This

amounted to about 4 to 5% overhead. Using the disk operating system BASIC, the T command to turn off the interrupt will speed up the execution of programs not requiring clock functions. Listing 4 represents the Z80 assembly-language version of the prime number finding program.

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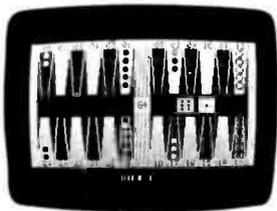
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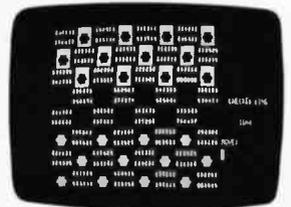
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Listing 6: Test program coded in assembler language for the IBM 370. Writing in the native language of this very fast machine, we obtain the shortest time for finding prime numbers from 5 to 10,000.

	LA	R2,S	STARTING VALUE FOR TEST
	SR	R10,R10	COUNT OF PRIME NUMBERS
	LA	R6,2	LOOP INCREMENT - INNER LOOP
	LR	R8,R6	LOOP INCREMENT - OUTER LOOP
	LH	R9,=H'10000'	UPPER LIMIT FOR OUTER LOOP
OLOOP	LA	R3,3	STARTING VALUE FOR TESTING NUMBER
	LR	R7,R2	COMPUTE INNER LOOP LIMIT
	SRL	R7,1	DIVIDE BY TWO
ILOOP	SR	R4,R4	ZERO EVEN DIVIDEND PAIR
	LR	R5,R2	LOAD ODD DIVIDEND VALUE
	DR	R4,R3	R3 IS DIVISOR
	LTR	R4,R4	CHECK REMAINDER
	BZ	NEXTO	ZERO IS NOT PRIME
	BXLE	R3,R6,ILOOP	INNER LOOP
	CVD	R2,WORK	CONVERT PRIME NUMBER TO DECIMAL
	UNPK	DATA(7),WORK + 4(4)	MAKE EBCDIC
	OI	DATA + 6,X'F0'	SET SIGN CORRECT
	PUT	SYSPRINT, DATA	OUTPUT PRIME NUMBER
	LA	R10,1,(R10)	INCREMENT PRIME NUMBER COUNT
NEXTO	BXLE	R2,R8,OLOOP	OUTER LOOP
	CVD	R10,WORK	CONVERT COUNT TO DECIMAL
	UNPK	DATA(7),WORK + 4(4)	AND TO EBCDIC
	OI	DATA + 6,X'F0'	SET SIGN CORRECT
	PUT	SYSPRINT, DATA	OUTPUT COUNT

Test Problem and the Large System

At the completion of the TRS-80 testing phase, I coded two versions of the test problem to be run on the IBM 370-148. Listings 5 and 6 show PL/I language and 370 assembler language codings of the prime-number generator. The execution times showed little difference. The PL/I version (compiled, rather than interpreted) ran in 1 minute and 19 seconds of processor time. The test run in assembler language used 56 seconds of processor time.

The best comparison between the two machine's capabilities is arranged by counting the number of instructions needed to perform division; twelve for the TRS-80 (ten of which are looped sixteen times) and one for the 370. Performance difference is also indicated by the average execution time of 1108 μ s for the Z80 division subroutine versus 30.7 μ s for the DR (divide register into register) instruction of the 370-148. This is a time ratio of 36 to 1. If you compare a less complex function, such as 16-bit storage-to-register load, the TRS-80 performs closer to the 370 capability; the Z80 LD HL,(n) instruction takes 16 cycles or 9.008 μ s, and the 370 load halfword takes 1.958 μ s. The 16-bit load operation compares as a 4.6 performance ratio. Thus, it is shown that a single instruction comparison does not always represent the required work performance ratio.

Conclusions

The test program I chose can be run with the same results on both the TRS-80 and the IBM 370-148. There is a difference in system throughput and cost. An analysis of the TRS-80 performance indicates that the advertised improvements of Level I keyword abbreviations and Level II BASIC are present. The analysis of the TRS-80 BASIC versus Z80 assembler language shows a significant improvement in assembler language, if you care to code the program that way or if you need the speed. I now have an answer for my friends at work when they ask about the speed differences between my personal computer system and the personal IBM 370-148. ■

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```

x:n          : INTEGER;
sigma       : INTEGER;
which_rins  : (second,third);

a:brc      : absolute_time;
rins_time  : absolute_time;
second_contact_rins : absolute_time;
third_contact_rins : absolute_time;
tot_time   : absolute_time;
time_totality : absolute_time;
margin_time : absolute_time;
current_line : absolute_time;
half_time  : absolute_time;
quarter_line : absolute_time;
slack_in_totality : absolute_time;
dummy     : absolute_time;
total_duration : absolute_time;

maximum     : exposures;
total_eclipse : exposures;
rins_frames : exposures;
current_shot : exposures;

ten_shot_groupings : PACKED ARRAY[0..9] OF an_exposure_detail;
transient_shots    : PACKED ARRAY[0..1] OF an_exposure_detail;

PROCEDURE new_page;
VAR
  stuff : STRING[24];
  clear_screen : CHAR;
BEGIN
  stuff := '
  clear_screen := CHR(24);
  WRITELN(clear_screen,stuff);
  WRITELN(' ');
  WRITELN(' ');
  WRITELN(s);
END (new_page);

PROCEDURE set_parameter(VAR time : absolute_time);
VAR
  a_string : STRING[128];
  i : INTEGER;
  period : BOOLEAN;
  decimal_count : INTEGER;
  factor, result : INTEGER;

  PROCEDURE add_a_digit(position : INTEGER);
  VAR
    digit : INTEGER;
  BEGIN
    digit := (ORD(a_string[position])-ORD('0'));
    IF period THEN
      BEGIN
        decimal_count := decimal_count + 1;
        IF decimal_count < 4 THEN
          BEGIN

```

```

line.thousandths := time.thousandths
+ ((1000 * digit) DIV factor);
factor := 10 * factor;
END
END
ELSE (before period)
  time.units := (time.units * factor) + digit;
END;

BEGIN (set_parameter)
PAGE(OUTPUT);
time.units := 0;
time.thousandths := 0;
WHILE ((time.units=0) AND (time.thousandths=0)) DO
  BEGIN
    factor := 10;
    decimal_count := 0;
    period := FALSE;
    WRITELN(s);
    READLN(a_string);
    FOR i := 1 TO LENGTH(a_string) DO
      BEGIN
        CASE a_string[i] OF
          '0','1','2','3','4','5','6','7','8','9':
            add_a_digit(i);
          ' ':
            period := TRUE;
        END
      END
    END
  END
END (set_parameter);

PROCEDURE initialize;
VAR
  i : INTEGER;
BEGIN (initialize)
  s := ' ';
  current_line.units := 0;
  current_line.thousandths := 0;
  current_shot := 0;
  ten_shot_groupings[0].duration := 1;
  ten_shot_groupings[1].duration := 4;
  ten_shot_groupings[2].duration := 16;
  ten_shot_groupings[3].duration := 64;
  ten_shot_groupings[4].duration := 128;
  ten_shot_groupings[5].duration := 256;
  ten_shot_groupings[6].duration := 512;
  ten_shot_groupings[7].duration := 1024;
  ten_shot_groupings[8].duration := 2048;
  ten_shot_groupings[9].duration := 4096;
  FOR i := 0 TO 9 DO
    ten_shot_groupings[i].wait_after := overhead_duration;
  END
  transient_shots[0].duration := 4;
  transient_shots[1].duration := 32;
  FOR i := 0 TO 1 DO

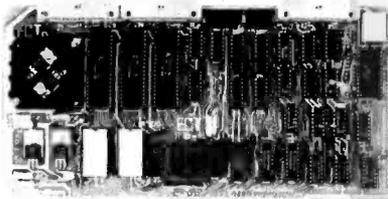
```

Listing 1 continued on page 98

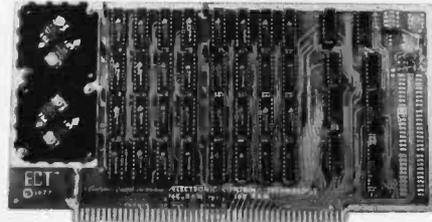
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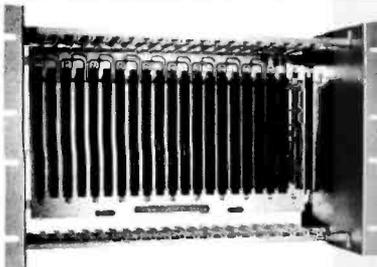
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Listing 1 continued:

```
transient_shots[i].wait_after := overhead_duration;
new_page;
WRITELN('Totality' is defined as time from second to third contacts');
s := 'Enter number of exposures';
set_parameter(dummy);
maximum := dummy.units;
s := 'Enter number of exposures during totality';
REPEAT
BEGIN
set_parameter(dummy);
total_eclipse := dummy.units
END
UNTIL
(total_eclipse > 0)
AND
(total_eclipse < maximum);
s := 'Enter time of totality in "seconds.thousandths"';
set_parameter(time_totality);
s := 'Enter slack time margin (in seconds)';
set_parameter(slack_in_totality);
crash_ahead := TRUE
END (initialize);

PROCEDURE error_abort;
BEGIN
maximum := 250;
total_eclipse := 200;
rings_frames := 25;
WRITELN('Unrecoverable error in data');
crash_ahead := FALSE
END;

PROCEDURE subtract_time(a,b : absolute_time; VAR c : absolute_time)
BEGIN
c.thousandths := a.thousandths - b.thousandths;
sigma := 0;
IF c.thousandths < 0 THEN
BEGIN
c.thousandths := c.thousandths + 1000;
sigma := -1
END;
c.units := a.units - b.units + sigma
END;

PROCEDURE divide_time(
VAR a : absolute_time;
b : absolute_time;
n : INTEGER
);
[ a <- b DIV n ];
VAR
p : INTEGER(16);
BEGIN
a.thousandths := 0;
a.units := 0;
n := b.units;
a := a * 1000;
a := a + b.thousandths;
p := a DIV n;
p := a DIV 1000;
IF p < 32768 THEN
a.units := TRUNC(p);
p := a - (1000 * p);
IF p < 32768 THEN
a.thousandths := TRUNC(p)
END;

PROCEDURE add_time(a,b : absolute_time; VAR c : absolute_time);
BEGIN
sigma := a.thousandths + b.thousandths;
c.thousandths := sigma MOD 1000;
c.units := a.units + b.units + (sigma DIV 1000)
END;

PROCEDURE print_time(a : absolute_time);
VAR
z1000,z100 : STRING(13);
BEGIN
IF a.thousandths < 100 THEN z1000 := '0' ELSE z1000 := '';
IF a.thousandths < 10 THEN z100 := '0' ELSE z100 := '';
WRITELN(sva.units,' ',z1000,z100,a.thousandths)
END;

PROCEDURE normalize_timings;
VAR
i : INTEGER;

PROCEDURE sum_up_rings(rings : INTEGER; VAR rings_total : absolute_time);
VAR
index,i : INTEGER;
this_rings : absolute_time;
BEGIN
rings_total.units := 0;
rings_total.thousandths := 0;
FOR i := 1 TO rings_frames DO
BEGIN
this_rings.units := 0;
this_rings.thousandths := transient_shots[rings].wait_after;
add_time(this_rings,rings_total,rings_total);
this_rings.thousandths := transient_shots[rings].duration;
add_time(this_rings,rings_total,rings_total)
END
END;

PROCEDURE sum_up_eclipse(VAR eclipse_total : absolute_time);
VAR
this_shot : absolute_time;
index,i,j : INTEGER;
BEGIN
eclipse_total.units := 0;
eclipse_total.thousandths := 0;
FOR i := 1 TO total_eclipse DO
BEGIN
```

Listing 1 continued on page 100



THE DATA BASE SPECIALIST

HDBS - HIERARCHICAL DATA BASE MANAGEMENT SYSTEM MDBS - OUR FULL NETWORK DATA BASE MANAGEMENT SYSTEM

HDBS FEATURES	ADDITIONAL FEATURES IN MDBS	
<ul style="list-style-type: none"> • HIERARCHICAL DATA STRUCTURES • FIXED LENGTH RECORDS • READ/WRITE PROTECTION AT FILE LEVEL • ONE-TO-MANY SET RELATIONSHIPS ALLOWED 	<ul style="list-style-type: none"> • HIERARCHICAL AND FULL NETWORK DATA STRUCTURES (CODASYL ORIENTED) • FIXED AND VARIABLE LENGTH RECORDS • MULTIPLE LEVELS OF READ/WRITE PROTECTION AT ITEM, RECORD, SET AND FILE LEVELS 	<ul style="list-style-type: none"> • EXPLICIT REPRESENTATION OF ONE-TO-ONE, ONE-TO-MANY, MANY-TO-ONE AND MANY-TO-MANY SETS • RECORD TYPES MAY OWN OTHER OCCURRENCES OF THE SAME RECORD TYPE • A SINGLE SET MAY HAVE MULTIPLE OWNER AND MEMBER RECORD TYPES

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STRAIGHT FORWARD USE OF ISAM-LIKE STRUCTURES
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REQUIREMENTS

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- 8080 APPROXIMATELY 20K MEMORY -
- IN ADDITION TO THE OPERATING SYSTEM, HOST LANGUAGE, USER'S PROGRAM AND SOME BUFFER AREA
- 6502 APPROXIMATELY 26K MEMORY

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MDBS-DRS FEATURES

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THIS FEATURE CAN ONLY BE ADDED TO THE MDBS SYSTEM.

HDBS and MDBS PACKAGES INCLUDE

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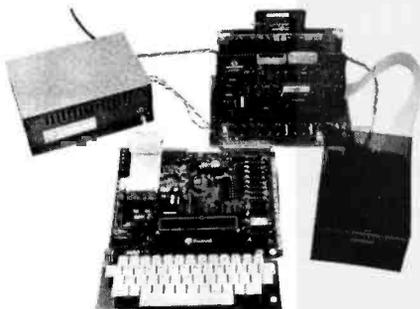
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Listing 1 continued:

```

this_shot.units := 0;
index := (i-1) MOD 10;
this_shot.thousandths := ten_shot_groupings[index].wait_after;
add_time(this_shot,eclipse_total,eclipse_total);
this_shot.thousandths := ten_shot_groupings[index].duration;
add_time(this_shot,eclipse_total,eclipse_total)
END
END;

PROCEDURE preliminary_allocation;
BEGIN
s := 'Allocation of Eclipse Times...';
new_page;
s := '          Total time for eclipse = ' ;
Print_time(time_totality);

WRITELN('-----');
which_rins := second;
sum_up_rins(ORD(which_rins),second_contact_rins);

s := 'Time required for second contact transient = ' ;
Print_time(second_contact_rins);

which_rins := third;
sum_up_rins(ORD(which_rins),third_contact_rins);

s := 'Time required for third contact transient = ' ;
Print_time(third_contact_rins);

add_time(second_contact_rins,third_contact_rins,rins_time);
s := 'Total time devoted to diamond rins sequences= ' ;
Print_time(rins_time);
divide_time(quarter_time,second_contact_rins,2);
s := 'Anticipation time for first diamond rins = ' ;
Print_time(quarter_time);

WRITELN('-----');
sum_up_eclipse(tot_time);
s := '          Time devoted to totality = ' ;
Print_time(tot_time);
s := '          Slack time margin at end of totality = ' ;
Print_time(slack_in_totality);

divide_time(half_time,rins_time,2);
s := 'Extra slack due to diamond rins overlaps = ' ;
Print_time(half_time);

add_time(tot_time,slack_in_totality,total_duration);
add_time(total_duration,half_time,total_duration);
s := 'Total time committed before margin alloc. = ' ;
Print_time(total_duration);

WRITELN('-----');
subtract_time(time_totality,total_duration,margin_time);
s := '          Difference is time margin for allocation = ' ;
Print_time(margin_time)
END (preliminary_allocation);

PROCEDURE margin_dispersion;
VAR
margin_per_frame : absolute_time;
i : INTEGER;
BEGIN
divide_time(margin_per_frame,margin_time,total_eclipse);
FOR i := 0 TO 9 DO
ten_shot_groupings[i].wait_after :=
ten_shot_groupings[i].wait_after +
(1000 * margin_per_frame.units) +
margin_per_frame.thousandths;
s := '          Margin per totality frame = ' ;
Print_time(margin_per_frame)
END (margin_dispersion);

PROCEDURE final_allocation;
BEGIN
sum_up_eclipse(tot_time);
s := '          Adjusted time devoted to total phase = ' ;
Print_time(tot_time);

add_time(tot_time,slack_in_totality,total_duration);
add_time(total_duration,half_time,total_duration);
s := '          Adjusted total time committed = ' ;
Print_time(total_duration);

WRITELN('-----');
subtract_time(time_totality,total_duration,margin_time);
s := '          Margin time after allocation to totality = ' ;
Print_time(margin_time)
END (final_allocation);

PROCEDURE alloc_exposures;
BEGIN
rins_frames :=
(maximum - total_eclipse) DIV 2;
IF rins_frames < 2 THEN error_abort;
sigma := maximum - (total_eclipse + (2 * rins_frames));
total_eclipse := total_eclipse + sigma;
WRITELN('');
WRITELN('Exposures map:');
WRITELN('  First diamond rins = ',rins_frames);
WRITELN('  Totality = ',total_eclipse);
WRITELN('  Second diamond rins = ',rins_frames);
WRITELN('  -----');
WRITELN('          TOTAL = ',maximum);
WRITELN('');
WRITELN('');
WRITELN('Press return to continue');
READLN(s);
END (alloc_exposures);

BEGIN (normalize_timings)
alloc_exposures;
preliminary_allocation;

```

Listing 1 continued on page 102

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Everything Let on Shopping List #10 runs on 64K TRS-80 Model II

- CP/M is a trademark of Digital Research.
- Z80 is a trademark of Zilog, Inc.
- UNIX is a trademark of Bell Laboratories.
- WHATSI7 is a trademark of Computer Software.
- Electric Pencil is a trademark of Michael Strayer Software.
- TRS-80 is a trademark of Tandy Corp.
- CP/M for Health, TRS-80 Model I and PolyMorphic 8813 are modified and must use specially compiled versions of system and applications software.
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Listing 1 continued:

```

margin-dispersal;
final_allocation
END (normalize_linings);
PROCEDURE await_cue;
BEGIN (await_start);
END (await_start);
PROCEDURE diamond_rins_burst;
BEGIN (diamond_rins_burst);
END (diamond_rins_burst);
PROCEDURE totality;
BEGIN (totality);
END (totality);
PROCEDURE summarize;
BEGIN (summarize);
WRITELN('Press return to end program');
READLN(s);
END (summarize);
BEGIN (eclipse_monitor_simulation)
initialize;
normalize_linings;
await_cue;
diamond_rins_burst;
totality;
await_cue;
diamond_rins_burst;
summarize
END. (eclipse_monitor_simulation)

```

Listing 2: Preliminary allocation steps. The first stage of the execution of the program is this listing of an interactive sequence to determine the independent variables of the simulation.

```

Preliminary data initialization
"totality" is defined as time from second to third contacts
Enter number of exposures
250
Enter number of exposures during totality
200
Enter time of totality in "seconds.thousandths"
240
Enter slack time margin (in seconds)
6

Exposures map:
First diamond ring = 25
Totality           = 200
Second diamond ring = 25
-----
TOTAL              = 250

Press return to continue

```

Editorial text continued from page 12:

time is calculated as the difference between all the time commitments and the total time available during totality. (Half the time required for the diamond ring effects is assumed to take place during actual totality, so that the transient effects will be bracketed in time.) The margin time must be equally divided among the individual shots during totality. The procedure "margin-dispersal" is used to divide the margin by the number of totality exposures, then add this amount to the "wait-after" field of each of the ten unique totality exposure specifications in the array "ten-shot-grouping."

Finally, the procedure "final-allocation" reports on the actual allocation achieved by recalculating the margin time. This second margin time calculation reflects the allocation's effect. In photo 3, the value of 0.17 seconds is well within the limits of human hand/eye coordination by yours truly. (Hand/eye coordination will be used to

Listing 3: Final computation. Using a brute force technique of adding up various time intervals, the program arrives at this calculated model of the parameters. It first sums up the required time budget for all the events that must happen. The difference between this value and the time of totality is a margin value. This value is then evenly allocated to the timing of exposures during the main part of the eclipse. In the example, I have assumed 250 exposures total, 200 of which occur in the main portion of a 240.0 second eclipse event with a 6.0 second margin for manual timing at the end of the main sequence of totality.

```

Allocation of Eclipse Times...
Total time for eclipse = 240.000
-----
Time required for second contact transient = 5.100
Time required for third contact transient = 5.800
Total time devoted to diamond ring sequences = 10.900
Anticipation time for first diamond ring = 2.550
-----
Time devoted to totality = 202.980
Slack time margin at end of totality = 6.000
Extra slack due to diamond ring overlaps = 5.450
Total time committed before margin alloc. = 214.430
-----
Difference is time margin for allocation = 25.570
Margin per totality frame = 0.127
Adjusted time devoted to total phase = 228.380
Adjusted total time committed = 239.830
-----
Margin time after allocation to totality = 0.170
Press return to end program

```

observe the digital wristwatch set to Universal Coordinated Time and pick the precise time to start the real-time sequence of the program by hitting any key on the Apple keyboard. Later in the eclipse, the second diamond ring event (third contact) will be initiated by a similar procedure while watching the eclipsed sun.)

As it stands in listing 1, the program still must be filled out with the actual details of procedures "await-cue," "diamond-ring-burst," "totality," and "summarize." These are all relatively straightforward procedures, which will execute the real-time process of the eclipse observation. Other details to be verified include the actual model of the bulb-release exposure event (ie: what fixed overhead time is associated with the mirror flip/shutter opening action of the mechanism), calibration of a Pascal "do nothing" timing loop running with the Apple II's crystal clock so that the entire program executes all exposures within the time set by the model, and so forth. I will have more details on this in a forthcoming editorial, as I complete the model and finish verifying the system concept.

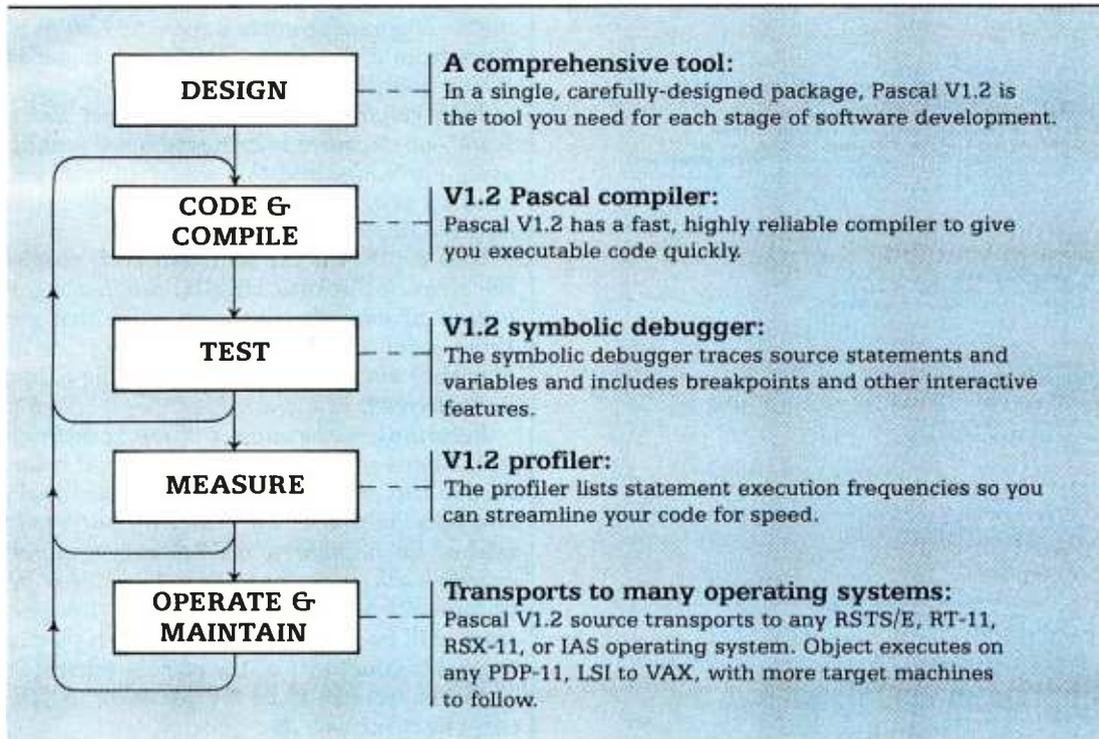
The most important concept here is the very real machine-independent viability of a high-level language, such as Pascal, in designing and then communicating the idea of a program. The functional simulation stage of my eclipse control program is now complete in concept and awaits some final details to be added over the next week or so. When it is done, going from the functional simulation to the actual eclipse control program I bring with me to Africa will be achieved by the simple act of reconfiguring the textual displays for a more limited 40-column output display and making multiple, redundant copies of the software on floppy disks for my travels.

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Listing 4: A camera interface test program. This Pascal test program exercises the camera shutter control interface of figure 1 by alternating the state of Apple II Game I/O annunciator output ANO.

```

Moultkin test_interface;
(* This program, written December 25, 1979 is designed to test out
the interface to the Nikon MB-2 motor drive by alternately
setting the state of output transistor Q2 in response to carriage
return characters. A delay count set by a null FOR statement
is used to allow repeated actuation with a minimum time between
output state changes. A variant record technique is used in the
Pascal software of the procedure "ref_memory" in order to set and
reset the output bit at absolute addresses C058 and C059 hexadecimal.
*)

CONST
  open_shutter_address = -16295 (sets ANO output to "1");
  close_shutter_address = -16296 (resets ANO output to "0");

VAR
  reiterations : INTEGER;
  j,k,i : INTEGER;
  s : CHAR;

PROCEDURE ref_memory(address : INTEGER);
(* This procedure uses the variant record technique to
reference an address passed to it as a 16 bit signed
INTEGER. The Apple-II hardware will set or reset the
annunciator outputs of the Game I/O connector if the
appropriate addresses are simply referenced by a program.
*)
  TYPE
    ptr = TCHAR;

    memory_access = (pointer: number)
  ; This is a dummy statement required by the syntax of
  Pascal variant records such as "memory" below. The
  variant record "trick" is not the most elegant way to
  reference an absolute hardware address, since it
  requires an implementation-dependent assumption about
  variant records, i.e. that a 16 bit signed two's complement
  INTEGER type maps bit for bit into the 16 bit positive
  integer value of an address stored in a Pascal pointer
  data type.
  ;);

  memory =
    RECORD
      CASE memory_access OF
        pointer : (a_pointer : ptr);
        number : (a_number : INTEGER)
      END;
    END;

VAR
  anybyte : memory;
  anychar : CHAR;

BEGIN
  anybyte.a_number := address;
  anychar := anybyte.a_pointer;
END (ref_memory);

PROCEDURE end_exposure;
BEGIN
  WRITELN('Motor drive now fires... and shutter cocks');
  ref_memory(close_shutter_address);
END (end_exposure);

PROCEDURE start_exposure;
BEGIN
  WRITELN('Shutter opens with a "click"');
  ref_memory(open_shutter_address);
END (start_exposure);

PROCEDURE change_reiterations;
BEGIN
  WRITELN('Enter integer time delay count');
  WRITELN(' (old count was = ',reiterations,' )');
  READLN(reiterations);
  IF reiterations < 1 THEN reiterations := 1;
  IF reiterations > 2500 THEN reiterations := 2500;
END (change_reiterations);

BEGIN
  reiterations := 1000;
  FOR i := 1 TO 1000 DO
    BEGIN
      FOR j := 1 TO reiterations DO;
        WRITELN('*** Shutter is now closed ***');
        READLN(s);
        IF s = ' ' THEN
          ELSE IF s = 'N' THEN change_reiterations;
          ELSE IF s = 'E' THEN i := 1000;
        start_exposure;
        FOR j := 1 TO reiterations DO;
          WRITELN('***** Shutter is now open *****');
          READLN(s);
          IF s = ' ' THEN
            ELSE IF s = 'N' THEN change_reiterations;
            ELSE IF s = 'E' THEN i := 1000;
          end_exposure;
        END;
      END;
    END;
  END;
END;

```

Bar Codes and Home Brewing . . . Progress Reports

As of early December 1979, we received some exciting word about the state of manufacturing of bar-code-reader wands. This word comes from John Sien of Hewlett-Packard's Optoelectronics Division in Palo Alto, California. Hewlett-Packard has just completed the formal announcement of a truly inexpensive optical bar-code reader, which will be available from stocking distributors of their component lines, possibly by the time you are reading this issue of BYTE.

The bar-code reader interfaces to transistor-transistor logic (TTL) or complementary metal-oxide semiconductor (CMOS) logic with three wires: signal, ground and power. It enables an individual with a personal computer to read Universal Product Codes (as on grocery items) or PAPERBYTES bar codes, or a host of other possible machine-readable printed formats. This reader costs a mere \$99.50 in single quantities from a distributor and much lower in manufacturing quantities.

John reports that there is a great deal of interest from one or more microwave-oven manufacturers in using bar codes and this reader to transfer individual cooking programs from food-packets or recipe books into the oven's control circuitry.

This product is the same bar-code reader used with the Hewlett-Packard HP-41C calculator for the distribution of miscellaneous user-submitted programs. In short, now that the single enabling piece of hardware is widely available in an inexpensive form, bar codes have arrived.

Returning to the subject of my homebrew 6809 project, I have put off further work until return from the eclipse trip early this month. In a personal analogy to concepts held dear by many of our readers, I have pushed the homebrew 6809 down on my internal procedure stack, in order to execute a higher priority procedure that has a definite, celestial time deadline. The stack will be popped up upon return from my trip, so the next installment of the 6809 homebrew project can occur no sooner than the issues of BYTE published early next summer. ■

Articles Policy

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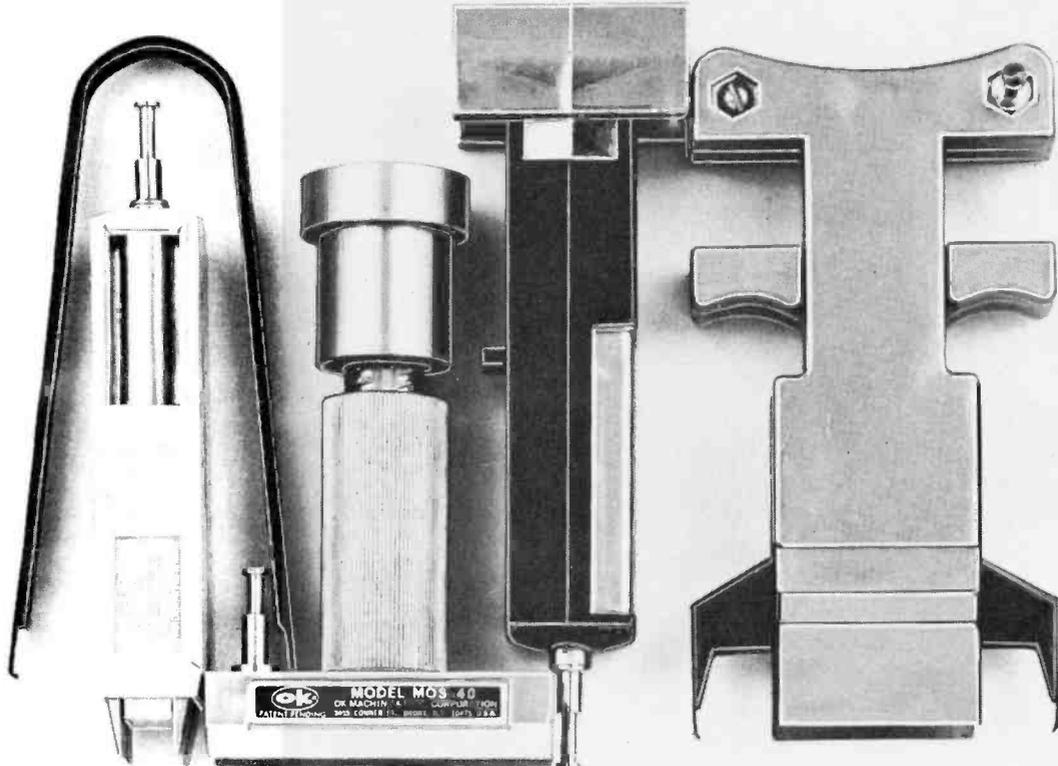


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BYTE News . . .

FRANCE TO INTRODUCE HOME TERMINALS: The French Postal and Telecommunications agency is undertaking a project to put a computer terminal in every home. According to a report that appeared in *Business Week* magazine, the government agency intends to give all telephone customers a free two-way video display terminal, in lieu of printed directories. A similar machine that can send and receive a full page of text in two minutes will also be offered for under \$500. Over 1000 terminals will be installed early next year. Each terminal is expected to cost the agency less than \$100.

IBM MOVES TO ASCII: Until now you either did it the ASCII way or the IBM way. In other words, all IBM communication was done in Extended Binary-Coded-Decimal Interchange Code (EBCDIC), while all other computer manufacturers used the American Standard Code for Information Interchange (ASCII). Anyone who has tried to interface an IBM terminal to a non-IBM system has encountered the problem.

Now IBM has introduced their first product that uses ASCII, the model 3101 video terminal. Depending on options, prices range from \$1300 to \$1520. These units can be ordered over the telephone, and IBM installation is not required, as is the case with all other IBM products. The unit, largely made in Japan, qualifies for discounts up to 20%—a new departure for IBM.

IBM has apparently been forced to compete with other computer component makers on their level. This may be the forerunner of a new IBM marketing philosophy for small-computer systems.

Rumor has it that IBM will become more aggressive in the small-computer market with enhancements to its 5110 tabletop computers. Look for IBM to increase the number of "retail stores" for small-business computer systems to 200 by the end of 1980. Most of these stores will be in branch offices of the General Systems Division.

TANDY, APPLE AND ATARI ASK FCC FOR DELAY: Atari asked the Federal Communications Commission (FCC) to delay the effective date of the waiver of rules for Texas Instruments (as previously reported in the January 1980 *BYTE News*) until a rulemaking proceeding on television-interface devices is completed. Atari cited allegedly illegal action by the FCC in granting the waiver and noted the potential increased radio and television interference. After two weeks consideration, the FCC rejected Atari's request.

Tandy Corporation and Apple Computer Company asked the FCC to delay the deadline for compliance with the FCC's new radio frequency interference (RFI) standard, which is due to go into effect on July 1, 1980. Both firms have claimed that this is too short a time to change manufacturing processes and order the necessary components.

LATEST RUMORS: Designers of Radio Shack's successor to the TRS-80 Model I have changed their minds and will employ Microsoft for writing the BASIC interpreter and operating system. Motorola also made a bid to do this software development; however, Microsoft ended up with the contract. Radio Shack had been planning to call the unit the "TRS-90," but the firm is now leaning toward "TRS-80/COLOR." . . . It is rumored that Sony and Texas Instruments have reached an agreement whereby Sony will sell Texas Instruments' personal-computer systems in the United States under the Sony name, with a Sony Trinitron color video monitor, instead of the Zenith monitor Texas Instruments is currently using. . . . Microtype Corporation will soon introduce a \$250 electronic typewriter with RS-232 input/output (I/O). It will use a daisy-wheel-like printing method, and it will print 15 characters per second. Look for it by the end of 1980. . . .

RANDOM NEWS BITS: Burroughs has introduced a 6 megabyte floppy-disk drive. It holds two disks on a common spindle and uses four data-transfer heads on a common assembly. Cost is only \$1950 in original equipment manufacturers quantities. . . . GR Electronics Ltd of Santa Monica, California, has introduced a pocket ASCII terminal in a case the size of a standard pocket calculator. It has forty keys and transmits the 128 ASCII character codes. It has an light-emitting diode display and stores thirty received characters. It has an RS-232C interface (110 or 300 bits per second), requires 5 V at 400 mA for power, and sells for \$395. . . . Hewlett-Packard (HP) has introduced its personal-computer system. The system costs \$3250 and is being manufactured at HP's Corvallis, Oregon, calculator division. See page 60 in this issue for a report. . . . Godbout Electronics, Oakland Airport, California, plans to introduce an S-100 processor circuit card that contains both 8088 and 8085 microprocessors on the same card. The 8088 is a 16-bit processor with 8-bit I/O (it executes 8086 ob-

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COBOL-80 Compiler The best implementation of the world's most widely used programming language is COBOL-80 from Microsoft. As small business applications become not-so-small, COBOL-80 is ready with powerful use of disk files, data manipulation facilities, CHAIN, segmentation and interactive ACCEPT/DISPLAY. Plus three-dimensional arrays, full COPY facility, indexed and relative files and an optional packed decimal format that saves on mass storage by as much as 40%. Comes with macro assembler and loader. Runs on CP/M, ISIS-II, and TRSDOS. \$750.

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At last, a sophisticated math package for microcomputers. muMATH performs mathematical operations efficiently and accurately. Use it to solve equations and simplify formulas; or perform exact arithmetic, symbolic integration and differentiation, infinite precision integer arithmetic and symbolic matrix inversion. muMATH is an invaluable tool for engineering and scientific applications involving lengthy, analytical computations. It is also an ingenious teaching method for all levels of math from arithmetic to calculus. muMATH is implemented in muSIMP, a highly structured language for complex symbolic manipulations. muSIMP/muMATH Package, CP/M versions: \$250.

NEW muLISP-79 LISP—the lingua franca of the artificial intelligence world—is now available in this efficient, low-cost version for microcomputers. Features include dynamic allocation of storage resources; program control structures such as an extended COND and a multiple exit LOOP; user functions defined as CALL by Value or CALL by Name; and 83 LISP functions. muLISP-79, CP/M version: \$200.

NEW XMACRO-86 For the development of 8086 programs, our new XMACRO-86 cross assembler has just been released. It supports the same features as our MACRO-80 assembler. Develop 8086 programs now on your current CP/M, ISIS-II, or TEKDOS system. \$300.

NEW Micro-SEED DBMS If you are developing applications software in-house or bundling hardware and software for resale, a database manager could be the software tool you've been looking for. Micro-SEED is the first CODASYL compatible database management system to run with CP/M; and Microsoft's FORTRAN-80 has been implemented as the host language. When an application becomes limited by traditional floppy disk file handling, but remains overpowered by the cost and maintenance of a minicomputer, the solution is Micro-SEED. \$900.

FORTRAN-80 Compiler Microsoft FORTRAN-80 is the most complete microcomputer FORTRAN available. It has all of ANSI-66 FORTRAN (except COMPLEX data), plus unique enhancements for use in the microcomputer environment. An extensive library of single and double

precision scientific functions, too. Comes with macro assembler and loader. Versions for CP/M, ISIS-II, TEKDOS. \$500.

MACRO-80 Assembler The most powerful microcomputer assembler on the market today is Microsoft's MACRO-80. It is fast, and it supports Intel-standard macros, relocation pseudo-ops, conditionals and listing controls. MACRO-80 comes with a relocatable linking loader and runs with CP/M, ISIS-II, and TEKDOS. \$200.

EDIT-80 Text Editor Random access to floppy disk files makes EDIT-80 the fastest microcomputer text editor. It's the essential tool for creating and maintaining all files. EDIT-80 includes FILCOM, a file compare utility. EDIT-80, CP/M version: \$120.

Prices quoted are USA domestic only. OEMs should contact Microsoft for prices.

MICROSOFT OS	CP/M	ISIS-II	TRSDOS	TRSDOS Md II	TEKDOS
BASIC-80 INTERPRETER	●	●			●
BASIC COMPILER	●	●		●	
FORTRAN-80 COMPILER	●	●			●
COBOL-80 COMPILER	●	●		●	
muMATH/muSIMP muLISP	●		●		
MICROSEED DBMS	●				
EDIT-80 TEXT EDITOR	●				
MACRO-80 ASSEMBLER	●	●			●

MICROSOFT

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ject code). A user can run the standard CP/M operating system on the 8085 to handle all I/O devices, and use the 8088 to run software such as a multi-user BASIC system. The processor card will drive 24 address lines (16 megabytes of memory space), and has a direct-memory-access (DMA) peripheral controller. . . .Heath Company has decided to resume production of the H8 8080-based microcomputer system. Surprisingly, the sales of the H8 have increased, despite the introduction of the Heath/Zenith H89 integrated Z80-based system. Apparently, with its plug-in bus construction, the H8 is more to the liking of hobbyists who prefer to configure their own systems. Also, Zenith is now producing the assembled Heath H19 video terminals on one of its television set production lines. . . .Mattel Electronics and General Instrument are about to start testing a television attachment that can receive a variety of video games sent over cable television. . . .McGraw-Hill, *The New York Times*, *Times-Mirror*, and *Time Magazine* are considering setting up systems which would allow personal-computer users to access their data bases.

HIGH-DENSITY 5-INCH DISK DRIVES: Micropolis Corporation and several other floppy-disk drive makers have announced 5-inch floppy-disk drives with a density of 96 tracks per inch (tpi). Forty-eight tracks per inch has been standard, while some firms have sold 77 tpi drives.

The Micropolis disk system will read older 48 tpi disks by skipping every other track under software control. The new drives will range in capacity from 436 K to 1064 K unformatted bytes and will cost between \$450 to \$570 each.

PERSONAL COMPUTER SYSTEM DELIVERIES DELAYED: Texas Instruments (TI), Mattel Electronics, and Atari have all experienced delayed deliveries of their personal computer systems in the past few months. Delays were due to a shortage of parts, which restricted production of these new systems. Atari did not start shipping units until October 1979, and TI did not start until November. Quantities were severely limited during the Christmas season. Mattel did not even start shipping until after Christmas. In all cases, the companies claimed that "silicon shortages" caused the delays. TI and Atari had promised to start deliveries in August. This problem is common throughout the computer industry, due to an unexpectedly high demand for integrated circuits.

DATA-STORAGE ADVANCES PREDICTED: A San Jose, California, market research firm has released an interesting report on the future of microcomputer storage systems. Creative Strategies International predicts that during the next two years we will see the introduction of new, low-cost 5-inch and 8-inch Winchester-technology disks, new sizes (4-inch and 6-inch) of Winchester drives, "back-end" processors (disk controller and data base manager), and on-line archives in both video-disk and cartridge-tape form.

Low-cost, 5-inch floppy-disk drives and digital cassettes are expected from Japan. They will be mass-produced for intelligent-typewriter and home-computer applications. Prices of floppy-disk and Winchester disk drives are expected to drop to less than one-third of current prices.

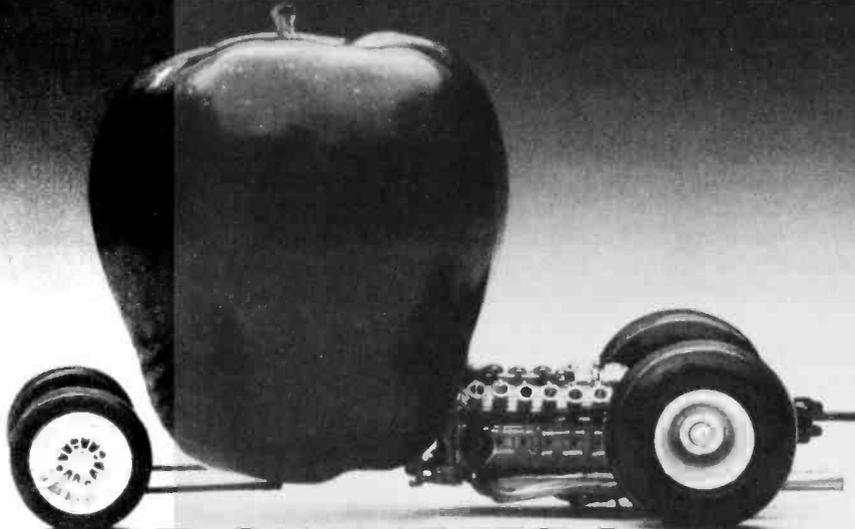
The new small Winchester disk drives, or micro-Winchesters, will have storage capacities starting at 1 megabytes and removable disk modules about the size of an 8-track audio tape cartridge. The back-end processors will be available by the mid-1980s. They will combine Winchester-disk-controller and data-base-management functions in large-scale integrated circuits, with fast parallel architecture, content-addressed memory, charge-coupled memory systems or bubble memory. On the other hand, 8-inch floppy disks should reach the 5 megabyte capacity by the mid-1980s.

BUBBLE MEMORY STATUS REPORT: Bubble memory has developed considerably during the past year. Device size has jumped from 64 K bit, serial shift-register architectures to 1 megabit major/minor-loop, block-replicate architecture. Four megabit devices, organized as 4- and 8-bit words, are expected next year. Access times have dropped from hundreds of milliseconds; under 10 milliseconds is expected by the end of 1980. Five companies, Fujitsu, Intel, Plessey, Rockwell and Texas Instruments, are now competing for a share of the developing bubble memory business. Three more companies, Hitachi, Motorola, and Siemens, are expected to enter the market this year.

SPEECH-SYNTHESIS TECHNOLOGY IMPROVING: A year and a half ago when Texas Instruments introduced its Speak & Spell toy with voice output, the experts were amazed at its voice quality and low cost. Now single-board synthesizers, which can be easily interfaced to computers, are available from Texas Instruments, the Votrax Division of Federal Screw Works in Troy, Michigan, and Telesensory Systems Inc (TSI) of Palo Alto, California (TSI specializes in products for aiding the blind). Even IBM has added voice output to a typewriter. Further, Texas Instruments has now made available a low-cost voice synthesizer chip set for use by game and appliance manufacturers.

The Texas Instrument synthesizer stores words in its memory and thus is limited to 180 standard words, plus up to 180 words stored in external read-only memory. On the other hand, the Votrax unit is programmed with 62 phonemes (sound units) and can form an unlimited number of words.

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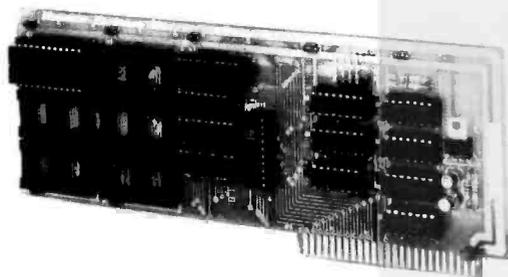
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The voice quality of present units is acceptable but still leaves much to be desired. Most listeners agree that the Texas Instruments' unit produces better quality voices. There is no doubt that next year we will see a larger number of devices and appliances with voice output on the market, some possibly with voice input.

ANALOG MEMORY DEVELOPED: Sanyo Electric Company of Tokyo, Japan, recently reported at a Institute of Electrical and Electronics Engineers conference that it has developed a nonvolatile analog memory. The memory permits the direct storage of analog signals, eliminating the current technique of digitizing the analog signal and storing it in binary form. Analog memory could greatly simplify the circuitry used in voice and music synthesizer equipment, as well as in such applications as television tuning.

TANDY TO ENTER DISK DRIVE BUSINESS: Tandy Corporation has agreed to form a joint floppy-disk manufacturing venture with Datapoint Corporation. Final approval is still pending from the boards of directors of both companies. Tandy currently buys floppy-disk drives for its Radio Shack computers from Shugart Associates, Control Data, and Tandon Magnetics. Datapoint makes their own units under a license from Shugart. Last year, Tandy attempted to purchase Perkins Elmer's Orbis floppy-disk operation for \$2.2 million, but was outbid (\$2.5 million) by Siemens.

DUAL-SIDED FLOPPY-DISK AVAILABILITY IMPROVES: In 1977, floppy-disk manufacturers started showing prototypes of their dual-sided floppy-disk drives. Shipments started in early 1979, but the firms soon ran into production problems. The double-sided drives caused excessive wear on disks and had other reliability problems. Manufacturers now have apparently learned how to manufacture these drives reliably and are finally getting into quantity production.

Last year a total of nearly 250,000 8-inch drives and 500,000 5-inch drives were made. It is expected that well over 1 million 5-inch drives will be made this year, and that nearly 30% will be double-sided.

RADIO SHACK TAKES ACTION TO PROTECT TRS-80 TRADEMARK: At the opening of a recent microcomputer show in Boston, federal court injunctions were served to three exhibitors, ordering them to immediately stop selling or distributing anything with the characters "TRS-80" written on it, and to hand over all such items and literature to Tandy-Radio Shack for disposal. Further, Radio Shack demanded \$10,000 for damage done to Radio Shack by each of the three companies.

Radio Shack claimed the companies were using the TRS-80 trademark illegally and in such a manner that people would think they were buying Radio Shack products. Further, Radio Shack claimed that business was being stolen from them, and that should the products prove defective, Radio Shack's reputation would be damaged.

The exhibitors had no prior warning of the injunction. Two of the exhibitors immediately appealed the injunction, pointing out that Radio Shack was clearly credited as the trademark owner in all advertising; the injunction was rescinded. The third exhibitor, who failed to take immediate legal action, was prevented from selling his regular merchandise at the show; instead he substituted a line of goods contained in packages not bearing the legend "TRS-80."

16-BIT MICROPROCESSOR STATUS REPORT: Intel has been producing its 8086 16-bit processor in volume since the spring of 1979. The 8086 has been successful but it is generally considered to be a less powerful device than either the Zilog Z8000 or Motorola 68000. While Zilog has been providing samples of the Z8000 for over six months, the firm is only now beginning volume production. Reportedly the samples did not execute all instructions correctly. Motorola has been sampling the 68000 for several months, and production quantities are expected soon. Recipients of sample devices from Motorola have reported that some instructions do not execute correctly and that the device will not operate at maximum rated speed. The companies are aware of these problems, and actual production units are expected to operate properly.

Other problems slowing the adoption of the Zilog and Motorola processors are lack of availability of peripheral devices (such as the Zilog memory-management integrated circuit), lack of software, and the fact that second-source suppliers are still far from production.

MAIL NOTE: I receive a lot of mail each month, as a result of this column. If you write to me and wish a response, enclose a self-addressed, stamped envelope.

Sol Libes
Amateur Computer Group of New Jersey
(ACG - NJ)
1776 Raritan Rd
Scotch Plains NJ 07076

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March 1980

Do divers and gymnasts violate the law?

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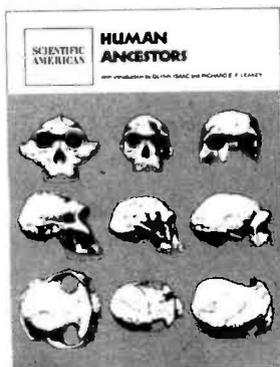
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We are accustomed to seeing divers and gymnasts begin to twist and somersault long after they have left the springboard or the floor. Indeed, in order to win gold medals divers need to perform such complex feats in midair as the forward two-and-a-half somersault with two twists. But, you may ask, doesn't this violate the law of conservation of angular momentum? It postulates: *In the absence of torques, or rotational forces, the angular momentum of a body is conserved.* In the March SCIENTIFIC AMERICAN you will see how this paradox is resolved. You may be relieved to learn that divers and gymnasts (and free-falling cats, too) perform their midair rotations without violating any laws of physics. Moreover, the underlying

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Electronic Planimetry

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Gregory Hansen
Medical Research East
University of Minnesota
2630 University Ave SE
Minneapolis MN 55414

A planimeter is an instrument (formerly mechanical) for measuring the area of a two-dimensional figure by tracing its perimeter. Area measurements obtained from planimeters are useful for a variety of applications, such as cartography, geology, metallurgy and biology. Our biomedical application requires area and length measurements of irregularly shaped two-dimensional figures. To this end an *electronic planimeter* has been designed consisting of a Summagraphics Bit Pad and a Terak microcomputer programmed in UCSD Pascal (Version I.5).

In practice, a user specifies a scale factor and then traces the boundary line of a figure using either a stylus or a single-button cursor. To improve the accuracy of the area measurement, the program detects closure (ie: when the end of the tracing meets the beginning) and displays the calculations. You can trace additional figures with the same scale by using only the stylus or cursor switch. Using this electronic planimeter, area and perimeter length measurements are more accurate and can be obtained faster than with a mechanical planimeter.

The Terak Microcomputer

The Terak 8510 (see photo 1) is a

completely self-contained, 16-bit microcomputer using a Digital Equipment Corporation (DEC) LSI-11 with the hardware floating-point option. The Terak contains 56 K bytes of memory, a single 8-inch floppy disk drive, 128-character ASCII keyboard, 12-inch video monitor with a 320-by-240 graphics dot matrix, a 24-line-by-80-character display, and an RS-232C and 20 mA serial interface. The cabinet also houses an additional serial or 16-bit parallel interface card. The Terak is supported by the DEC RT-11 operating system and UCSD Pascal.

The Terak is well suited for UCSD Pascal, which can be purchased for a reasonable price. The Terak is a conservative, but well-designed system which performs with a high degree of reliability. It serves as a general-purpose laboratory computer and in this application as a host computer for the Summagraphics Bit Pad digitizer.

The Summagraphics Bit Pad

The Bit Pad includes a digitizing surface or data tablet, control unit, power supply, and writing stylus or a single-button cursor. The control unit consists of an 8-bit microcomputer (Intel 8035), a control program in erasable, programmable read-only

memory, and binary counters. The control unit generates X and Y coordinate points of the location of the stylus or cursor as it travels across the tablet surface. These coordinate points are generated as serial or parallel data and can be used by a host computer for a variety of applications.

Theory of Operation

The Bit Pad operates on a magnetic principle. Current is pulsed along a *send* wire that lies perpendicular to a mesh of magnetostrictive wires lying beneath the writing surface of the tablet. The current pulse changes the dimensions of the magnetostrictive material and a strain wave simultaneously propagates down all the wires in one direction. This propagated strain wave is sensed by a *receive* coil in the stylus or cursor. The control unit times the delay

Terak is a registered trademark of Terak Corporation.

RT-11 and LSI-11 are registered trademarks of Digital Equipment Corporation.

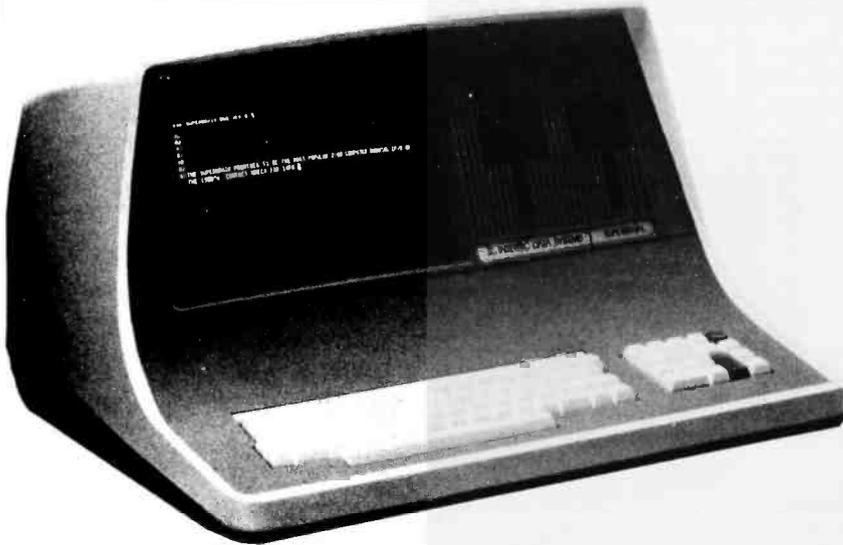
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System Specifications

CPU	
Microprocessors	Twin Z80A's with 4MHz Clock Frequency. One Z80A (the host processor) performs all processor and screen related functions. The second Z80A is "down-loaded" by the host to execute disk I/O. When not processing disk data, the second Z80 may be programmed by the host for other processor related functions.
Word Size	8 bits
Execution Time	1.0 microseconds register to register
Machine Instructions	158
Interrupt Mode	All interrupts are vectored.
Floppy Disk	
Storage Capacity	285K total bytes formatted on two double density drives. Optional external 10-300 megabyte hard disk storage is available using optional S-100 bus adaptor.
Data Transfer Rate	250K bits/second
Average Access Time	250 milliseconds, 35 milliseconds track-to-track
Media	5 1/4 inch mini-disk
Disk Rotation	300 RPM
Internal Memory	
Dynamic RAM	64K bytes dynamic RAM.
Static RAM	256 bytes of static RAM is provided in addition to the main processor RAM. This memory is used for program and/or data storage for the auxiliary processor.
ROM Storage	1K bytes standard. Allows ROM "bootstrapping" of system at power-on. ROM storage is 2708 compatible and may be reprogrammed by the user for custom applications.
CRT	
Display Size	12-inch, dynamically focused, P4 phosphor
Display Format	25 lines x 80 characters per line.
Character Font	8 x 8 character matrix on a 8 x 12 character field
Line Drawing Characters	Eleven special graphics symbols used for form generation.
Display Presentation	Light characters on a dark background. Reversible through keyboard/program selection.
Bandwidth	20 MHz.
Cursor	Reversed image (block cursor)
Communications	
Screen Data Transfer	Memory-mapped at 38 kilobaud. Serial transmission of data at rates up to 9600 bps.
Auxiliary Interface	Universal RS-232 asynchronous. Synchronous interface optional.
Parallel Interface	Radio Shack TRS-80 compatible.
S-100 Bus	Printed circuit edge connector provided for connection of optional S-100 bus adaptor.
Transparent Mode	Enables display of all incoming and outgoing control codes.
Parity	Choice of even, odd, marking, or spacing.
Transmission Mode	Half or Full Duplex. One or two stop bits.
Addressable Cursor	Direct positioning by either discrete or absolute addressing.
System Utilities	
Disk Operating System	CP/M
DOS Software	An 8080 disk assembler, debugger, text editor and file handling utilities.
Optional Software	
FORTRAN	ANSI standard. Relocatable, random and sequential disk access.
COBOL	ANSI standard. Relocatable, sequential, relative and indexed disk access.
BASIC	Sequential and random disk access. Full string manipulation, interpreter.
Application Packages	Extensive software development tools are available including software for the following applications: Payroll, Accounts Receivable, Accounts Payable, Inventory Control, General Ledger and Word Processing.
Keyboard	
Alphanumeric Character	Generates all 128 upper and lower case ASCII characters.
Special Features	N-Key Rollover, Automatic repeat (at 15 CPS), Keyboard lock/unlock.
Numeric Pad	0-9, decimal point, comma, minus and four user-programmable function keys.
Special Functions Keys	Up to 64 user-defined two-key function sequences.
Cursor Control	Up, down, forward, backward, and home.
Internal Construction	
Cabinetry	Structural foam.
Component Layout	Two board modular design. All processor related functions and hardware are on a single printed circuit board. All video and power related circuits on a separate single board. These two boards are interconnected via a single 22-pin ribbon cable.
Mounting	CRT and two circuit boards mounted to base. CRT in a rigid steel frame. Disk Drive assembly mounted into upper cover for ease of servicing.
Environment	
Weight	Approximately 45 pounds
Physical Dimensions	14 1/2" (H) x 21 1/2" (W) x 23 1/2" (D)
Environment	Operating: 0° to 50° C Storage: 0° to 85° C, 10 to 95% rel. humidity - non condensing.
Power Requirements	115 VAC, 60 HZ, 1 AMP (optional 230VAC/50HZ model available)
	*Specifications subject to change without notice.

SuperBrain users get exceptional performance for just a fraction of what they'd expect to pay. Standard system features include: two double density mini-floppies with 285 K bytes of disk storage, 64K of RAM memory to handle even the most sophisticated programs, a CP/M Disk Operating System with a high powered text editor, assembler, debugger and a disk formator. And, with SuperBrain's S-100 bus adaptor, you can add all the programming power you will ever need . . . even a 10 megabyte disk!

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Photo 1: The Terak microcomputer with dual floppy-disk drive, video display, and keyboard. The Summagraphics Bit Pad consists of the digitizing tablet and the microcomputer control unit.

required for the strain wave to reach the receive coil, and this delay is used to calculate X and Y coordinate data.

Digitizing Tablet

The data tablet is a low-profile, plastic pad that has an active surface area of approximately 784 square centimeters. The X,Y origin is located in the lower left corner of the tablet and is not relocatable. The active surface area can be visualized as a square matrix of 2795 by 2795 points with a resolution of 0.1 mm. The Bit Pad can also be configured for English unit measurements.

Microcomputer Control Unit

The control unit contains six front-panel, push-button switches (see photo 1). One is a reset switch, three switches control the digitizing rate, and two switches control the operating mode. These switches may be overridden by software from the host processor, thus allowing complete

host control.

The three rate switches select 64, 32, 16, 8, 4, 2, or 1 coordinate pairs to be generated per second. The two mode switches select point, switch-stream, or stream operating mode.

A coordinate pair is generated for each depression of the Z-axis switch in the stylus or cursor in the *point* mode. In the *switch-stream* mode, coordinate pairs are generated continuously as long as the Z-axis switch remains depressed. Coordinate points are generated continuously in the *stream* mode. It should be noted that no points are generated unless the stylus or cursor is within 4 mm of the active surface area of the tablet.

The control unit also contains an 8-bit input and output (I/O) port, an interrupt line, a single-bit reset line, and optionally a TTL or RS-232C serial line. The input port (also referred to as the command byte, figure 1) allows for control of both the operating mode and transmission rate of

the Bit Pad by a host processor. Three bits are allocated for the transmission rate, two bits for the operating mode and three bits serve as hand-shaking signals between the host processor and the Bit Pad.

The three handshaking bits are: *status valid*, which is used by the host computer to signal a change in mode or rate; *byte received*, which indicates that a byte of data has been read by the host; and *next byte*, which is used by the host to request the next byte of data from the Bit Pad. An additional single-bit line (*in strobe*) enables the host to reset the Bit Pad's control unit.

A host processor can receive data from the Bit Pad by polling or handshaking, or the Bit Pad interface can be driven by interrupts. The output port of the Bit Pad provides coordinate points to the host processor in a sequence of five data bytes (see figure 2). A 1 in the most significant bit of the first byte signals the host

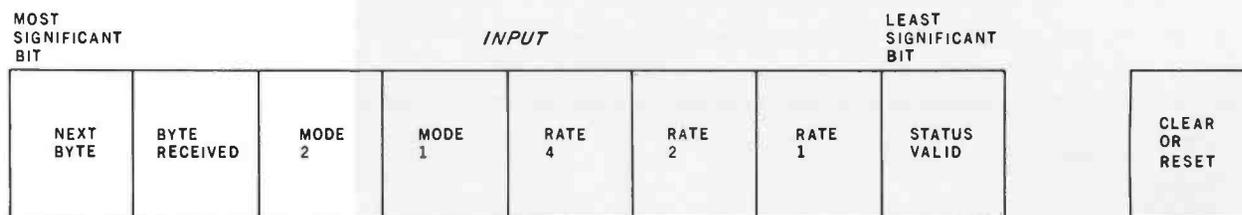


Figure 1: The bit format of the input or command byte for the Bit Pad. In addition, a single line is used by the host computer to reset or clear the Bit Pad's electronic circuitry.

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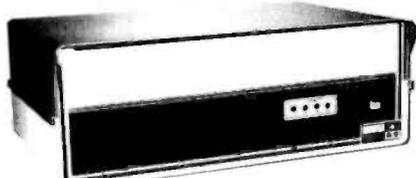
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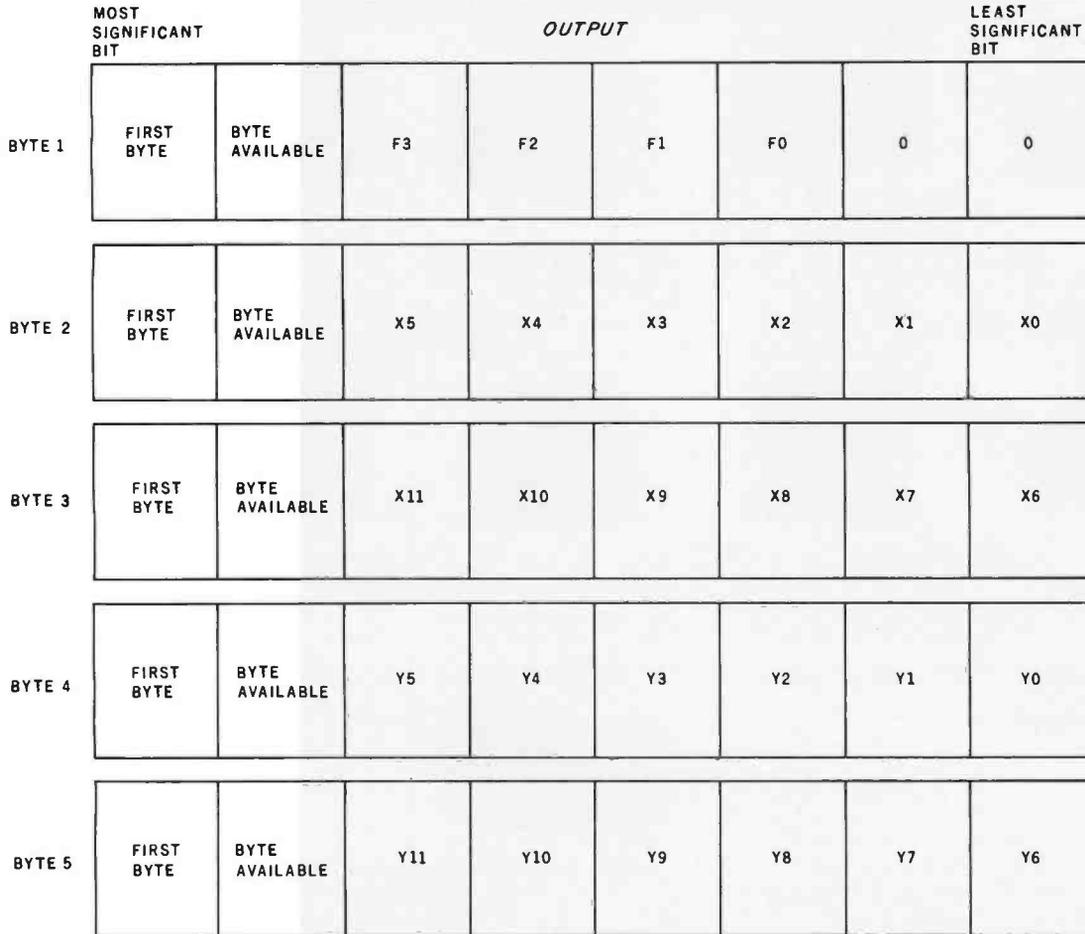


Figure 2: Five bytes of data are transmitted from the Bit Pad's output port for each coordinate pair of points generated. The first byte contains information concerning depression of the Z-axis switch. The next four bytes contain a 12-bit representation of the X and Y coordinates. Each byte also contains two control bits, which are used for handshaking purposes.

that the current byte is the first of the five-byte sequence. The next bit (*byte available*) when set to 1 indicates that a byte of data is available, and the bit labeled F0 corresponds to the status of the Z-axis switch.

An optional four-button cursor may also be used. The four buttons correspond to bits F0 thru F3 in byte 1. The next four bytes in the sequence contain a 12-bit representation of the X and Y coordinates. This data can also be transmitted in serial format with parity and stop bits, at data transmission rates from 37.5 bps to 28,000 bps.

The control unit does not contain a pilot light; however, it does contain two diagnostic routines that can be used to check its circuits and interface connections to the host processor. The control unit requires power sup-

plies of +5 V and +12 V, and -12 V or, with optional regulators, +8 V, +16 V, and -16 V.

Pascal Program: PLANIMETER

This program, which appears in listing 1, receives coordinates points five bytes at a time from the Bit Pad. The line length and area of a closed two-dimensional figure are calculated by integrating the figure with trapezoids. By using Pascal and the Terak, it is possible to receive and process approximately thirty coordinate points per second.

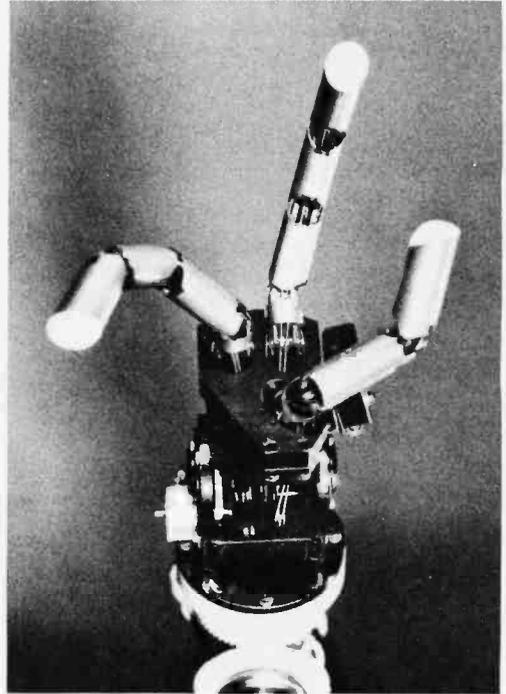
User-defined data types are used to interface the Bit Pad to the Terak minicomputer. LOWBYTE is the image of the output from the Bit Pad. It contains three fields: the data (D), READY (*byte available*) and the FIRST-byte bits. DEVICE is a data-

type that represents the I/O buffers on the Terak's port which are connected to the Bit Pad.

At the beginning of the main program, the pointer BITPAD is set to the integer value -160 (which is the address of the port) using a variant record type. The pointer BITPAD.P points to the port, and BITPAD.P1 contains the Terak I/O buffers for the parallel port.

Each input byte is read as LOOKB := BITPAD.P1.INBUF in the procedure NEXTBYTE using handshaking. The sequence begins by waiting for the next byte to be ready (LOOKB.READY is true). The Terak signals the Bit Pad that it has read the data by sending the command byte OUTRECEIVED. The program increments the counter (BYT), waits for the Bit Pad to clear and then signals

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```

PROGRAM PLANIMETER;
(* Written by: John Fryhofer

and modified by Greg Hansen.

This program reads parallel data from a digitizing tablet and calculates
the area and perimeter of a closed figure traced on it *)

CONST
  PORTADDR = -160;
  OUTRECEIVED = 95 (* 01011111 *);
  OUTNEXT = 159(* 10011111 *);
  MINPTS = 13;

TYPE
  (* Output from BIT PAD *)
  LOWRYTE = PACKED RECORD
    D : 0..63;
    READY : BOOLEAN;
    FIRST : BOOLEAN;
  END;
  (* this is what the device looks like *)
  DEVICE = PACKED RECORD
    CSR : PACKED ARRAY [0..15] OF BOOLEAN;
    OUTBUF : INTEGER;
    INBUF : LOWRYTE;
  END;

VAR
  BITPAD : RECORD (* Loads the device address as an integer and
    points to it *)
    CASE BOOLEAN OF
      FALSE : (P : ↑DEVICE);
      TRUE : (I : INTEGER);
    END;

  CALCDELTA, CLOSEDELTA, BYT, P : INTEGER;
  LOOKB: LOWRYTE;
  RESPON: CHAR;
  START, (* Start new figure *)
  DIDPRINT: (* Already printed for button up *)
    BOOLEAN;
  FIRSTX, FIRSTY, LASTX, LASTY, X, Y,
    AREA, LEN, CUMAREA, CUMLEN, MAGR: REAL;
  N: PACKED ARRAY [0..1] OF CHAR; (* Dummy array; N[0] holds command *)
  PTR : INTERACTIVE;

PROCEDURE NEXTBYTE;
VAR W: LOWRYTE;
BEGIN
  (* Reads next byte from BIT PAD *)
  REPEAT
    IF NOT UNITBUSY(2) THEN UNITREAD(2, N[0], 1, 1); (* Look for command *)
    LOOKB := BITPAD.P↑.INBUF;
  UNTIL LOOKB.READY OR (N[0] = 'Q'); (* Good data *)
  BITPAD.P↑.OUTBUF := OUTRECEIVED;

  IF LOOKB.FIRST THEN BYT := 0;
  BYT := BYT + 1;

  REPEAT
    W := BITPAD.P↑.INBUF;
  UNTIL NOT W.READY; (* BIT PAD reset *)
  BITPAD.P↑.OUTBUF := OUTNEXT; (* BIT PAD sends next byte *)
END (* NEXTBYTE *);

PROCEDURE REBUGO;
(* used for debussing only *)
BEGIN
  WRITE(LOOKB.D);
  IF LOOKB.READY THEN WRITE(' READY');
  IF LOOKB.FIRST THEN WRITE(' FIRST');
  WRITELN;
END;

PROCEDURE PRINT;
(* Print results *)
BEGIN
  WRITELN ('# Points :', P:5, ' / Area :', SQR(MAGR)*ABS(CUMAREA):9:6,
    ' sq mm / Length :', MAGR*CUMLEN:9:6, ' mm');
  IF (N[0] = 'P') AND (P <> 0) THEN
    WRITE (PTR, '# Points :', P:5, ' / Area :', SQR(MAGR)*ABS(CUMAREA):9:6,
      ' sq mm / Length :', MAGR*CUMLEN:9:6, ' mm', CHR(10));
END; (* PRINT *);

PROCEDURE NEWFIGURE;
(* initialize *)
BEGIN
  START := FALSE;
  FIRSTX := X;
  FIRSTY := Y;
  LASTX := X;
  LASTY := Y;
  P := 0;
  CUMAREA := 0;
  CUMLEN := 0;
  WRITE ('*DOWN', CHR(7));

```

Listing 1 continued on page 122

Listing 1: Pascal program that uses input from the Summagraphics Bit Pad and determines the area perimeter of a traced figure.

the Bit Pad with OUTNEXT that the next byte is ready to be received.

The first loop in the main program waits for the depression of the cursor Z-axis switch ("button down" in the listing). The loop also synchronizes the program with the five data bytes from the Bit Pad. Only the first byte of the five-byte sequence contains a 1 in bit 7 (FIRST is TRUE), and a 1 in bit 2 (D = 4) when the switch is depressed. Bit 6 is set to 1 (READY is TRUE) by the Bit Pad when the byte is available. When the switch is released the results are displayed using the procedure PRINT.

The second loop is executed for each point when the switch is depressed and coordinates are being received. Bits 0 thru 5 (D) of input bytes 2 and 3 contain the 12-bit X coordinate and D in bytes 4 and 5 contain the Y coordinate. After each byte is fetched, the CASE-statement code transfers the data into the integers X and Y by adding up the values. When the final byte is taken, it may then start a new figure if the switch was just pushed, calculate the next point, and/or detect closure and print the results.

The procedure CALC is called after each X,Y coordinate input that is located at a distance at least CALCDELTA away from the last point. X and Y are the integer coordinates in units of the Bit Pad's increments, which are 0.1 mm from the tablet's origin (lower left corner). The maximum value possible for X and Y is 2795. The length is calculated with the formula for the distance (d) between two points:

$$(d) = \sqrt{(X1 - X0)^2 + (Y1 - Y0)^2}$$

where X1 and Y1 are the current coordinates and X0 and Y0 are the last coordinates. Since many points are processed, the length of an irregular line is calculated from a number of short straight lines that yield a good approximation of the true line length.

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program the number and spacing of your labels. With more features than can be described here, this high-powered program sells for \$125.00.

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Listing 1 continued:

```

END; (*NEWFIGURE*)

PROCEDURE CALC;
BEGIN
    P:= P + 1;
    AREA:= (X - LASTX) * (Y + LASTY) / 2 / 100;
    LEN:= SQRT(SQR(LASTX-X) + SQR(LASTY-Y)) / 10;
    CUMAREA:= CUMAREA + AREA;
    CUMLEN:= CUMLEN + LEN;
    IF KCOJ = 'A' THEN (* Print each point *)
        PRINT;
    LASTX:= X; (* Save this point *)
    LASTY:= Y
END; (* CALC *)

PROCEDURE CLOSURE;
BEGIN
    (* back at first point: finish *)
    CUMAREA:= CUMAREA + (FIRSTX - LASTX)*(FIRSTY + LASTY) / 2 / 100;
    CUMLEN:= CUMLEN + SQRT(SQR(LASTX-FIRSTX) + SQR(LASTY-FIRSTY)) / 10;
    Writeln ('*CLOSURE', CHR(7));
    PRINT;
    DIDPRINT:= TRUE;
    START := TRUE;
END;

BEGIN (* MAIN *)
    REWRITE(PTR,'REMOTE:');
    BITPAD.I := PORTADDR;
    BITPAD.Pt.OUTBUF := OUTNEXT;
    Writeln(' LENGTH AND AREA MEASUREMENTS');
    Writeln;
    Writeln('Please leave all the switches out. The program sets the BIT PAD to');
    Writeln(' stream mode and full speed. ');
    Writeln;
    Writeln('Type a "Q" at any time to change magnification or quit. ');
    Writeln(' "A" to see all the points displayed ( with speed degradation ) ');
    Writeln(' "P" to turn on the printer. ');
    Writeln(' and press a space to turn off the modes. ');
    REPEAT
        KCOJ := ' ';
        Writeln;
        WRITE('CALCDELTA: ');
        READLN(CALCDELTA);
        WRITE('CLOSEDELTA: ');
        READLN(CLOSEDELTA);
        WRITE('MAGNIFICATION FACTOR? ');
        READLN(MAGR);
        Writeln('READY. FACTOR = ', MAGR :9:7);
        START := TRUE;
        DIDPRINT := TRUE;

        WHILE KCOJ <> 'Q' DO
            BEGIN
                (* Loop for each point *)

                REPEAT
                    (* Wait for button down *)
                    NEXTBYTE;
                    IF (BYT = 1) AND (LOOKB.D <> 4) AND NOT DIDPRINT THEN
                        BEGIN
                            (* If first point and button up *)
                            Writeln('*UP', CHR(7));
                            PRINT;
                            DIDPRINT:= TRUE;
                            START := TRUE
                        END
                    (* If first point and button up *)
                UNTIL (BYT = 1) AND (LOOKB.D = 4) OR (KCOJ = 'Q');
                (* Button is down *)
                WHILE (BYT < 5) AND (KCOJ <> 'Q') DO
                    BEGIN (* Get whole point *)
                        NEXTBYTE;
                        DIDPRINT:= FALSE;
                        CASE BYT OF
                            2: X := LOOKB.D;
                            3: X := X + 64*LOOKB.D;
                            4: Y := LOOKB.D;
                            5: BEGIN
                                    Y := Y + 64*LOOKB.D;
                                    IF START THEN
                                        NEWFIGURE
                                    ELSE IF (ABS(X - LASTX) > CALCDELTA) OR
                                        (ABS(Y - LASTY) > CALCDELTA) THEN
                                        CALC; (* Only take points far enough away *)
                                    IF (ABS(X-FIRSTX) < CLOSEDELTA) AND
                                        (ABS(Y-FIRSTY) < CLOSEDELTA) AND (P > MINPTS) THEN
                                        CLOSURE; (* Back at first point +/- DELTA *)
                                END; (* 5: *)
                            END; (* CASE *)
                        END; (* Get whole point *)

                    END; (* Next point *)
                    WRITE('ANOTHER MEASUREMENT? ');
                    READ(RESPONS);
                    UNTIL RESPONS = 'N';
                END.
            END.

```

Area Calculation

Area is calculated by integration, by dividing the figure being traced into trapezoids. The trapezoids are calculated with the X axis as the base and up to the present and last points as the top. This formula is calculated for each new point:

$$\text{Area} = [(X1 - X0) \times (Y1 + Y0)] / 2.$$

When the current point is within a distance equal to CLOSEDELTA of the first point, closure is detected. This is done in order to achieve the lowest possible error by ending the figure where it started (ie: within 0.3 mm of the beginning of the trace). When closure is detected, final calculations are made to close the figure. The results are printed, and START is set so it will clear the variables the next time around for a new figure.

CALCDELTA is used to correct for oscillation of the coordinates due to the analog-to-digital (A/D) conversion, which results in inaccurately measured line lengths. If CALCDELTA is too small, then oscillation between points causes many coordinates to be inappropriately summed resulting in an overestimation of the true length of the traced figure. If CALCDELTA is too large, not enough points will be fitted, resulting in a less accurate approximation. Good results have been obtained with CALCDELTA = 3 (that is, 0.3 mm).

Conclusion

This electronic planimeter has been used for thousands of measurements in a laboratory environment. It is faster to use and more accurate than a mechanical planimeter. The relative error between twenty repeated area-tracings of several different figures was consistently less than 0.5%. This electronic planimeter is less expensive and more flexible than commercially available dedicated-microprocessor systems that are specifically designed for planimetry, such as the Leitz Image Analysis System and the Zeiss MOP-3. A microcomputer or mini-computer user whose application involves length and area calculations of irregularly shaped figures will find this system useful and relatively inexpensive to construct. ■

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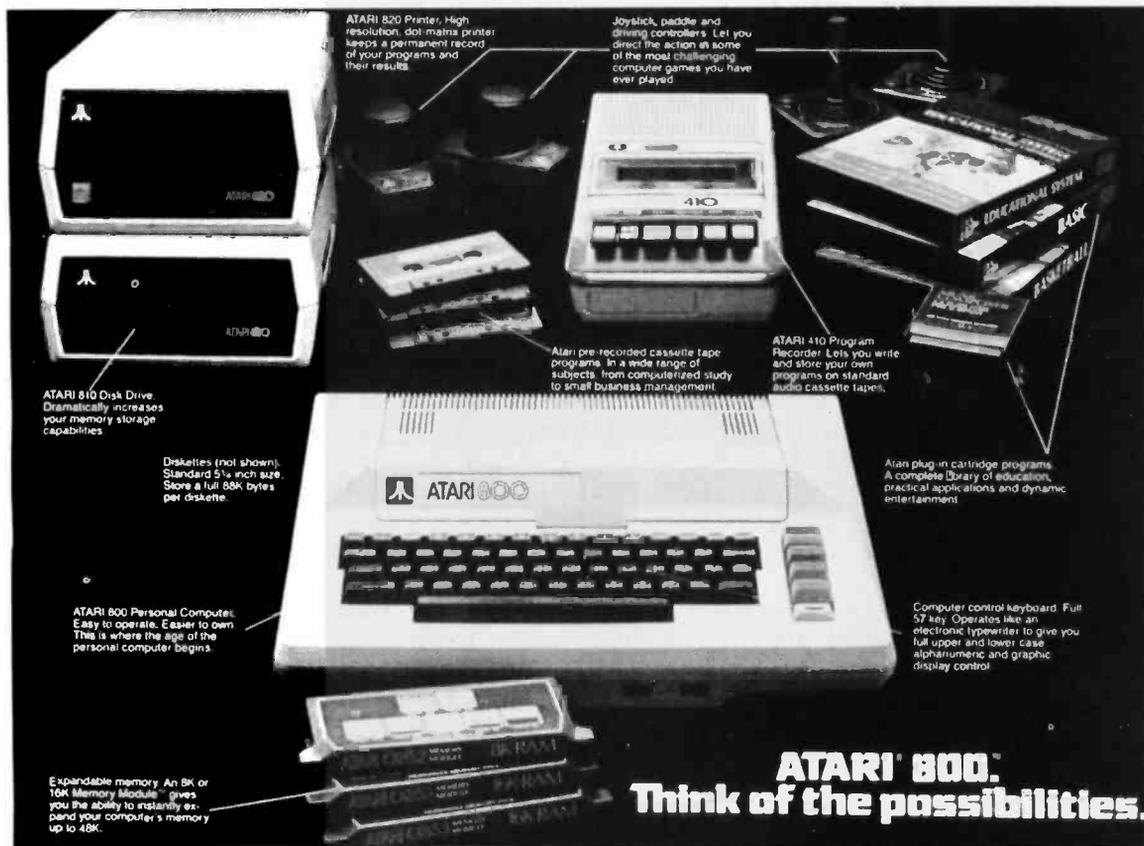
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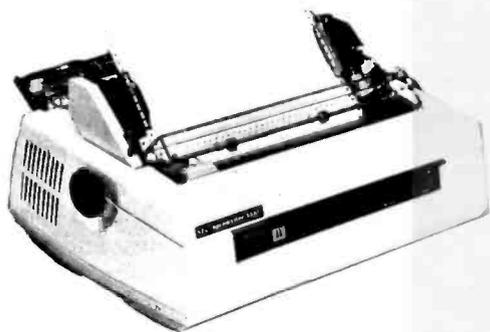
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A Power-Line Protection Circuit

Neil A Schneider
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Several years ago while he was working with color organ circuits, a friend of mine connected a color organ to an All American Five radio receiver. For those of you who are too young to remember, the All American Five was a popular five-tube radio design containing no power transformer. To my friend's surprise, and fortunately not to his harm, the connection of his color

organ to this radio resulted in foot-high flames as the audio output transformer burned.

The radio receiver had a "hot" internal chassis which was isolated from the outside world by its plastic case. The power cord was not polarized to connect the chassis to the low side of the AC power line. As my friend made his connection, he placed the 117 VAC power line current across the 8 ohm impedance audio-output secondary winding of the transformer, and across the speaker. This resulted in flames and a destroyed radio receiver.

Home computer enthusiasts of

today face the same problem. While my friend's error only resulted in the loss of a radio (about \$15), the connection of computer circuits to transformerless hot-chassis television sets can result in the loss of hundreds of dollars in digital circuits.

The obvious solution is to use three-wire power cords on all equipment to insure that the television chassis is at *earth ground*. This solution works fine as long as no wiring errors have been made in the AC power socket. If you transport your computer to a friend's house, you are again betting the hundreds of dollars, and maybe your life, on the accuracy of *his* electrical system.

The circuit shown in figure 1 is a better solution. This circuit is less expensive than an isolation transformer, and it can even incorporate a power-line fault indicator. The circuit simply detects ground-fault conditions. The 117 VAC relay connects between the cold-side power and earth-ground lines.

If a wiring error has been made, and the cold terminal is hot with respect to earth ground, the relay closes to *reverse* the power connection to the television. A neon lamp wired across the relay will provide a line-fault indication. **CAUTION!** No protection is provided with this circuit if the earth-ground line is defeated.

All that is required to provide full power-line protection is the addition of a double-pole, double-throw on/off switch as shown in figure 2. This switch is used to present reversible power to the relay. When the AC line is switched to the proper connection, the relay activates, and applies power to the load. If any attempt is made to defeat the earth ground, the circuit will not function, and the load will not receive power.

The result is a circuit that is, for most applications, less expensive and physically smaller than an isolation transformer. This relay circuit should fit inside almost any television set that you wish to modify for your video terminal. It may protect you and your equipment from a fatal mistake. ■

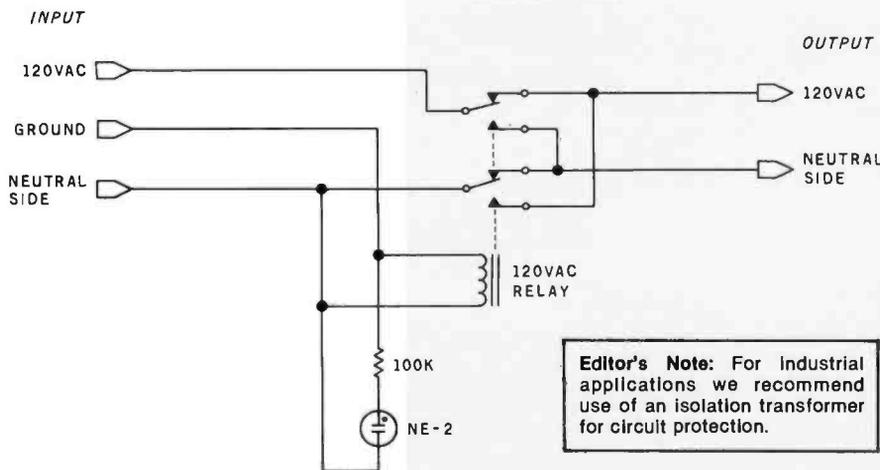


Figure 1: A simple circuit that offers some protection by using a relay to reverse connections to the power line. However, no protection is provided if the earth-ground line is defeated.

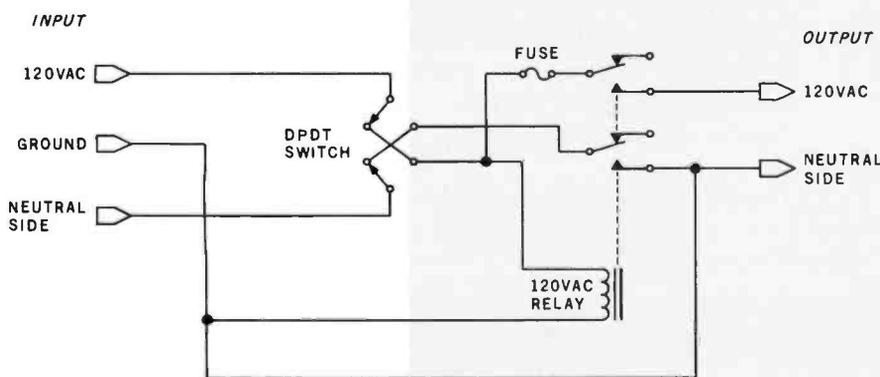
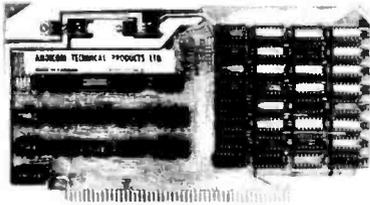


Figure 2: A better circuit that uses a double-pole, double-throw switch to present reversible power to the relay. If an attempt is made to defeat the earth ground, the power is cut off.

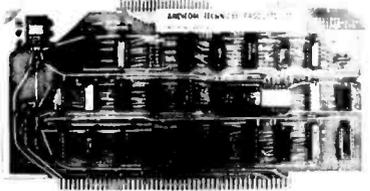
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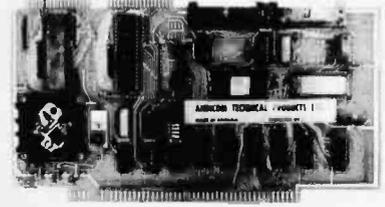
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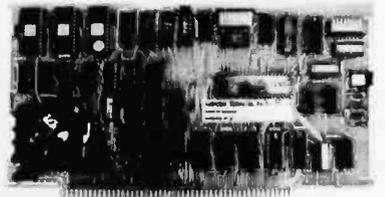
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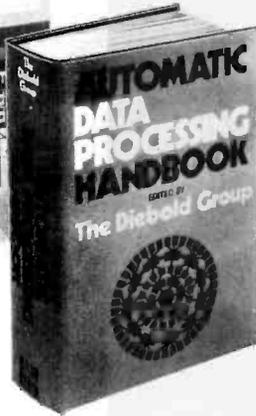
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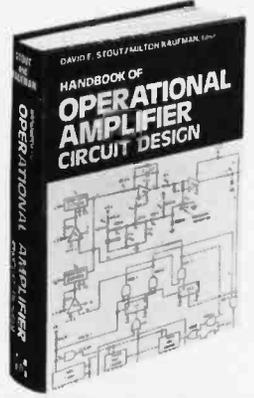
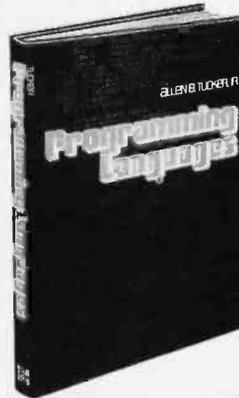


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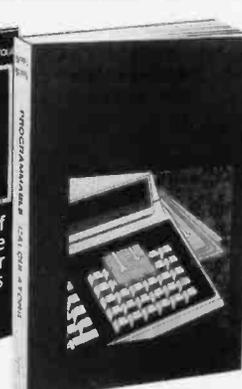
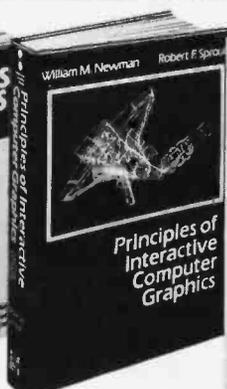
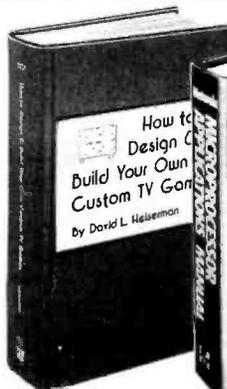
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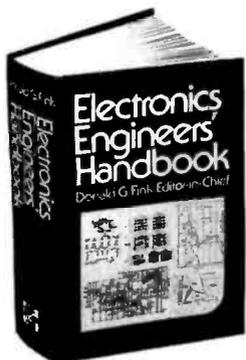
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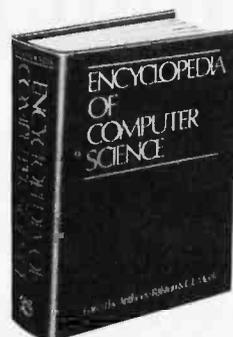
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Spokane WA 99218

This article describes a program that simulates the landing of a jet-propelled craft on a random surface. The surface is generated by a random-number generator. As seen in photo 1, the craft can be steered vertically or horizontally by the firing of the main jet, the side jets, or

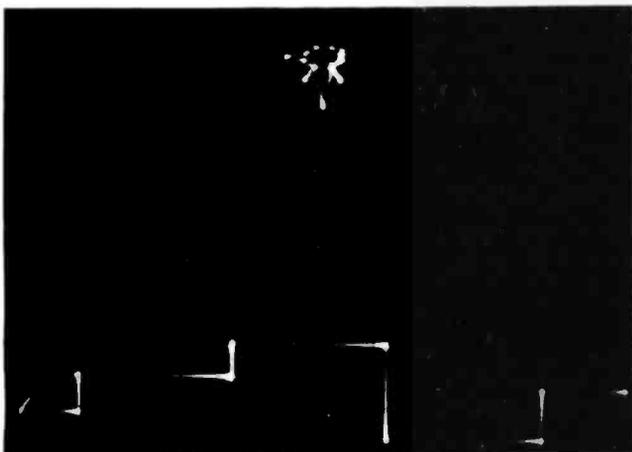


Photo 1: Landing module hovering over the five-segment random surface as it cautiously approaches its landing site.

both of them. During the dynamic simulation, the craft will move vertically along the central vertical line of the oscilloscope. The horizontal movement of the random surface causes the craft to appear to move in the opposite direction.

The sequence of the simulation is as follows:

- The dynamic equations of the craft are solved by Euler's method. The solutions are velocity and displacement.
- The craft is displayed according to the vertical

displacement, and the jets are made visible when they are fired.

- The random surface is displayed relative to the horizontal displacement of the craft. There are 256 segments of random surface which form a continuous terrain. Only five surface segments are shown on the oscilloscope at one time.
- When the craft has touched down on the surface, the vertical and horizontal velocity are compared with the crash velocity. If the craft exceeds the crash velocity, it will disappear from the screen. If it lands safely, it will remain on the surface waiting for lift-off.

The needed hardware is: a Motorola MEK6800 D2 Kit, two 8-bit digital-to-analog (D/A) converters, and an oscilloscope with DC inputs, as shown in figure 1. The capacitors at the output of the digital-to-analog converter are used to obtain a straight line display between two points. The keyboard will be used to enter the following commands:

- G — Go to start the simulation
- M — Main jet firing
- R — Right jet firing
- P — Left jet firing

After the program has been entered, the microprocessor will be directed to execute the program beginning at hexadecimal address 00F1 (listing 1). The oscilloscope will display a stationary craft and a random surface. Closure of the G key will start the dynamic simulation. Now you may control the firing of jet engines by pressing the M, R, or P keys. The objective of the control is to land safely. If the craft crashes, it will disappear from the screen. By pressing the G key, a new craft for you to command will appear on the screen. A star will be

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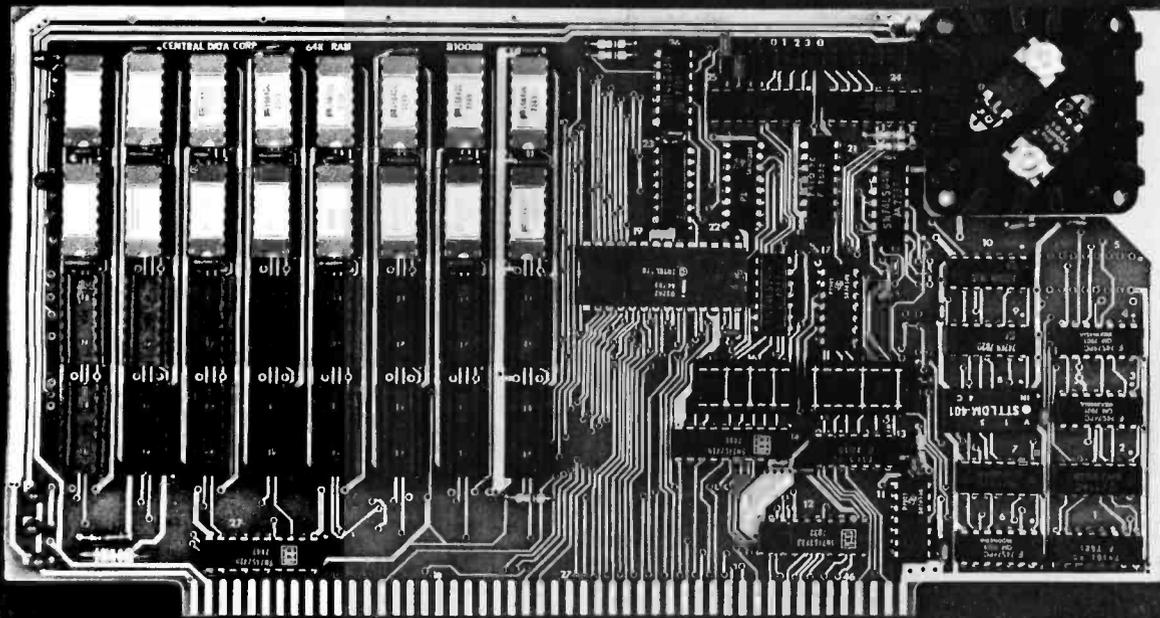
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32K Board Pictured Above

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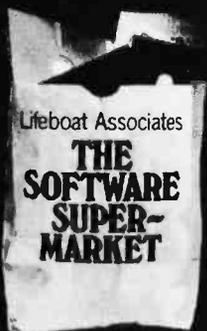
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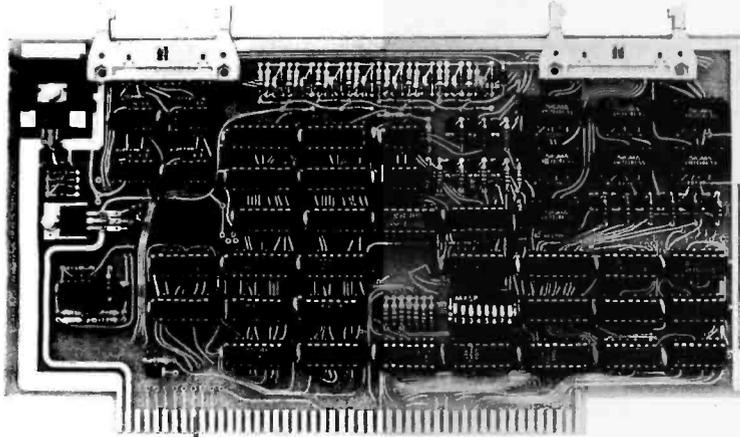
Listing 1 continued:

00052	0044	2E	02		BGT	LFIRE	52.
00053	0046	D6	09		LDA B	JR	53.
00054	0048	8D	03	LFIRE	BSR	EULER	54.
00055	004A	97	01		STA A	X2	55.
00056	004C	39			RTS		56.
00057	004D	CE	0002	EULER	LIX	##2	57.
00058	0050	57		E0	ASR B		58.
00059	0051	09			DEX	E0	59.
00060	0052	26	FC		BNE		60.
00061	0054	1B			ABA		61.
00062	0055	39			RTS		62.
00063	0056	D6	04	RAND	LDA B	RND	63.
00064	0058	17			TBA		64.
00065	0059	58			ASL B		65.
00066	005A	58			ASL B		66.
00067	005B	1B			ABA		67.
00068	005C	58			ASL B		68.
00069	005D	1B			ABA		69.
00070	005E	4C			INC A		70.
00071	005F	97	04		STA A	RND	71.
00072	0061	39			RTS		72.
00073	0062	D6	0E	SRFGEN	LDA B	ODOM	73.
00074	0064	D7	0D		STA B	TEMP	74.
00075	0066	D6	05		LDA B	RND	75.
00076	0068	D7	04		STA B	RND	76.
00077	006A	8D	EA	NXT	BSR	RAND	77.
00078	006C	7A	000D		DEC	TEMP	78.
00079	006F	26	F9		BNE	NXT	79.
00080	0071	CE	0010		LIX	##GETSRF	80.
00081	0074	C6	05		LDA B	##5	81.
00082	0076	D7	0D		STA B	TEMP	82.
00083	0078	8D	DC	NXTS	BSR	RAND	83.
00084	007A	44			LSR A		84.
00085	007B	44			LSR A		85.
00086	007C	A7	00		STA A	O,X	86.
00087	007E	08			INX		87.
00088	007F	7A	000D		DEC	TEMP	88.
00089	0082	26	F4		BNE	NXTS	89.
00090	0084	39			RTS		90.
00091	0085	7F	000F	BXING	CLR	FLAG4	91.
00092	0088	96	00		LDA A	X1	92.
00093	008A	84	3F		AND A	##3F	93.
00094	008C	81	30		CMF A	##30	94.
00095	008E	2A	09		BFL	XING	95.
00096	0090	81	10		CMF A	##10	96.
00097	0092	2B	05		BMI	XING	97.
00098	0094	84	20		AND A	##20	98.
00099	0096	97	15		STA A	B5	99.
01000	0098	39			RTS		100.
01010	0099	84	20	XING	AND A	##20	101.
010102	009B	16			TAB		102.
010103	009C	90	15		SUB A	B5	103.
010104	009E	27	0F		REQ	OUT	104.
010105	00A0	2B	05		BMI	PLUS	105.
010106	00A2	7A	000E		DEC	ODOM	106.
010107	00A5	20	03		BRA	SAVE	107.
010108	00A7	7C	000E	PLUS	INC	ODOM	108.
010109	00AA	7C	000F	SAVE	INC	FLAG4	109.
010110	00AD	D7	15		STA B	B5	110.
010111	00AF	39		OUT	RTS		111.
010112	00B0	8D	D3	TERR	BSR	BXING	112.
010113	00B2	D6	0F		LDA B	FLAG4	113.
010114	00B4	27	02		REQ	SISFLY	114.
010115	00B6	8D	AA		BSR	SRFGEN	115.
010116	00B8	8D	01C0	SISFLY	JSR	SURF	116.
010117	00BB	39			RTS		117.
010118	00BC	4F		KEY	CLR A		118.
010119	00BD	97	0A		STA A	FLAG1	119.
010120	00BF	97	0B		STA A	FLAG2	120.
010121	00C1	86	20		LDA A	##20	121.
010122	00C3	8D	25		BSR	TKEY	122.
010123	00C5	2B	03		BMI	L	123.
010124	00C7	7C	000A		INC	FLAG1	124.
010125	00CA	86	10	L	LDA A	##10	125.
010126	00CC	8D	1C		BSR	TKEY	126.
010127	00CE	2B	03		BMI	R	127.
010128	00D0	7C	000B		INC	FLAG2	128.
010129	00D3	86	A0	R	LDA A	##A0	129.
010130	00D5	8D	13		BSR	TKEY	130.
010131	00D7	2B	03		BMI	EXT	131.
010132	00D9	7A	000B		DEC	FLAG2	132.

Listing 1 continued on page 136

IDS Announces S-100 Energy Management Module

The 100-EMM Energy Management Module provides temperature measurement at four separate locations indoors or out; monitors eight (8) doors, windows, or fire sensors; controls six external devices via relay or optoisolator; and provides an intrusion alarm with battery backup (alarm operates even during primary power outages). Put the 100-EMM to use in your home or business and claim a 30% tax credit for the cost of your S-100 computer system including the 100-EMM. (Purchasing the 100-EMM can actually save you several times its cost in tax credits. Full instructions for filing are included in the 100-EMM manual.)



**BUY THIS S-100 BOARD
AND GET UP TO A 30%
TAX CREDIT BASED ON
THE COST OF YOUR
COMPUTER SYSTEM!**

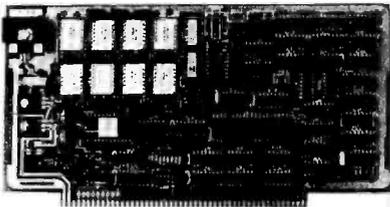
**100-EMM Energy Management Module
Assembled and Tested \$395.00
Kit \$345.00**

Options for 100-EMM:

CP-52 Cable Panel - Terminates two 26-conductor flat cables in 26 screwlugs. Use it for convenient interconnection of the 100-EMM to the "outside world". **\$45.00**

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Listing 1 continued:

```

00133 00DC 39      EXT   RTS      133.
00134 00DD 7F 000C GO   CLR     FLAG3 134.
00135 00E0 86 E0     LDA A  $$$E0 135.
00136 00E2 8D 06     BSR     TKEY   136.
00137 00E4 2B 03     BHI     0      137.
00138 00E6 7C 000C   INC     FLAG3 138.
00139 00E9 39      0     RTS      139.
00140 00EA 87 8022 TKEY STA A  SCNREG 140.
00141 00ED 7D 8020   TST     DISREG 141.
00142 00F0 39      0     RTS      142.
00143 00F1 7F 8005 BEGIN CLR     CRA   143.
00144 00F4 7F 8007   CLR     CRB   144.
00145 00F7 86 FF     LDA A  $$$FF 145.
00146 00F9 87 8004   STA A  FIA   146.
00147 00FC 87 8006   STA A  FIR   147.
00148 00FF 86 25     LDA A  $$$25 148.
00149 0101 87 8005   STA A  CRA   149.
00150 0104 87 8007   STA A  CRB   150.
00151 0107 4F      0     INIT   CLR A      151.
00152 0108 97 03     STA A  Y2    152.
00153 010A 86 0A     LDA A  $$$A  153.
00154 010C 97 01     STA A  X2    154.
00155 010E 86 60     LDA A  $$$60 155.
00156 0110 97 02     STA A  Y1    156.
00157 0112 86 20     LDA A  $$$20 157.
00158 0114 97 0E     STA A  ODOM  158.
00159 0116 96 04     LDA A  RND   159.
00160 0118 97 05     STA A  RND0  160.
00161 011A 8D 5C     START  BSR     LANDER 161.
00162 011C 8D 00B0   JSR     TERR  162.
00163 011F 8D BC     BSR     GO    163.
00164 0121 D6 0C     LDA B  FLAG3 164.
00165 0123 27 F5     BEQ     START 165.
00166 0125 8D 95     MOTION BSR     KEY   166.
00167 0127 8D 0016   JSR     SYS   167.
00168 012A 8D 4C     BSR     LANDER 168.
00169 012C 8D 4A     BSR     LANDER 169.
00170 012E 8D 48     BSR     LANDER 170.
00171 0130 8D 00B0   JSR     TERR  171.
00172 0133 96 02     LDA A  Y1    172.
00173 0135 8B 80     ADD A  $$$80 173.
00174 0137 90 12     SUB A  SUR   174.
00175 0139 22 EA     BHI     MOTION 175.
00176 013B 81 FB     CMP A  $$$FB 176.
00177 013D 2B 10     BHI     CRASH 177.
00178 013F 96 01     LAND   LDA A  X2  178.
00179 0141 81 08     CMP A  $$$8  179.
00180 0143 2A 0A     BPL     CRASH 180.
00181 0145 81 FB     CMP A  $$$FB 181.
00182 0147 2B 06     BHI     CRASH 182.
00183 0149 96 03     LDA A  Y2    183.
00184 014B 81 F0     CMP A  $$$F0 184.
00185 014D 2A 0B     BPL     SAFE  185.
00186 014F 8D 00B0   CRASH JSR     TERR  186.
00187 0152 8D 89     BSR     GO    187.
00188 0154 D6 0C     LDA B  FLAG3 188.
00189 0156 2E AF     BGT     INIT  189.
00190 0158 20 F5     BRA     CRASH 190.
00191 015A C6 04     SAFE   LDA B  $$$4  191.
00192 015C D7 03     STA B  Y2    192.
00193 015E 5F      0     CLR B      193.
00194 015F D7 01     STA B  X2    194.
00195 0161 D7 0A     STA B  FLAG1 195.
00196 0163 D7 0B     STA B  FLAG2 196.
00197 0165 CE A04D SF   LDX     $S   197.
00198 0168 8D 39     BSR     DSPLY 198.
00199 016A 8D 0C     BSR     LANDER 199.
00200 016C 8D 00B0   JSR     TERR  200.
00201 016F 8D 00BD   JSR     GO    201.
00202 0172 D6 0C     LDA B  FLAG3 202.
00203 0174 2E AF     BGT     MOTION 203.
00204 0176 20 ED     BRA     SF    204.
00205 0178 CE 01F1 LANDER LDX     $TOP  205.
00206 017B 8D 26     BSR     DSPLY 206.
00207 017D D6 0B     LDA B  FLAG2 207.
00208 017F 2F 05     BLE     RJET  208.
00209 0181 CE 01FA   LDX     $LJ   209.
00210 0184 8D 1D     BSR     DSPLY 210.
00211 0186 CE A031 RJET  LDX     $LS   211.
00212 0189 8D 18     BSR     DSPLY 212.
00213 018B D6 0A     LDA B  FLAG1 213.

```

Listing 1 continued on page 138

TIME after TIME



BATTERY SUPPORTED CALENDAR CLOCKS

PDP-11*

TCU-100 • \$495

- Provides month, day, hour, minute and second.
- Can interrupt on date/time, or periodic intervals.

TCU-150 • \$460

- Provides year, month, day, hour, minute and second.
- Automatic leap year.
- Patches for RSX-11M, RT-11 FB/SJ VO2, VO3 and UNIX.

LSI-11/2*

TCU-50D • \$325

- Provides month, day, hour, minute and second.
- Dual size board.
- Patches for RT-11 SJ/FB VO2, VO3B.

Lockheed SUE

TCU-200 • \$550

- Provides year, month, day, hour, minute, second and milli-second.
- Interval interrupts between 1/1024 seconds and 64 seconds.

Computer Automation (Naked Mini)

TCU-310 • \$385

- Provides year, month, day, hour, minute and second.

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Multi-Bus**

TCU-410 • \$325

- Provides year, month, day, hour, minute and second.
- SBC/BLC compatible.

HP 2100

TCU-2100 • \$395

- Correct time restored after power failure.
- Compatible with the HP TBG card.

Serial Clock (RS 232 or 20 mA)

SLC-1 • \$640

- Connects between any terminal and host computer.
- Provides date, time and more!

All Digital Pathways TCUs have on board NICAD batteries to maintain time and date during power down. Timing is provided by a crystal controlled oscillator. Prices are U.S. domestic single piece. Quantity discounts available.

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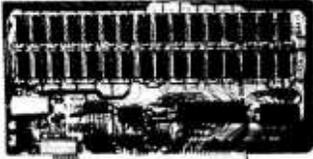


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the ultrabyte memory board

\$199.95 (complete kit with 16K memory)

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Look what JAWS offers you: Hidden refresh... fast performance... low power consumption... latched data outputs... 200 NS 4116 RAMs... on-board crystal... 8K bank selectable... fully socketed... solder mask on both sides of board... designed for 8080, 8085, and Z80 bus signals... works in Explorer, Sol, Horizon, as well as all other well-designed S100 computers.

GIVE YOUR COMPUTER A BIG BYTE OF MEMORY POWER WITH JAWS—SAVE UP TO \$90 ON INTRODUCTORY LIMITED-OFFER SPECIAL PRICES!

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Listing 1 continued:

00214	018D	27	05		REQ	NOJET	214.
00215	018F	CE	A03A		LIX	#MJ	215.
00216	0192	8D	0F		BSR	DSFLY	216.
00217	0194	CE	A03D	NOJET	LIX	#RS	217.
00218	0197	8D	0A		BSR	DSFLY	218.
00219	0199	D6	08		LIA B	FLAG2	219.
00220	0198	2C	05		BGE	NORJ	220.
00221	019D	CE	A048		LIX	#RJ	221.
00222	01A0	8D	01		BSR	DSPLY	222.
00223	01A2	39		NORJ	RTS		223.
00224	01A3	A6	00	ISFLY	LIA A	0,X	224.
00225	01A5	27	12		REQ	END	225.
00226	01A7	E7	8004		STA A	PIA	226.
00227	01AA	A6	01		LIA A	1,X	227.
00228	01AC	9B	02		ADD A	Y1	228.
00229	01AE	8B	70		ADD A	##70	229.
00230	01B0	E7	8006		STA A	FIB	230.
00231	01B3	08			INX		231.
00232	01B4	08			INX		232.
00233	01B5	8D	03		BSR	TDELAY	233.
00234	01B7	20	EA		BRA	DSFLY	234.
00235	01B9	39		END	RTS		235.
00236	01BA	C6	80	TDELAY	LIA B	##80	236.
00237	01BC	5A		DELAY	DEC B		237.
00238	01BD	26	FD		BNE	DELAY	238.
00239	01BF	39			RTS		239.
00240	01C0	CE	0010	SURF	LIX	#GETSRF	240.
00241	01C3	4F			CLR A		241.
00242	01C4	E6	00		LIA B	0,X	242.
00243	01C6	E7	8004		STA A	PIA	243.
00244	01C9	F7	8006		STA B	FIB	244.
00245	01CC	8D	EC		BSR	TDELAY	245.
00246	01CE	96	00		LIA A	X1	246.
00247	01D0	43			COM A		247.
00248	01D1	84	3F		AND A	##3F	248.
00249	01D3	E7	8004	NEXTS	STA A	PIA	249.
00250	01D6	8D	E2		BSR	TDELAY	250.
00251	01D8	08			INX		251.
00252	01D9	E6	00		LIA B	0,X	252.
00253	01DB	F7	8006		STA B	FIB	253.
00254	01DE	8D	DA		BSR	TDELAY	254.
00255	01E0	8C	0014		CFX	#GETSRF+4	255.
00256	01E3	27	04		REQ	LAST	256.
00257	01E5	8B	40		ADD A	##40	257.
00258	01E7	20	EA		BRA	NEXTS	258.
00259	01E9	86	FF	LAST	LIA A	##FF	259.
00260	01EB	E7	8004		STA A	PIA	260.
00261	01EE	8D	CA		BSR	TDELAY	261.
00262	01F0	39			RTS		262.
00263	01F1	8820		TOF	FDR	##8820,##8424,##7C24,##7820	263.
		01F3	8424				
		01F5	7C24				
		01F7	7820				
00264	01F9	00			FCB	\$00	264.
00265	01FA	701E		LJ	FDR	\$701E	265.
00266	01FC	00			FCB	\$00	266.
00267	A031				ORG	##A031	267.
00268	A031	781C		LS	FDR	##781C,##7C18,##7810,##7C18	268.
		A033	7C18				
		A035	7810				
		A037	7C18				
00269	A039	00			FCB	\$00	269.
00270	A03A	8000		MJ	FDR	##8000	270.
00271	A03C	00			FCB	\$00	271.
00272	A03D	8418		RS	FDR	##8418,##8810,##8418,##881C,##8820	272.
		A03F	8810				
		A041	8418				
		A043	881C				
		A045	8820				
00273	A047	00			FCB	\$00	273.
00274	A048	901E		RJ	FDR	##901E,##881C	274.
		A04A	881C				
00275	A04C	00			FCB	\$00	275.
00276	A04D	8540		S	FDR	##8540,##8050,##7B40,##884A	276.
		A04F	8050				
		A051	7B40				
		A053	884A				
00277	A055	784A			FDR	##784A,##8540	277.
		A057	8540				
00278	A059	00			FCB	0	278.
00279					END		279.

Text continued from page 132:

we do not have much room to move around, but the landing simulation is very realistic. In numerical calculation the 2's complement arithmetic is used. The 2's complement number has a range of decimal -128 to +127, or hexadecimal 80 to 7F. Since the number can be positive or negative, the summation will only be sufficient to perform addition and subtraction. The shift instructions ASL and ASR can be used to perform multiplication or division by 2 respectively. By repeating the use of shift operation, it is possible to multiply or divide a number by 2, 4, 8, and so on.

The dynamic equations for the landing craft are given by the following four first-order ordinary differential equations:

$$\frac{dX_1}{dt} = X_2$$

$$\frac{dX_2}{dt} = \pm SJET$$

$$\frac{dY_1}{dt} = Y_2$$

$$\frac{dY_2}{dt} = -g + JET$$

where:

- X_1 = horizontal displacement
- X_2 = horizontal velocity
- $SJET$ = side jet thrust; negative for the right-hand side jet, positive for the left-hand side jet, and 0 when neither are firing
- Y_1 = vertical displacement
- Y_2 = vertical velocity
- g = gravity
- JET = main jet thrust; 0 when it is not firing
- t = time

According to the Euler's method (see reference on "Applied Numerical Methods"), an equation of the form:

$$\frac{dZ}{dt} = f(t, Z)$$

can be replaced by the following equivalent numerical routine:

$$\begin{aligned} Z_{n+1} &= Z_n + hf(t_n, Z_n) \\ t_{n+1} &= t_n + h \\ n &= 0, 1, 2, \dots \end{aligned}$$

where the quantity Z_{n+1} , at the time t_{n+1} , can be calculated by adding the previously calculated value Z_n , and the product of the time increment h and the function $f(t_n, Z_n)$. Starting from the given initial value Z_0 at t_0 , the solution for Z_n at t_n can be obtained by repeating the calculation from the Euler's routine. This concept has been carried

out in the program SYS (address 0016). An assumption is made that the time increment h is equal to $\frac{1}{4}$ second.

A total of 553 bytes of memory is needed for the program. If you have more memory space available, you may want to add more constraints to your simulation. The limited fuel capacity can be added to the program. The fuel gauge, velocity, altitude, displacement, and elapsed time can also be displayed on the screen. The trace between craft and surface can be blanked by the beam-intensity modulation. The control line on the peripheral interface adapter (PIA), such as CA2 or CB2, can be used for the blanking control.

The microprocessor can be a useful tool in the classroom for the dynamic simulation. An automobile traveling on a random surface can be an interesting subject for studying the suspension system. Even a simple mass, spring, and dashpot system would prove to be an interesting simulation to observe on the oscilloscope. ■

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1. Carnahan, B, H A Luther, and J O Wilkes, *Applied Numerical Methods*, John Wiley and Sons Inc, New York, 1969, chapter 6.
2. Grieser, D, "Pseudorandom Number Generator," BYTE, November 1977, page 218.
3. *M6800 Microprocessor Programming Manual*, Motorola Inc, chapter 4.

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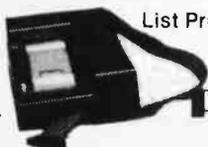


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The Dirt-Cheap Bootstrap

More Notes on Bringing Up a Microcomputer

Albert S Woodhull
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How do you take the very first steps into learning about microprocessors? An article by Sol Libes ("Notes on Bringing up a Microcomputer," January 1978 BYTE, page 162) described a procedure for the initial testing of a homebrew microcomputer which uses simple procedures to determine whether or not address and control signals are functioning properly. The procedures described are effective, but in order to use them you need a way to load some programs into memory.

If you are building a kit or following a complete microcomputer design, then the details of input and output interfacing will be provided for — a bootstrap program will either be available in read-only memory or can be easily entered from a front panel. But suppose you are just feeling your way along, as I did. I had obtained an 8080A chip set through Intel's University Program, but I had no intention of building a real computer. I had full access to an Altair and an IMSAI at the college where I teach; I wanted only to learn a little about how the hardware worked. I certainly did not want to spend either

the money or the time to imitate the Altair's front panel. The following is a description of how I solved this problem in an economical way.

To set the stage: I had the 8080A microprocessor interfaced with the 8224 clock generator/driver device and 1 K bytes of programmable memory. I had thirty-two light-emitting diodes (LEDs), driven by simple emitter-follower transistor buffers, which indicated the state of the bidirectional data bus, the address bus, and the decoded status signals. Three problems seemed important:

- I needed to be able to single-step the processor so that the light-emitting diodes would show more than a meaningless blur.
- I needed a way to transfer data from the outside world to memory.
- I needed some kind of keyboard or switch panel for entering data.

Single-Stepping

The 8080A is a dynamic device. This means that you can't slow it down to human speed by slowing its clock signal. The 8080A can, however, be made to enter a *wait*

state in which it essentially does nothing at high speed. While in the wait state, the processor uses the clock signal to keep its internal registers refreshed, but does not change its state.

To single-step through a program to make the computer perform each operation only at my command, I needed to be able to hold the processor in a wait state. The processor would stay in this wait state until I asked it to take a step; it would then immediately return to the wait state. As shown in the schematic diagram of figure 1, it was very easy to do this with only a single flip-flop.

The output of the flip-flop (half of a 7474 dual D edge-triggered type) was connected to the RDYIN line on the 8224 clock generator and driver. This line initiates a wait state when it is pulled low. Three inputs of the 7474 were used. The D (data) line was connected to ground. The clock input on the 7474 was driven by the SYNC output of the 8080A. Finally, a simple pulse generator drove the SET input to the flip-flop.

The operation of this circuit resembles that of a person whose reflexive response to the sound of an

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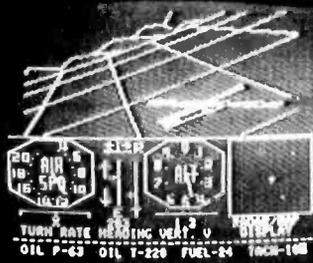
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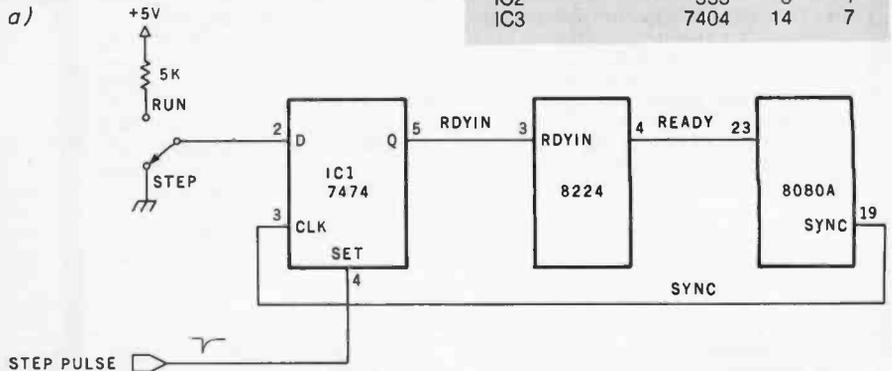


Figure 1a: A single-step mode can be implemented on an 8080A processor by using a flip-flop and the 8080A SYNC signal to clock a low-logic level through to the READY line. This puts the 8080A into a wait state. A very brief pulse to the SET input of the flip-flop ends the wait state until the next SYNC signal.

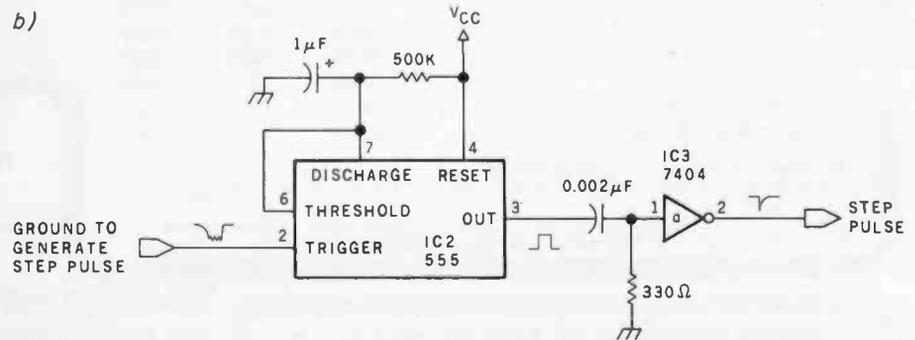


Figure 1b: The very narrow STEP pulse can be generated by a half-monostable circuit, a resistor-capacitor network at the input to a 7400 inverter. The manual switch contact must be debounced by a monostable circuit with a 0.1 to 1 second pulse width, for which a 555 timer is well-suited.

alarm clock is to roll over and turn it off. Normally the processor is in the wait state. A pulse to the SET input of the flip-flop ends the WAIT state, allowing the computer to complete execution of the process that is in suspension. At the very beginning of the processor's next cycle, it will send out a SYNC signal which will again clock the flip-flop output low, and reinitiate the processor wait state.

Getting the Data In

There are two ways an 8080A can access the outside world. IN or OUT instructions generate status signals which can be decoded, along with an 8-bit address, to activate input buffers or output latches. Alternatively, a memory address that is not actually used by memory devices can be decoded, along with read-from-memory or write-to-memory status signals. This can be used to activate a

memory-mapped buffer or latch. If a limited amount of memory and a small number of I/O (input/output) ports are to be addressed, the decoding can be ambiguous—some of the address lines may be ignored.

For bootstrapping purposes I took this to the limit: I arranged a switch to allow all memory-read signals to activate an input buffer, regardless of the state of the address lines. The principle is illustrated in the schematic diagram of figure 2. In the LOAD position of the switch, the real memory is never read, but memory-write signals are still capable of performing their normal function. When the processor begins an instruction cycle, it reads a byte from "memory" which is interpreted as an instruction. It makes no difference to the processor if the byte actually originates on the front panel.

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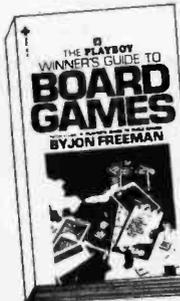
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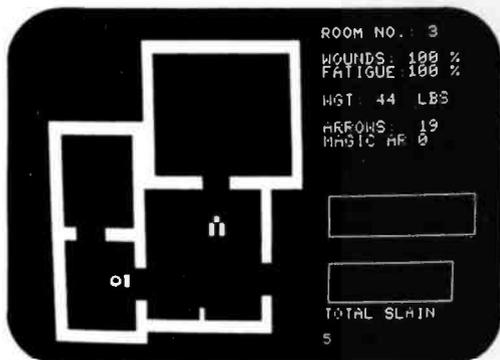
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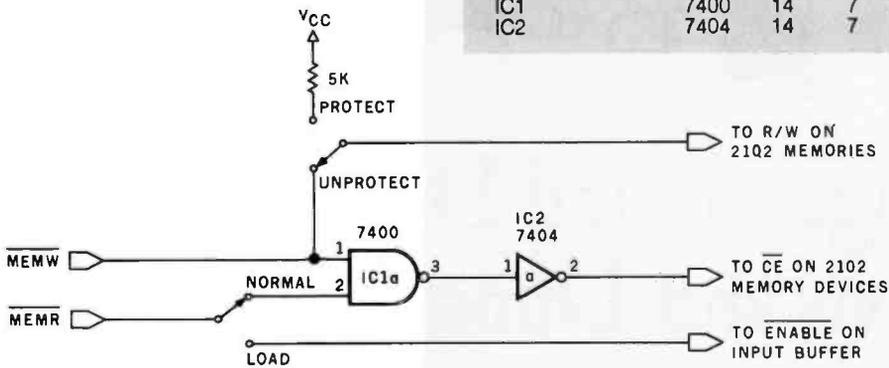


Figure 2: The LOAD/NORMAL switch routes the $\overline{\text{MEMR}}$ signal to an input buffer instead of to the memory, thus enabling the operator to control the processor by entering instruction codes from the outside. Also shown is another switch which can protect memory from inadvertent writing during debugging.

to move a byte of data from the front panel to the real memory by first setting up the code for a *move immediate data to memory* instruction (MVI M) on the panel, allowing the processor to execute a single step, and then setting up the value to be loaded on the panel. A second single step will read the data from the panel input,

and a third step will then write that data into a memory location.

The particular memory location must be specified somehow, so several additional bytes of instructions must have been *previously* entered. A few simple additions to the hardware already described make it necessary to do this only once, even if

many bytes are to be loaded into memory. A look at the computer to human interface should come first, however.

Cheap Keyboard Substitute

Figure 3 illustrates the ultimate in low-budget input devices. I took a scrap of copper-clad circuit board, scored it with a hacksaw into two rows of ten copper-bearing squares each, and soldered a length of wire to each square. Eight pairs of wires went to the inputs of simple latch circuits made by cross-connecting 7400 NAND gates; the other four pads on the circuit board were available for other controls. Light-emitting diodes (LEDs) indicated the state of each of the eight bits. A probe made from a defunct ball-point pen could be used to momentarily ground any of the pads.

In this way I could set up any desired combination on the latches; their outputs were in turn connected to the input port of the computer. One of the extra pads was connected to the single-step pulse generator mentioned earlier, via a debouncing circuit, and another was connected to the processor RESET line.

A Few Extras

Some additions to the elementary circuits described above were incorporated into the final version. The first of these is a trick I call "double addressing." An input port is physically just a buffer; there is no reason why a single physical port cannot have multiple logical identities.

I set up some logic gates to decode the input status signal and an address, along with an additional gate, to allow either the result of this decoding or a memory-read signal from the LOAD switch to activate the input buffer. The LOAD mode is used to load a simple bootstrap program. The bootstrap routine specifies a starting address for the program to be loaded, gets the data from the input port, moves it to memory, increments the pointer to memory, and then loops back to get another byte from the input. Once this bootstrap program has been loaded, the MEMR signal is switched back to the real programmable memory, but an IN instruction can still read the input port.

Text continued on page 148

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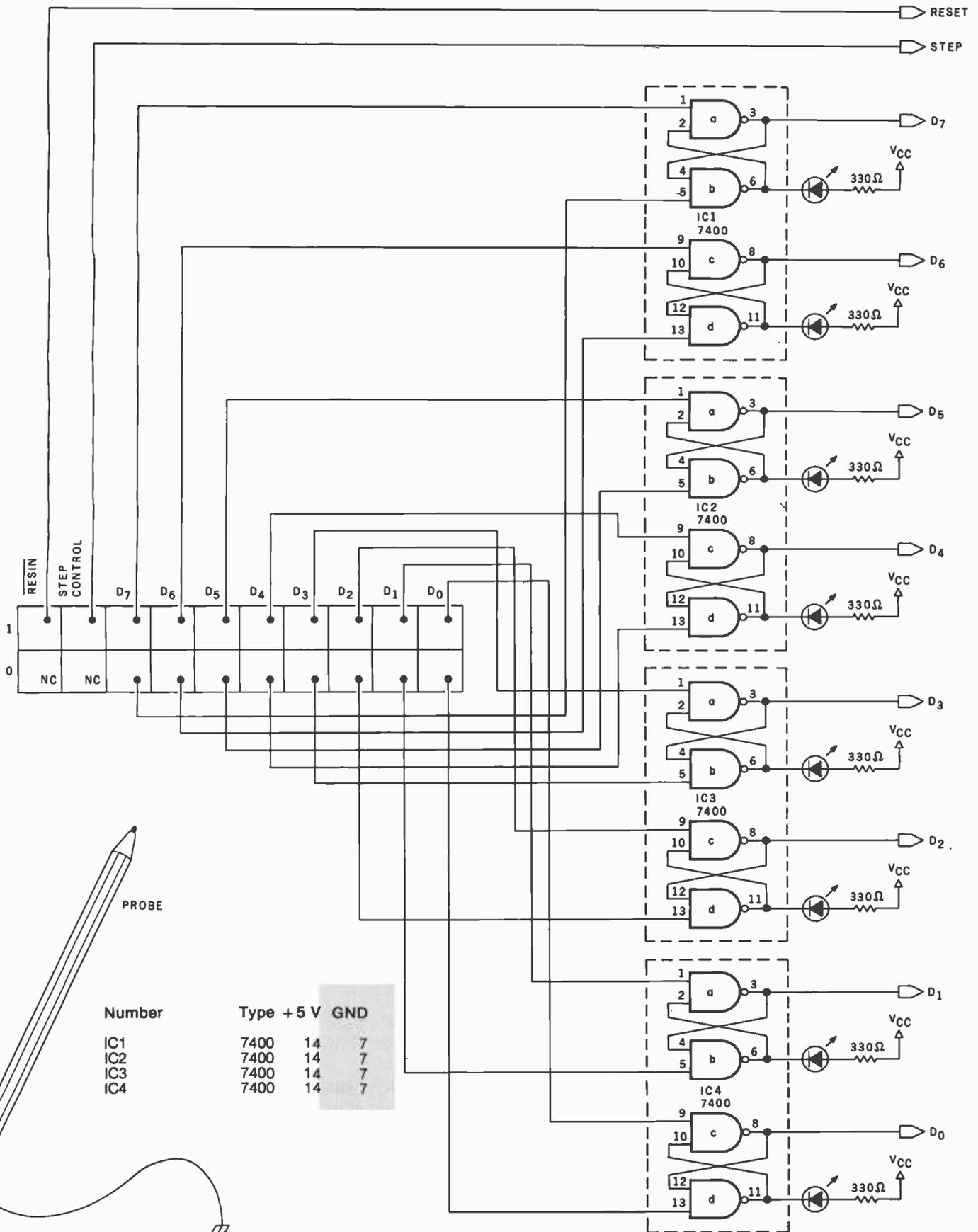


Figure 3: A small scrap of printed circuit board, an old ball-point pen, and some latch flip-flop circuits make a very inexpensive input device. With a little practice, an 8-bit number can be set up as easily and quickly as on a row of toggle switches. The surface of the printed circuit board has been scored to create isolated areas of copper for sensing purposes.

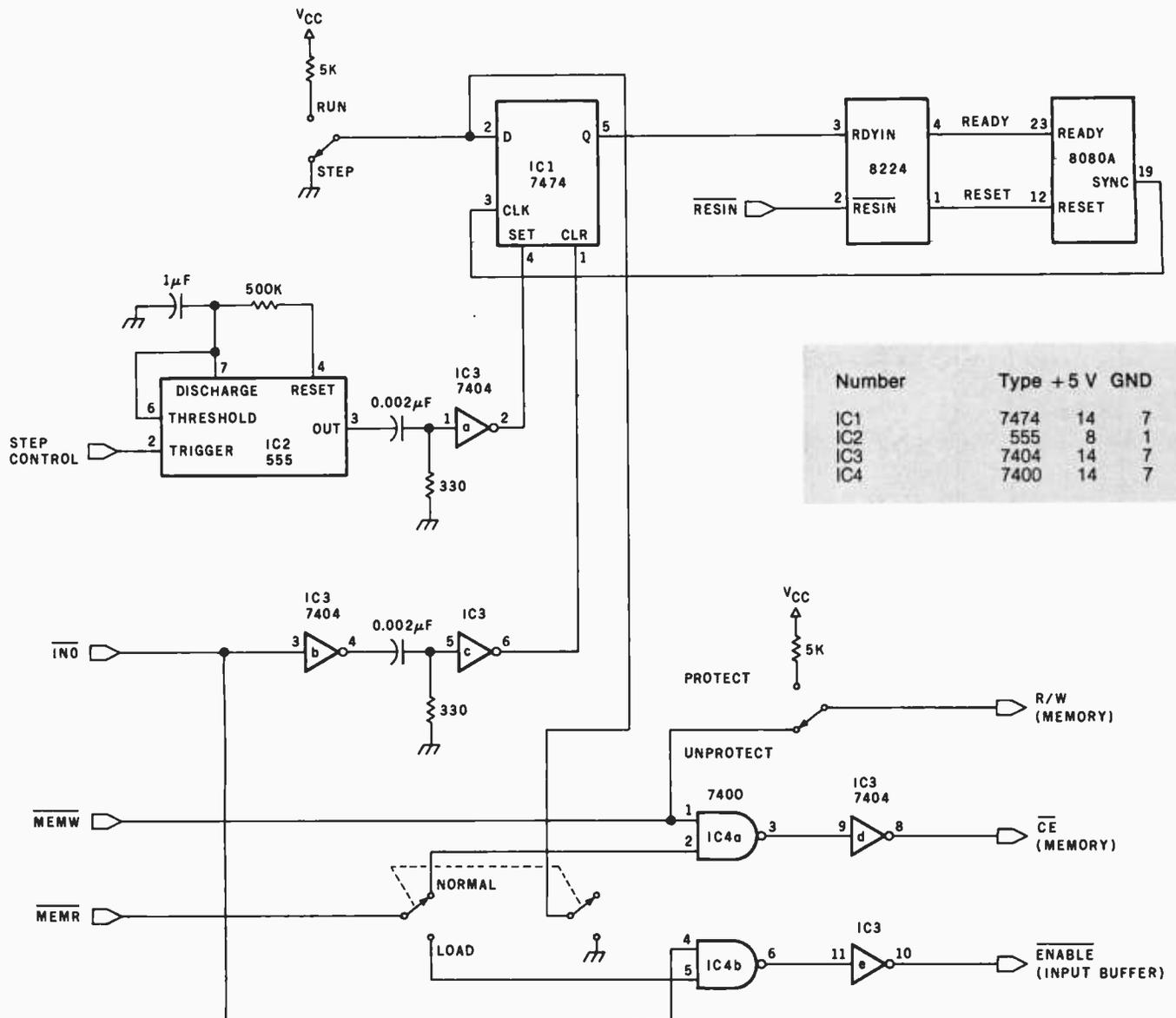


Figure 4: The complete control hardware package described in this article. $\overline{IN0}$ is a control signal produced by getting the \overline{IN} status signal from the 8080A and the address bus. Its orthodox function is to enable the input buffer; in this circuit the input buffer may also be enabled by a \overline{MEMR} signal when the LOAD/NORMAL switch is in the LOAD position. $\overline{IN0}$ also causes the 7474 single-step flip-flop to be cleared, thus forcing the processor into a wait state so that a human operator can set up the desired data on the input latch. Note the additional section of the LOAD/NORMAL switch which forces single-step operation in the LOAD mode, when full machine speed would be useless.

Text continued:

In the apparatus described so far, it would be necessary to single-step through the bootstrap program loop because at full machine speed the very first byte of data entered would be rapidly written into every possible memory location. Most monitor programs for handling such inputs have some provision for ensuring that they read each keystroke on a terminal only once. This is usually done by using a second input port as a control port which signals when new data is available. The hardware and software required for this would have

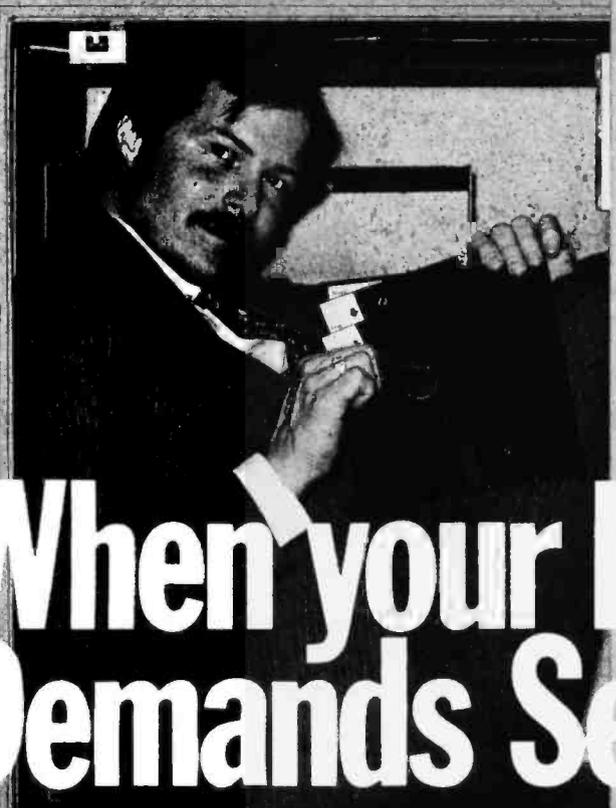
been inconveniently complicated for my early breadboard system.

A second unconventional trick avoided the problem. I made wait states programmable by adding a second pulse generator which was driven by the same decoder that activated the input buffer. The output of this pulse generator was fed to the RESET input on the single-step flip-flop. Instead of directly grounding the D input on the flip-flop, I put in a RUN/STEP switch which selects either a logic 1 or a logic 0 level for this input.

When the 0 level is selected, opera-

tion in the single-step mode proceeds as previously described. When the 1 level is selected, the processor runs at full speed until the program calls for data to be input. As the input port is selected, a wait state is initiated. At human speed, the required data can be set up on the input latches. A touch on the STEP pad then causes execution to resume. Figure 4 shows the circuit that incorporates all of these features, and example 1 in the text box describes in detail the procedure for loading the bootstrap program.

Text continued on page 152



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Example 1 Cold Start Bootstrap

The following sequence of operations is used with the hardware system described in the text to load a program when power is supplied to the computer:

1. Set LOAD/NORMAL switch to LOAD.
2. Momentarily ground the RESIN line. This clears the program counter and ensures that the processor will interpret the first byte it reads as an instruction.
3. Set up the input latch with the binary data 00100001. This is hexadecimal 21, the op code for a load-immediate data into the HL register pair (LXI H) instruction. When ready, ground the STEP line.
4. The processor will now expect a second and third byte for the LXI H instruction. These bytes will be loaded into the L and H registers and will act as a pointer to a particular memory address. To start at address 0000, set up all zeros on the input and STEP twice.
5. Set up the op code for the load immediate data into a memory location pointed to by the HL pair (MVI M) instruction, hexadecimal 36, then STEP by grounding the line.
6. The processor will now expect a byte of data. Set up hexadecimal DB on the latches. This is the code for the IN (receive input) instruction. Then STEP twice, once for the processor to read the data, and once for it to write the data into the memory.
7. Now set up hexadecimal 23 and STEP. This is the op code for the INX H instruction. This operation increments the address stored in the L and H registers and prepares the processor to write a byte to the next address in memory.

Only the last three operations of this sequence must be repeated to load additional bytes of data into the memory. Furthermore, only six more repetitions of steps 5, 6, and

7 are needed to complete the loading of the program given as listing 1.

After you enter this program, reset the program counter by grounding the RESIN line. Switch the LOAD/NORMAL control to NORMAL. The single-step mode can be used to verify that the program has been loaded properly, and then the full-speed run mode can be entered. Loading additional data into memory requires only that you set up the data on the input device and ground the STEP line. With an almost imperceptible flicker of the light-emitting diodes (LEDs), the data is read from the input and written into the memory. The processor again waits for another byte.

Example 2 Examination of a Memory Location

To examine a particular location follow this procedure:

1. Set the LOAD/NORMAL switch to LOAD.
2. Momentarily ground the RESIN line.
3. Enter hexadecimal C3, the code for a JMP, then STEP.
4. Enter the low byte of the desired address, then STEP.
5. Enter the high byte of the desired address, then STEP.
6. Setting the LOAD/NORMAL switch back to NORMAL will put the data at the desired location on the data bus, thus displaying it on the data LEDs.

After examining a location, a STEP will start execution from that location. You can then conduct another examine operation to show a new location, or the examine-next procedure of example 3 can show the next location.

Example 3 The Examine-Next Function

To look at a program or data in memory without executing it, first examine the first byte in the

desired memory segment, then do the following:

1. Set the LOAD/NORMAL switch to LOAD. Do not ground RESIN.
2. Set up all zeros on the input latch. This is the code for a no operation (NOP) instruction.
3. STEP, then switch to NORMAL. The next byte in memory will be displayed on the data LEDs.

This procedure can be repeated as desired. Note, however, that strange things can happen if you start execution while examining a byte which is the second or third byte of a multibyte instruction. This error of starting in the wrong place is also possible with most conventional front panels.

Example 4 Temporary Patches

When a program contains loops that are repeated many times, single-step debugging can be simplified by substituting instructions. For example, a subroutine that generates eight cycles of 2400 Hz audio to record a logic 1 bit on magnetic tape is shown in listing 2.

To verify that this program worked properly, you would not want to single-step through the inner loop 416 times! You might step through it once, but the next time you came to the JNZ instruction, you could use the LOAD function to make the processor see three successive NOPs. Alternately, you might change the cycle counting and timing bytes at locations 0102 and 0104 to the value 01. Since the LOAD substitution does not actually alter memory contents, this procedure can also be used for a program stored in read-only memory. There is no need to go back and undo patches after tracing the program. In these respects the LOAD function of this simple control system is more versatile than most conventional front panels. If a permanent patch is needed, you can use the LXI H and MVI M instructions.



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Listing 1: Program instructions which are loaded into the 8080 memory by manual means, and are then used to load further memory locations more quickly.

Hexadecimal Data Loaded	Instruction Mnemonic	Explanation
DB 00	IN	Input Input port address (hardware dependent)
77	MOV M,A INX H	Copy data from accumulator to memory
23		Increment HL, the memory pointer
C3 00 00	JMP	Jump Jump address, low byte Jump address, high byte

Listing 2: A routine for the 8080 which can record a logic 1 bit on a cassette tape by generating eight cycles of a 2400 Hz audio signal.

Address	Label	Mnemonic	Explanation
0100	MARK	XRA A	Set accumulator to zero
0101		MVI B	Set up a counter
0102		10	to count 16 half cycles
0103	HALFCY	MVI C	And another counter
0104		1A	to time 26 loops
0105		OUT	Then output to
0106		00	port 0
0107	TIMELOOP	DCR C	Countdown the timer
0108		JNZ TIMELOOP	And stay in the loop
0109		07	until counter is zero
010A		01	
010B		CMA	Complement the accumulator
010C		DCR B	Countdown half cycles
010D		JNZ HALFCY	And send more until
010E		0	cycle counter is zero
010F		01	
0110		RET	Then return to main program

Text continued:

Additional Applications

The LOAD mode permits direct control of the computer at any time. Most of the functions of the front panel on an IMSAI or Altair can be simulated by causing the processor to execute instructions loaded directly from the crude printed-circuit-pad "front panel." For example, executing a JMP instruction is equivalent to the *examine* function of the usual front panel. *Examine next* is implemented by single-stepping a no-operation (NOP) instruction. A program can also be temporarily patched during single-step debugging to break out of a loop, or to try an alternative instruction. Examples 2, 3, and 4 in the text box explain these functions in more detail.

Evolution of the System

While developing the circuits I have described, I became hooked on microprocessors. What started out as a breadboard project is now a computer, but I have spent less money along the way than is ordinarily paid for a system of less capability.

To encourage others who might wish to follow a route similar to mine, I want to emphasize that all of the effort and material that went into my first experiments were useful in the larger system that grew from it. The single input port that served my printed circuit board input device was later shared by an ASCII keyboard and a cassette recorder.

The addition of a single *output* port made possible the use of software timing in a routine to generate audio tones for recording programs on tape. Another bit of the same output port can drive a printer in serial mode; again, software timing can be used.

The first 256-byte block of read-only memory that I added was adequate to hold all of the programs that I needed to read cassette tapes. During the few weeks it took me to develop those programs, not wishing to lose the programs by removing power from the programmable memory, I connected an old car battery to the memory to keep it alive.

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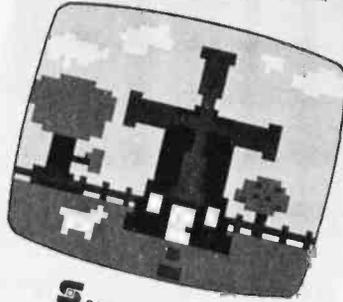
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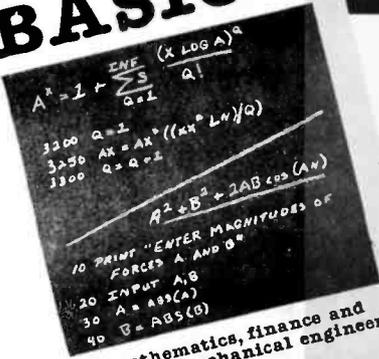
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Hydrocarbon Molecule Constructor

Randall S Matthews
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To an organic chemist learning to program a newly acquired microcomputer (in my case, the 16 K byte Apple II), the challenge of "teaching" chemical principles to the computer naturally arises. For example: can the Apple II learn the rudiments of structural organic chemistry, and use that knowledge to assemble and draw simple molecules? This subject is usually covered early in the first semester of sophomore organic chemistry. I decided to write a BASIC program that would accept a hydrocarbon molecular formula as input, and then randomly construct a molecule fitting that formula and draw its structure using high-resolution graphics as output.

Initialization

First, the program must be initialized and the input accepted and analyzed. The user will enter a molecular formula in the form C_nH_m (where C is the number of carbon atoms and H is the number of hydrogen atoms in the molecule).

Clearly, the program must accept only values of C and H that are positive, and less than the maximum numbers allowed by the dimension statement (line 100). However, the dictates of organic chemistry force further restrictions.

In a neutral, ground-state, hydrocarbon molecule, every carbon atom must have exactly four bonds (ie: connections to other atoms), and every hydrogen atom must

have exactly one bond. In 3-methyl-1-butene, as shown in figure 1, notice that each carbon has four connections.

Carbon atom number 2 (C-2) has one bond to C-3, one bond to a hydrogen (H), and two bonds to C-1. Similarly, each H has only one bond. This *valence* restriction means that, for a given number of carbons C, the maximum number of hydrogens is $2 \times C + 2$. A little thought will verify that conclusion.

Consider the propane structure, as shown in figure 2, with a formula C₃H₈ ($8 = 2 \times 3 + 2$). No more hydrogens can be added, since each carbon already has its maximum number of connected atoms. Note that if we make a double bond (C-1 to C-2) to form 1-propene, two hydrogens must be removed. This observation leads to a second restriction: the total number of hydrogens in a hydrocarbon must always be even. A good exercise is to try to draw a counter-example, remembering the valence restrictions.

Connection Table

Having accepted and screened the input, our program must now put together carbon and hydrogen atoms to form a molecular structure that fits the formula input. This process involves the construction of a *connection table*. To illustrate this concept, consider again the molecule in figure 1. How can the information in that structure be numerically represented? One convenient

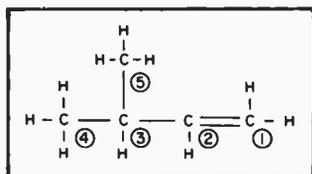


Figure 1: In the hydrocarbon 3-methyl-1-butene, each carbon atom has four connections. This is true of any hydrocarbon molecule.

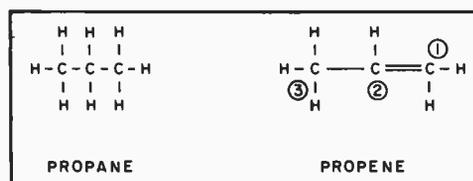


Figure 2: Examples of propane and propene. For any given hydrocarbon with C carbon atoms, the maximum number of possible hydrogen atoms, H, is $2 \times C + 2$.

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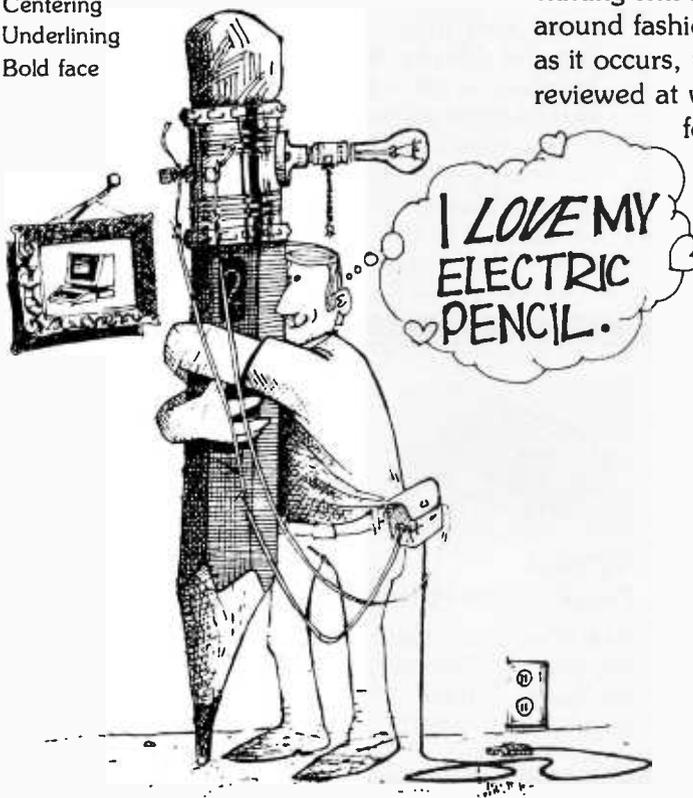
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Figure 3: A possible method of representing a connection table. This connection table represents every bond for every carbon atom. The information is stored by the computer in the form shown in figure 4.

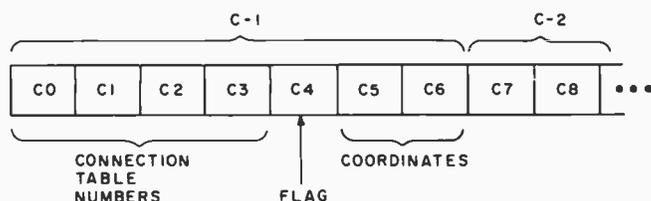


Figure 4: The connection table is stored in array C.

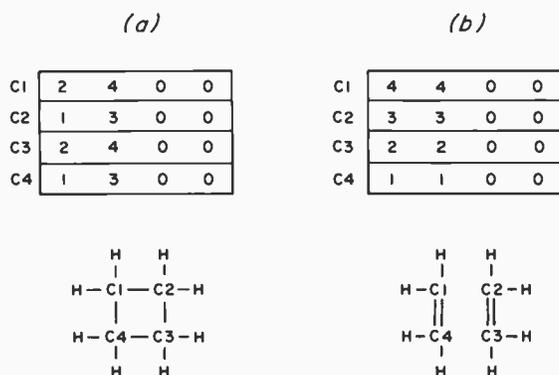


Figure 5: Using the random method of generating connection tables may result in some difficulties. Two connection tables for C_4H_8 are shown. One possible and acceptable connection table is figure 5a. Figure 5b is an unacceptable connection table since it results in two separate molecules.

method is shown in figure 3.

This connection table indicates every bond for every carbon atom. For example, in column 2 of row C3 is a 5, indicating that the second bond of C-3 connects to carbon atom number 5 (C-5). An entry of 0 in the table means connection to a hydrogen. Thus, the number of 0s in the table necessarily equals the number of hydrogens in the molecule. Reading across row C2, we find that carbon C-2 is connected twice to C-1, constituting a *double bond*, once to C-3, and once to a hydrogen.

In the computer, the information contained in the connection table is stored in array C, as indicated in figure 4. The information for C-1 is stored in array elements C(0) thru C(6); the information for C-2 is stored in elements C(7) thru C(13); etc. In every such block of seven elements, the first four elements contain the four numbers from the connection table for that carbon atom. Thus, using the connection table in figure 3 as an example, we have: C(0)=2, C(1)=2, C(2)=0, C(3)=0, C(7)=1, C(8)=1, C(9)=0, C(10)=3, etc. The use of the other elements in the array is explained later.

My first programming impulse was to construct the connection table entirely at random. Unfortunately, this method proved inadequate for several reasons. First, it was very slow. After each attempt at constructing the table, the program would check if the generated numbers were consistent with the input molecular formula. If they were not, as was often the case, the program recycled to try again. This process was very inefficient.

The second problem was that the connection tables generated often *did* satisfy the formula, but led to disconnected structures. For example, suppose the formula C_4H_8 (4,8) is input. Figure 5 shows two connection tables, along with their corresponding structures, that fit this formula. Clearly, the output in figure 5b is unacceptable because it is two separate structures, even though its connection table still conforms to the input.

How may these problems be solved? The answer lies in the new algorithm illustrated in figure 6, which again uses the hypothetical input C_4H_8 . This method begins by connecting C-1 to C-2. A random integer between 0 and 3 is then selected, and C-3 is bound to the carbon atom with



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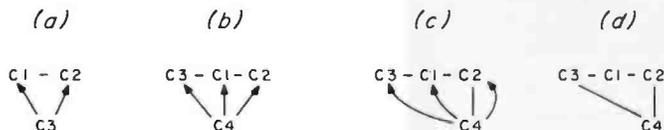


Figure 6: A more efficient method for connecting the carbon atoms is to first connect C-1 to C-2. A random number between 0 and 3 is then selected and C-3 is bound to that carbon atom (6a,6b). C-4 is then randomly connected to one carbon atom in the range C-1 thru C-3. After all carbon atoms have been connected thus, the table is cleaned up by another routine. Two different carbon atoms are chosen randomly and a bond is formed between them if their valence restrictions allow. (Remember there may be only four bonds to a carbon atom.) In the example the final connection is between C-4 and C-3. All of the available bonds will be filled with hydrogen atoms in the final molecule.

that number as shown in figures 6a and 6b. An integer between 0 and 4 is randomly chosen, and C-4 is connected to that atom as shown in figures 6b and 6c.

After all of the carbons have been thusly connected, another routine is used to finish the table, wherein more connections are randomly made as follows. Two different carbons in the existing structure are randomly chosen, and, if the valence restriction allows, a bond is made between them.

In our example, the final connection is made between C-4 and C-3. (See figures 6c and 6d.) After connecting all the carbons, the number of such additional bonds that must be made can be calculated beforehand from the molecular formula according to the equation:

$$EU = ((2 \times C + 2) - H) / 2$$

where EU represents the number of additional bonds to be formed, and C and H are the formula input numbers. The origin of this equation is not within the scope of this article, but the enterprising reader might be able to derive it. EU stands for *elements of unsaturation*. In the example above, $EU = 1$ (for C_4H_8), so only one additional bond

had to be made to complete the connection table. (See figures 6c and 6d.)

Assigning Coordinates

Having assembled the molecule, coordinates for each carbon must now be assigned before drawing the structure. For the final drawing to be as clear as possible, the assignments need to satisfy at least two requirements. First, no two carbons should have the same coordinates; and second, carbons that are bound to each other should be plotted next to each other whenever possible.

The following algorithm was devised to assign coordinates according to the two criteria. Carbon C-1 is given the coordinates 120,75 in the Apple's 270 by 160 high-resolution graphics display. Next, all of the carbons connected to C-1 that do not already have coordinates are assigned coordinates next to C-1. These coordinates are stored in the sixth and seventh elements of the requisite block in array C as shown in figure 4. After its neighbors have been given coordinates, the flag element in C-1's block of array C is set to 1. (Again, see figure 4.) If it has already received its coordinates, the same procedure is then followed for C-2 and continued until all of the carbons have been used. This method does not always give the best or even an adequate representation, but it does offer the advantages of simplicity and speed. Also, the confusing drawings that sometimes result are in most cases easily improved.

Drawing the Structure

With all the necessary information now contained in array C, the final structure may be drawn. This straightforward process uses Apple's machine-language, high-resolution graphics subroutines (stored in hexadecimal locations C00 thru FFF prior to running the program), as well as the several vector tables given in the text box, allowing the atomic symbols to be easily drawn by the shape subroutine. These vector tables must be stored in hexadecimal locations 1000 thru 1129, and are protected by a LOMEM setting that is automatically performed by the BASIC program (line 5).

Text continued on page 166

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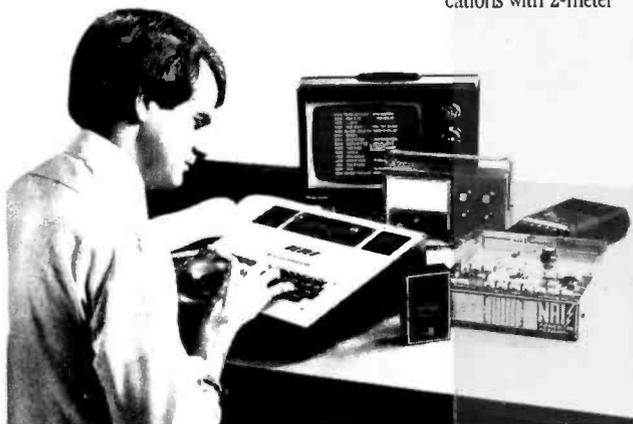
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Listing 1: An Apple II integer-BASIC program for generating hydrocarbon representations using the available high-resolution graphic routines. The high-resolution routines use the graphics tables in listing 2.

```

5 POKE 284,4400 MOD 256: POKE 285,4400/256: POKE 74,4400 MOD 256: POKE
  75,4400/256
10 GOTO 100
30 POKE 802,Y: POKE 800,X MOD 256
35 POKE 801,X/256: RETURN
40 POKE 804,X MOD 256: POKE 805,X/256: RETURN
100 DIM C(110)
110 TEXT : CALL -936: VTAB 5: TAB 8: PRINT "APPLE-CHEM II"
120 VTAB 10: PRINT "THIS PROGRAM WILL DRAW A MOLECULE": PRINT "FOR A GIVEN M
  OLECULAR FORMULA."
130 VTAB 15: PRINT "ENTER A MOLECULAR FORMULA": PRINT "IN THE FORM 'C,H', W
  HERE"
140 PRINT "'C' = THE NUMBER OF CARBON ATOMS": PRINT "IN THE MOLECULE, ETC."

150 INPUT NC,NH
152 NF=0
155 IF NC#-100 THEN 160:NC= RND (7)+2:NH=((2*NC)/2)+2
157 NF=1: CALL -936: VTAB 22: PRINT "C-";NC;"H-";NH: GOTO 180
160 IF NC>1 AND NC<16 AND NH>-1 AND NH<=2*NC+2 AND (NH/2=NH-NH/2) THEN
  180
170 PRINT : PRINT "IMPROPER DATA!": PRINT "C MUST BE >= 2 AND < 16": PRINT
  "H MUST BE EVEN, >= 0 AND <= 2*C+2": GOTO 150
180 EU=((2*NC+2)-NH)/2
190 FOR I=0 TO NC+7:C(I)=0: NEXT I
200 C(0)=2:C(7)=1: IF NC=2 THEN 300
210 FOR I=3 TO NC
220 X= RND (I-1)+1
230 IF C((X-1)*7+1)#0 THEN 250
240 C((I-1)*7)=X:C((X-1)*7+1)=I: GOTO 290
250 IF C((X-1)*7+2)#0 THEN 270
260 C((I-1)*7)=X:C((X-1)*7+2)=I: GOTO 290
270 IF C((X-1)*7+3)#0 THEN 290
280 C((I-1)*7)=X:C((X-1)*7+3)=I
290 NEXT I
300 IF EU=0 THEN 410
310 FOR K=1 TO EU
320 X= RND (NC)+1:Y= RND (NC)+1: IF X=Y THEN 320
330 FOR I=1 TO 3: IF C((X-1)*7+I)#0 THEN 350
340 X1=I: GOTO 360
350 NEXT I: GOTO 320
360 FOR I=1 TO 3: IF C((Y-1)*7+I)#0 THEN 380
370 Y1=I: GOTO 390
380 NEXT I: GOTO 320
390 C((X-1)*7+X1)=Y:C((Y-1)*7+Y1)=X
400 NEXT K
410 FOR I=4 TO (NC-1)*7+4 STEP 7: FOR J=0 TO 2
420 C(I+J)=0: NEXT J: NEXT I
430 GOSUB 1000: GOSUB 2000
435 CALL -936: VTAB 22
437 IF NF#1 THEN 440:NC=-100: GOTO 155
440 PRINT "HIT 'D' TO DRAW THIS DIFFERENTLY"
450 PRINT "HIT 'I' FOR A NEW ISOMER (SAME FORMULA)"
460 PRINT "HIT 'F' FOR A NEW MOLECULAR FORMULA"
470 KEY= PEEK (-16384): IF KEY<128 THEN 470
480 POKE -16368,0
490 IF KEY=196 THEN 410: IF KEY=201 THEN 190: IF KEY=198 THEN 110
500 END

```

```

1000 C(5)=120:C(6)=75
1010 FOR K=1 TO NC: IF C((K-1)*7+4)=0 AND C((K-1)*7+5)#0 THEN 1030
1020 NEXT K: GOTO 1090
1030 FOR I=0 TO 3:J=(K-1)*7+I: IF C(J)=0 THEN 1080
1040 IF C((C(J)-1)*7+5)#0 THEN 1080
1050 GOSUB 1500
1060 FLAG=0: GOSUB 1600: IF FLAG=1 THEN 1050
1070 C((C(J)-1)*7+5)=TX:C((C(J)-1)*7+6)=TY
1080 NEXT I:C((K-1)*7+4)=1: GOTO 1010
1090 RETURN
1500 TX=C((K-1)*7+5):TY=C((K-1)*7+6)
1510 A1=( RND (3)*30)-30:A2=( RND (3)*30)-30
1520 TX=TX+A1:TY=TY+A2
1530 IF TX<4 OR TX>264 OR TY<4 OR TY>152 THEN 1500
1540 RETURN
1600 FOR II=1 TO NC
1610 IF C((II-1)*7+5)=TX AND C((II-1)*7+6)=TY THEN 1630
1620 NEXT II: GOTO 1640
1630 FLAG=1
1640 RETURN
2000 CALL 3072: POKE 812,255: POKE 806,1: POKE 807,0
2010 S=3805:L=3786:P=3780: POKE 28,255
2020 FOR I=1 TO NC: FOR J=0 TO 3: IF C((I-1)*7+J)=0 THEN 2160
2030 FLAG=0: IF C((I-1)*7+J)<I THEN 2160
2040 FOR K=0 TO 3: IF K=J THEN 2060
2050 IF C((I-1)*7+K)=C((I-1)*7+J) THEN FLAG=FLAG+1
2060 NEXT K:T=C((I-1)*7+J)
2070 X1=C((I-1)*7+5):Y1=C((I-1)*7+6):X=X1:Y=Y1
2080 GOSUB 30: CALL P
2090 X2=C((T-1)*7+5):Y2=C((T-1)*7+6):X=X2:Y=Y2
2100 GOSUB 30: CALL L: IF FLAG<1 THEN 2160
2110 X=X1+6:Y=Y1+3: GOSUB 30: CALL P
2120 X=X2+6:Y=Y2+3: GOSUB 30: CALL L
2130 IF FLAG#2 THEN 2160
2140 X=X1-3:Y=Y1-6: GOSUB 30: CALL P
2150 X=X2-3:Y=Y2-6: GOSUB 30: CALL L
2160 NEXT J: NEXT I
2170 FOR I=1 TO NC:X1=C((I-1)*7+5):Y1=C((I-1)*7+6)
2180 POKE 812,0:X=X1:Y=Y1+2: GOSUB 30: CALL P
2190 POKE 804,4199 MOD 256: POKE 805,4199/256: CALL S: POKE 812,255
2220 X=X1:Y=Y1: GOSUB 30: CALL P: FLAG=0
2230 FOR J=0 TO 3
2240 IF C((I-1)*7+J)=0 THEN FLAG=FLAG+1
2250 NEXT J
2260 IF FLAG#0 THEN 2280
2270 X=4096: GOSUB 40: GOTO 2330
2280 IF FLAG#1 THEN 2300
2290 X=4107: GOSUB 40: GOTO 2330
2300 IF FLAG#2 THEN 2320
2310 X=4130: GOSUB 40: GOTO 2330
2320 X=4166: GOSUB 40
2330 CALL S: NEXT I: RETURN

```

Listing 2: The program in listing 1 uses a high-resolution shape (or vector) table which is shown here. It stores shapes for the chemical symbols. The operation of the shape table is defined in the Apple II Programmer's Manual and in the documentation for the high-resolution routines. These vector tables are used to draw the different parts of molecules on the video screen.

1000-	22	64	2D	15	96	F2	3F	07	1028-	17	17	36	28	2D	D5	DB	C3
1008-	20	04	00	24	2D	2D	24	34	1030-	18	08	18	24	24	24	DF	33
1010-	36	36	FE	1B	24	24	24	D7	1038-	36	36	3E	D8	1E	3F	07	20
1018-	E3	3F	17	36	36	0E	2D	05	1040-	24	64	2D	15	06	00	2E	2D
1020-	20	00	2D	2D	4D	62	AD	F6	1048-	AD	09	0C	AD	36	3F	2D	36

Listing 2 continued on page 164

Listing 2 continued:

1050-	1E	3F	E0	D8	24	24	24	DF	10C0-	2D	3E	3F	3F	3F	3F	3F	3F
1058-	33	36	36	3E	D8	1E	3F	07	10C8-	3F	3F	3F	3F	37	2D	2D	2D
1060-	20	24	64	2D	15	06	00	24	10D0-	2D							
1068-	24	24	24	3C	3F	3F	3F	3F	10D8-	3F							
1070-	3F	2D	10E0-	3F	3F	3F	37	2D	2D	2D	2D						
1078-	2D	2D	2D	2D	3E	3F	3F	3F	10E8-	2D	3E						
1080-	3F	37	10F0-	3F													
1088-	2D	10F8-	3F	3F	37	2D	2D	2D	2D	2D							
1090-	2D	2D	2D	3E	3F	3F	3F	3F	1100-	2D	2D	2D	2D	2D	2D	3E	3F
1098-	3F	3F	3F	3F	3F	3F	37	2D	1108-	3F							
10A0-	2D	1110-	3F	37	2D	2D	2D	2D	2D	2D							
10A8-	2D	2D	3E	3F	3F	3F	3F	3F	1118-	2D	2D	2D	2D	2D	3E	3F	3F
10B0-	3F	3F	3F	3F	3F	37	2D	2D	1120-	3F							
10B8-	2D	1128-	07	00													

Table 1.

Program Lines	Function
5	Set LOMEM:4400
30-40	Subroutines used for drawings.
100-170	Accept and analyze input.
180-400	Construct connection table.
435-500	Special features.
1000-1640	Subroutine to assign coordinates.
2000-2330	Subroutines to draw molecule.

Program Notes

Since remark statements were deleted from the final program to increase execution speed, the explanations provided in table 1, should prove useful when reading the program. Table 2 provides a list of all machine language accesses in the Apple II used in this program. These explanations should help implement the chemistry program on a different computer.

Table 2.

Command	Occurrence	Effect
POKEs to 204, 205, 74, 75	line 5	Set LOMEM:4400. This protects the vector table in the Apple's memory from being written over.
POKEs to 802, 801, 800	lines 30, 35	These locations hold the coordinates for the next point to be plotted.
POKEs to 804, 805	line 40	These locations hold the address of the part of the vector table containing the shape about to be drawn.
CALL 3072	line 2000	Initializes high-resolution graphics mode.
POKE 812, 255 POKE 806, 1	lines 2000, 2190 line 2000	Set color to white. Set scaling factor to 1. (full size)
POKE 807, 0	line 2000	Set rotation factor to 0. (right side up)
CALL P	lines 2080, 2110, 2140, 2180, 2220	Causes point to be plotted at coordinates set in SUB 30.
CALL L	lines 2100, 2120, 2150	Causes line to be drawn from last point plotted to coordinates set in SUB 30.
POKE 812, 0 CALL S	line 2180 lines 2190, 2330	Set color to black. Cause shape to be drawn starting at last point plotted (line 2180). Shape is determined by which section of vector table is poked into locations 804 and 805 as shown below:
	table location	figure drawn
	4199	blank space
	4096	C
	4107	CH
	4130	CH ₂
	4166	CH ₃

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Text continued from page 160:

Program Description and Instructions

To run the program, load the high-resolution graphics subroutines, the vector tables, and the BASIC program (remembering to set HIMEM;8192) and type RUN. You will be asked to input a molecular formula. To test the program, type 4,8. In a few seconds, an isomer of butene should appear. At the bottom of the screen, you will note several special features. Pressing the D key will draw a new picture of the same compound; in other words, the same connection table is used, but different coordinates are assigned. This command is very useful, particularly for complicated structures, when the initial drawing is too confusing to understand. You may continue to press the D key until a satisfactory drawing results. Pressing the I key isomerizes the structure (ie: a different compound with the same molecular formula is drawn). Thus, you could investigate some of the many isomers of tetrahydrene (C_4H_4). Pressing the F key simply recycles the program to allow new input. Pressing any other key ends the run.

One other very interesting special feature is demonstrated by entering the "formula" -100,0. This input is a signal for the program to begin drawing structures from randomly chosen molecular formulae. It will continue to draw new compounds until interrupted by control-C. This feature makes a fascinating demonstration display for the Apple II.

Concluding Comments

Finally in possession of a running program, you may well inquire: what good is it? Certainly, for a practicing organic chemist, the program has little practical value. However, by exposing several of my chemist friends to the program, I have found that they do enjoy playing with it, especially the isomerization feature. It is fun!

For those who are interested in practical applications of microcomputing, I stress that this program has valuable use in chemical education. For beginning organic students, it provides an enjoyable introduction to numerous seminal concepts of structural chemistry (eg: to the ideas of structural isomerism and valence requirements). Moreover, it could be used to test comprehension of nomenclature, particularly for more advanced students. For instance, I have enjoyed entering formulae and challenging others to assign International Union of Pure and Applied Chemistry (IUPAC) names to the resulting structures.

In closing, I must point out that the program described here is only a beginning. Several potential improvements immediately spring to mind. One is the possibility of the Apple drawing three-dimensional representations. Also, anyone with much chemical background will quickly realize that many structures generated by the program are rather unlikely, if not practically impossible. For instance, the Apple does not hesitate to draw cyclopropadiene, an impossibly strained ring. It might be possible to teach the Apple such concepts as ring strain and Bredt's rule; however, I am not sure if that would be desirable. Much of the program's charm derives from its naive approach to molecular assemblage, yielding delightfully unexpected structures. And who knows? Recent experience in organic synthesis has demonstrated that improbable structures are not always impossible. ■



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Book Reviews

What Computers Can't Do

Hubert L Dreyfus
Harper and Row
New York 1972
hardcover, 259 pages
\$10.95

Brain, Mind and Computers

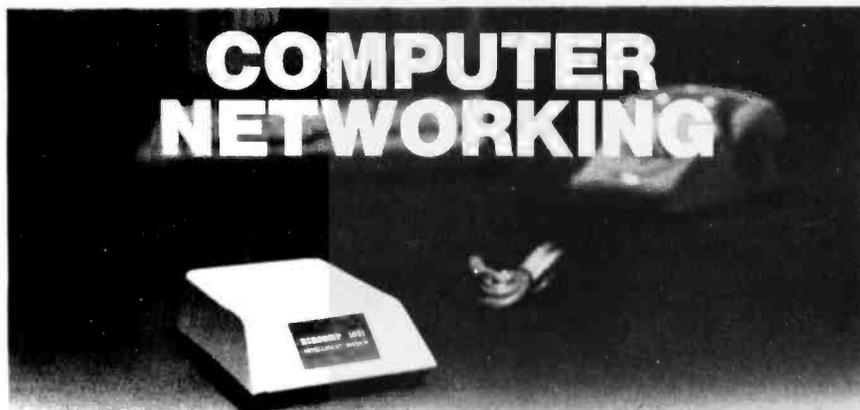
Stanley L Jaki
Gateway Editions
1969
softcover, 267 pages
\$4.95

What Computers Can't Do and *Brain, Mind and Computers* are two widely available critiques of artificial intelligence. Their authors bring somewhat different credentials to the task. Hubert Dreyfus is a philosopher who has worked in artificial intelligence research for well over a decade, and Dr Jaki is a theologian concerned with the philosophy of science.

What Computers Can't Do is a follow-up on a RAND Corporation paper which Dreyfus did in the mid-1960s. The question he raises is why, after the rapid advances in artificial intelligence research during the 1950s, was there such a slowdown in results during the 1960s and early 1970s? Many of the results which were forecast for the period 1969 thru 1979 never occurred (such as general-purpose language translation, innovative work in mathematics by computers, etc). Dreyfus believes that there are a number of mistaken assumptions underlying the hopes in artificial intelligence research; assumptions about how we think and about the nature of the world. His conclusion is that more attention must be paid to the ways in which humans think about things and how these differ from the ways in which computers work. He argues that the result of this is a classification of tasks into different groups, some of which are definitely fair game for machines, some of which pose serious problems, and some of which are not likely to yield human-type performance to computers as they are presently designed.

Overall, this book is very interesting reading, and contains well-thought-out discussions of many of the issues in artificial intelligence research.

Brain, Mind and Computers was originally published ten years ago and has since been reissued. It is ostensibly a discussion of artificial intelligence research; it is in fact a refutation of physicalism, which the author maintains is synonymous with determinism. While discussing artificial intelligence at length, Dr Jaki never defines what he means by it; he seems to mean a machine which will be fully equivalent to the human mind in all respects. Given this implicit definition, the task of arguing against the possibility is simplified.



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The MAGIC WAND allows you to set the left, right, top and bottom margins, page length, indentation, paragraph indentation, (including "hanging" paragraphs), text left flush, right flush, justified (two ways), literal or centered, variable line and pitch settings, variable spacing (including half lines), bold face, underlining (solid or broken), conditional hyphenation, sub- and superscripting. You may change any of these commands at run-time *without reformatting the file*.

Merging with external data files

You may access any external data file, with either fixed length or sequential records. The MAGIC WAND converts the record into variables that you define and can use like any other variable. Of course, you may use the data for automatic form letter generation. But you can also use it for report generation.

Variables

You may define up to 128 variables with names of up to seven characters. The current value of a variable may be up to 55 characters, and you may print it at any point in the text without affecting the current format. Although the MAGIC WAND stores the variables as strings, you may also treat them as integer numbers or format them with commas and a decimal point. You may increment or decrement numeric variables or use them in formatting commands.

Conditional commands

You may give any print command based on a run-time test of a pre-defined condition. The conditional test uses a straightforward IF statement, which allows you to test any logical condition of a variable. You may skip over unneeded portions of the file, select specific records to print, store more than one document in a single file, etc.

True proportional printing

The MAGIC WAND supports proportional print elements on NEC, Diablo and Qume printers. Other formatting commands, including justified columns, boldface, underline, etc., are fully functional while using proportional logic.

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Brain, Mind and Computers is an excellent guide to the history of physicalism in scientific thought. The computer is taken as a metaphor for "machine," and artificial intelligence is taken in its strongest sense—a sense that is almost unknown in the current artificial intelligence research literature.

John A Lehman
716 Hutchins #2
Ann Arbor MI 48103

Z80 Software Gourmet Guide and Cookbook

Nat Wadsworth
Scelbi Publications, 1979
softcover, 322 pages
\$14.95

The *Z80 Software Gourmet Guide and Cookbook* is one in a series of such books which Scelbi has published; previous "cookbooks" have appeared for the 8080 and the 6800

processors. The primary theme behind these books is to explain how to perform common assembly-language programming tasks for the various microprocessors, and to provide tested routines for these tasks which can be included as part of larger programs.

The Z80 volume covers the Z80 instruction set, utility operations (such as multibyte arithmetic), stack operations, input/output (I/O) processing, character-code conversion, searching

and sorting, decimal arithmetic, and floating point arithmetic. These topics were also covered in the 8080 volume. Additional chapters in the Z80 book include one that presents a simple space-capture game, and one entitled "Creative Programming Concepts," which discusses data structures. Appendices include the Z80 instruction set, character code and number-base tables, and hexadecimal object code dumps for the major programs in the book.

The first question that comes to mind is, "How does this book differ from the 8080 volume?" Obviously, the sections on the instruction set are changed. Besides having many more instructions to explain, the Z80 book uses Zilog mnemonics. Unfortunately, much of the rest of the book contains the old 8080 code with new mnemonics. Even the discussion of interrupts in the I/O section treats only mode 0 (8080-compatible), which is probably the least useful for anyone not trying to write 8080-executable code.

Another example of the lack of changes: absolute-jump instructions are used throughout the book where almost any Z80 programmer would use relative jumps. The major changes in the book then seem to be the discussion of the instruction set, the two new chapters, and the fact that the floating point routines appear to be shorter. If you have the 8080 volume, do not purchase this volume.

If you do not have the 8080 volume, then that is another story. Whether you want to convert American Standard Code for Information Interchange (ASCII) to Baudot code (or Selectric correspondence code), parse an input string, change number representations, fill memory, write timing loops, or whatever, you will probably find just the subroutine you are looking for. I have been taking subroutines out of the 8080 version of this book for two years now, and have yet to

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have one not work.

In conclusion, if you already have the *8080 Software Gourmet Guide and Cookbook*, just buy Scelbi's *Z80 Instruction Handbook*; the two together will give you almost everything in this volume, and you will save the cost of a floppy disk or two. If you do not have the 8080 volume, then the *Z80 Software Gourmet Guide and Cookbook* could be a good addition to your

assembler reference library.

John A Lehman
716 Hutchins #2
Ann Arbor MI 48103

BASEX

Paul Warme
BYTE Books
Peterborough NH, 1979
softcover, 97 pages
\$8

BASEX is an interactive compiler written for the 8080 family of computers. The book is complete with bar code, source listing and machine code listing.

Many language systems for microprocessors are written as interactive interpreters which do not convert the sentence-like statements of the language into machine code, but simply perform the command in each line of source program as the line is

scanned. In short, the language system interprets statements and performs tasks via interpretative run-time routines. In contrast, a compiler does not immediately execute statements in source code, but translates the source code into object code which can be directly executed by the machine.

There are advantages to both approaches in implementing a computer language, and I simply will refer the reader to the almost never-ending discourse in any of the computer journals for the facts and opinions. My bias is towards use of compilers.

When you purchase BASEX, you receive a well-written document describing an interesting approach to compiler construction. First, you get a complete assembler source listing of all the run-time routines that add, subtract, multiply, and divide; and that perform memory block-move, memory read, memory write, memory compare, accumulator OR operations; plus routines that perform input and output. You also get a listing of the BASEX compiler and a relocating loader, both written in BASEX. What you do not get is floating point math, error messages, error recovery operations, and mass storage operations.

I bought BASEX to see if it could be used in a business environment. It simply is not sophisticated enough for business use, but it is ideal for text editors, disk operating systems, and other applications where high speed, simple math, and well-defined static applications prevail. If serious use of BASEX is contemplated, the following should be developed:

- mass storage capabilities;
- error intercept and recovery routines;
- a trace function for debug purposes;
- a binary look up routine for the symbol table; and
- routines to let the compiler perform memory



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management for line insert and delete.

Linking BASEX to CP/M

BASEX may be run as a command (COM) file under CP/M. First, enter the entire BASEX compiler into your computer. If you do not have a bar-code reader, prepare yourself for a three-hour exercise in data entry. Next, move the code residing at hexadecimal locations 0000 thru 0103 to hexadecimal locations 2000 thru 2103. Then place a JMP

instruction at location 0100 which causes a branch to hexadecimal location 2105 (object code C3 05 21). At memory location 2105 assemble the following:

```

MOVIT LXI H,2000H
      LXI D,0H
      MOV A,M
      STAX D
      INX D
MOV   A,D
      CPI 01H
      JNZ MOVIT
      MOV A,E
      CPI 03H
      JNZ MOVIT
      JMP 0H
  
```

Follow the instructions in the BASEX book for changing I/O addresses in BASEX. Now save BASEX with CP/M as "BASEX.COM". Now type BASEX. You should be able to start using BASEX, unless you made an error somewhere.

I would be interested in hearing other readers' experiences with the BASEX compiler.

Wayne F Miller
905 Fairmont
Jefferson City MO 65101

BYTE's Bits

Wozniac Receives 1979 ACM Grace Murray Hopper Award

Stephen Wozniac, Vice President of Research and Development for the Apple Computer Co, Cupertino, California, received the Association for Computing Machinery (ACM) Grace Murray Hopper Award for "his many contributions to the rapidly growing field of personal computing and, in particular, to the hardware and software for the Apple Computer." The award acknowledges his work on programmable pocket calculators which he accomplished while employed by Hewlett-Packard. The annual award is given in recognition of achievements in the computer field made before attaining the age of 30. The \$1000 award is donated by Sperry Univac, a longtime employer of Dr Hopper.

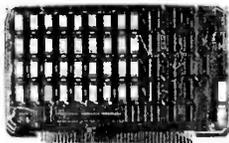
Real-Time BASIC Available Free

If you are doing process control applications in real time, you should investigate Lawrence Livermore Laboratory's (LLL) version of BASIC. It was developed with public funds, hence copies are available for just the duplication fee. Contact Harry Edwards, National Software Center, 9700 S Cass Ave, Bldg 221, Argonne IL 60439.

LLL BASIC was designed to run on an 8080-based system. The interpreter can execute BASIC source code contained in a read-only memory. A companion compiler can produce faster and more efficient object code. LLL BASIC has machine control statements and works with the Advanced Micro Devices AMD9511 mathematical-function integrated circuit for faster execution time. ■

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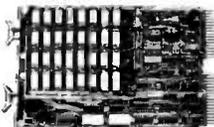
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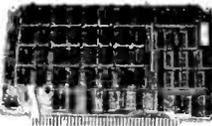
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Clubs and Newsletters

International Computer Chess Association

The International Computer Chess Association was established at the Second World Computer Chess Championship in Toronto in 1977. It currently has about 200 members, and publishes

the *ICCA Newsletter* three or four times per year. The cost of membership for a single year is \$10 in US funds. Contact Professor Ben Mittman, Vogelback Computer Center, Northwestern University, Evanston IL 60201.

Lincoln Micro-Computer Club

This club has changed its name from the Lincoln Computer Club to the present name. They meet on the first Wednesday of each month at 7 PM at the State Federal Savings and Loan on

40th St and South St in Lincoln, Nebraska. The club is open to users and owners of all types of microcomputers. Yearly subscription fees are \$5. Contact Hubert Paulson Jr, 1209 Garber Ave, Lincoln NE 68521.

Micro

This club is open to users and owners of microcomputers. The members meet at 9:30 AM on the second Saturday of each month at the NWTI in Green Bay, Wisconsin. Contact Stuart Mong, 1824 Glenview Ave, Green Bay WI 54303.

Change in Meeting Place for Chicago Area Computer Hobbyist's Exchange (CACHE)

The CACHE group meets at the same time but now at the DeVry Technical Institute, 3300 N Campbell, Chicago IL. This is one block west of Western Ave.

New Information on the AIM-65 Newsletter

For information on AIM-65, contact Target, c/o Don Clem, RR 2, Spencerville OH 45887. Inquiries should include a self-addressed, stamped envelope and all orders must be prepaid. Sample copies are \$1 each; a bi-monthly, one year subscription is \$5 in the US and Canada and \$12 (airmail) elsewhere.

CP/M Users Group

The Washington CP/M Users Group generally meets on the third Wednesday of each month at members' homes. Most members own S-100 disk systems with a variety of microprocessors, disks, terminals, printers, and boards. CP/M is the format of software exchange and the subject of frequent meetings. Annual dues are \$6, primarily to cover postage. Contact Winston Riley III, 7315 Wisconsin Ave, Washington DC 20014.

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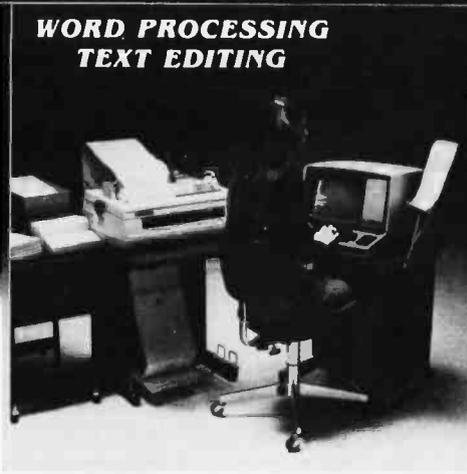


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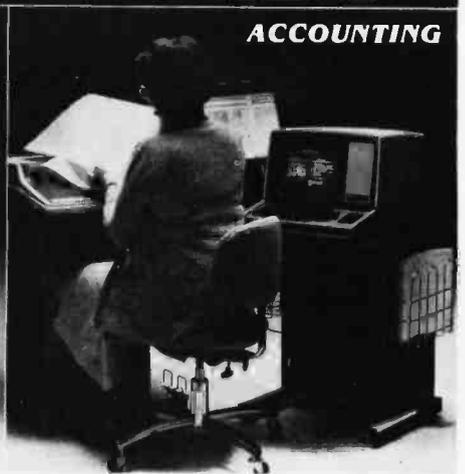
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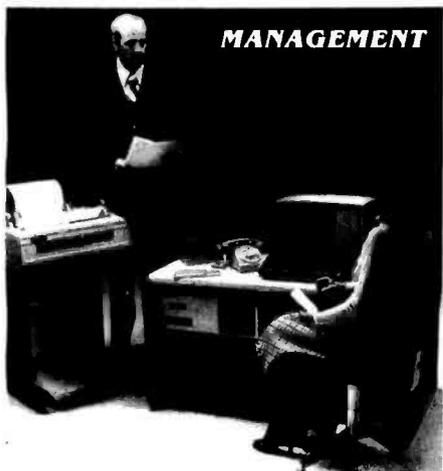
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Wyoming Valley Computer Club

The TRS-80 users club in Pennsylvania is seeking new members. The Wyoming Valley Computer Club meets on the second Tuesday of every month at 7:30 PM at the Artco Electronics building in Kingston, Pennsylvania. There is a monthly newsletter for all members. For more information, contact Art Prutzman, Artco Electronics, 302 Wyoming Ave, Kingston PA 18704.

Apple Educators' Newsletter

This publication is devoted to educators and researchers using the Apple II system and other compatible systems. Articles concerning educational programs, grants for microcomputers and education, exchanges of ideas using computers in education, and general items are featured. Contact *Apple Educators' Newsletter*, 9525 Lucerne, Ventura CA 93003.

Apple Users Group in Arlington TX

The Fort Worth Apple Users Group (FWAUG) has been created to help users, owners and beginners understand and fully utilize their Apple II systems. The group meets on the third Sunday of each month at 3 PM at the CompuShop Store, 6353 Camp Bowie, Fort Worth TX. The group has a software program exchange and a library for members. The *FWAUG*

Newsletter is an eight-page monthly publication, sent to all members. Dues are \$9 per year. For more information, contact FWAUG, c/o Lee Meador, 1401 Hillcrest Dr, Arlington TX 76010.

OSI Superboard Club

This newsletter contains programs, ideas, technical data, hints and suggestions on the use of Ohio Scientific Challenger IP and Superboards. The newsletter will be published every two months. Send a self-addressed business envelope and \$1 for further information to Superboard Club, POB 55, Agincourt, Ontario M1S 3B4 CANADA.

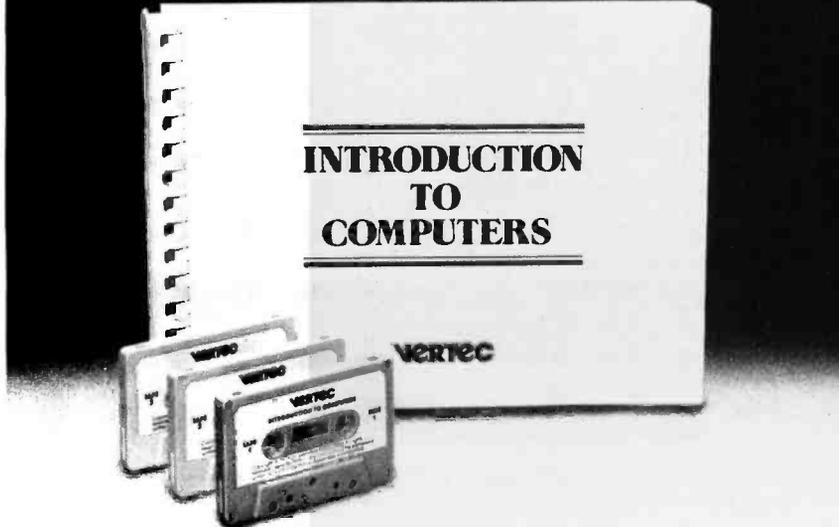
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The DCN is a group of dentists, physicians and office management people that have interests in computers. DCN offers members a monthly newsletter, software exchange, advice and experience, and access to members in specific areas. Annual membership dues are \$12 per year. Back issues of the *Dental Computer Newsletter* are \$1 each and \$10 per year. Membership and equipment listings are \$5. Commercial software lists and DCN software exchange lists are free with a \$0.28 stamped, self-addressed envelope. Contact *Dental Computer Newsletter*, E J Neiburger, editor, 1000 North Ave, Waukegan IL 60085.

Computer Law Journal

Each issue of the *Computer/Law Journal* is devoted to a single topic of computer law, and contains feature articles by experts in the field, a comprehensive bibliography on the featured topic, case digests of all significant court and administrative agency decisions on the topic, and other reference materials. Topics have included patent protection of computer software and computer-assisted legal research. Future issues will

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focus on computer related evidence, electronic funds transfer systems (EFTS), computer crimes and software taxation. The journal is published by the Center for Computer Law, 530 W 6th St, 10th Floor, Los Angeles CA 90014.

Scampus

Articles on bus structures, software, conversion circuits and other aspects of micro-computers are covered in this monthly newsletter. The

material comes from members of the group, so ideas and items are constantly needed and welcomed. There are no membership fees. A large supply of self-addressed, stamped envelopes are the only requirements. Write to *Scampus*, POB 132, Knob Noster MO 65336.

Another Apple II Club

The Adam and Eve Apple II Users Group meets at the

Madison Public Library in Madison, Wisconsin on the second Tuesday of each month at 7 PM. The group wants to exchange newsletters and software with other groups and receive advice on software. Adam and Eve is a subscriber of *The Source*, an information network. The dues are \$1 per meeting or \$3 per year for the *Adam & Eve Newsletter*. For more information, write to Adam and Eve, Apple II Users Group, 11 S Hancock St, Madison WI 53703. ■

BYTE's Bugs

Reversi Bug Makes Computer End Game Too Quickly

Several readers have pointed out a problem in the program published in "Programming Strategies in the Game of Reversi," November 1979 BYTE, page 66. In the program given in listing 1, the published code behaves in the following manner. Either after you have twice forced the computer into a position where it has no legal moves, it concedes the game and resigns; or after the computer has forced you into a moveless position twice, it declares itself to have won the game. Thanks to Darrell Pittman, Jack Guinnip, Delmer Hinrichs, Willy Verwoerd, and Betty Vogel for spotting the error.

Mr Guinnip deserves special praise, not only for spotting the error so quickly, but for doing it while working through the program with pencil and paper. He does not have access to a computer, as an inmate of the Sheridan Correctional Center in Illinois.

A simple patch suggested by Mr Pittman was published in the February 1980 BYTE on page 168, but readers may instead wish to make the somewhat more complete correction suggested by Mr Hinrichs. This includes a change to line 1382 and insertion of two other lines:

```
1382IF B(K) = THEN 1396
1396LET T3 = 0
1398RETURN
```

To improve the quality of play, Ms Vogel suggests that line 4200 be deleted, and that line 5310 be changed to read:

```
5310LET E(79) = 5
```

Peter B Maggs
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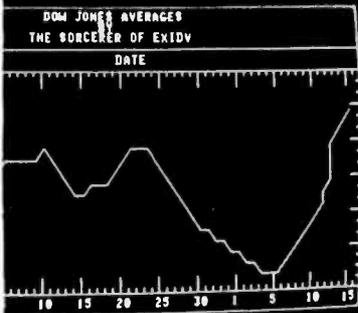
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Product Reviews

Lucidata P-6800 Pascal

Phil Hughes, POB 2847, Olympia WA 98507

If you own a Southwest Technical Products Corporation (SwTPC) compatible system that runs Technical Systems Consultants' FLEX 2.0 or mini-FLEX operating system, you too can use Pascal. P-6800 Pascal is a substantial subset of full Pascal, and is designed for a SwTPC with FLEX or mini-FLEX.

I mailed my order for P-6800 Pascal, and thirteen days later the manual and disk arrived. I would consider this excellent delivery if Lucidata were in Kansas, but they are in the Netherlands! Even if it had not worked, I think I would have been amazed.

Two major items missing from this Pascal subset are the REAL and RECORD data types. Also missing are some of the capabilities of other directives. For example, the TYPE directive only supports enumerated types.

Looking at the capabilities in a more positive light, files, procedures, functions, recursion, and multidimensional arrays are supported. The branching constructs IF . . THEN . . ELSE and CASE . . OF as well as the looping constructs REPEAT . . UNTIL and WHILE . . DO are also supported. Data types that are supported are BOOLEAN, CHAR, ALFA (six-character string), INTEGER, and BYTE as well as scalars which can be made members of sets.

The standard input/output (I/O) procedures (RESET, REWRITE, READLN, WRITELN, READ, WRITE) are defined, as are the standard ordinal and predicate functions ORD, CHR, SUCC, PRED, ODD, EOF and EOLN. Additionally, the procedures HALT and POKE are defined as are the functions PEEK and USER.

The compiler generates pseudocode (p-code) that is in-

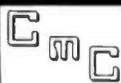
terpreted by the run-time system. The run-time system simulates the Pascal P-machine. For those unfamiliar with Pascal, this is a standard approach. The P-machine is a theoretical, stack-oriented machine designed specifically for execution of Pascal. This makes it possible to transport the compiler to another machine by writing a p-code interpreter for the new machine.

The Lucidata run-time system allows automatic paging of the p-code file. In other words, if all of the p-code for your program does not fit in available memory, the run-time system reads it in pieces from a disk as required. Because of this feature, it is possible to run the compiler in 12 K bytes (plus 4 K or 8 K for mini-FLEX or FLEX).

The manual describes this particular subset of Pascal in detail, then discusses the run-time system. This includes a description of how to use files. The memory requirements are discussed next. This includes how to estimate memory required for p-code, stack, and file buffers, and for the run-time system. The estimation of disk storage requirements is also discussed. The final chapters cover fine tuning of your programs and the run-time system. The customizing of the run-time system includes interfacing your program to assembly language subroutines and support of non-FLEX-compatible peripheral devices.

Five appendices are included. The first is the syntax diagrams for P-6800 Pascal. Next is a list of compiler error messages. Then there is a list of run-time error messages. The fourth appendix consists of sample programs that demonstrate most of the system capabilities. These sample programs are also on the system disk so you can play with them. The last appendix is a bibliography of further reading on Pascal.

What you receive is a P-6800 Pascal compiler and run-time package, a good manual, sample programs, and excellent delivery. If you are running FLEX 2.0 or mini-FLEX, the Pascal system can be installed in a few minutes. The P-6800 package costs \$150.00 from Lucidata, Oosteinde 223, 2271 EG Voorburg, Netherlands. Their telephone number in the Netherlands is 70-862387. ■



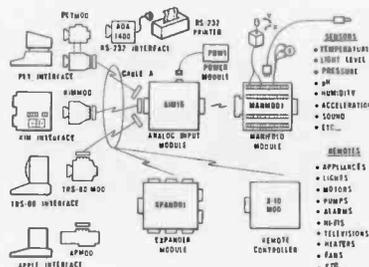
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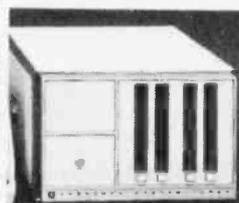
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Technical Forum

The Direct Impact of the Computer

Richard S Shuford, Editor

Some years ago, I was doing volunteer work for a non-profit organization. Late one evening we were preparing an important newsletter for mailing the next day. We had used a computer at Lenoir-Rhyne College, where I was a student, to prepare our adhesive address labels. We had pasted on all the labels when we found that our rubber stamp that said "ADDRESS CORRECTION REQUESTED" had been lost.

Groaning over our misfortune, we were just about to begin the time-consuming task of writing this message on every envelope by hand, when I had the following thought: the computer printed the address labels for us; why can't it print *this* simple message?

I began to consider how the job could be handled using the computer facilities available. Adhesive labels were too expensive to print the message on and then affix to the envelopes. But wait, perhaps we do not have to use the labels. Could the computer printer print directly on the envelopes?

A time-honored principle is that if there is a simple test to be made, make it. So I gathered up several newsletter envelopes and hastened to the college's academic computer center to try it.

The particular printing peripheral I had in mind was a Centronics Model 101A, high-speed, serial character impact printer, which we loosely called a "line printer." This Centronics machine prints dot-matrix characters by driving a column of print pins into an inked ribbon held before the paper as the print head moves horizontally. (Many other printers also work in this manner.) The Centronics printer has a paper-thickness adjustment, which soon became important.

The Centronics printer was attached to a minicomputer timesharing system. I logged into the system, and quickly wrote a BASIC program. After a brief period of experimentation, I saved my program, logged out, and dashed back to the other late-night envelope-stuffers to report success.

I led a disbelieving troop of workers carrying stacks of envelopes back to the computer room to see how I was going to save them a lot of work by letting the machine do some. My demonstration worked like this.

I logged in and called up the BASIC program I had written for my experiment. This program is shown in listing 1. I typed "RUN" on my terminal, and with one hand held a newsletter envelope carefully inside the print position of the Centronics printer, just behind the ribbon. As the others crowded around to see what I was doing, I hit the carriage return key on the terminal with my free

hand. The print head buzzed and moved across the envelope. I held up the letter, and all could see that "ADDRESS CORRECTION REQUESTED" was plainly printed on it in dot-matrix characters.

Well, we set up an assembly line to insert envelopes into the printer and then to stack them. We found that using the computer printer actually was faster than using the rubber stamp, but I do not recommend buying a computer if you can get by using a rubber stamp under normal conditions. The computer did allow us to get our mailing out on time. (Later on, of course, it was not so much fun to pay \$0.25 for every corrected address that came back, but we got our mailing list updated).

If you want to try to use this rubber-stamp simulator, observe these points. The print head can move very fast, and you *can* hurt yourself if you are not careful as you hold the paper inside the printer. You have to be sure to hold the paper in the right place. With the Centronics, the right place is approximately 5 cm (2 inches) to the right of the print head's rest position, behind the ink ribbon. Timing is not critical with this program. Note that the program requires that you press the return key before it will print anything. There is no rush to insert the paper into the printer, since you just hit the key when you are ready.

Finally, note that the paper-thickness adjustment is fairly critical for printing on an envelope that has a newsletter in it. Adjust carefully, so that the print head neither shreds the envelope, nor fails to print, nor jams and becomes damaged.

The moral of this story is not that rubber stamps are obsolete. Rather this: a general-purpose computer system is *exactly* that—general purpose. If you buy a computer to assist you in keeping up with your tax records or the like, that is fine. But don't forget that the *program* determines the function of the computer. The next time you have a problem, whether simple or complex, perhaps the computer can help you with it.

Listing 1: A BASIC program that uses a computer equipped with an impact printer to simulate a rubber stamp in printing a simple message many times.

Line 10 determines what message is printed. Lines 20, 30, and 40 print the message on the terminal for verification. Line 50 is used to give the human operator time to put the paper inside the printer in the correct position. The computer will not output the message to the printer until the operator presses the return key in response to the INPUT statement in line 50. Variable B\$ is merely a dummy variable.

The LPRINT statement in this version of BASIC causes output to the line printer. The TAB(10) function causes 10 spaces to be printed before the message. Line 70 causes the program to loop indefinitely. Execution must be terminated by some means provided by the system. Such a means could be typing control-C, pressing a Break key, or hitting a Reset switch.

```

5 REM RUBBER STAMP SIMULATOR
6 REM USE WITH COMPUTER IMPACT PRINTER
10 A$ = "ADDRESS CORRECTION REQUESTED"
20 PRINT "HIT 'RETURN' KEY TO PRINT"
30 PRINT A$
40 PRINT "WITH PRINTER."
50 INPUT B$
60 LPRINT TAB(10); A$
70 GOTO 50
99 END ■

```

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Technical Forum

Cutting the Gregorian Knot

Myron Pulier MD, 101 Cedar Ln, Teaneck NJ 07666

Program development is more an artistic process of playful reshaping than it is an analytic process of systematic logic. This proved true in a search for an efficient way of handling dates in computer programs.

Using dates in Julian day-number form simplifies manipulation of date information. For example, if the Julian date of the calendar date January 1 is 1, then February 2 would be 33 and December 31 would be 365, or 366 on leap year. Clearly it is easier to store a single number than to wrestle with a number triplet like 9/8/79. Furthermore, the Julian concept makes finding the number of days between two dates a trivial process.

Calculation of the Julian date is complicated because Roman legislators altered Julius Caesar's orderly scheme by making the months uneven in length. This inspired Richard Grafton's famous table lookup. In the year 1570 he wrote "Thirty days hath November, April, June, and September," etc. While there's no longer much danger of copyright infringement, Grafton's method wastes memory space, rest his soul.

According to Grafton the months with thirty days are the eleventh, fourth, sixth and ninth, which seems difficult to convert into a formula. If only Grafton and his politician forebears had given the second month thirty days as well! We would then be close to the familiar sequence 2,4,6,8,10, which can be calculated by the formula $B = 2 \times A$. If we plot the numbers 2, 4, 6, 9, 11 as the first, second, third, fourth, and fifth numbers of a set (as shown in figure 1), all we need is a formula that threads a line slightly above the desired values for B. We can then throw away the fractional parts by truncating the resulting B value to an integer. In other words, we want a formula of the form:

$$B = \text{INT} (C1 \times A + C2) \quad (1)$$

The determination of suitable values for the constants C1 and C2 may not be immediately obvious. An empirical method for finding C1 and C2 is trial-and-error substitution using the following BASIC program:

```

110 INPUT C1, C2
120 FOR A = 0 TO 13
130 LET B = C1 * A + C2
140 PRINT A, INT ( B ), B
150 NEXT A
160 GOTO 110
    
```

I suggest you enter the above program on your own computer and try values for C1 and C2.

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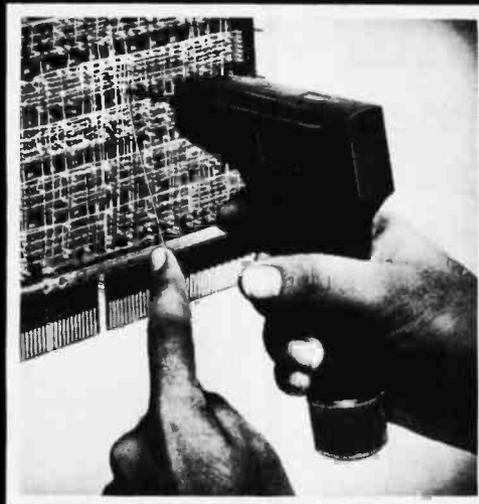
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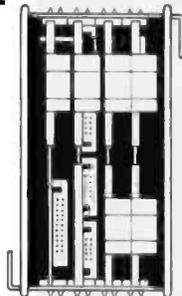
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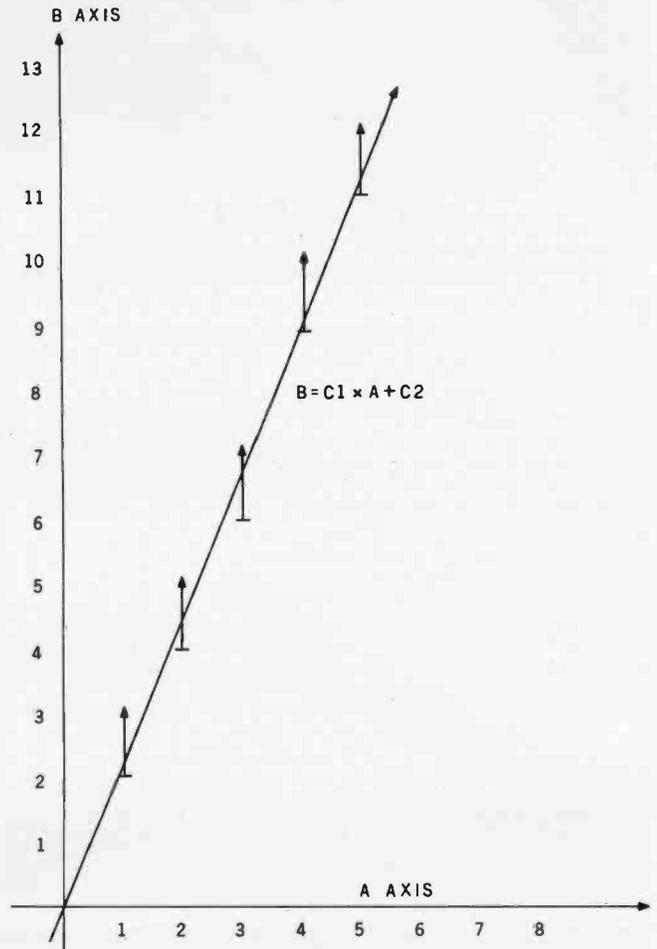


Figure 1: Fitting the numbers 2, 4, 6, 9, 11 to the straight-line equation $B = C1 \times A + C2$. Given the sequence 2, 4, 6, 9, 11, we can represent this in two dimensions by letting the horizontal axis represent the order of the number in the sequence (first, second, etc), and the vertical axis, the value of the number (2, 4, etc). Thus, the fourth number in the sequence, 9, gives the point (4,9) to be plotted. These numbers are almost, but not quite, on a straight line. But if we stipulate that the line can go through the unit line segments extending above each point, then the integer values can be obtained by truncating the values obtained with the INT function in BASIC.

Playing around with this program shows that C1 can range between 2 and 2.5 if C2 is suitably chosen between -0.5 and 1. For example, setting C1 to 2.25 and C2 to 0 gives the desired sequence of 2,4,6,9,11, . . . for INT(B).

Now we can turn our attention to the irregularities in the Gregorian calendar. First, let us temporarily give February thirty days (remember that month 2, February, is included in the above sequence). Next, calculate the Julian values of the last days of each month in this altered year. The numbers are 31, 61, 92, 122, 153, 183, 214, 245, 275, 306, 336, 367. (The extra two days in February give us a 367-day year). Can we find a formula that threads its way along the last days of each month?

We have 367 days divided among 12 months. That comes to a new month about every 30.58 days. If we use 30.58 for C1 in the program we wrote, we find that the output comes close to the sequence we want. A few minutes of tinkering with C2 shows that 0.5 works nicely. The expression M-1 gives us the last day of the

preceding month. Substituting the values for C1 and C2, and using (M-1) in place of A in equation (1) produces the equation:

$$B = \text{INT} (30.58 \times M - 30.08) \quad (2)$$

A quick check with our BASIC program shows that we can get away with three bytes less with the following equation:

$$B = \text{INT} (30.57 \times M - 30) \quad (3)$$

If we compensate for leap years and for the 28-day February, we have the following BASIC subroutine for computing the Julian date, Z, given the month, M, day, D, and year, Y.

```

210  Z = INT ( 30.57 * M - 30 ) + D
220  IF M < 3 THEN RETURN
230  IF INT ( Y / 4 ) * 4 = Y
      THEN Z = Z - 1 : RETURN
240  Z = Z - 2 : RETURN

```

Using the constant values we found for equation (3), line 210 calculates the Julian date of the end of the month preceding month M. Adding the day of the month to this produces a first estimate of the Julian date of the given calendar date. Line 220 says that if it is before March, we are done. Otherwise, in line 230 we adjust for a 29-day February if it is leap year (until now we were crediting February with 30 days), or for 28 days if it is not leap year. Let us forget about leap centuries for now.

We can improve on this system. We have been defining the Julian date, Z, as the number of days since the previous December 31. To include information about the year, we can define a new type of Julian date, J, as the number of days elapsed since December 31 of some base year, say 1972. To calculate J, we first find Z, then add the days in each year between the present year and 1972. Years have an average of 365.25 days. If we try 365.25 for C1 and 0 for C2 in our original BASIC program tool, we get the Julian dates of the last day of each year. Taking December 31, 1972 as our base and the year, Y, in the form "yy" rather than "19yy" we modify equation (3) to:

$$B = \text{INT} (30.57 \times M - 30) + \text{INT} (365.25 \times (Y - 1 - 72)) \quad (4)$$

This may be rearranged to:

$$B = \text{INT} (30.57 \times M) + \text{INT} (365.25 \times Y - 26693.25) \quad (5)$$

bringing us to the new BASIC subroutine:

```

310  J = INT ( 30.57 * M ) + INT ( 365.25
      * Y - 26693.25 ) + D
320  IF M < 3 THEN RETURN
330  IF INT ( Y / 4 ) * 4 = Y
      THEN J = J - 1 : RETURN
340  J = J - 2 : RETURN

```

The above will return negative values for dates before December 31, 1972.

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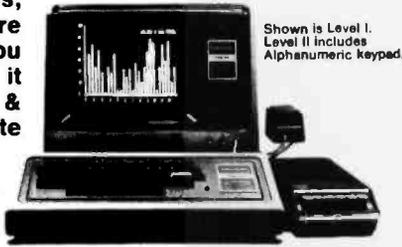
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Listing 1: BASIC routines for converting between the Julian date and the calendar (month, day, year) date and for determining the day of the week from the Julian date. In Processor Technology BASIC, the multiple-line user-defined functions (ending with FNEND) are permitted; also, J\$(A,B) is the substring of the unsubscripted string variable "J\$", from Ath to Bth character.

```

700 REM=====
710 REM
720 REM.          DATE HANDLING PACKAGE
730 REM
740 REM=====
750 REM-----
760 REM.  CALENDAR TO JULIAN CONVERSION
770 REM
780 REM.Given day, D, month, M and year, Y
790 REM.returns the number of days elapsed
800 REM.since December 31, 1900.
810 REM-----
820 DEF FNJ(D,M,Y)
830 LET X=INT(30.57*M)+INT(365.25*Y-395.25)+D
840 IF M<3 THEN RETURN X
850 IF INT(Y/4)*4=Y THEN RETURN X-1
860 RETURN X-2
870 FNEND
880 REM
890 REM-----
900 REM.  JULIAN TO CALENDAR CONVERSION
910 REM
920 REM.Given D, number of days elapsed since
930 REM.December 31, 1900, returns day, D,
940 REM.month, M, and year, Y.
950 REM-----
960 LET Y=INT(J/365.26)+1
970 LET D=J+INT(395.25-365.25*Y)
980 LET D1=2: IF INT(Y/4)*4=Y THEN LET D1=1
990 IF D>91-D1 THEN LET D=D+D1
1000 LET M=INT(D/30.57),D=D-INT(30.57*M): RETURN
1010 REM.
1020 REM-----
1030 REM.  JULIAN COMPACTION
1040 REM
1050 REM.Given julian, J, returns 2-byte
1060 REM.representation of J
1070 REM-----
1080 DEF FNJ$(J)
1090 LET J1=INT(J/256): RETURN CHR(J1)+CHR(J-J1*256)
1100 FNEND
1110 REM
1120 REM-----
1130 REM.  JULIAN EXPANSION
1140 REM
1150 REM.Given J$, a 2-byte representation of a
1160 REM.julian, returns decimal value of julian
1170 DEF FNJ1(J$)=256*ASC(J$(1,1))+ASC(J$(2,2))
1180 REM
1190 REM-----
1200 REM.  DAY OF WEEK CALCULATION
1210 REM
1220 REM.Returns day of week (Sunday = 1) given
1230 REM.the julian, J
1240 REM-----
1250 DEF FNW(J)
1260 LET W=(J+1)/7: RETURN INT((W-INT(W))*7+1.1)
1270 FNEND
    
```

Now that we have a way of abbreviating the calendar date into a Julian date, we need a program for reversing the conversion. This is done by extracting the year, correcting for a 28- or 29-day February, then extracting the month to leave the day of the month as the remainder:

```

410  Y = INT ( J / 365.25 + 73 )
420  Z = J + INT ( 26693.25 - 365.25 * Y )
430  D1 = 2 : IF INT ( Y / 4 ) * 4 = Y
      THEN D1 = 1
440  IF Z > 91 - D1 THEN Z = Z + D1
450  M = INT ( Z / 30.57 )
460  D = Z - INT ( 30.57 * M )
470  RETURN

```

Line 420 computes the day of the year, Z. Then D1 is set to 1 if the year is a leap year, or 2 otherwise. Z is adjusted for the proper February length in line 440, if the day is after February. The month is extracted in line 460, leaving D, the day of the month. Unfortunately, the program above is wrong for New Year's Day after a leap year because the value for Y lags a bit. This can be managed by setting the divisor in line 410 to 365.26. The resulting inaccuracy will not cause trouble for thousands of years.

You will see that selecting 1900 rather than 1972 as the base year will save two bytes each in lines 310 and 420 and one in line 410. [Note: Astronomers calculate Julian day numbers using the date January 1, 4713 BC as a base; all historical dates become positive numbers. . . .RSS]

If your version of BASIC handles character strings, it can compact each non-negative Julian date into two bytes of storage, which could speed input and output of dates by a factor of four. The following routine in Processor Technology BASIC essentially converts the decimal value of the Julian date to a base-256 number:

```

510  J1 = INT ( J / 256 )
520  J$ = CHR( J1 ) + CHR( J - J1 * 256 )

```

where CHR (J1) is the character with the ASCII code J1. Converting the string J\$ back to a decimal value is done as follows:

```

610  J = 256 * ASC ( J$ ( 1 , 1 ) ) + ASC
      ( J$ ( 2 , 2 ) )

```

where J\$ (n , n) is the n-th character in J\$ and where ASC(C\$) is the decimal value of the ASCII code for C\$. The two bytes in J\$ can cover a span of $256 \times 256 / 365.25 = 179$ years.

The day of the week is readily calculated from the modulo 7 value of the Julian date. We can now reshape our programs into a compact and efficient package for handling dates between 1901 and 2080.

As for leap centuries, Pope Gregory luckily decreed the year 2000 a leap year, although 1900 was not. Century years not evenly divisible by 400 are not leap years. Therefore, the routines in listing 1 will be wrong for dates before March 1, 1900, but are useful for most practical applications. ■

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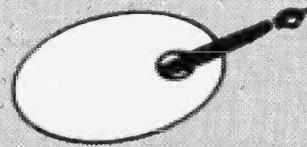
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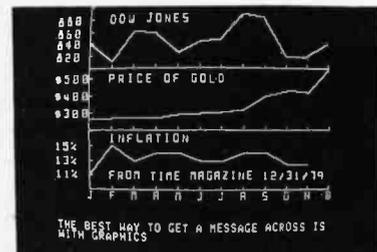


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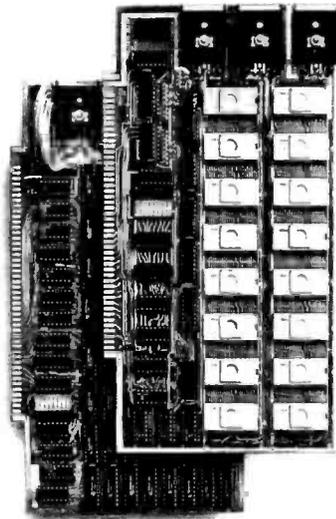
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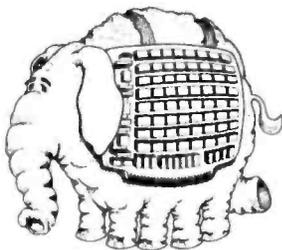
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Operation Codes of the 8080, 8085, and Z80 Processors

D Martin Harrell
313 Hollyberry Rd
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Manual conversion between assembly language mnemonics and hexadecimal object code can be tedious — particularly if much code is involved. However, the task does not have to be overwhelming. A conversion table helps immensely and is also a good training aid for novice programmers. It presents the entire instruction set in compact form, revealing useful patterns, and also inconsistencies.

8080 and 8085 Operation Codes

Operation codes for the Intel 8080 and 8085 microprocessors are shown in table 1. The only difference between the instruction sets for this pair is that the 8085 has two additional instructions: the read-interrupt-mask instruction (mnemonic RIM, hexadecimal code 20), and the set-interrupt-mask instruction (mnemonic SIM, hexadecimal code 30). They allow the user to control interrupts and a serial I/O (input/output) line, thus making them useful additions.

The position of an 8080/8085 operation code in the table does not give a reliable clue about the implied addressing mode. Table 1 is generally organized according to the operands involved. Residing in the middle eight columns of the table (columns 4 thru 8) for example, are the instructions for single-byte move, arithmetic, and logical operations. (Length attributes in this article refer to data, rather than instruction length, unless other-

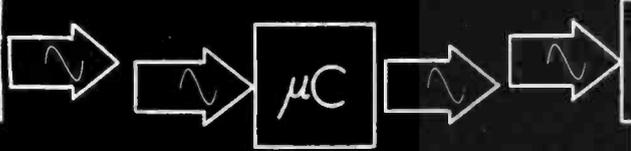
wise noted.) Regardless of the column, progression through the eight possible choices for the source (second) operand is always in the same sequence as the user moves down a column: registers B thru L; followed by memory reference; and finally, register A, the accumulator. Then, because each column has sixteen entries, the sequence repeats. If the arithmetic and logical instruction groups do not seem to conform to this rule, note that the first operand (always register A) is implied rather than stated explicitly.

This same sequence is used for advancing through choices for the destination (first) operand. In this case, however, progression is column to column from left to right, with each successive column containing two of the eight possible operands. The double-byte instructions also conform to this first-operand type of arrangement. Most of these appear in the first four columns of the table; however, the stack commands to PUSH and POP double-byte data are located at the far right in the top section.

An apparent inconsistency appears in the middle of the table. Hexadecimal code 76 is the instruction to halt the processor (HLT). Expected there instead is MOV M,M, the op code meaning "move the content of the memory location whose address is in the H and L register pair into that

Text continued on page 197

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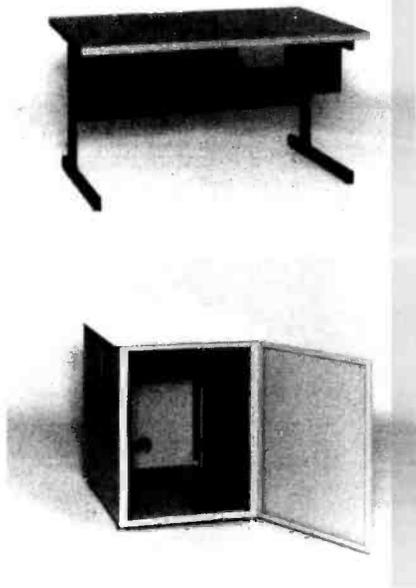
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0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
HOP		RNC	SYB	MOV B,B	MOV D,B	MOV H,B	MOV H,B	ADD B	SUB E	ANA B	ORA B	RNZ	RNC	RPO	RP
LXI B	LXI D	LXI H	LXI SP	MOV B,C	MOV D,C	MOV H,C	MOV H,C	ADD C	SUB C	ANA C	ORA C	POP B	POP D	POP H	POP PSW
STAX B	STAX D	SHLD	STA	MOV B,D	MOV D,D	MOV H,D	MOV H,D	ADD D	SUB D	ANA D	ORA D	JNZ	JNC	JFO	JP
INX B	INX D	INX H	INX SP	MOV B,E	MOV D,E	MOV H,E	MOV H,E	ADD E	SUB E	ANA E	ORA E	JMP	OUT	XTHL	DI
INR B	INR D	INR H	INR M	MOV B,H	MOV D,H	MOV H,H	MOV H,H	ADD H	SUB H	ANA H	ORA H	CNZ	CNC	CFO	CP
DCR B	DCR D	DCR H	DCR M	MOV B,L	MOV D,L	MOV H,L	MOV H,L	ADD L	SUB L	ANA L	ORA L	PUSH B	PUSH D	PUSH H	PUSH PSW
MVI B	MVI D	MVI H	MVI M	MOV B,M	MOV D,M	MOV H,M	MOV H,M	ADD M	SUB M	ANA M	ORA M	ADI	SUI	ANI	ORI
RIC	RAL	DMA	STC	MOV B,A	MOV D,A	MOV H,A	MOV H,A	ADD A	SUB A	ANA A	ORA A	RST 0	RST 16	RST 32	RST 48
				MOV C,B	MOV E,B	MOV L,B	MOV L,B	ADC B	SBB B	XRA B	ORF B	RZ	RC	RPE	RM
DAD B	DAD D	DAD H	DAD SP	MOV C,C	MOV E,C	MOV L,C	MOV L,C	ADC C	SBB C	XRA C	ORF C	RET		PCHL	SPHL
LDA B	LDA D	LDA H	LDA	MOV C,D	MOV E,D	MOV L,D	MOV L,D	ADC D	SBB D	XRA D	ORF D	JZ	JC	JPE	JM
DCX B	DCX D	DCX H	DCX SP	MOV C,E	MOV E,E	MOV L,E	MOV L,E	ADC E	SBB E	XRA E	ORF E		IN	XCHG	EI
INR C	INR E	INR L	INR A	MOV C,H	MOV E,H	MOV L,H	MOV L,H	ADC H	SBB H	XRA H	ORF H	CZ	CC	CPE	CM
DCR C	DCR E	DCR L	DCR A	MOV C,L	MOV E,L	MOV L,L	MOV L,L	ADC L	SBB L	XRA L	ORF L	CALL			
MVI C	MVI E	MVI L	MVI A	MOV C,M	MOV E,M	MOV L,M	MOV L,M	ADC M	SBB M	XRA M	ORF M	ACI	SBI	XRI	CPI
RRC	RAR	CMA	CNC	MOV C,A	MOV E,A	MOV L,A	MOV L,A	ADC A	SBB A	XRA A	ORF A	RST 8	RST 24	RST 40	RST 56

Table 1: Mnemonics of the operation codes of the 8080 and 8085 microprocessors arranged conveniently for conversion to the hexadecimal object code. This task is aided by the organizational consistency of the instruction set. The two instructions (RIM and SIM) found only in the 8085 are indicated by shading.

Text continued from page 194:

same memory location." The expected instruction is effectively just a slow equivalent of the no operation (NOP) located at hexadecimal 00. Hence, its replacement by the halt command improves, rather than degrades the power of the instruction set. Still, I wonder why an otherwise empty spot in the table was not chosen — as was done for the two additional 8085 instructions.

The right quarter of the table mainly contains program branching and data exchange instructions. Excluding the previously mentioned stack commands, none of these have explicit operands so the previously discussed organization is impossible. The miscellaneous nature of these instructions also tends to prevent predictable order.

Nonetheless, the op codes in this area have a consistent structural style. Most are arranged in complementary order, with mutually exclusive conditions placed in the same column, separated by eight rows. The group of return instructions is typical. The unconditional return from subroutine command is hexadecimal C9. Starting immediately above it and proceeding to the right, four of the eight conditional return instructions are found. The other four (the complements) are eight rows higher.

The order in which these conditions appear is uniform from group to group. To determine that this is so, compare similar elements of the call, jump, and return groups. The unconditional jump (JMP) instruction is a curious exception. Its expected code is CB, but it actually appears eight rows higher in the table. Such exceptions are few enough not to be bothersome.

Z80 Operation Codes

The Z80 is an enhanced version of the 8080. It runs faster, has twice as many general purpose registers, and has a much larger instruction set. Included as a subset in this instruction is the entire repertoire of the 8080. (This compatibility exists at the machine language level, but not the assembly language level; standard mnemonics and assembly language formats for the two processors differ considerably.) Thus, in hexadecimal object form, almost any program written for the 8080 will produce identical results when executed by a

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- (6). Dump BASIC program on disk for later appending.
- (7). Append BASIC program from tape.
- (8). Append BASIC program from disk.
- (9). Renumber BASIC program with standard beginning line number and increment.
- (10). Renumber BASIC program with custom beginning line number and increment.
- (11). Display contents of registers.
- (12). Display memory.
- (13). Execute machine language program starting at address in program counter.
- (14). Execute machine language program beginning at address given.
- (15). Exit to BASIC.
- (16). Compact BASIC program, removing all unnecessary spaces.
- (17). Eliminate from BASIC program range of line numbers given.
- (18). Display directory for disk drive #0.
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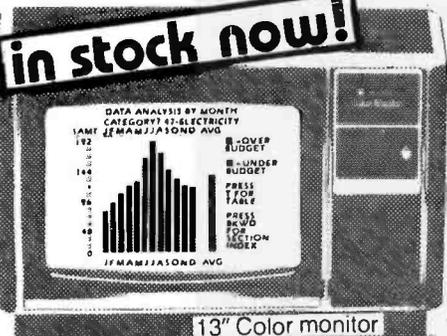
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Z80. Because of the Z80's generally higher speed, software timing loops are an exception to this upward compatibility feature. [Editor's note: There is also a slight difference in the operation of the parity flag . . . RSS]

The similarities of the two instruction sets can be seen by comparing corresponding positions of table 1 and table 2. Table 2 is the basic conversion table for the Z80. For every valid 8080 instruction in table 1, its correspondent in table 2 produces logically equivalent results. The differences between the two instruction sets stem from the twelve positions unused by the 8080. These, which are clearly indicated in table 2, are used to greatly expand the Z80's capability.

The Zilog Corp used the seven unfilled positions on the left side of table 1 and the uppermost one on the right side to give the Z80 processor the ability to perform relative branching and to exchange the contents of its two sets of registers. However, the use of hexadecimal codes 20 and 30 for two of the jump relative instructions means that the Z80 is not as compatible with the 8085 as it is with the 8080.

The real expansion of the Z80's instruction set over that of the 8080 is the result of the interesting use of the four other empty spaces in table 1. In essence, the Z80 uses them as pointers to four additional 16 by 16 tables, thus increasing the number of possible op codes by 1532. (The Z80 does not use most of these, but flexibility for future expansion is certainly there.) Had this innovative use of the unimplemented codes not been done, the Z80 would have been limited to 256 different op codes, which is only twelve more than the 8080.

There is a penalty for this flexibility: all instructions in these expansion sets must be multibyte. The first byte identifies the appropriate expansion instruction set, after which, the second byte identifies the operation to be performed. Sometimes there is an additional third or fourth byte to provide data or addressing information.

Shift, Rotate, and Bit Manipulation Instructions

Consider these pointer instructions one at a time. All of the instructions which begin with hexadecimal CB are contained in table 3. All of the direct-

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First Nybble

0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
NOP	LD HL, DE	LD HL, DE	LD HL, DE	LD B, B	LD D, B	LD H, B	LD (HL), E	ADD A, B	SUB B	AND E	OR B	RET NZ	RET NC	RET PO	RET P
LD BC, nn	LD HL, nn	LD HL, nn	LD SP, nn	LD B, C	LD D, C	LD H, C	LD (HL), C	ADD A, C	SUB C	AND C	OR C	POP BC	POP DE	POP HL	POP AF
LD (BC), A	LD (nn), HL	LD (nn), HL	LD (nn), A	LD B, D	LD D, D	LD H, D	LD (HL), D	ADD A, D	SUB D	AND D	OR D	JP NZ, nn	JP NC, nn	JP PO, nn	JP F, nn
INC BC	INC HL	INC HL	INC SP	LD B, E	LD D, E	LD H, E	LD (HL), E	ADD A, E	SUB E	AND E	OR E	JP nn	OUT (n), A	EX (SP), HL	DI
INC B	INC H	INC H	INC HL	LD B, H	LD D, H	LD H, H	LD (HL), H	ADD A, H	SUB H	AND H	OR H	CALL NZ, nn	CALL NC, nn	CALL PO, nn	CALL P, nn
DEC B	DEC H	DEC H	DEC HL	LD B, L	LD D, L	LD H, L	LD (HL), L	ADD A, L	SUB L	AND L	OR L	PUSH BC	PUSH DE	PUSH HL	PUSH AF
LD B, n	LD H, n	LD H, n	LD (HL), n	LD B, (HL)	LD D, (HL)	LD H, (HL)	HALT	ADD A, (HL)	SUB (HL)	AND (HL)	OR (HL)	ADD A, n	SUB n	AND n	OR n
RCA	DAA	DAA	SCF	LD B, A	LD D, A	LD H, A	LD (HL), A	ADD A, A	SUB A	AND A	OR A	RST 00H	RST 10H	RST 20H	RST 30H
ADD HL, BC	ADD HL, DE	ADD HL, HL	LD C, E	LD C, B	LD E, B	LD L, B	LD A, B	ADC A, B	SBC A, B	XOR B	CP B	RET Z	RET C	RET PE	RET M
LD A, (BC)	LD A, (DE)	LD HL, (nn)	LD A, (nn)	LD C, C	LD E, C	LD L, C	LD A, C	ADC A, C	SBC A, C	XOR C	CP C	RET	EX	JP (HL)	LD SP, HL
DEC BC	DEC HL	DEC HL	DEC SP	LD C, D	LD E, D	LD L, D	LD A, D	ADC A, D	SBC A, D	XOR D	CP D	JP Z, nn	JP C, nn	JP PE, nn	JP M, nn
INC C	INC L	INC L	INC A	LD C, E	LD E, E	LD L, E	LD A, E	ADC A, E	SBC A, E	XOR E	CP E	See Table 2	IN A, (n)	EX DE, HL	EI
DEC C	DEC L	DEC L	DEC A	LD C, H	LD E, H	LD L, H	LD A, H	ADC A, H	SBC A, H	XOR H	CP H	CALL Z, nn	CALL C, nn	CALL PE, nn	CALL M, nn
LD C, n	LD L, n	LD L, n	LD A, n	LD C, L	LD E, L	LD L, L	LD A, L	ADC A, L	SBC A, L	XOR L	CP L	CALL nn	See Table 4	See Table 6	See Table 6
RCA	CPL	CPL	CCF	LD C, (HL)	LD E, (HL)	LD L, (HL)	LD A, (HL)	ADC A, (HL)	SBC A, (HL)	XOR (HL)	CP (HL)	ADC A, n	SEC A, n	XOR n	CP n
				LD C, A	LD E, A	LD L, A	LD A, A	ADC A, A	SBC A, A	XOR A	CP A	RST 08H	RST 18H	RST 28H	RST 38H

Second Nybble

Table 2: Mnemonics of the operation codes of the Z80 microprocessor arranged for conversion to hexadecimal object code. Corresponding positions of table 1 and table 2 generally perform the identical function, despite differences in notation. Enhancements of the 8080 instruction set are indicated by shading. Mnemonics used here are those specified by Zilog.

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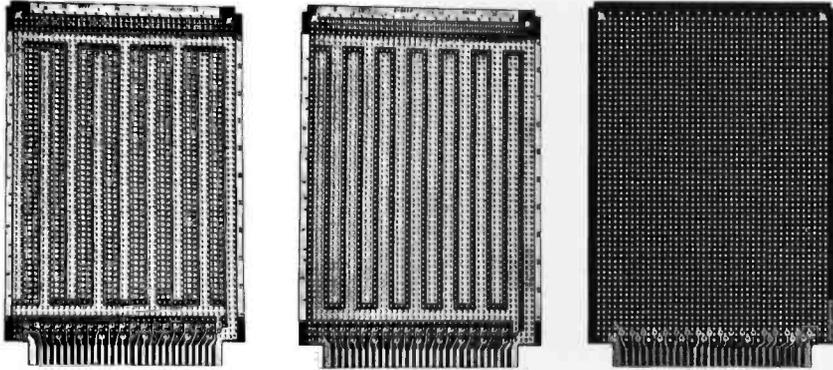


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mode instructions to shift or rotate (in either direction) any byte in memory or in any of the eight active registers are located here. Table 3 also contains the direct-mode instructions to set, reset, or test any bit in any of these bytes. All of these operations have a length of two bytes. Interestingly, there are more valid instruction combinations derived from the ten basic instructions in this table than there are in the entire 8080 set.

Two features of table 3 are notable. The first is the absence of a "shift left logical" counterpart to the SRL command group. The shift left logical counterpart is not there because it is not needed; the "arithmetic shift left" instructions in column 2 (hexadecimal) accomplish this function. The use of the same general organizational rules indicated earlier for the 8080 is the more important of the two properties of this table. Such uniformity is a good aid in locating instructions in this table.

Indexed Instructions

Instructions beginning with hexadecimal DD are in one of two indexed classes of instructions. These use the IX and IY registers respectively in forming a data address. Those related to the former are depicted in table 4 and its associated table 5.

The analogy between tables 2 and 4 and between tables 3 and 5 is striking. The organizational patterns are identical — even to the point of using the same expansion technique. They should be identical. Each of these indexed instructions was formed by replacing the (HL) operand of an equivalent register-indirect instruction with the indexed notation (IX+d). Thus, every operation that can be performed in the register-indirect mode by the 8080 or Z80 can also be performed in the indexed mode by the Z80.

The resulting positional equivalence between the two sets of tables is most helpful in determining the required hexadecimal code for the indexed instructions. An easy way to do this without having to refer to tables 4 or 5 is to first select from table 2 or 3 (as appropriate) the hexadecimal code for the register-indirect form of the desired operation. Then place a DD prefix in front of this code if the operation was found in table 2, or a DDCB prefix, if found in table 3.

Text continued on page 207

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0	RUC B	RL B	SIA B		BIT 0,B	BIT 2,B	BIT 4,B	BIT 6,B	RES 0,B	RES 2,B	RES 4,B	RES 6,B	SET 0,B	SET 2,B	SET 4,B	SET 6,B
1	RUC C	RL C	SIA C		BIT 0,C	BIT 2,C	BIT 4,C	BIT 6,C	RES 0,C	RES 2,C	RES 4,C	RES 6,C	SET 0,C	SET 2,C	SET 4,C	SET 6,C
2	RUC D	RL D	SIA D		BIT 0,D	BIT 2,D	BIT 4,D	BIT 6,D	RES 0,D	RES 2,D	RES 4,D	RES 6,D	SET 0,D	SET 2,D	SET 4,D	SET 6,D
3	RUC E	RL E	SIA E		BIT 0,E	BIT 2,E	BIT 4,E	BIT 6,E	RES 0,E	RES 2,E	RES 4,E	RES 6,E	SET 0,E	SET 2,E	SET 4,E	SET 6,E
4	RUC H	RL H	SIA H		BIT 0,H	BIT 2,H	BIT 4,H	BIT 6,H	RES 0,H	RES 2,H	RES 4,H	RES 6,H	SET 0,H	SET 2,H	SET 4,H	SET 6,H
5	RUC L	RL L	SIA L		BIT 0,L	BIT 2,L	BIT 4,L	BIT 6,L	RES 0,L	RES 2,L	RES 4,L	RES 6,L	SET 0,L	SET 2,L	SET 4,L	SET 6,L
6	RUC (HL)	RL (HL)	SIA (HL)		BIT 0,(HL)	BIT 2,(HL)	BIT 4,(HL)	BIT 6,(HL)	RES 0,(HL)	RES 2,(HL)	RES 4,(HL)	RES 6,(HL)	SET 0,(HL)	SET 2,(HL)	SET 4,(HL)	SET 6,(HL)
7	RUC A	RL A	SIA A		BIT 0,A	BIT 2,A	BIT 4,A	BIT 6,A	RES 0,A	RES 2,A	RES 4,A	RES 6,A	SET 0,A	SET 2,A	SET 4,A	SET 6,A
8	RUC B	RR B	SRA B	SRL B	BIT 1,B	BIT 3,B	BIT 5,B	BIT 7,B	RES 1,B	RES 3,B	RES 5,B	RES 7,B	SET 1,B	SET 3,B	SET 5,B	SET 7,B
9	RUC C	RR C	SRA C	SRL C	BIT 1,C	BIT 3,C	BIT 5,C	BIT 7,C	RES 1,C	RES 3,C	RES 5,C	RES 7,C	SET 1,C	SET 3,C	SET 5,C	SET 7,C
A	RUC D	RR D	SRA D	SRL D	BIT 1,D	BIT 3,D	BIT 5,D	BIT 7,D	RES 1,D	RES 3,D	RES 5,D	RES 7,D	SET 1,D	SET 3,D	SET 5,D	SET 7,D
B	RUC E	RR E	SRA E	SRL E	BIT 1,E	BIT 3,E	BIT 5,E	BIT 7,E	RES 1,E	RES 3,E	RES 5,E	RES 7,E	SET 1,E	SET 3,E	SET 5,E	SET 7,E
C	RUC H	RR H	SRA H	SRL H	BIT 1,H	BIT 3,H	BIT 5,H	BIT 7,H	RES 1,H	RES 3,H	RES 5,H	RES 7,H	SET 1,H	SET 3,H	SET 5,H	SET 7,H
D	RUC L	RR L	SRA L	SRL L	BIT 1,L	BIT 3,L	BIT 5,L	BIT 7,L	RES 1,L	RES 3,L	RES 5,L	RES 7,L	SET 1,L	SET 3,L	SET 5,L	SET 7,L
E	RUC (HL)	RR (HL)	SRA (HL)	SRL (HL)	BIT 1,(HL)	BIT 3,(HL)	BIT 5,(HL)	BIT 7,(HL)	RES 1,(HL)	RES 3,(HL)	RES 5,(HL)	RES 7,(HL)	SET 1,(HL)	SET 3,(HL)	SET 5,(HL)	SET 7,(HL)
F	RUC A	RR A	SRA A	SRL A	BIT 1,A	BIT 3,A	BIT 5,A	BIT 7,A	RES 1,A	RES 3,A	RES 5,A	RES 7,A	SET 1,A	SET 3,A	SET 5,A	SET 7,A

Second Nybble

Table 3: Enhancement operation codes of the Z80 invoked by the hexadecimal CB instruction prefix. These CB class operations give bit manipulation, data shifting, and enhanced rotation capability to the Z80.

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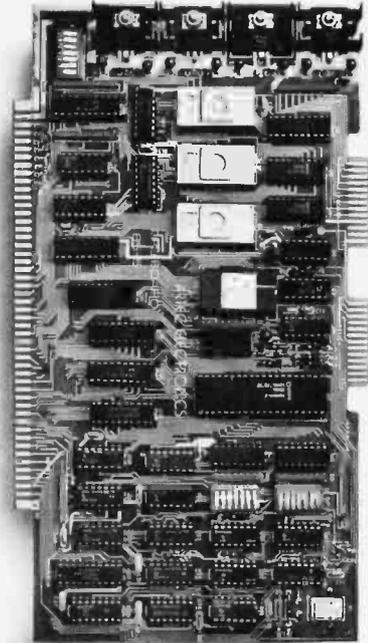


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Second Nybble	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0								LD (IX+d),B								
1			LD IX,(nn)					LD (IX+d),C							POP IX	
2			LD (nn),IX					LD (IX+d),D								EX (SP),IX
3			INC IX					LD (IX+d),E								
4								LD (IX+d),H								PUSH IX
5								LD (IX+d),L								
6					LD B,(IX+d)	LD D,(IX+d)	LD H,(IX+d)		ADD A,(IX+d)	SUB (IX+d)	AND (IX+d)	OR (IX+d)				
7								LD (IX+d),A								
8																
9	ADD IX,BC	ADD IX,DE	ADD IX,IX	ADD IX,SP											JP (IX)	LD SP,IX
A			LD IX,(nn)													
B			DEC IX													
C																
D																
E					LD C,(IX+d)	LD E,(IX+d)	LD L,(IX+d)	LD A,(IX+d)	ADC A,(IX+d)	SBC A,(IX+d)	XOR (IX+d)	CP (IX+d)				
F																

Table 4: Operations of the Z80 invoked by the instruction prefix DD. These provide indexed-mode instructions equivalent to the indirect-mode instructions and employ the IX register.

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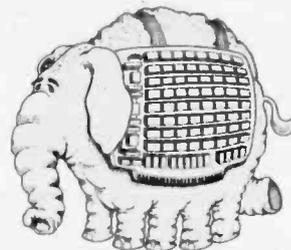
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First Nybble		Second Nybble															
	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
0																	
1																	
2																	
3																	
4																	
5																	
6	RUC (IX+d)	RL (IX+d)	SIA (IX+d)		BIT 0, (IX+d)	BIT 2, (IX+d)	BIT 4, (IX+d)	BIT 6, (IX+d)	RES 0, (IX+d)	RES 2, (IX+d)	RES 4, (IX+d)	RES 6, (IX+d)	SET 0, (IX+d)	SET 2, (IX+d)	SET 4, (IX+d)	SET 6, (IX+d)	
7																	
8																	
9																	
A																	
B																	
C																	
D																	
E	RRC (IX+d)	RR (IX+d)	SRA (IX+d)	SRL (IX+d)	BIT 1, (IX+d)	BIT 3, (IX+d)	BIT 5, (IX+d)	BIT 7, (IX+d)	RES 1, (IX+d)	RES 3, (IX+d)	RES 5, (IX+d)	RES 7, (IX+d)	SET 1, (IX+d)	SET 3, (IX+d)	SET 5, (IX+d)	SET 7, (IX+d)	
F																	

Table 5: These DDCB-class operation codes are an indexed equivalent of the indirect-mode operation codes of the Z80 shown in table 3.

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Second Nybble	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0																
1		LD IY,nn						LD (IY+d),B							POP IY	
2		LD (nn),IY						LD (IY+d),C								
3		INC IY						LD (IY+d),D								
4								LD (IY+d),E								
5								LD (IY+d),H								
6								LD (IY+d),L								
7								LD (IY+d),A								
8																
9	ADD IY,BC	ADD IY,DE	ADD IY,IY	ADD IY,SP												
A			LD IY,(nn)													
B			DEC IY													
C																
D																
E																
F																

Table 6: Indexed instructions employing the IY register. Note the similarity with table 4. These operation codes begin with the FD prefix.

First Nybble	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0																
1																
2																
3																
4																
5																
6	RL (IY+d)	RL (IY+d)	SLA (IY+d)	BIT 0, (IY+d)	BIT 1, (IY+d)	BIT 2, (IY+d)	BIT 4, (IY+d)	BIT 6, (IY+d)	RES 0, (IY+d)	RES 2, (IY+d)	RES 4, (IY+d)	RES 6, (IY+d)	SET 0, (IY+d)	SET 2, (IY+d)	SET 4, (IY+d)	SET 6, (IY+d)
7																
8																
9																
A																
B																
C																
D																
E	RRC (IY+d)	RR (IY+d)	SRA (IY+d)	SRL (IY+d)	BIT 1, (IY+d)	BIT 3, (IY+d)	BIT 5, (IY+d)	BIT 7, (IY+d)	RES 1, (IY+d)	RES 3, (IY+d)	RES 5, (IY+d)	RES 7, (IY+d)	SET 1, (IY+d)	SET 3, (IY+d)	SET 5, (IY+d)	SET 7, (IY+d)
F																

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Table 7: Indexed instructions of the FDCB class, again employing the IY register. Note the similarity with table 5.

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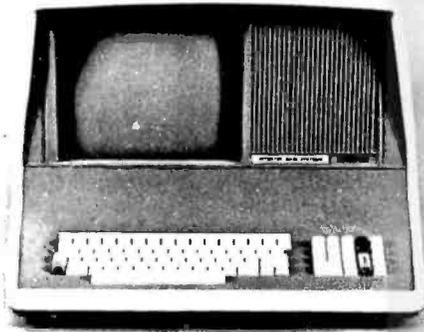
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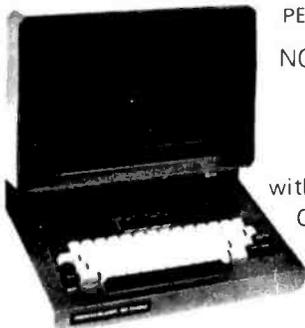
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0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	IN B,(C)	OUT (C),B	SBC HL,BC	LD (nn),BC	NBC	RETN	IN 0	LD I,A	IN C,(C)	OUT (C),C	ADC HL,BC	LD BC,(nn)	RETI	LD R,A	
1	IN D,(C)	OUT (C),D	SBC HL,DE	LD (nn),DE			IN 1	LD A,I	IN E,(C)	OUT (C),E	ADC HL,DE	LD DE,(nn)			
2	IN H,(C)	OUT (C),H	SBC HL,HL					RRD	IN L,(C)	OUT (C),L	ADC HL,HL				
3			SBC HL,SP	LD (nn),SP					IN A,(C)	OUT (C),A	ADC HL,SP				
4	LDI														
5	CPI														
6	INI														
7	OUTI														
8															
9															
A	LDD														
B	CPD														
C	IND														
D	OUTD														
E															
F															

Table 8: The class of miscellaneous instructions invoked by the ED prefix.

Text continued from page 200:

Finally, place after this code group a displacement suffix, d.

The Z80 also has a second index register, which is designated the IY register. Op codes which use it for addressing are contained in tables 6 and 7. It takes only a quick glance to notice the strong similarity between tables 4 and 6 and between tables 5 and 7. As might be expected, virtually everything said previously about the IX class of op codes also refers to the IY class. The sole exception to this statement is that the IY-type instructions begin with hexadecimal code FD, instead of DD.

Miscellaneous Additions

All fifty-six instructions in the last of the four expansion sets begin with hexadecimal code ED. They are listed in table 8. Though they are quite heterogeneous, they add considerably to the power of the Z80. Among these, for example, are instructions that enhance the 16-bit arithmetic capability, set interrupt modes, permit complementing the accumulator, and allow a register-indirect type of I/O to be performed. There are instructions also, which allow counting or block processing to be done during loading, comparison, and I/O operations. Even if the other three expansion sets were omitted, the instructions in this set would be highly useful additions to the basic 8080 complement.

With such a hodgepodge of function, it is rather surprising that any order at all can be made of these ED class instructions. Nonetheless, consistency with the other tables is maintained. It is evident from the arithmetic and the leftmost I/O instructions that arrangement by order of first and second operands is used whenever possible. Separation of complementary functions by eight rows in a column is also followed.

There are 696 valid op codes in the seven Z80 tables. Without organizational consistency, conversion of these instructions from mnemonic to hexadecimal form would be extremely difficult and probably ridden with error. Fortunately, these codes are very well arranged, following the pattern established for the 8080. It takes a little practice to become adept at making these transformations, but with the aid of these tables it can be accomplished successfully. ■

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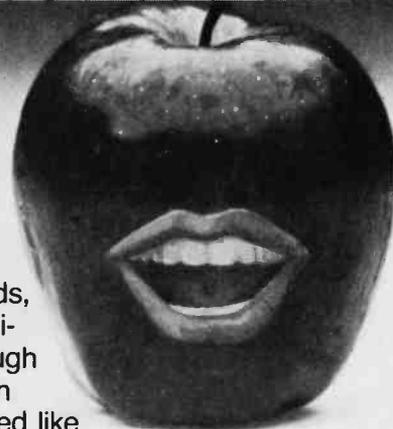


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Text continued on page 210

Listing 1: Keystrokes for the periodic-table program. The TI-59 should be configured for 319 program steps and 79 data registers, and the program will require two magnetic cards for storage. When running the program, the user can recover from an error condition by pressing CLR and beginning again.

```

000 76 LBL
001 10 E*
002 32 X:Y
003 86 STF
004 03 03
005 87 IFF
006 01 01
007 02 02
008 65 65
009 22 INV
010 86 STF
011 03 03
012 86 STF
013 01 01
014 86 STF
015 02 02
016 01 1
017 69 DP
018 17 17
019 47 CMS
020 08 8
021 69 DP
022 17 17
023 01 1
024 42 STD
025 04 04
026 32 X:Y
027 91 R/S
028 76 LBL
029 11 A
030 71 SBR
031 01 01
032 63 63
033 29 DP
034 67 EQ
035 00 00
036 40 40
037 42 STD
038 04 04
039 91 R/S
040 43 RCL
041 04 04
042 91 R/S
043 76 LBL
044 12 B
045 71 SBR
046 01 01
047 63 63
048 29 DP
049 67 EQ
050 00 00
051 55 55
052 42 STD
053 06 06
054 91 R/S
055 43 RCL
056 06 06
057 91 R/S
058 76 LBL
059 13 C
060 71 SBR
061 01 01
062 63 63
063 43 RCL
064 05 05
065 99 PRT
066 98 ADV
067 91 R/S
068 76 LBL
069 15 E
070 71 SBR
071 01 01
072 63 63
073 43 RCL
074 06 06
075 32 X:Y
076 00 0
077 77 GE
078 00 00
079 92 92
080 01 1
081 00 0
082 06 6
083 22 INV
084 77 GE
085 00 00
086 92 92
087 87 IFF
088 02 02
089 00 00
090 96 96
091 92 RTN
092 02 2
093 94 +/-
094 34 FX
095 91 R/S
096 43 RCL
097 06 06
098 55 +
099 02 2
100 85 +
101 93 .
102 05 5
103 95 =
104 42 STD
105 01 01
106 59 INT
107 42 STD
108 02 02
109 32 X:Y
110 43 RCL
111 01 01
112 22 INV
113 67 EQ
114 01 01
115 19 19
116 02 2
117 42 STD
118 03 03
119 01 1
120 09 9
121 44 SUM
122 02 02
123 73 RC*
124 02 02
125 42 STD
126 00 00
127 01 1
128 52 EE
129 06 6
130 64 PD*
131 02 02
132 73 RC*
133 02 02
134 59 INT
135 22 INV
136 74 SM*
137 02 02
138 55 +
139 01 1
140 52 EE
141 03 3
142 95 =
143 22 INV
144 52 EE
145 97 DSZ
146 03 03
147 01 01
148 27 27
149 48 EXC
150 00 00
151 72 ST*
152 02 02
153 48 EXC
154 00 00
155 65 X
156 43 RCL
157 04 04
158 95 =
159 44 SUM
160 05 05
161 99 PRT
162 91 R/S
163 22 INV
164 87 IFF
165 02 02
166 00 00
167 92 92
168 22 INV
169 86 STF
170 01 01
171 92 RTN
172 76 LBL
173 17 B*
174 87 IFF
175 02 02
176 00 00
177 92 92
178 29 CP
179 22 INV
180 87 EQ
181 01 01
182 88 88
183 43 RCL
184 07 07
185 61 GTD
186 02 02
187 18 18
188 55 +
189 01 1
190 52 EE
191 03 3
192 95 =
193 42 STD
194 00 00
195 01 1
196 52 EE
197 06 6
198 22 INV
199 64 PD*
200 01 01
201 43 RCL
202 00 00
203 74 SM*
204 01 01
205 69 DP
206 21 21
207 93 .
208 05 5
209 22 INV
210 44 SUM
211 01 01
212 69 DP
213 27 27
214 43 RCL
215 07 07
216 22 INV
217 52 EE
218 91 R/S
219 61 GTD
220 01 01
221 88 88
222 76 LBL
223 16 A*
224 42 STD
    
```

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227	87	IFF	246	00	0	265	43	RCL
228	01	01	247	95	=	266	07	07
229	00	00	248	42	STD	267	32	X:T
230	92	92	249	01	01	268	42	STD
231	22	INV	250	59	INT	269	08	08
232	86	STF	251	32	X:T	270	25	CLR
233	02	02	252	43	RCL	271	22	INV
234	71	SBR	253	01	01	272	67	EQ
235	00	00	254	22	INV	273	02	02
236	75	75	255	67	EQ	274	37	37
237	43	RCL	256	00	00	275	43	RCL
238	07	07	257	92	92	276	08	08
239	75	-	258	87	IFF	277	32	X:T
240	01	1	259	03	03	278	61	STD
241	95	=	260	02	02	279	00	00
242	55	+	261	75	75	280	09	09
243	02	2	262	43	RCL			

(a)	A'	B'	C'	D'	E'
	A	B	C	D	E

(b)	Atomic Weights			
	Load Atomic Number	Load Atomic Weight		Initialize
	N (Occurrence of an Atom)	Atomic Number	Sum of Weights	Run

Figure 1: Placement and definition of user-defined keys. Given the placement of the user-defined keys in figure 1a, the program tape in figure 1b shows the meaning of each key. For example, user-defined key A is used when entering the value for N. See tables 1 and 2, which describe the usage of these keys.

Table 1: Loading and changing atomic weight information. The first routine allows the user to enter the atomic weight for all elements, starting with element 1 and continuing through element 106. The second routine allows the user to make changes to a group of consecutive elements. Since two atomic weights are stored in a single register, both weights for an odd-even pair must be entered even if only one of the two is to be changed. Pressing the R/S button causes the calculator to request the next odd-even pair of atomic weights. The E' key, used to end this loop, can be pressed only when the atomic number showing in the display is odd.

Steps	Procedure	Press	Display
1.	To load atomic weight Initialize.	E'	does not change
2.	Enter 1.	A'	1
3.	Enter atomic weight for atomic number 1.	B'	2
4.	Enter atomic weight for atomic number 2.	R/S	3
	·	·	·
	·	·	·
	·	·	·
5.	Enter atomic weight for atomic number 106. Initialize.	R/S	107
		E'	does not change
6.	Load data into banks 2, 3, and 4. (Refer to owner's manual for TI Programmable 58/59.) (The program is now complete. The load subroutines will not be needed unless a change of data is required at a later date.)		
7.	To change atomic weight data Initialize.	E'	does not change
8.	Enter n, where n = 1, 3, 5, . . . 103, 105.	A'	n
9.	Enter atomic weight for n.	B'	n + 1
10.	Enter atomic weight for n + 1. (n + 1 is even)	R/S	n + 2
	·	·	·
	·	·	·
	·	·	·
11.	If the number displayed is odd, press E' to exit the "change atomic weight data" routine.	E'	does not change
12.	To recall atomic number for the next atomic weight to be entered. (Step 12 is performed when the operator initializes with n, an even integer, thereby initiating an error condition.)	CLR, B'	Atomic number
13.	Repeat steps 9, 10, and 11 to continue.		

Table 2: Retrieval of data from the program. The first routine finds an element's atomic weight, given its atomic number. The second routine calculates the molecular weight of a molecule given a set of quantity/atomic-number pairs that describe the molecule. The quantities marked with asterisks (*) denote numbers that will be printed when a PC-100A or PC-100C printer is attached.

Steps	Procedure	Press	Display
1.	To find atomic weight Initialize. (When program is initialized, the display is preserved.)	E'	does not change
2.	Enter atomic number.	B, E	value of atomic weight*
3.	Repeat step 2 for new atomic number.		
4.	To find molecular weight Initialize.	E'	does not change
5.	Enter atomic number.	B	does not change
6.	Enter how many of that particular element.	A, E	A x atomic weight*
7.	Repeat steps 5 and 6 for each element.		
8.	Calculate total weight (sum weight.)	C	total weight of mole- cule*
9.	(Note: label C is a subtotal.) To find weight of a new formula, go to step 4.		
10.	Recall last A entry (when desired)	CLR, A	Last A
11.	Recall last B entry (when desired) (Steps 10 and 11 are merely for conve- nience and do not interfere with program flow.)	CLR, B	Last B

Table 3: Table showing usage of registers 00 thru 79 in the periodic-table program, listing 1. The atomic weights must be in the form of XXX.XXX; leading and trailing zeros will be automatically inserted.

Register Number	Use
00 thru 09	Used.
10 thru 19	These registers are left open to allow the operator to store additional data during program use without altering internal program executions.
20 thru 72	Used to store atomic weights.
73 thru 79	Not used.

Text continued from page 208:

I realized that a programmable calculator could easily be used to store and retrieve data contained in the periodic chart; once this is done, the user can manipulate periodic-chart data with a small chance of error. Using the Texas Instruments TI-59, I developed the program shown in listing 1.

This program, documented in tables 1 and 2, contains two types of routines, the first for loading atomic weights, and the second for retrieving them. I decided to

sacrifice speed of execution for ease of operation and protection of loaded data.

This program will enable you to:

- Display atomic weights by entering the corresponding atomic numbers.
- Calculate molecular weights.
- Calculate any combination of atomic weights.
- Load atomic weights either sequentially or randomly.
- Print values using the PC-100A or PC-100C printers. ■

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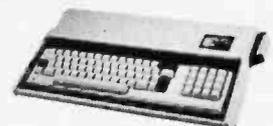
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KIM-1 Multiplication and Division

James C Couchman, General Dynamics Corp, Fort Worth
Division, POB 748, Fort Worth TX 76101

When I bought a MOS Technology KIM-1 microcomputer to use in a specific control function, it arrived with a set of comprehensive instruction, programming, and hardware books. As soon as I connected a 5 V power supply, I was able to interact with the machine through the hexadecimal keyboard and light-emitting diode (LED) display. It was a bit more difficult to get our Teletype to work with the KIM-1, but with a slight adjustment to the teleprinter timing, the problem was cured.

The KIM-1 is still a real bargain, with features including the 6502 microprocessor, 2 K bytes of read-only memory (containing the Keyboard Input Monitor from which the name is derived), an interval timer, fifteen input and output lines, 1 K bytes of programmable memory (with address logic for 16 K bytes), and probably some features I have not yet discovered.

Since the KIM-1 is programmed in machine language using a set of fifty-six instructions, I believe that the best way to learn to program it is to not just read about it, but do it. One should just start writing code, and, in time, the power of the basic instruction set will really be understood and appreciated.

Once the user is familiar with the capabilities of the KIM-1, he begins to wish that it could do more. One tool that provides more capability is a set of software routines that perform sixteen-bit multiplication and division on the 6502 processor. After I searched for a suitable set of routines, I concluded that I would have to write my own.

To prevent you from having to "reinvent the wheel," I am presenting these routines here. In developing these routines, I enlisted the invaluable assistance of my associates G R Arnett and J R Williamson. These routines should work without much difficulty on other 6502-based computers.

Sixteen-Bit Routines

These routines can multiply and divide two 16-bit signed quantities together and produce a signed 16-bit result. The routines are written as relocatable sub-routines.

In multiplication, the high-order byte of the first multiplicand is loaded into hexadecimal location 0000, and the low-order byte into location 0001. The high-

order byte of the second multiplicand is put into location 0006, and the low-order byte into location 0007.

In division, the high-order byte of the divisor is loaded into hexadecimal location 0000; the low-order byte into location 0001. The high-order byte of the dividend is placed into location 0006, and the low-order byte is loaded into location 0007. If the value of the divisor is zero, the division routine will return control to the calling program.

For both the multiplication and the division routines, the answer is returned in hexadecimal locations 0002 (high-order) and 0003 (low-order byte). It should not be very hard to change this if need be.

An example of a simple calling routine is shown in listing 1. The calling sequence is essentially the same for both multiplication and for division; only the value contained in the two bytes that follow the jump-to-subroutine (JSR) instruction must be changed.

Listing 1a: Calling sequence for 16-bit multiply subroutine.

Address	Code
0007	20 (JSR)
0008	00
0009	01 (multiply)
000A	A9 (LDA)
000B	00
000C	F0
000D	FC

Listing 1b: Calling sequence for 16-bit divide subroutine.

Address	Code
0007	20 (JSR)
0008	30
0009	00 (divide)
000A	A9 (LDA)
000B	00
000C	F0
000D	FC

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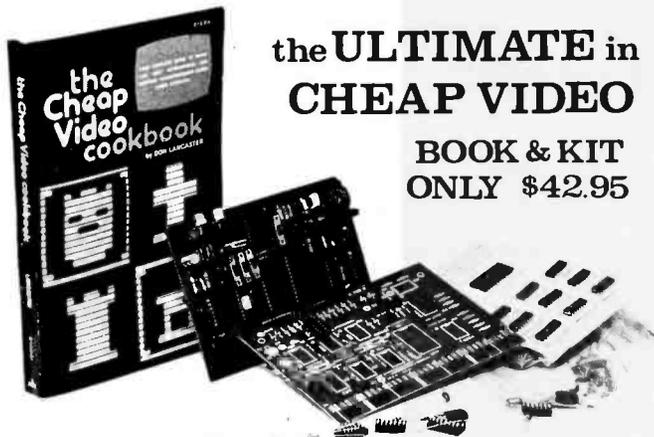
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The assembler mnemonics and hexadecimal code for the multiplication subroutine are given in listing 2. The division subroutine is given in similar form in listing 3. The multiplication subroutine is shown in hexadecimal memory-dump form in listing 4; the division code in that form in listing 5.

My colleagues and I hope that these programs will help other KIM-1 users. We know that having had them prepared for us would have saved us much time.

Listing 2: Relocatable subroutine to perform multiplication of 16-bit quantities on the 6502 microprocessor as used in the MOS Technology KIM-1. Both assembler mnemonics and hexadecimal code are given. Entry point is hexadecimal location 0100.

Address	Mnemonic	Hexadecimal Code
0100	CLC	18
0101	CLD	D8
0102	LDA #0	A9 00
0104	TAX	AA
0105	STA 0002	85 02
0107	STA 0003	85 03
0109	LDA 0000	A5 00
010B	BNE	D0 11
010D	LDA 0001	A5 01
010F	BEQ	F0 0C
0111	CMP #1	C9 01
0113	BNE	D0 1D
0115	LDA 0006	A5 06
0117	STA 0002	85 02
0119	LDA 0007	A5 07
011B	STA 0003	85 03
011D	RTS	60
011E	BPL	10 12
0120	INX	E8
0121	LDA 0001	A5 01
0123	CLC	18
0124	EOR FF	49 FF
0126	ADC #1	69 01
0128	STA 0001	85 01
012A	LDA 0000	A5 00
012C	EOR FF	49 FF
012E	ADC #0	69 00
0130	STA 0000	85 00
0132	LDA 0006	A5 06
0134	BNE	D0 26
0136	LDA 0007	A5 07
0138	BEQ	F0 18
013A	CMP #1	C9 01
013C	BNE	D0 32
013E	DEX	CA
013F	BNE	D0 12
0141	LDA 0001	A5 01
0143	CLC	18
0144	EOR FF	49 FF
0146	ADC #1	69 01
0148	STA 0003	85 03
014A	CDA 0000	A5 00
014C	EOR FF	49 FF
014E	ADC #0	69 00
0150	STA 0002	85 02
0152	RTS	60
0153	LDA 0001	A5 01
0155	STA 0003	85 03
0157	LDA 0000	A5 00
0159	STA 0002	85 02
015B	RTS	60
015C	BPL	10 12
015E	INX	E8
015F	LDA 0007	A5 07

Listing 2 continued on page 215

Listing 2 continued:

0161	CLC	18
0162	EOR FF	49 FF
0164	ADC #1	69 01
0166	STA 0007	85 07
0168	LDA 0006	A5 06
016A	EOR FF	49 FF
016C	ADC #0	69 00
016E	STA 0006	85 06
0170	LDA 0000	A5 00
0172	STA 0004	85 04
0174	LDA 0001	A5 01
0176	STA 0005	85 05
0178	LDA 0003	A5 03
017A	CLC	18
017B	ADC 0001	65 01
017D	STA 0003	85 03
017F	LDA 0002	A5 02
0181	ADC 0000	65 00
0183	STA 0002	85 02
0185	SEC	38
0186	LDA 0007	A5 07
0188	SBC #1	E9 01
018A	STA 0007	85 07
018C	LDA 0006	A5 06
018E	SBC #0	E9 00
0190	STA 0006	85 06
0192	CMP #0	C9 00
0194	BNE	D0 E2
0196	LDA 0007	A5 07
0198	CMP #0	C9 00
019A	BNE	D0 DC
019C	DEX	CA
019D	BNE	D0 15
019F	LDA 0002	A5 02
01A1	EOR FF	49 FF
01A3	STA 0002	85 02
01A5	LDA 0003	A5 03
01A7	EOR FF	49 FF
01A9	CLC	18
01AA	ADC #1	69 01
01AC	STA 0003	85 03
01AE	LDA 0002	A5 02
01B0	ADC #0	69 00
01B2	STA 0002	85 02
01B4	RTS	60

Listing 3: Relocatable subroutine to perform division of 16-bit quantities on the 6502 microprocessor of the KIM-1, with assembler mnemonics. Entry point is hexadecimal location 0030.

Address	Mnemonic	Hexadecimal Code
0030	CLC	18
0031	CLD	D8
0032	LDA #0	A9 00
0034	TAX	AA
0035	STA 02	85 02
0037	STA 03	85 03
0039	LDA 00	A5 00
003B	BNE	D0 05
003D	LDA 01	A5 01
003F	BNE	D0 15
0041	RTS	60
0042	BPL	10 12
0044	INX	E8
0045	LDA 01	A5 01
0047	CLC	18
0048	EOR FF	49 FF
004A	ADC #1	69 01
004C	STA 01	85 01
004E	LDA 00	A5 00
0050	EOR FF	49 FF

Listing 3 continued on page 216

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Listing 3 continued:

```

0052      ADC #0          69 00
0054      STA 00         85 00
0056      LDA 06         A5 06
0058      BNE           D0 26
005A      LDA 07         A5 07
005C      BEQ          F0 18
005E      CMP #1        C9 01
0060      BNE           D0 32
0062      DEX           CA
0063      BNE           D0 12
0065      LDA 01         A5 01
0067      CLC           18
0068      EOR FF        49 FF
006A      ADC #1        69 01
006C      STA 03         85 03
006E      LDA 00         A5 00
0070      EOR FF        49 FF
0072      ADC #0          69 00
0074      STA 02         85 02
0076      RTS           60
0077      LDA 01         A5 01
0079      STA 03         85 03
007B      LDA 00         A5 00
007D      STA 02         85 02
007F      RTS           60
0080      BPL           10 12
0082      INX           E8
0083      LDA 07         A5 07
0085      CLC           18
0086      EOR FF        49 FF
0088      ADC #1        69 01
008A      STA 07         85 07
008C      LDA 06         A5 06
008E      EOR FF        49 FF
0090      ADC #0          69 00
0092      STA 06         85 06
0094      LDA 03         A5 03
0096      CLC           18
0097      ADC #1        69 01
0099      STA 03         85 03
009B      LDA 02         A5 02
009D      ADC #0          69 00
009F      STA 02         85 02
00A1      SEC           38
00A2      LDA 01         A5 01
00A4      SBC 07         E5 07
00A6      STA 01         85 01
00A8      LDA 00         A5 00
00AA      SBC 06         E5 06
00AC      STA 00         85 00
00AE      LDA 00         A5 00
00B0      BMI           30 08
00B2      BNE           D0 E0

```

```

00B4      LDA 01         A5 01
00B6      BNE           D0 DC
00B8      BEQ          F0 0D
00BA      SEC           38
00BB      LDA 03         A5 03
00BD      SBC #1        E9 01
00BF      STA 03         85 03
00C1      LDA 02         A5 02
00C3      SBC #0        E9 00
00C5      STA 02         85 02
00C7      DEX           CA
00C8      BNE           D0 15
00CA      LDA 02         A5 02
00CC      EOR FF        49 FF
00CE      STA 02         85 02
00D0      LDA 03         A5 03
00D2      EOR FF        49 FF
00D4      CLC           18
00D5      ADC #1        69 01
00D7      STA 03         85 03
00D9      LDA 02         A5 02
00DB      ADC #0        69 00
00DD      STA 02         85 02
00DF      RTS           60

```

Listing 4: Multiplication subroutine in hexadecimal memory-dump form.

```

; 18010018D8A900AA85028503A500D011A501F00CC901D01DA50685097A
; 18011802A5078503601012E8A5011849FF69018501A50049FF6900081D
; 1801308500A506D026A507F018C901D032CAD012A5011849FF69010A0B
; 1801488503A50049FF6900850260A5018503A5008502601012E8A5088F
; 180160071849FF69018507A50649FF69008506A5008504A5018505081B
; 180178A5031865018503A5026500850238A507E9018507A506E90007C0
; 1801908506C900D0E2A507C900D0DCCAD015A50249FF8502A503490BE6
; 1801A8FF1869018503A5026900850260E9008D0600C900D0D8A0C70962
; 0000080008 0

```

Listing 5: Division subroutine in hexadecimal memory-dump form.

```

; 18003018D8A900AA85028503A500D005A501D015601012E8A5011808C7
; 18004849FF69018501A50049FF69008500A506D026A507F018C9010992
; 180060D032CAD012A5011849FF69018503A50049FF6900850260A50A0Q
; 180078018503A5008502601012E8A5071849FF69018507A50649FF08AA
; 18009069008506A5031869018503A5026900850238A501E50785010735
; 1800A8A500E5068500A5003008D0E0A501D0DCFO0D38A503E901850B00
; 1800C003A502E9008502CAD015A50249FF8502A50349FF186901850A0E
; 1800D803A5026900850260002A3F3C3B3F1E3E3E3EFE1E3E7E7A7F07B2
; 0000080008 ■

```

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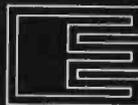
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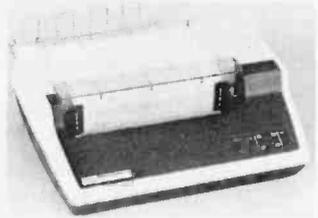
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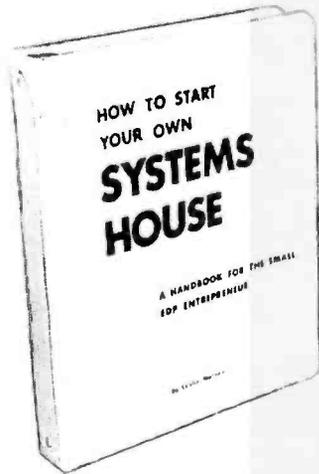
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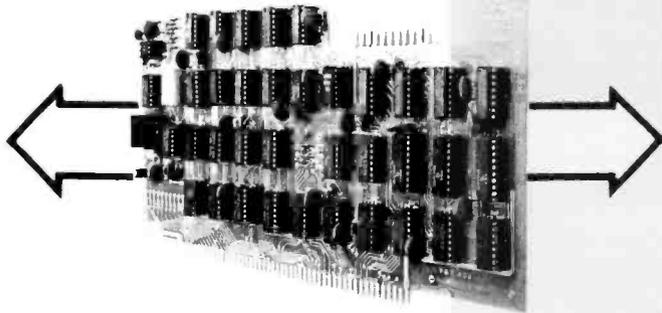
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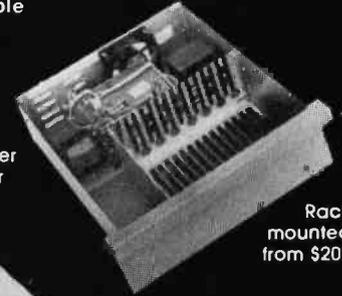


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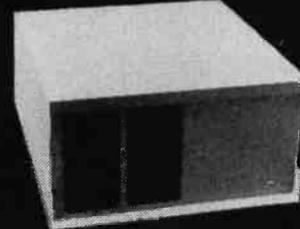
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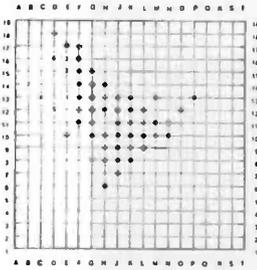
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March 30

Greater Baltimore Hamboree and Computefest, Maryland State Fairgrounds, Timonium MD. Personal, dealer, and small business computer displays and exhibits will be featured. Space is available outside the fairgrounds for tailgate sales and swaps. For more information, contact Joseph Lochte Jr, 2136 Pine Valley Dr, Timonium MD 21093.

March-June

Computer and Office Systems Expo and Conference. This is an exposition for marketers of office systems equipment. The show and conference will focus on the local problems and opportunities of each region. The exposition and conference will be held in major cities around the nation. Contact The Conference Co, 60 Austin St, Newton MA 02160, or phone (617) 964-4550.

Signal Processing, Fairmont Hotel, Denver CO. The IEEE Acoustics, Speech and Signal Processing Society is sponsoring this conference devoted to experimental and theoretical aspects of signal processing, speech, and acoustics. For more information, contact IEEE, 1100 14th St, Denver CO 80202.

April 10

Electronic Road Shows, Anaheim Convention Center, Anaheim CA. See March 20th for details.

April 11-12

10th Annual Virginia Computer Users Conference. This conference is sponsored by the Virginia Tech Association for Computing Machinery (ACM) student chapter. The topics of discussion will be programming languages and system and personnel management. For more information, contact VCUC10, 562 McBryde Hall, VPI&SU, Blacksburg VA 24061.

April 13-16

A Gateway to the Use of Computers in Education, Chase Park Plaza Hotel, St Louis MO. The purpose of this convention is to provide a forum for the exchange of information and ideas between individuals, to inform educators of developments in computer technology, and to expose participants to innovations in computing which can be utilized in the field of education.

Educators are encouraged to exhibit and make presentations of instructional microprocessor materials during the convention. Contact the Association for Educational Data Systems (AEDS), POB 951, Rolla MO 65401.

April 14-18

High-Speed Computer Organization, 6266 Boelter Hall, UCLA Extension, Los Angeles CA. This course is for computer designers, system architects, project leaders and managers. The course provides an understanding of the principles of high-speed com-

APRIL 1980

April 1-2

Southeast Printed Circuits and Microelectronics Exposition, Sheraton-Twin Towers Convention Center, Orlando FL. This show is a specialized event devoted entirely to the packaging, production and testing of printed circuits, multilayers, semiconductor devices, and hybrids. The conferences are aimed at electronics specialists. Contact ISCM, 222 W Adams St, Chicago IL 60606.

April 9-11

The Practical APL Conference, Washington DC. This conference is addressed to business executives and systems designers. For more information, contact Joan Gurgold, STSC, 7 Holland Ave, White Plains NY 10603.

April 9-11

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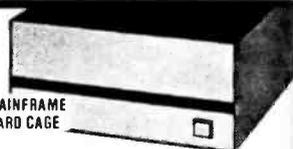


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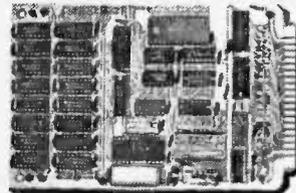
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For more information, contact the UCLA Extension at POB 24901, Dept K, UCLA Extension, Los Angeles CA 90024.

April 21-25

National Micrographics Association 29th Annual Conference and Exposition, Sheraton Center Hotel and Coliseum, New York NY. The theme for the show is "Focus on Productivity in Office Management." Highlighting the conference and exposition will be presentations and talks concerning the use in offices for computer systems and related items.

For more information, contact the Conference Dept, National Micrographics Association, 8719 Colesville Rd, Silver Spring MD 20910.

April 23-25

International DP Training Conference, Hyatt Regency, Chicago IL. The theme for this event will be "The 1980s: The Information Decade." The conference is a symposium for data processing experts and corporate training executives. For information, contact

Deltak Inc, 1220 Kensington Rd, Oak Brook IL 60521.

April 27-30

17th Numerical Control Society Annual Meeting and Technical Conference, Hartford Civic Center, Hartford CT. This convention will offer technical sessions covering such areas as computer-aided design engineering, business management, tool design and graphics; computer-aided assembly, facilities planning, inventory control, and management information systems; numerical control in various areas; data base structure and management; and other educational programs. There is also a large exhibition being presented.

For more information, contact Numerical Control Society, 1800 Pickwick, Glenview IL 60025.

April 28-30

Managing Technical Programs and Projects, White Plains NY. For more information, contact the Institute for Advanced Professional Studies, One Gateway Ctr, Newton MA 02158.

April 30-May 2

Computerized Office Equipment Expo, O'Hare Exposition Center, Rosemont IL. The latest developments in

computers, word processors, copiers/duplicators, telephone systems, and other business equipment will be featured. The seminars will cover guidelines on buying computer systems, telephone and copier systems; the use of word processors, and more. Contact Industrial and Scientific Conference Management Inc, 222 W Adams St, Chicago IL 60606.

MAY 1980

May

IEEE Computer Society Conferences and Meetings. For a list of events, contact the Executive Secretary, Harry Hayman, POB 639, Silver Spring MD 20901, or phone (301) 439-7007.

May 5-11

Engineering, Science, and Public Policy, 16th Annual Meeting, Baltimore Convention Center, Baltimore MD. Companies from around the world and the US will be exhibiting. The conference is being sponsored by the AIAA. Contact Lawrence Craner, Director of Technical Displays, AIAA, 1290 Avenue of the Americas, New York NY 10019, or the Conference General Chairman, Laurence Adams at Martin Marietta

Aerospace.

May 6-8

Micro/Expo 80, Centre International de Paris, Paris France. This is one of the leading shows in Europe for microcomputer users and manufacturers. Exhibits of new equipment, presentations, games, educational materials, and more will be featured. For more information, contact Sybex Inc, 2020 Milvia St, Berkeley CA 94704.

May 6-8

The 7th International Symposium on Computer Architecture, La Baule, France. This symposium will consist of discussions and readings in the following areas: distributed architectures, special-purpose architectures, hardware description languages, fault-tolerant architectures, high-speed computers, control schema, evaluation of architecture performance, and more.

Contact, Daniel E Atkins, Dept of Electrical and Computer Engineering, University of Michigan, Ann Arbor MI 48109.

May 6-10

8th Annual Canadian Association for Information Science, Toronto, Canada. Technology, commodity, and rights are the themes of this conference. Topics will

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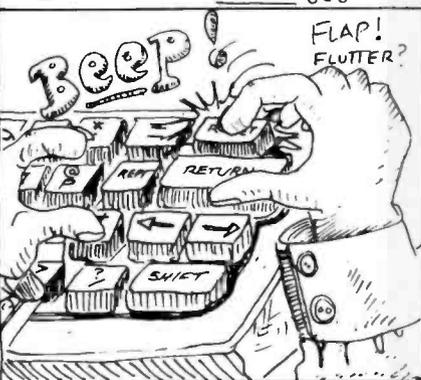
his concentration is broken for a brief moment... UNKNOWN to ARNOLD, he will do something that many others have done in the past.



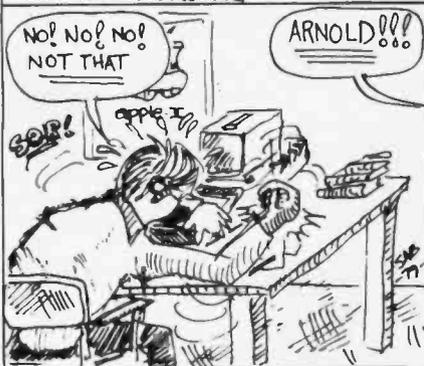
as ARNOLD'S fingers, frantically, fly across the keyboard.... he is about to cross over into obscurity.....



...only missed it by that much!!...one silly centimeter... RESET!!!



he has hit RESET, Instead of hitting RETURN... Alas, if he only knew about ta da..... ResetGuard™..... FIN



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cover information in the marketplace, information transfer and policy issues, right to access, new information technologies and applications, and other subjects. For more information, contact the Program Chairman, 8th Annual CAIS Conference, Technical Information Centre, Bell Northern Software Research, 12th floor, 522 University Ave, Toronto Ontario M5G 1W7 CANADA.

May 13-15

Electro/80 Show and Convention, Hynes Auditorium and Boston Sheraton, Boston MA. This show consists of presentations and exhibitions by manufacturers in the computer industry. Contact Electronic Conventions Inc, 99 N Sepulveda Blvd, El Segundo CA 90245.

May 13-16

9th Annual Conference of MUMPS Users Group, Islandia Hyatt House, San Diego CA. The meeting will bring

together scientific, medical, and business professionals to discuss current research and application development. Areas of participation are paper presentations, workshops and tutorials, and vendor exhibits. Contact Dr Jack Bowie, MUG 80 Program Chairman, The MITRE Corp, Mail Stop 641, 1820 Dolley Madison Blvd, McLean VA 22102.

May 14-16

Carnahan Conference on Crime Countermeasures, Carnahan House, Lexington KY. This conference is devoted to the application of engineering and science to law enforcement, security, and crime prevention. Emphasis will be on effective research and development in computer security.

Contact the Office of Continuing Education, College of Engineering, University of Kentucky, Lexington KY 40506.

May 15

Electronic Road Shows,

Griswold's Restaurant, Pomona CA. See March 20th for details.

May 19-22

1980 National Computer Conference, Anaheim Convention Center, Anaheim CA. The conference program will include more than 120 sessions covering computing careers and education, office automation, and auditing in the area of management; computers in earth resource management, human services, and word processing in the field of applications; programming languages, design techniques and methodology, and voice simulation and recognition in software; earth resources, education, women and minorities in the computing discipline in the area of social implications; microcomputers and mini-computers, computer architecture, and new concepts in memories in the area of hardware.

For information, contact American Federation of In-

formation Processing Societies Inc, 1815 N Lynn St, Arlington VA 22209.

May 21-22

2nd Clemson Small Computer Conference, Clemson University, Clemson SC. This conference will discuss applications in engineering, science, manufacturing, small business data processing, and education. Contact William J Barnett, Electrical and Computer Engineering Dept, Riggs Hall, Clemson University, Clemson SC 29631.

May 24-25

Amateur Radio and Computer Hobbyists 2nd Annual Convention, Cervantes Convention Center, St Louis MO. Speakers, presentations, equipment displays, and a flea market will be featured. For more information, contact the Gateway Amateur Radio Association Inc, POB 68, Marissa IL 62257. ■

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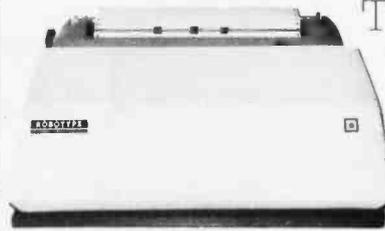
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To Err Is Human

GIGO (garbage in, garbage out) is an expression heard so often by programmers that it is accepted as truth and even offered as an excuse for poorly written programs. It is a truism that ought to be examined, especially in the area of human prepared input that is typed.

If the instructions in figure 1a are entered instead of the correct instructions of figure 1b, the great majority of microprocessor assemblers will be unable to locate any of the program symbols. This inability compels the user to go through the tedious process of calling an edit program, making corrections, calling the assembler, and trying once more to assemble the source code, hoping that no new errors have been introduced. This procedure can be very time consuming; it is always frustrating. An examination of how the errors are detected in a normal assembler

Label	Operation	Operand
1 LOOP	CPY	SPAEC
2	JSR	PRJNT
3	CMP	STRE
4	BEQ	LOOPS
5 COPY	EUQ	LOOP

Figure 1a: A section of code which illustrates several common typing errors often made during entry of an assembly program. These particular errors can be detected and corrected by a simple algorithm which determines if the operand is "close enough" to what it is supposed to be. If the operand has two transposed letters, one character wrong, or one character too many or too few, it is automatically changed to the correct form listed in the symbol table.

Label	Operation	Operand
1 LOOP	CPY	SPACE
2	JSR	PRINT
3	CMP	STORE
4	BEQ	LOOP
5 COPY	EUQ	LOOP

Figure 1b: The code from figure 1a after error detection and correction.

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Littleton CO 80123

or compiler may shed light on how an automated correction can be attempted.

Normally, after a symbol has been segregated from the source text, it is passed to a symbol table lookup routine as a search argument. The function of the lookup routine is to find an entry in the symbol table whose symbol matches the search argument, and to either return that entry (a hit) or set some indicator to inform the calling routine of an unsuccessful search (a no-hit). Both hits and no hits are valid returns, depending on the pass being made on the source code.

The first pass causes two types of lookup calls; *definition* and *reference*. For a definition lookup, a symbol has been extracted from the label field. That symbol and its attributes are to be entered into the symbol table if and only if the symbol is not already present in the symbol table. However, if the symbol is already present, it is multiply defined and in error. For a reference lookup, a symbol found in the operand field is needed for a compile time computation (line 5 of figure 1b). For this lookup, the symbol must be present in the symbol table or an error condition exists.

During any other pass, a no-hit constitutes an error. It is at this point that error correction may be attempted in the form of an alternate (associated) symbol lookup.

If the lookup routine can find another symbol in the symbol table that is "close enough" to the search argument, then the entry's symbol is associated with the argument symbol and may be returned as a hit. When an alternate symbol is substituted in this fashion, the programmer must be given a warning as the substitution may not be correct. By checking the object code generated, the programmer can verify the substitution.

What constitutes "close enough" before a symbol table entry can be substituted for the search argument?

About the Author

Roger McGregor works as a systems programmer on a large IBM system. He has written or worked on many operating systems, assemblers, compilers, and interpreters, and has successfully used the techniques presented here in an assembler.

"Close enough" is defined as two characters transposed (line 1, figure 1a), one character wrong (line 2, figure 1a), one missing character (line 3, figure 1a), or an extra character (line 4, figure 1a).

Given the above criteria, only certain symbols in the symbol table need be reexamined. Those symbols are the ones possessing an equal number of characters, or one more or one less character than the search argument. An exception occurs when the search argument consists of only a single character: if this happens, error correction should be terminated and a no-hit returned. Those symbols with an equal number of characters should be compared for transposed characters or one wrong character in the string. Those symbols with one more or one less character than the search argument should be checked for a single character difference. If any symbol in the symbol table passes one of the above tests, an association has occurred and the associated entry should be returned as a hit.

Generally, making a single pass through the symbol table and returning the first entry passing a check is sufficient. However, if the keyboard layout is more conducive to wrong characters due to upper and lower case shifting than to the other common errors of transposition, addition, or deletion, then a first pass through the symbol table checking only equal character count symbols for wrong characters could prove to be more accurate. Alternate strategies do however increase memory usage and execution time. The execution time is well spent if a proper association prevents the edit and reassemble process already described. Memory usage is another matter. The less memory used by the correction routine, the better.

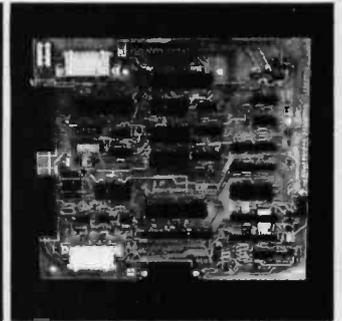
Besides alleviating reassembly problems, the error correction process tends to encourage better documented programs. Due to the nature of the checks made for the association, longer symbols have a better chance of being correctly associated. They are also usually more meaningful.

The above correction process is by no means limited to just the symbol table of an assembler and compiler. It can be applied to any dictionary type lookup including op codes, text processors, and console commands.

The only obvious limitation would occur when symbols intentionally differ by a transposition or length. In order to overcome this objection, we simply require an explicit declaration statement and correct spelling in such statements with the extended error correction applied to uses of a name. ■

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```

10 DIM#(256),S(64),W(3,76),T(76),N(6,64),P(4),V(64)
20 C1$="0123456789"VP(0)=22VP(1)=147VP(2)=1030VP(3)=2VP(4)=3
30 OPEN#0,"A16"LINE#0
40 FORA=1T076\READ#0,W(0,A),W(1,A),W(2,A),W(3,A)\NEXT\FORA=1T064
50 READ#0,N(0,A),N(1,A),N(2,A),N(3,A),N(4,A),N(5,A),N(6,A)\NEXT
60 CLOSE#0\INPUT"0 TO 9 : 0 I PLAY BEST AND 9 WORST ? ",Z=1+(Z/10)
100 FORA=1T064\B=A*4\C$(B-3,B)="          "\C=INT(A/10)\B=A-(C*10)
110 C$(B-1,B-1)=C1$(C+1,C+1)\C$(B,B)=C1$(B+1,B+1)\NEXT
120!"HERE IS MY BOARD"!""\GOSUB1000!""!\ENTER MOVES BY",
130!" NUMBER AND YOUR'RE X"
140!"\INPUT"YOUR MOVE ? ",X\IFX<10RX>64THEN140\IFS(X)<>0THEN140
150 S(X)=1\A=X*4\C$(A-3,A)="XXX"\P=1\GOSUB900
160 B=0\FORA=1T076STEPZ\C=T(A)\IFC<0THEN200\IFC=15THENEXIT400
170 IFC<>0THEN180\B=1\GOSUB500\GOTO200
180 IFC>4THEN190\B=P(C-1)\GOSUB500\GOTO200
190 C=INT(C/5)+2\B=P(C)\GOSUB500
200 NEXT\FORA=1T064\IFV(A)<0THEN210\Q=V(A)\X=A
210 V(A)=0\NEXT\IFQ=0ANDZ=1THEN1600\IFQ<>0THEN220
215 FORA=1T064\IFS(A)=0THENEXIT217\NEXT\GOTO1600
217 S(A)=1\X=A
220 S(X)=1\A=X*4\C$(A-3,A)="0000"\P=5\GOSUB900
230!"I WENT",X!""\GOSUB1000\GOTO140
400!"THE COMPUTER WINS WITH BOXES",W(0,A),W(1,A),W(2,A),W(3,A)\GOTO2000
500 FORF=0T03\G=W(F,A)\IFS(G)=0THENV(G)=V(G)+B\NEXT\RETURN
900 FORA=0T06\C=N(A,X)\IFC=0THEN950\IFT(C)<0THEN950
910 T(C)=T(C)+P\IFT(C)<4THEN950\IFT(C)=4THENEXIT1700
920 D=INT(T(C)/5)\IFD*5<>T(C)THENT(C)=-1
950 NEXT\RETURN
1000 FORA=0T03\FORB=2T00STEP-2\FORC=0T03\FORD=1T04
1010 E=((C*16)+D+(A*4))*4-B\C$(E-1,E),\IFD<4THEN!" = ",
1020 NEXT\IFC<3THEN!" ",\NEXT!\!"\NEXT\IFA=3THEN1040
1030 FORE=1T03!\!"===== ",\NEXT!\!"=====
1040 NEXT\RETURN
1600!"\!"IT'S A DRAW"\GOTO2000
1700!"\F=C\GOSUB1000!""\C=F!\YOU WON",W(0,C),W(1,C),W(2,C),W(3,C)
2000 INPUT"CARRIAGE RETURN ENDS, ANYTHING ELSE PLAYS AGAIN ? ",Z#
2005 IFZ$=""THENEND\FORA=1T076\T(A)=0\NEXT\FORA=1T064\B(A)=0\V(A)=0\NEXT
2010 GOTO100
READY

```

Listing 1: Super TIC, a three-dimensional tic-tac-toe computer game written in North Star BASIC. (All other programs in this article are also written in North Star BASIC.)

Super TIC

J Roehrig
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Listing 2: Modifications to listing 1 to change the three-dimensional version into two-dimensional 4 by 4 tic-tac-toe.

```

140!"\INPUT"YOUR MOVE ? ",X\IFX<10RX>16THEN140\IFS(X)<>0THEN140
160 B=0\FORA=1T010STEPZ\C=T(A)\IFC<0THEN200\IFC=15THENEXIT400
1000 FORA=0T03\FORB=2T00STEP-2\FORC=0T00\FORD=1T04
1030!"=====

```

Super Micro-Tic

This article describes Super TIC, a program that plays three-dimensional (4 by 4 by 4) tic-tac-toe. It was written specifically for microprocessors and has the following features:

- It is fast, despite the fact that it checks every possible move. The response time is 13 seconds per move (worst case) using an IMSAI 8080 computer with North Star BASIC, and it averages less than six seconds per move.

- It gives a graphic display of the game (designed for a 24 line by 80 character terminal) without requiring a graphics board.
- It plays at ten different levels of skill without requiring modification of the program.
- One program line can be modified to change the program's strategy so that it plays defensively or aggressively.
- The modification of four lines (see listing 2) allows the game to be played in a two-dimensional 4 by 4 format.

Listing 3 shows a sample run of the 4 by 4 by 4 version. The computer asks for the level of play desired and gives a display of the game board. The player enters a move selection (a number from 1 to 64 corresponding to the desired box) and the computer answers with its move. Next, the

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entire game board is reprinted with the player's boxes represented by Xs and the computer's boxes by Os.

For those readers not familiar with three-dimensional tic-tac-toe, table 1 shows all of the 76 possible winning combinations. The

first player to occupy 4 squares (or, more properly, "cubes") in a straight line wins. Note that there are ten ways to win on each of the four boards (four horizontal, four vertical and two diagonal) and 36 ways to win by occupying one adjoining square on each of the separate boards.

For comparison of strategies, the tic-tac-toe program, written by R K Loudon ("TTT3D" in *Programming the IBM 1130 and 1800*, Prentice-Hall, 1967), keeps totalling values for the 76 winning combinations after each move, tests for only three or four critical situations and always examines the 64 squares for vacant positions. The use of this technique would take a few minutes for each move using a microcomputer, and the program is considerably longer.

The key to writing a program efficient enough to operate on a microcomputer is to limit the number of operations performed. Instead of constantly totalling winning combinations after each move, a running total is maintained in Super TIC. The importance of winning combination totals is simple. A 0 is assigned to blank squares, a 1 to squares with Xs and a 5 to squares with Os. A winning combination totalling 0 represents a line that either player can still win with; a combination value less than 5 and greater than 0 is a combination in which only X can win; a combination total evenly divisible by 5 represents a possible O win; and all other values are blocked (no one can win) combinations. This same totalling method shows how many Xs or Os occupy the four squares of the winning combinations.

In order to make Super TIC execute quickly, only the 76 winning combinations are checked to determine the computer's

Table 1: The 76 possible ways to win in 4 by 4 by 4 three-dimensional tic-tac-toe. The columns labelled M1, M2, M3 and M4 given an integer identification of a particular cube in the three-dimensional 4 by 4 by 4 matrix.

COMB	M1	M2	M3	M4	COMB	M1	M2	M3	M4
1	1	2	3	4	2	5	6	7	8
3	9	10	11	12	4	13	14	15	16
5	1	5	9	13	6	2	6	10	14
7	3	7	11	15	8	4	8	12	16
9	1	6	11	16	10	4	7	10	13
11	17	18	19	20	12	21	22	23	24
13	25	26	27	28	14	29	30	31	32
15	17	21	25	29	16	18	22	26	30
17	19	23	27	31	18	20	24	28	32
19	17	22	27	32	20	20	23	26	29
21	33	34	35	36	22	37	38	39	40
23	41	42	43	44	24	45	46	47	48
25	33	37	41	45	26	34	38	42	46
27	35	39	43	47	28	36	40	44	48
29	33	38	43	48	30	36	39	42	45
31	49	50	51	52	32	53	54	55	56
33	57	58	59	60	34	61	62	63	64
35	49	53	57	61	36	50	54	58	62
37	51	55	59	63	38	52	56	60	64
39	49	54	59	64	40	52	55	58	61
41	1	17	33	49	42	2	18	34	50
43	3	19	35	51	44	4	20	36	52
45	5	21	37	53	46	6	22	38	54
47	7	23	39	55	48	8	24	40	56
49	9	25	41	57	50	10	26	42	58
51	11	27	43	59	52	12	28	44	60
53	13	29	45	61	54	14	30	46	62
55	15	31	47	63	56	16	32	48	64
57	1	22	43	64	58	5	22	39	56
59	9	26	43	60	60	13	26	39	52
61	2	22	42	62	62	14	26	38	50
63	3	23	43	63	64	15	27	39	51
65	4	23	42	61	66	8	23	38	53
67	12	27	42	57	68	16	27	38	49
69	1	21	41	61	70	1	18	35	52
71	4	19	34	49	72	4	24	44	64
73	13	25	37	49	74	13	30	47	64
75	16	31	46	61	76	16	28	40	52

Listing 3: Sample printout of the beginning of Super TIC.

```

O TO 9 : 0 I PLAY BEST AND 9 WORST ? 0
HERE IS MY BOARD

  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
01 = 02 = 03 = 04   17 = 18 = 19 = 20   33 = 34 = 35 = 36   49 = 50 = 51 = 52
=====
  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
05 = 06 = 07 = 08   21 = 22 = 23 = 24   37 = 38 = 39 = 40   53 = 54 = 55 = 56
=====
  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
09 = 10 = 11 = 12   25 = 26 = 27 = 28   41 = 42 = 43 = 44   57 = 58 = 59 = 60
=====
  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
13 = 14 = 15 = 16   29 = 30 = 31 = 32   45 = 46 = 47 = 48   61 = 62 = 63 = 64

ENTER MOVES BY NUMBER AND YOUR'RE X

YOUR MOVE ? 1
I WENT 64

XX =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
XX = 02 = 03 = 04   17 = 18 = 19 = 20   33 = 34 = 35 = 36   49 = 50 = 51 = 52
=====
  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
05 = 06 = 07 = 08   21 = 22 = 23 = 24   37 = 38 = 39 = 40   53 = 54 = 55 = 56
=====
  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
09 = 10 = 11 = 12   25 = 26 = 27 = 28   41 = 42 = 43 = 44   57 = 58 = 59 = 60
=====
  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =  =
13 = 14 = 15 = 16   29 = 30 = 31 = 32   45 = 46 = 47 = 48   61 = 62 = 63 = 00

YOUR MOVE ?

```

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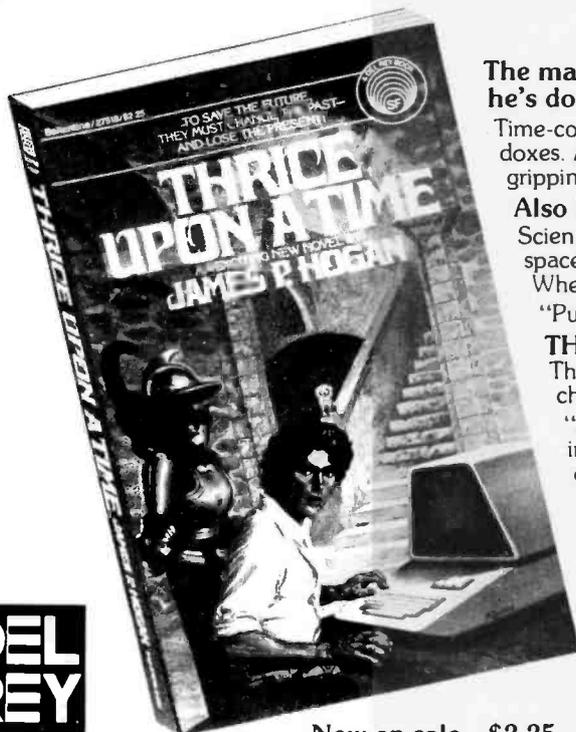
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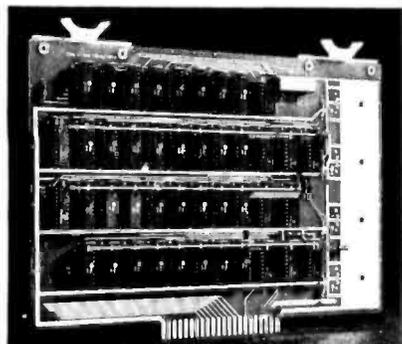
Combination	Variable	Value (Defensive Version)	Value (Aggressive Version)
All Blanks		1	1
One X	P(0)	22	7
Two Xs	P(1)	147	22
Three Xs	P(2)	1030	147
One O	P(3)	2	2
Two Os	P(4)	3	3
All Others	—	0	0

NOTE: The computer is O and the values described are used to determine the computer's move. A value for three Os is not needed, since the computer will select that as its winning move without additional evaluation.

Table 2: Values assigned to squares under consideration. Each time a combination of four squares is checked by the program, these values are assigned to blank squares depending upon the nearest neighbors forming the best partial pattern combination listed.

NUM	C1	C2	C3	C4	C5	C6	C7	NUM	C1	C2	C3	C4	C5	C6	C7
1	1	5	9	41	57	69	70	2	1	6	42	61	0	0	0
3	1	7	43	63	0	0	0	4	1	8	10	44	65	71	72
5	2	5	45	58	0	0	0	6	2	6	9	46	0	0	0
7	2	7	10	47	0	0	0	8	2	8	48	66	0	0	0
9	3	5	49	59	0	0	0	10	3	6	10	50	0	0	0
11	3	7	9	51	0	0	0	12	3	8	52	67	0	0	0
13	4	5	10	53	60	73	74	14	4	6	54	62	0	0	0
15	4	7	55	64	0	0	0	16	4	8	9	56	68	75	76
17	11	15	19	41	0	0	0	18	11	16	42	70	0	0	0
19	11	17	43	71	0	0	0	20	11	18	20	44	0	0	0
21	12	15	45	69	0	0	0	22	12	16	19	46	57	58	61
23	12	17	20	47	63	65	66	24	12	18	48	72	0	0	0
25	13	15	49	73	0	0	0	26	13	16	20	50	59	60	62
27	13	17	19	51	64	67	68	28	13	18	52	76	0	0	0
29	14	15	20	53	0	0	0	30	14	16	54	74	0	0	0
31	14	17	55	75	0	0	0	32	14	18	19	56	0	0	0
33	21	25	29	41	0	0	0	34	21	26	42	71	0	0	0
35	21	27	43	70	0	0	0	36	21	28	30	44	0	0	0
37	22	25	45	73	0	0	0	38	22	26	29	46	62	66	68
39	22	27	30	47	58	60	64	40	22	28	48	76	0	0	0
41	23	25	49	69	0	0	0	42	23	26	30	50	61	65	67
43	23	27	29	51	57	59	63	44	23	28	52	72	0	0	0
45	24	25	30	53	0	0	0	46	24	26	54	75	0	0	0
47	24	27	55	74	0	0	0	48	24	28	29	56	0	0	0
49	31	35	39	41	68	71	73	50	31	36	42	62	0	0	0
51	31	37	43	64	0	0	0	52	31	38	40	44	60	70	76
53	32	35	45	66	0	0	0	54	32	36	39	46	0	0	0
55	32	37	40	47	0	0	0	56	32	38	48	58	0	0	0
57	33	35	49	67	0	0	0	58	33	36	40	50	0	0	0
59	33	37	39	51	0	0	0	60	33	38	52	59	0	0	0
61	34	35	40	53	65	69	75	62	34	36	54	61	0	0	0
63	34	37	55	63	0	0	0	64	34	38	39	56	57	72	74

Table 3: Winning combinations for each square. The 64 squares of the board are listed under NUM, to the right of which are the winning combination numbers involved with each square (see table 1). After each combination is examined, the value shown in table 2 is assigned to any blank square in the combination. These values are accumulated as each combination is evaluated. The square with the highest value becomes the computer's next move.



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move. Furthermore, once the combination is considered blocked (at least one X and at least one O in the four boxes making up the possible winning combination) a negative value is assigned and the combination is never checked again.

This leaves us with the problem of selecting a move. Each time a combination is checked, a value is assigned to the group of four squares making up the combination. These values are shown in table 2 for two possible versions of Super TIC, and are contained on line 20 of the program.

The next difficulty is determining which winning combinations are associated with each square. These values are calculated ahead of time using a short program and are read into the program as data. Table 3 shows the 64 game squares and which of the winning combinations use which particular squares (the winning combination numbers refer back to the combinations detailed in table 1). After each combination is examined, the value shown in table 2 is assigned to any blank square in the combination. These values are accumulated as each combination is evaluated. The square with the highest value becomes the computer's move.

In order to test the program as well as the different strategies, the program shown in listing 4 can be used to pit the computer against itself. The defensive game always plays itself to a draw. Note that line 35 in listing 4 adds a new variable Y(4) that gives a different strategy to be used for the player moving first when the computer plays against itself. To my surprise, the defensive version can be beaten.

As mentioned earlier, the game plays at ten different levels. Level 0 checks all 76 combinations, while level 9 checks only 40 combinations. Table 4 shows which levels check how many combinations and which specific combinations.

Listing 4: Program to enable the computer to play against itself in the game of Super TIC.

```

10 DIMC$(256),S(64),W(3,76),T(76),N(6,64),F(4),V(64)
15 DIMM(1,36)
20 C1$="0123456789\NP(0)=2\N(1)=147\N(2)=1030\N(3)=2\N(4)=3
30 OPEN#0,"A16"\LINE130
35 DIMY(4)\Y(0)=2\Y(1)=147\Y(2)=1030\Y(3)=2\Y(4)=3
40 FORA=1TO76\READ#0,W(0,A),W(1,A),W(2,A),W(3,A)\NEXT\FORA=1TO64
50 REA#0,N(0,A),N(1,A),N(2,A),N(3,A),N(4,A),N(5,A),N(6,A)\NEXT
60 CLOSE#0:Z=1
90 N(0,30)=14
100 FDRA=1TO64\B=A*4\C$(B-3,B)="    "C=INT(A/10)\D=A-(C*10)
110 C$(B-1,B-1)=C1$(C+1,C+1)\C$(B,B)=C1$(D+1,D+1)\NEXT
114 FORI9=1TO64\X=I9\C9=1
115 "!"\GAME STARTED WITH",I9
141 GOT0150
145 GOT0660
150 S(X)=1\A=X*4\C$(A-3,A)="XXX"\P=1\GOSUB900
155 M(0,C9)=X
160 Q=0\FORA=1TO76STEPZ\C=T(A)\IFC<0THEN200\IFC=15THENEXIT400
170 IFC<>0THEN180\B=1\GOSUB500\GOTO200
180 IFC>4THEN190\B=P(C-1)\GOSUB500\GOTO200
190 C=INT(C/5)+2\B=P(C)\GOSUB500
200 NEXT\FORA=1TO64\IFV(A)<0THEN210\Q=V(A)\X=A
210 V(A)=0\NEXT\IFQ=0THEN190
220 S(X)=1\A=X*4\C$(A-3,A)="0000"\P=5\GOSUB900
230 M(1,C9)=X\C9=C9+1\GOTO145
400 !"THE COMPUTER WINS WITH BOXES",W(0,A),W(1,A),W(2,A),W(3,A)\GOTO2000
500 FORF=0TO3\G=W(F,A)\IFS(G)=0THENV(G)=V(G)+B\NEXT\RETURN
660 Q=0\FORA=1TO76STEPZ\C=T(A)\IFC<0THEN700\IFC=3THENEXIT400
670 IFC<>0THEN680\B=1\GOSUB500\GOTO700
680 IFC<5THEN690\B=INT(C/5)\B=Y(B-1)\GOSUB500\GOTO700
690 B=Y(C+2)\GOSUB500
700 NEXT\FORA=1TO64\IFV(A)<0THEN710\Q=V(A)\X=A
710 V(A)=0\NEXT\IFQ=0THEN190
720 GOT0150
900 FORA=0TO6\C=N(A,X)\IFC=0THEN950\IFT(C)<0THEN950
910 T(C)=T(C)+F\IFT(C)<4THEN950\IFT(C)=4THENEXIT1700
920 D=INT(T(C)/5)\IFD#5<>T(C)THENT(C)--1
950 NEXT\RETURN
1000 RETURN
1700 !"F=C\GOSUB1000!"\C=F!"YOU WDN",W(0,C),W(1,C),W(2,C),W(3,C)
1900 "!"\IT'S A DRAW"
2000 Z$=" "
2005 IFZ$=""THENEND\FORA=1TO76\T(A)=0\NEXT\FORA=1TO64\S(A)=0\U(A)=0\NEXT
2020 !"PLAYER 1"\FORA=1TO36\IFM(0,A)=0THENEXIT2030\!X3I,M(0,A),\NEXT
2030 "!"\!PLAYER 2"\FORA=1TO36\IFM(1,A)=0THENEXIT2035\!X3I,M(1,A),\NEXT
2035 "!"\FORA=1TO36\M(1,A)=0\M(0,A)=0\NEXT
2040 NEXTI9\END
READY
RUN

```

```

GAME STARTED WITH 1
THE COMPUTER WINS WITH BOXES 1 2 3 4
PLAYER 1
 1 61 52 49 25 47 60 16  4 42 38 22 19 36 26  2
PLAYER 2
 64 41 58 57 13 35 17 28 46 23 27  6 34 20 50 62
GAME STARTED WITH 2

```

SL5...A NEW PROGRAMMING SYSTEM FOR A NEW DECADE

James M Goldenberg
Silicon Valley OEM Corp.

March 1, 1979

Dear Jim:

We've done it. SL5 is ready for distribution, and its pure dynamite. I'm convinced it's the OEM programming system for the 80's. SL5 is a well structured (built-in recursion & CASE statements), stack oriented, interactive programming tool for small systems and is based on the 1977 Forth standard.

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Sincerely,
Dave
Dave DeLauter

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Listing 5: Sample printout of two-dimensional version of Super TIC (see listing 2).

```

O TO 9 : O I PLAY BEST AND 9 WORST ? 5
HERE IS MY BOARD:

  =   =   =
01 = 02 = 03 = 04
=====
  =   =   =
05 = 06 = 07 = 08
=====
  =   =   =
09 = 10 = 11 = 12
=====
  =   =   =
13 = 14 = 15 = 16

ENTER MOVES BY NUMBER AND YOUR'RE X

YOUR MOVE ? 9
I WENT 5

  =   =   =
01 = 02 = 03 = 04
=====
  =   =   =
00 =     =     =
00 = 06 = 07 = 08
=====
  =   =   =
XX =     =     =
XX = 10 = 11 = 12
=====
  =   =   =
13 = 14 = 15 = 16

```

COMB	0	1	2	3	4	5	6	7	8	9	COMB	0	1	2	3	4	5	6	7	8	9
1	X	X	X	X	X	X	X	X	X	X	2	X	X	X	X	X	X	X	X	X	X
3	X	X	X	X	X						4	X	X	X	X	X	X	X	X	X	X
5	X	X	X	X	X	X					6	X	X	X	X						
7	X	X	X	X	X	X	X				8	X	X	X	X	X					
9	X	X	X	X	X	X	X				10	X	X	X	X	X	X				
11	X	X	X	X	X	X	X				12	X	X	X	X	X	X				
13	X	X	X	X	X	X	X				14	X	X	X	X	X	X				
15	X	X	X	X	X	X	X				16	X	X	X	X	X	X				
17	X	X	X	X	X	X	X				18	X	X	X	X	X	X				
19	X	X	X	X	X	X	X				20	X	X	X	X	X	X				
21	X	X	X	X	X	X	X				22	X	X	X	X	X	X				
23	X	X	X	X	X	X	X				24	X	X	X	X	X	X				
25	X	X	X	X	X	X	X				26	X	X	X	X	X	X				
27	X	X	X	X	X	X	X				28	X	X	X	X	X	X				
29	X	X	X	X	X	X	X				30	X	X	X	X	X	X				
31	X	X	X	X	X	X	X				32	X	X	X	X	X	X				
33	X	X	X	X	X	X	X				34	X	X	X	X	X	X				
35	X	X	X	X	X	X	X				36	X	X	X	X	X	X				
37	X	X	X	X	X	X	X				38	X	X	X	X	X	X				
39	X	X	X	X	X	X	X				40	X	X	X	X	X	X				
41	X	X	X	X	X	X	X				42	X	X	X	X	X	X				
43	X	X	X	X	X	X	X				44	X	X	X	X	X	X				
45	X	X	X	X	X	X	X				46	X	X	X	X	X	X				
47	X	X	X	X	X	X	X				48	X	X	X	X	X	X				
49	X	X	X	X	X	X	X				50	X	X	X	X	X	X				
51	X	X	X	X	X	X	X				52	X	X	X	X	X	X				
53	X	X	X	X	X	X	X				54	X	X	X	X	X	X				
55	X	X	X	X	X	X	X				56	X	X	X	X	X	X				
57	X	X	X	X	X	X	X				58	X	X	X	X	X	X				
59	X	X	X	X	X	X	X				60	X	X	X	X	X	X				
61	X	X	X	X	X	X	X				62	X	X	X	X	X	X				
63	X	X	X	X	X	X	X				64	X	X	X	X	X	X				
65	X	X	X	X	X	X	X				66	X	X	X	X	X	X				
67	X	X	X	X	X	X	X				68	X	X	X	X	X	X				
69	X	X	X	X	X	X	X				70	X	X	X	X	X	X				
71	X	X	X	X	X	X	X				72	X	X	X	X	X	X				
73	X	X	X	X	X	X	X				74	X	X	X	X	X	X				
75	X	X	X	X	X	X	X				76	X	X	X	X	X	X				

```

FOR LEVEL 0 : 1.000% OR 76/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 1 : .908% OR 69/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 2 : .829% OR 63/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 3 : .763% OR 58/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 4 : .711% OR 54/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 5 : .671% OR 51/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 6 : .618% OR 47/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 7 : .592% OR 45/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 8 : .553% OR 42/76 OF THE COMBINATIONS ARE CHECKED
FOR LEVEL 9 : .526% OR 40/76 OF THE COMBINATIONS ARE CHECKED

```

Table 4: Winning combinations checked by each level of expertise in Super TIC. Level 0 is the most proficient level, level 9 the least. An X in the column for a given combination indicates that the given combination is to be checked.

Listing 6: Modifications to listing 1 to avoid the need for a disk data file.

```

30 LINE80
40 FORA=1TO76\READW(O,A),W(1,A),W(2,A),W(3,A)\FORB=OTO3\C=W(B,A)
50 FORD=OTO6\IFN(D,C)=OTHENEXIT52\NEXT
52 N(D,C)=A\NEXT\NEXT
3000 DATA 1, 2, 3, 4, 5, 6, 7, 8, 9,10,11,12,13,14,15,16, 1, 5, 9,13
3010 DATA 2, 6,10,14, 3, 7,11,15, 4, 8,12,16, 1, 6,11,16, 4, 7,10,13
3020 DATA17,18,19,20,21,22,23,24,25,26,27,28,29,30,31,32,17,21,25,29
3030 DATA18,22,26,30,19,23,27,31,20,24,28,32,17,22,27,32,20,23,26,29
3040 DATA33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,33,37,41,45
3050 DATA34,38,42,46,35,39,43,47,36,40,44,48,33,38,43,48,36,39,42,45
3060 DATA49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,49,53,57,61
3070 DATA50,54,58,62,51,55,59,63,52,56,60,64,49,54,59,64,52,55,58,61
3080 DATA 1,17,33,49, 2,18,34,50, 3,19,35,51, 4,20,36,52, 5,21,37,53
3090 DATA 6,22,38,54, 7,23,39,55, 8,24,40,56, 9,25,41,57,10,26,42,58
3100 DATA11,27,43,59,12,28,44,60,13,29,45,61,14,30,46,62,15,31,47,63
3110 DATA16,32,48,64, 1,22,43,64, 5,22,39,56, 9,26,43,60,13,26,39,52
3120 DATA 2,22,42,62,14,26,38,50, 3,23,43,63,15,27,39,51, 4,23,42,61
3130 DATA 8,23,38,53,12,27,42,57,16,27,38,49, 1,21,41,61, 1,18,35,52
3140 DATA 4,19,34,49, 4,24,44,64,13,25,37,49,13,30,47,64,16,31,46,61
3150 DATA16,28,40,52
READY

```

A sample run of the 4 by 4 version is given in listing 5. Here level 5 was used and, according to table 4, combination 3 is not checked. Therefore, combination 3 was an easy winner.

The data read into Super TIC was taken from a disk file using conventions of North Star BASIC. In order to modify this, merely take out the open file statement (line 30) and add data statements. The file designation in the line 40 and line 50 read statements should also be removed. Listing 6 shows how this can be accomplished.

Super TIC, as presented, is almost unbeatable (I believe that it is impossible to write an unbeatable version as long as the player always goes first and the computer second). You could probably play for days and never do better than a draw. However, armed with the computer generated winning combination in listing 4, you can beat the computer easily by remembering 16 exact moves. ■



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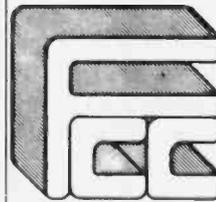


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The package will be available in those same three configurations. The CP/M version will run on any CP/M environment (includes CDOS, IMSAIDOS, etc.) and has its origin at 100H. The Northstar system will run on any Horizon or any non-relocated MDS system. It has origin at 2D00H. The SOLOS/CUTER system will run on any SOL or any CUTER system, and it has origin of 100H. All versions are designed to operate correctly in an interrupt driven environment.

The system has been designed to be upwardly compatible with the now unavailable Proc Tech Music System, so users of that system may run their programs with the new interpreter. The new interpreter has been dubbed Music Language #1 or ML/1 for short. The programs written for the old Music System will be greatly improved with the new system as the tones produced are much finer and more controllable.

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Programming Quickies

The Towers of Hanoi Solution Using BASIC Recursion

Stanley Switzer, 1019 W 27th St, Lawrence KS 66044

The Towers of Hanoi is an intriguing puzzle of the Orient. The puzzle requires three vertical rods and a given number of disks with holes in the center to be placed on the rods. Initially, all of the disks are placed on the leftmost rod, arranged by size with the largest disk on the bottom (see figure 1). The objective is to move all of the disks to the rightmost rod. There are, however, a few restrictions. Only one disk may be moved at a time, and no disk may be placed over a disk smaller than itself. The solution to this puzzle may seem difficult at first, but with the help of a recursive program, it is simple.

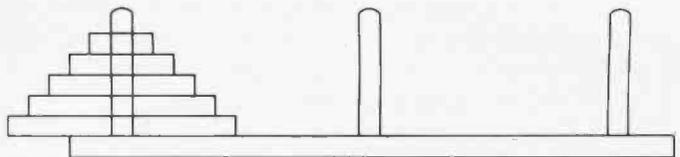


Figure 1: Initial configuration for the Towers of Hanoi problem. The objective is to move all the disks one at a time from the left rod to the right rod without ever placing a larger disk on top of a smaller disk. Intermediate moves can be made to the center rod, of course.

A recursive program is one that is defined in terms of itself. It is utilized when a problem can be broken into several parts, and when one of those parts is a similar problem of lesser magnitude. A common example is a definition of factorials:

$$0! = 1$$
$$n! = n(n-1)!$$

Here is a recursive program for factorials written in pseudocode:

```
factorial (n)
  if (n=0)
    return(1);
  else
    return(n × factorial(n - 1));
```

In this case an iterative definition is more practical for computational purposes, but this does illustrate the concept of recursion.

When broken into its basic parts, the solution to the Towers of Hanoi problem is as follows:

- When one disk is to be moved, the solution is ob-

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vious — move the disk from the source to the destination rod.

- When $n+1$ disks are to be moved:
- 1) Move n disks from the source rod to the intermediate rod;
- 2) Move one disk from the source rod to the destination rod; and
- 3) Move n disks from the intermediate rod to the destination rod.

Listing 1: Recursive solution to the Towers of Hanoi problem in BASIC.

```

010 REM Declare the stack arrays.
020 DIM S$(15),D$(15),I$(15)
030 PRINT
040 PRINT "Number of disks";
050 INPUT P
060 REM If P is too large or too small, STOP.
070 IF (P > 15) THEN 170
080 IF (P < 1) THEN 170
090 REM Move P disks from Left to Right.
100 LET S$(P) = "L"
110 LET D$(P) = "R"
120 LET I$(P) = "C"
130 REM Move those disks!
140 GOSUB 180
150 REM Since that was so much fun let us do it again.
160 GOTO 30
170 STOP
180 REM This is the recursive HANOI procedure.
190 REM If P = 1, move one disk from source to destination.
200 IF (P > 1) THEN 230
210 PRINT "Move a disk from ";S$(P);" to ";D$(P);"."
220 RETURN
230 REM Else, move P - 1 disks from Source to Intermediate.
240 LET P = P - 1
250 LET S$(P) = S$(P + 1)
260 LET D$(P) = I$(P + 1)
270 LET I$(P) = D$(P + 1)
280 GOSUB 180
290 REM Move one disk from Source to Destination.
300 PRINT "Move a disk from ";S$(P + 1);" to ";D$(P + 1);"."
310 REM Move P - 1 disks from Intermediate to Destination.
320 LET S$(P) = I$(P + 1)
330 LET D$(P) = D$(P + 1)
340 LET I$(P) = S$(P + 1)
350 GOSUB 180
360 LET P = P + 1
370 RETURN
380 END

```

*run

Number of disks?4

Move a disk from L to C.
Move a disk from L to R.
Move a disk from C to R.
Move a disk from L to C.
Move a disk from R to L.
Move a disk from R to C.
Move a disk from L to C.
Move a disk from L to R.
Move a disk from C to R.
Move a disk from C to L.
Move a disk from R to L.
Move a disk from C to R.
Move a disk from L to C.
Move a disk from L to R.
Move a disk from C to R.

Number of disks?2

Move a disk from L to C.
Move a disk from L to R.
Move a disk from C to R.

Number of disks?1

Move a disk from L to R.

Number of disks?0

ready

*

The fact that this algorithm is correct can be proven via the principle of mathematical induction. Since a solution is defined in the case of having to move one disk and since, given a solution for n disks, a solution can be found for $n+1$ disks. That is, given a solution for one disk, we have a solution for two disks; given a solution for two disks, we have a solution for three disks, and so on. The proof that this algorithm produces the fewest possible moves is left to the reader.

Now that our algorithm is defined, we can implement the program. In many BASICs, recursion is allowed in function calls. In my BASIC, however, it is not. It turns out that recursion is supported in all BASICs for subroutine calls. The only limiting factor is the depth of subroutine nesting allowed. In my case, this limit was fifteen levels. The only major problem was the method of parameter passing. Each invocation of the HANOI program has different source, intermediate, and destination rods. In order to keep these straight, the names of these rods [L (left), R (right), C (center)] must be kept on separate stacks [S\$ (source), D\$ (destination), I\$ (intermediate)]. The variable P tells the program the number of disks to move, as well as the offset into the arrays to find the current names of the rods.

Recursion, when applied effectively, is one of the most powerful tools a programmer has. Many computer languages support recursion more fully than BASIC. Among these are Pascal, LISP, and APL. These languages allow recursive functions and local variables (local variables have separate storage locations for each invocation of the function). I hope that this Programming Quickie will prompt you to try some recursive programs. If you have access to any of the above languages, I suggest that you use them. If not, BASIC will still work. ■

The Correct Order of Operations Can Shorten Code

Pointer Decrementing on the 6502

Philip K Hooper, 5 Elm St, Northfield VT 05663

Several instances of 6502 code I have come across decrement a 16-bit pointer as follows:

DEC POINTL	decrement low byte of the pointer.
LDA POINTL	move result to accumulator.
CMP \$FF	test for page crossing.
BNE 02	if not FF, no page crossing —decrementing complete.

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DEC POINTH otherwise, decrement high byte of pointer to cross page.

The following code produces the same result, but requires two fewer bytes of code and executes 2 μ s faster:

LDA POINTL bring low byte of pointer into accumulator.
BNE 02 if not zero, no page crossing, so branch ahead, skipping high byte.
DEC POINTH otherwise, decrement high byte of pointer.
DEC POINTL and decrement low byte of pointer.

Although this might seem a minor improvement, it amounts to 20% (for a pointer on page 0), and sometimes several similar small savings substantially shrink software storage space stress. ■

Sets Tutoring in BASIC

Linda M Schreiber, 29143 Carlton, Inkster MI 48141

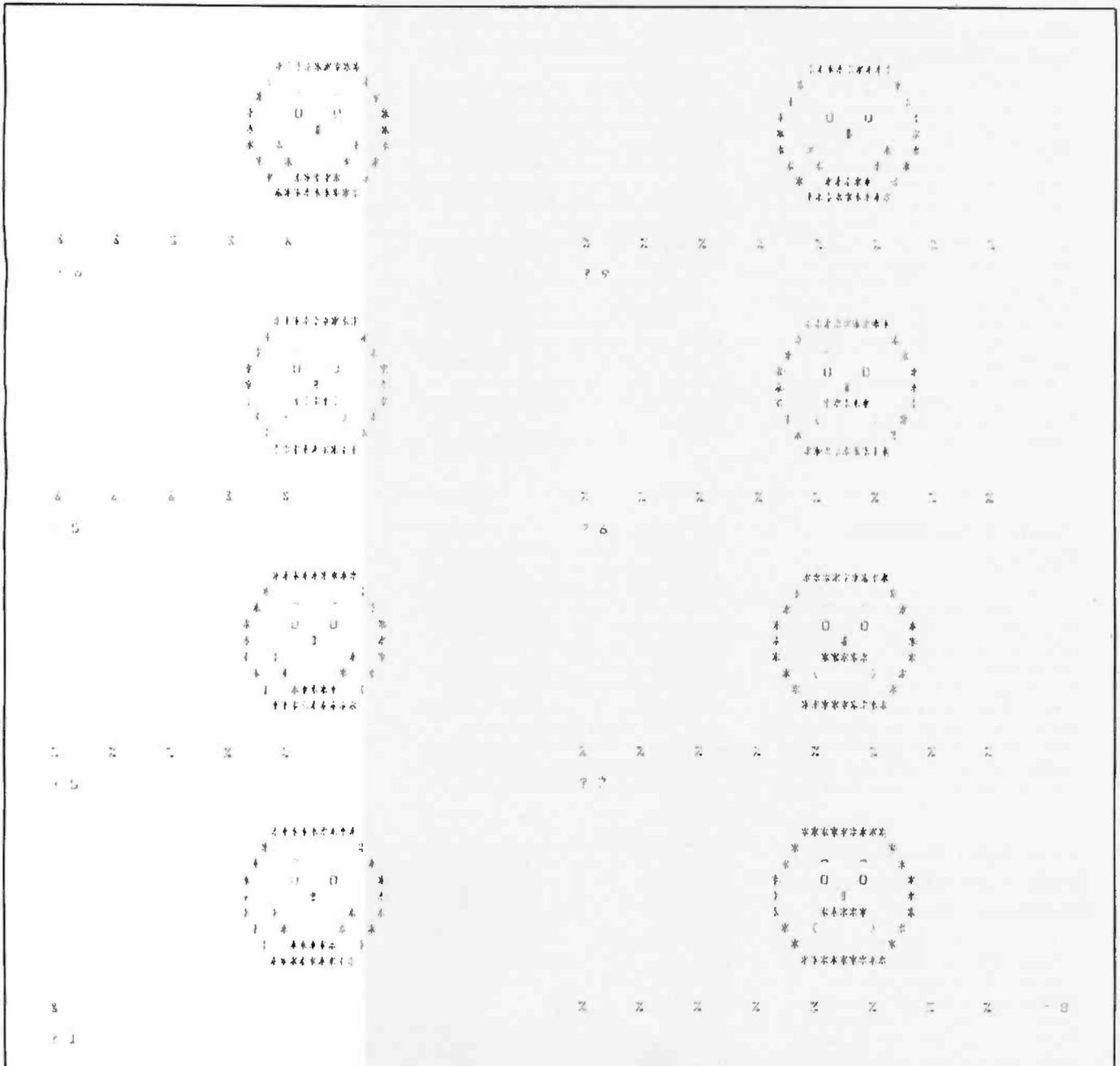
Listing 1: Altair Extended BASIC listing for helping children learn about sets.

```

10 ' ***** SETS VER. 1 *****
20 ' ** L. M. SCHREIBER **
30 ' * 4-78 ALTAIR EXTENDED-BASIC *
40 ' PURPOSE: TO TEACH NUMBER RECOGNITION & THE NUMERICAL VALUE
50 ' OF A GIVEN SET.
60 ' MESSAGE TO AN ADULT.
70 PRINT 'THE CHILD WILL BE SHOWN A SET OF CHARACTERS.'
80 PRINT 'AFTER COUNTING THE CHARACTERS, THE CHILD SHOULD ENTER'
90 PRINT 'THAT NUMBER FROM THE KEYBOARD. IF THE CORRECT NUMBER IS'
100 PRINT 'ENTERED, THE TERMINAL WILL SMILE. IF THE NUMBER IS WRONG.'
110 PRINT 'THE TERMINAL WILL FROWN.'
120 C=INT(RND(1)*4)+35 'CHOOSE ASCII CODE FOR CHARACTER
130 N=INT(RND(1)*9)+1 'CHOOSE A NUMBER BETWEEN 1 AND 9
140 T=T+1 'COUNT NUMBER OF SETS VIEWED
145 W=0 'CLEAR COUNTER FOR WRONG ANSWERS
150 C$=CHR$(C) 'CONVERT ASCII CODE TO CHARACTER
160 PRINT:PRINT:F$="" 'CLEAR FLAG FOR NEXT ANSWER
170 FOR P=1 TO N 'LOOP TO PRINT CHARACTERS
180 PRINT C$ ' '
190 NEXT P
195 IF W=3 THEN PRINT*="N:GOTO 120
200 PRINT:PRINT:INPUT G$ 'ENTER NUMBER OF CHARACTERS
210 IF VAL(G$)<>N THEN F$='FROWN' 'CHECK ANSWER
215 PRINT:PRINT
220 PRINTTAB(23)'*****'
230 PRINTTAB(22)'* * * * *'
240 PRINTTAB(21)'* * * * *'
250 PRINTTAB(20)'* * * * *'
260 PRINTTAB(20)'* * * * *'
270 IF F$='FROWN' THEN 330
280 PRINTTAB(20)'* * * * *'
290 PRINTTAB(21)'* * * * *'
300 PRINTTAB(22)'* * * * *'
310 PRINTTAB(23)'*****'
320 IF T<>5 THEN 120 ELSE 380
330 PRINTTAB(20)'* * * * *'
340 PRINTTAB(21)'* * * * *'
350 PRINTTAB(22)'* * * * *'
360 PRINTTAB(23)'*****'
365 W=W+1
370 GOTO 160
380 PRINT:PRINT:PRINT:PRINT'BYE'
390 END
OK
    
```

The program *Sets* (shown in listing 1) reinforces the recognition of numbers and their set values for a preschool child. Except for a message at the beginning of the program, no reading is required. All interaction be-

Listing 2: Sample run of program Sets. The computer outputs a smiling face when the child's answer is correct and a frowning face when the answer is incorrect.



tween the computer and the child is accomplished by the use of graphics.

The terminal prints out a set of 1 to 9 characters for the child to count (see listing 2 for sample run). The child enters the number from the keyboard. If the number entered is incorrect, a frown will appear on the terminal. When the correct number is entered, the terminal will show a smile. The child is allowed three attempts to answer each set correctly. The answer will be printed after the third attempt.

In line 200, a string variable is used for input, so that a

child who mistakenly enters a letter or symbol will not become frustrated with error messages. All incorrect inputs are treated in the same manner.

The T variable in line 140 counts the number of sets the child will be shown. In this version the program will end after 5 sets. The variable can be easily increased (lines 195 and 320) for a child with a longer attention span. Similarly, the 9 in line 130 can be changed to a greater value for the child who has mastered sets from 1 to 9.

Sets is written in Altair (Microsoft) Extended BASIC and uses just over 1 K bytes of memory. ■

What's New?

SOFTWARE

Z80-Based Disk Operating System Written in PL/M

A Z80-based operating system which allows up to four simultaneous users and hard disk-drive control has been released by Altos Computer Systems. AMEX (Altos Multi-User Executive) is written in PL/M and is compatible with CP/M versions 1.4 and 2.0. AMEX can manage up to four user-memory areas of up to 48 K bytes each. It utilizes a priority ordered interrupt-driven dispatching algorithm. Priority is given to input/output (I/O) bound tasks, while microprocessor compute-bound tasks tend to migrate to the bottom of the priority line.

Access to on-line storage on floppy or hard disk is handled for multiple users by AMEX, using direct memory address (DMA) hardware. AMEX features a

dispatcher and a spooler that allocate and free various peripheral devices as requested by user programs or commands. The system is designed to carry on multitasking operations within an individual user's 48 K memory block. AMEX includes a screen-oriented text editor, an 8080 assembler, built-in utilities, file management commands and a transient command handler which allows the user to define new disk-oriented commands separate from those implemented by CP/M.

AMEX requires an Altos ACS8000 series computer and 64 K bytes for one user, 112 K bytes for two users, and 208 K bytes for four users. It is priced at \$250 and comes on a single floppy disk. Contact Altos Computer Systems, 2338-A Walsh Ave, Santa Clara CA 95050.

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Apple II Animation Package

The A2-3D1 is a package of easy to use assembly language programs for three-dimensional and two-dimensional animation on the Apple II. The program allows users to view two- or three-dimensional scenes created in the standard XYZ coordinate system, zoom between wide angle and telephoto fields of view, select a location in space, and a direction of view. One feature allows users to generate an output array of line

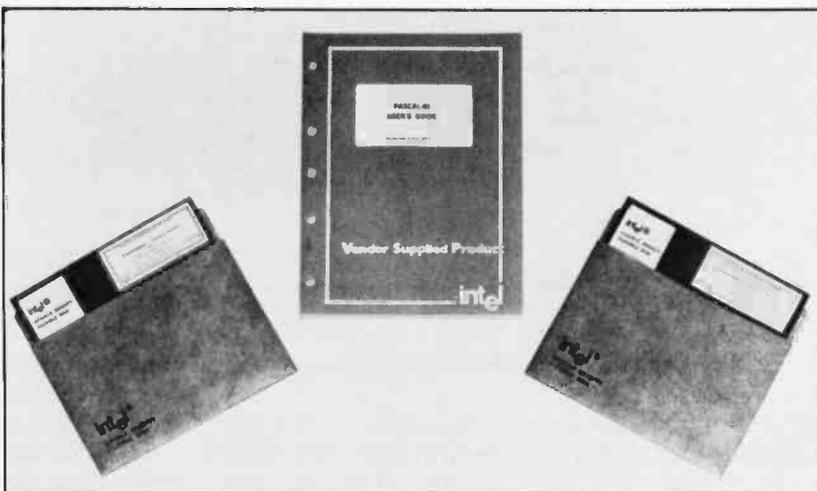
start and end points instead of plotting on the Apple screen. Other features include zero page restore which leaves all zero page variables intact after subroutine exit, page control for selective page erase, display, and draw for ping-ponging between screens for smooth animation. The load and go manual guides beginners through an orientation session with the A2-3D1 program. The technical manual is for advanced applications and describes the transformer algorithm in detail. The program requires 16 K bytes of pro-

grammable memory for the three-dimensional and two-dimensional transformer, small scenes, and small control programs. Larger scenes, control programs and the DEVELOP program require 24 K bytes of programmable memory. The program costs \$45 on cassette and \$55 on floppy disk. For more information, contact Sublogic, POB 5, Savoy IL 61874.

Circle 401 on Inquiry card.

Intel Adds Pascal-80 to 8080/8085 Microprocessor Software Development

Intel Corp has developed Pascal-80 to support 8080 and 8085 microprocessor software development on Intel microcomputer development systems. Similar to its PL/M, BASIC, and FORTRAN programs, the Pascal-80 package is available on floppy disk and runs under the ISIS-II operating systems on Intel Series II and MDS-800 models. This Pascal-80 offers extensions that make the language suitable for commercial and industrial applications. The extensions include three new data types—the string type, untyped files, and interactive files—plus twenty-eight predeclared procedures and functions. Pascal-80 provides a Trace facility allowing a user to monitor program execution, and a set of compile and runtime error diagnostics. Users create Pascal source programs using the Pascal-80 software and standard Intel microcomputers. The Pascal-80 software



package includes a floppy disk containing a compiler, a pseudocode interpreter and demonstration programs, a Pascal-80 user's manual and the *Pascal User Manual and Report*, second edi-

tion, by Jensen and Wirth. The software package is priced at \$975 and is available from Intel Corp, 3065 Bowers Ave, Santa Clara CA 95051.

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What's New?

SOFTWARE

Bell and Howell Introduces Software for Education

These software packages from Bell and Howell allow instructors to create courseware for students. No prior programming knowledge is needed by either instructor or students. Some of the features of the Generalized Instructional Systems (GENIS) include the authoring system which allows teachers to create curriculum material, obtain grade reports, control class enrollment, and more. A system that allows student interaction with the computer is included. The programs understand misspelled words; present lessons in words, animation, graphics, and color; grade student performance; generate drills, practice, and simulation programs; and other administrative projects. The GENIS program is priced at \$300. Write to Bell and Howell Audio-Visual Products Division, 7100 N McCormick Rd, Chicago IL 60645.

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Information Storage and Retrieval (ISAR) for TRS-DOS

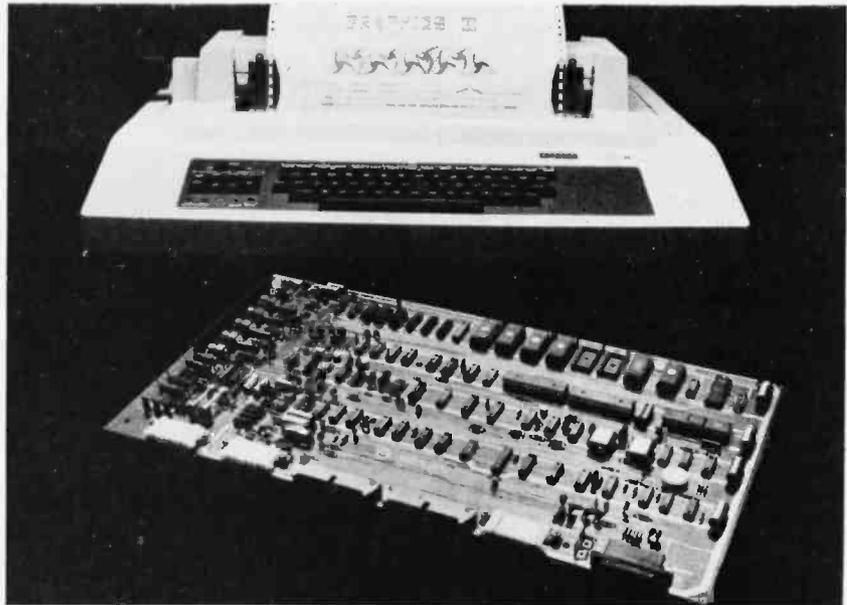
ISAR is a data base management system designed for users of TRS-DOS random file structures. The system utilizes the limited TRS-80 chaining techniques that keep as much of the program in memory as necessary to perform any given function.

The basic ISAR system consists of six modules which allow users to create new files, define all elements within each file, and manipulate each file. Each file or portion of a file can be sorted using BASIC Shell-Metzer sort. The package includes source listing, documentation, potential recovery techniques in the event of a system failure and suggested personal applications. ISAR comes on cassette for \$13.95 or diskette for \$16.95. For further information, contact The Alternate Source, 1806 Ada St, Lansing MI 48910.

Circle 405 on inquiry card.

Multitasking Disk Operating System for 8080, 8085, and Z80 Systems

EFAMOS is a disk-operating system for 8080, 8085, and Z80 systems that supports multitasking and multiusers with memory mapping. Up to 3 M bytes of memory can be available to users through 32 K byte memory banks. EFAMOS is compatible with all software



DECwriter Graphics Available for Timeshare Computers

Graphics II is a modification to the DECwriter II printer for conversion to a plotter. Graphics II features APL character set, forms control, horizontal and vertical tabs, answerback, bi-directional line feed, four character sets

with four different styles—characters can be printed in four directions. The average speed is 40 characters per second (cps). One inch per second for plotting and communication up to 12 bits per second (bps) is possible. The price is \$850, and Graphics II is available from Selanar Corp, 2403 DeLaCruz Blvd, Santa Clara CA 95050.

Circle 404 on inquiry card.

Space Shuttle Landing Simulator

This program is modeled after the NASA Shuttle Mission Simulator in Houston. It is a real flight simulator (except for roll motion) with a visual display of the sky and ground. High resolution graphics show the cockpit view using animation, projective geometry, and graphics to depict the runway, sky, ground, and distant mountains and clouds. The paddles control the pitch control and speed brakes. Speed, altitude, sink and climb rate, distance from the threshold, speed brake

setting, glide slope, and angle of attack are displayed. Warnings and messages are also displayed.

Functional features include angle of attack control, full stall capability, eject and eject warning, landing gear, speed brakes, and wheel brakes on rollout. Runway stripes on roll out give a visual indication of motion.

The program is available from Harvey's Space Ship Repair, POB 3478, University Park, Las Cruces NM 88003, for \$15 on cassette. A floppy disk version is also available.

Circle 406 on inquiry card.

developed under MVT-BASIC. It provides full system support to each memory bank, including assembler BASIC run-time, system utilities, BASIC, utilities and word processing. BASIC support includes chaining with parameter passing and machine language calls with over ten ISAM functions. Word processing activities with several concurrent users can be completely supported in one memory bank, while program development and data processing functions are supported in other

memory banks. Batch monitors can reside in any bank of memory and can process job files submitted from any other bank. One design feature of EFAMOS precludes terminal lockup during any input/output operation, which prevents the loss of characters in a busy multiuser environment. For licensing and terms, contact MVT Microcomputer Systems Inc, 9241 Reseda Blvd, Suite 203, Northridge CA 91324.

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What's New?

SOFTWARE

Pascal for the 8080 and Z80 Processors

Built upon Whitesmiths' C compiler and libraries, the Pascal Development System provides a software environment for Pascal programming on PDP-11, LSI-11, 8080 and Z80 computers. The compilers and all support utilities run under IDRIS, UNIX, RT-11, RSX-11M, RSTS, or IAS on the PDP-11 and LSI-11, and under CP/M or CDOS on the 8080 and Z80, producing code that runs faster than Pascal interpreters. Included as part of the package are an A-Natural assembler, an 8080 linking loader, a librarian, and other utilities. Users also receive the Whitesmiths' Portable Pascal and C library and manual. Supporting these portable libraries are an operating system-specific interface library, a machine library, and 64-bit floating point arithmetic. The 8080/Z80 and PDP-11 Pascal Development Systems, are available from Lifeboat Associates, 2248 Broadway, NY NY 10024, for \$750 per single micro-processor license.

Circle 408 on inquiry card.

Graham-Dorian Introduces a Software Medical Package

This package was written and tested by medical professionals. It handles billing insurance forms, treatment records, charge and payment entry, patient statements, Medicare submittals, collection accounting and dunning, patient processing, patient listing, aged accounts receivables, transaction reporting, and more.

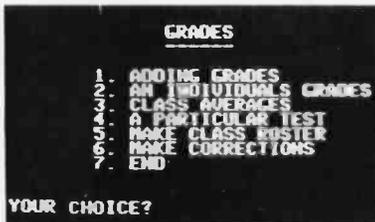
The package can be ordered on eight-inch floppy disks and includes a manual and hard copy source listing. The price for the program is \$1000 and is available from Graham-Dorian Software Systems Inc, 211 N Broadway, Wichita KS 67202.

Circle 409 on inquiry card.

Language Translator Program

This program translates from English to any foreign language, from any language back to English, or from one foreign language to another. Simple commands bring in the correct vocabulary or words. The program checks the entire sentence for the proper verb conjugation and word contractions. New words may be added at any time and saved as part of the vocabulary. One mode lets the translator receive

Machine Language Disk File Sorting Program for Apple II



Datacope, POB 55053, Hillcrest Sta, Little Rock AR 72205, has released an enhanced version of their sorting program that is compatible with either the Apple II or the Apple II Plus computer systems. The new version of the

Datacope Single Disk Sort performs user-specified direct commands upon completion of the sorts, for easy use in turn-key systems. The program employs one disk drive, and sorts a single file of fixed-length records on a single floppy disk. A file may fill the entire disk because the program uses no workspace on the disk. Blocks of consecutive records may be sorted without disturbing the remainder of the file. Files may contain records with 5000 characters and may be sorted by ten key fields simultaneously, with each key field in either ascending or descending alphabetical or numerical order. The program features other necessary functions. The package includes a manual and a floppy disk with the sort programs, a test file, and test file access programs in Applesoft II for \$49.95.

Circle 410 on inquiry card.

CP/M Compatible Operating System for TRS-80 Level II Computers

A fully CP/M compatible operating system for the TRS-80 II computer has been developed. The operating system works with CBASIC and all other CP/M programs, requiring no changes to the operating codes. The system sells for \$249.95 from MPU, POB 808, San Carlos CA 94070.

Circle 411 on inquiry card.

More Programs for Apple II Systems

Apple Barrel Bushel #1 is a collection of twenty-five programs including Mortgage Loan, Days Between Dates, Calendar, Savings, Checkbook, Addition, Subtraction, Metric Conversion, Luna C, Apple LeMans, Alien, and more. The package is available on cassette tape for \$24.95 or on floppy disk for \$29.95. Contact CDS Corp, 550 N Main St, Logan UT 84321.

Circle 412 on inquiry card.

A Forth Software Development Tool

The XL5 is an interactive programming system with compiler, interpreter, assembler, disk operating system, and a library of procedures. It is written in XL5 and is based on the recommendations of the 1977 Forth Standards Committee. A host-executable code kernel, a source code kernel, and a system generation program (SYSGEN) are provided. SYSGEN regenerates the kernel from the source or generates read-only memory (ROM) modules. An XL5 development system requires less than 32 K bytes of memory. The \$100 package includes source code and a reference manual. XL5 is available with a CP/M boot loader for the 8080 and the Z80. For information, contact XL Computer Products, 321 E Kirkwood Ave, Bloomington IN 47401.

Circle 414 on inquiry card.

1979 Federal Tax Programs for Microcomputers

Aardvark Software Inc, POB 26505, Milwaukee WI 53213, is marketing a software program which will calculate an individual's federal tax liability. The program displays the tax information as it would appear on an IRS form. It also calculates the tax liability using the tax tables, tax rate schedules, income averaging, maximum tax on earned income, and alternative minimum tax choosing the most favorable method. A manual is included to organize the tax information for input. Three programs are available at \$22, \$35, and \$50.

Circle 415 on inquiry card.

data in one language from a reader, and then sends the translation to a printer. Display formatting commands show vocabulary words alphabetically or in categories. Spelling errors are caught and corrected.

The Language Translator from Practical Programming Corp, POB 3069, N Brunswick NJ 08902, is available on CP/M or North Star floppy disk with one extended language for \$30. Additional languages are \$10 each.

Circle 413 on inquiry card.

What's New?

PUBLICATIONS

Guidebook for the TRS-80 Level II Microcomputer

Learning Level II, written by Dr David A Lien, is a step-by-step guide to help users of the Level II TRS-80. It contains a section updating the Level I manual to Level II. Readers are guided through the fundamentals and special characteristics of Level II BASIC, beginning with setting up the system. The book explains how to properly use the Editor to change and correct BASIC programs. Another section is devoted to the conversion of Level I programs to Level II. The book also explains dual cassette operation, using the expansion interface box with the real-time clock, printers and other peripheral devices. It is available from Computer Books Division, Compusoft Inc, 8643 Navajo Rd, San Diego CA 92119, for \$15.95, plus \$1.45 for postage and handling.

Circle 416 on inquiry card.

1980 Computer Catalog

Sara Tech Electronics Inc, POB 692, Venice FL 33595, is offering their sixteen-page 1980 computer catalog featuring more than 1000 products. All major brands of computers and equipment are carried. Write for a free copy.

Circle 417 on inquiry card.

Catalog Features Articles on Classroom Computing

Creative Publications is publishing a color newsletter/catalog of computer materials for the classroom. The publication features an article on the television documentary "Don't Bother Me, I'm Learning," which discusses computers in education. All products in the catalog are described with the educational user in mind. The catalog is available from Creative Publications, POB 10328, Palo Alto CA 94303.

Circle 418 on inquiry card.

Documentation Standards for Computer Systems

Norman L Enger's *Documentation Standards for Computer Systems*, Second Edition, is a reference manual that shows how to document a computer application to utilize the full potential of the computer resources. The book includes revised and expanded material that describes the evolution of a system through the stages of initiation, analysis, design, development, implementation, and operation. The sec-

TRS-80 Software Source

This catalog contains over 5000 software listings that are available from 380 suppliers. The publication lists business, education, games, home, math, and utility software with a section of addresses of the suppliers. A one-year subscription is \$15 and a single issue is \$6. Contact Computermart, POB 1664, Lake Havasu AZ 86403.

Circle 419 on inquiry card.

Computer Book Catalog Released by Sams

The Howard W Sams and Co Inc has released a catalog featuring a large selection of computer and computer related titles. It is organized for quick reference into five areas—basics, programming, computer technology, reference, and computer related. This free catalog details books that are directed to a wide range of people and interests, from the home hobbyist to the technically oriented professional.

For a catalog, contact the Advertising Director, Howard W Sams and Co Inc, 4300 W 62 St, POB 558, Indianapolis IN 46206.

Circle 420 on inquiry card.

New Renaissance!

New Renaissance! is a bimonthly magazine for lighting and laser artists and technicians who desire to share their works, events, goals, and discoveries with others in the field. It features performance news and reviews; projects, plans and schematics; new techniques and products; interviews; books and other data sources, and more. A one-year subscription is \$25 and is available from *New Renaissance!*, 5267 11th Ave NE, Seattle WA 98105.

Circle 421 on inquiry card.

tion on "Techniques and Tools for Analysis" facilitates the analyst's work. This book aids in determining the amount of documentation needed for specific types of projects. Procedures can be established to employ documentation standards adopted by the organization. Dr Enger's book is useful to computer professionals, students and novices in the computer industry. It is available by mail for \$25 from The Technology Press Inc, POB 125N, Fairfax Station VA 22039.

Circle 422 on inquiry card.

Magazine on Robotics



Robotics Age magazine contains readable articles of high technical content that present the latest results of research in robotics and artificial intelligence. The contents include well-documented electromechanical circuit designs, microcomputer interfaces, and programming techniques suitable for economical applications to small systems. Abstracts of research papers are also featured. New products items describe new commercially available kits and robotics related products. The quarterly publication is available at \$8.50 for one year from *Robotics Age*, POB 801, La Canada CA 91011.

Circle 423 on inquiry card.

Publication of Sorting Subroutines

Creative Computer Consultants Inc, POB 2111, 1 Quarry Ln, Norwalk CT 06851, has published volume 4 of *Sortmaster* in the Standard Software Library. *Sortmaster* contains listings of five BASIC subroutines designed to sort numeric data in memory. The subroutines have been designed to be integrated into the user's main line program. Numeric fields are sorted by designating that field as the sorting key. This makes it possible to sort records of any length and also permits multiple sorting keys. By adjustment of certain variables, all of the routines can handle alphanumeric data as well. *Sortmaster* includes an introduction to basic sorting concepts as an aid to beginners. The programs work with the TRS-80, PET, and Apple II. The book costs \$8.95.

Circle 424 on inquiry card.

What's New?

PERIPHERALS

Eight-Inch Winchester Disk Up to 20 M Bytes



The Series 7000 hard disk drives have unformatted capacities of 4 megabytes in the single disk version, 12 megabytes in the double-density version and 20

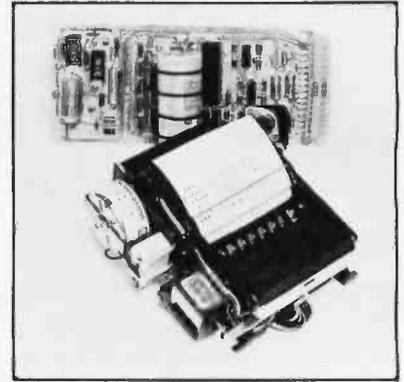
megabytes in the three-disk unit. Data transfer rates are 5.5 million bits per second (bps). The Series 7000 employs the Winchester technique, using an iron-less rotary actuator to position the heads in response to prerecorded servo-tracks on the lower side of the bottom disk.

Each 21 cm diameter surface has a 350-track cylinder with an inner track recording density of 5280 bits per inch. The interface is designed for use with microprocessor-based controllers. The drives utilize eight-bit bidirectional bus transfers. Line transceivers enable daisy-chain connection of other disks to the bus.

The 4 megabyte drive, the 7000-4, is \$2100; the 7000-12 is \$2300; and the 7000-20 is \$2650. The units are manufactured by Kennedy Co, 1600 S Shamrock Ave, Monrovia CA 91001.

Circle 425 on Inquiry card.

12 VDC Alphanumeric Printer System



The PR6024 printer controller and any SODECO PR Series print mechanism comprise a print system operable from a 12 V power source. The controller accepts a 7-bit parallel ASCII format and features an integral voltage regulator and adjustable input thresholds for immunity from environmental noise. The unit features a 54-character alphanumeric set. Applications include mobile electronics, such as truck-mounted fuel-dispensing systems, police cars, security systems, and battery sustained instrumentation and systems. The price for the 15-column tape printer and PR6024 controller is \$363 in unit quantity. For more information, contact the Sales Manager, Print Products, SODECO, Landis and Gyr Inc, 4 Westchester Plz, Elmsford NY 10523.

Circle 427 on Inquiry card.

Stockey Series of Keyboards

The Stockey Series offers ten general-purpose standard keyboard designs, including six with American Standard Code for Information Interchange (ASCII) encoded alphanumeric formats. These are available in ASR33, ANSI teletypewriter, IBM 3278 ASCII typewriter, IBM 3278 data entry, and IBM Selectric I and II typewriter formats. An eleven- and fifteen-Key

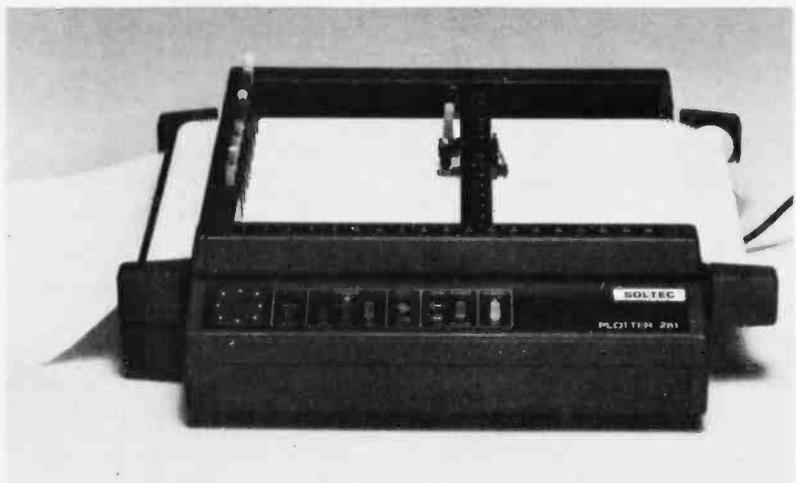
Expander pad can be added via a flex-strip jumper to any of the six alphanumeric designs to provide high-speed numeric entry.

The 53-key SK053 for the Model 33 teletypewriter features uppercase, but no lowercase, and costs \$139. The 67-key model includes uppercase and lowercase, a full ASCII set, and is priced at \$173. For additional information, contact Advanced Input Devices, POB 1818, Coeur d'Alene ID 83814.

Circle 426 on Inquiry card.

Eight-Color Digital Plotter with Microprocessor Control

Soltec's Model 281 Digital Plotter provides graphic representation of measured values, design data and calculated data using up to eight different color pens. A Z80 microprocessor controls the system, the automatic pen changing, off-scale data handling, and coordinate transformation. The programmable pen changing feature incorporates up to eight pens using multicolor fiber-tip pens or Rapidograph drafting pens. Firmware features include circle interpolation, character plotting, generation of axes and grids, various line types, window plotting and more. Model 281 also features character plotting in five fonts, automatic or interactive point digitizing, programmable offsets and programmable limits. The graph paper is standard DIN-A3 format or smaller. Inter-



faces include a choice of serial RS-232C/V.24 and 20 mA current loop. The plotter costs \$4725 and is available

from Soltec Corp, 11684 Pendelton St, Sun Valley CA 91352.

Circle 428 on Inquiry card.

What's New?

PERIPHERALS

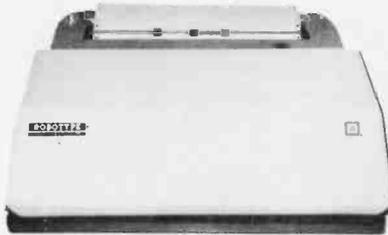
Miniature Alphanumeric Thermal Printer



The APP-20A2 twenty-column, panel-mount thermal printer uses only two input data wires for interfacing. It features serial 20 mA current loop and RS-232C ports. The printer can be used in data systems, factory data acquisition units, and industrial data loggers with a full alphanumeric printer. It can be used with a remote control unit or in medical systems, and as a portable test and measurement tool for laboratory or field use. The unit prints 1.2 lines per second. It measures 20 cm by 7 by 11.3 cm (8 by 2.76 by 4.44 inches) and weighs 1.9 kg (4.25 pounds). It is available from Datel Intersil, 11 Cabot Blvd, Mansfield MA 02048. The cost for the printer is \$880.

Circle 429 on inquiry card.

Robotype Converts Typewriter to Printer



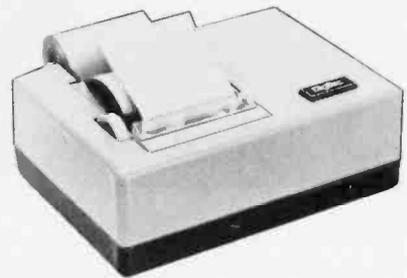
The Robotype Model 2100 is capable of interfacing with a Centronics-compatible parallel interface, RS-232C

serial interface, and a 20 mA current loop. The RS-232C serial interface has 110, 134.5 or 150 switch-selectable data rates. The Robotype can be attached to the IBM Selectric, Remington Rand, Olympia and Facit typewriters. The Robotype is placed over the keys of the typewriter. Plungers rest on the keys and push the keys down on command from the computer input. The unit types the maximum speed of the typewriter in use. The unit is available for under \$1000 from Applied Computer Systems Inc, 77 E Wilson Bridge Rd, Worthington OH 43085.

Circle 430 on Inquiry card.

Alphanumeric Thermal Printers

Priced at approximately \$440, the United Systems 6450 and 6460 alphanumeric thermal printers produce easy-to-read letters, numbers, and symbols on thermal paper with first-line-up printout. They print a set of 64 different characters with 21 characters per line and approximately 6500 lines per roll of paper. The Model 6450 provides a serial input with selectable RS-232C or 20 mA current loop format with data rates of 110 and 300 bits per second (bps). The Model 6460 is 8-bit parallel bus-compatible with data rates up to 1000



characters per second (cps). Both models respond to ASCII input. For more information, contact United Systems Corp, 918 Woodley Rd, Dayton OH 45403.

Circle 431 on Inquiry card.

Corvus Disk System for Apple Pascal Microcomputer

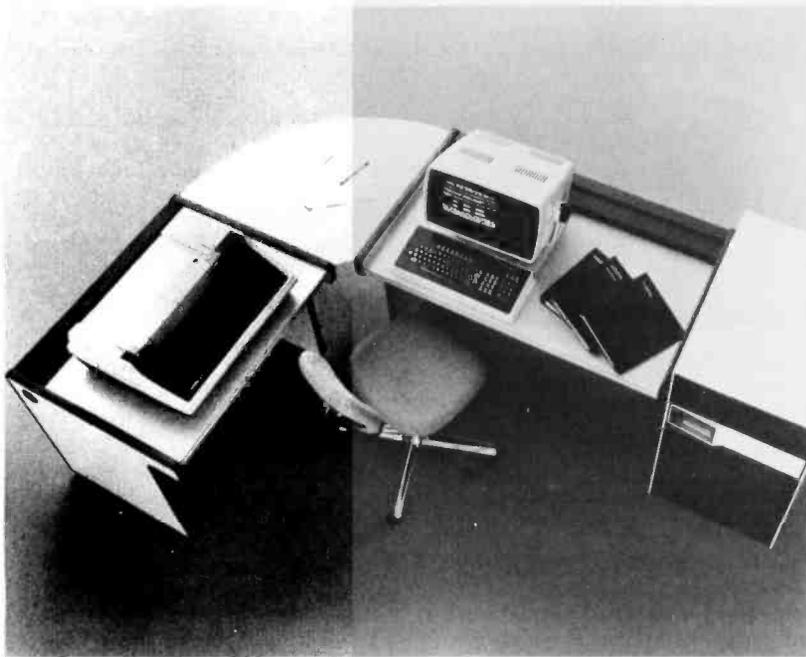
The Corvus model 11AP disk system being delivered for Apple Pascal is entirely compatible with the Apple system. No modifications are needed for the Apple Pascal disk-operating system, or any applications designed to run on the Apple floppy disks. Corvus has incorporated a utility called "dynamic volume management" that allows the ten million byte data base to be used as a single large block or to be broken into smaller blocks. Applications of the Apple Pascal equipped with the Corvus 11AP system include: customer and prospect mailing lists, accounting data, payroll and personnel records, courses in computer programming and usage, science applications, medical office use, and more. The system is priced at \$5350. The controller can handle up to three additional disks, which are priced at \$3690. Contact Corvus Systems, 900 S Winchester Blvd, Suite 4, San Jose CA 95128.

Circle 432 on inquiry card.



What's New?

SYSTEMS



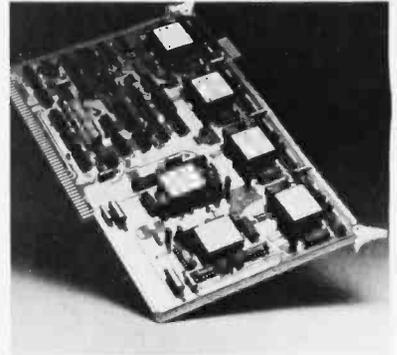
The 9000 Computer System from Compal

The Compal Model 9000 is designed for business and office environments. The system includes a 16-bit microNova 602 processor, 64 K bytes of programmable memory, video display terminal with a detached keyboard that can support up to three additional keyboards, a 10 M byte hard disk with a 5 M byte removable cartridge, and a high-speed

matrix printer. Included with the system are BASIC and assembly languages, manuals, training, starter supplies, and delivery. Programs for inventory control, sales analysis, accounts payable and receivable, general ledger, payroll, and other business applications are available. The system sells for \$19,995 from Compal Inc, 6300 Variel Ave, Woodland Hills CA 91604.

Circle 433 on Inquiry card.

TM990 Compatible Bubble Memory Module



A TM990-compatible board with up to 69 K bytes of non-volatile magnetic bubble memory storage has been announced by Texas Instruments Inc., POB 225012, M/S 308 (ATTN: TM990/210), Dallas TX 75265.

The TM990/210 board is supplied with two, four, or six 92 K bit TIB 0203 bubble memories for 23 K, 46 K, or 69 K bytes of storage, respectively. Data transfers from the module are via a memory-mapped mode. Access time is 4 ms, and data transfer rate is 45,000 bits per second (bps). The price for the TM990/210-1 two-bubble device is \$775; \$1150 for the TM990/210-2 four-bubble device; and \$1535 for the TM990/210-3 six-bubble device.

Circle 434 on Inquiry card.

Development Tool for 6500 Series Microprocessors

The MDT 1000 enables users to write programs and debug hardware and software. The MDT 1000 includes a 54-key keyboard and case; 12-inch video display; dual cassette interface; power supply; erasable-programmable read-only memory programmer; 4 K byte static programmable memory-board; sockets for extra boards; and a four-slot motherboard. Software support comes as 12 K bytes of read-only memory resident firmware; a 4 K byte monitor with debug features; and an 8 K byte assembler and editor, which operates on line-numbered text. A floating point BASIC and software for printer interfacing and other controls are available. The MDT 1000 is available for \$1495 from Synertek, 3001 Stender Way, Santa Clara CA 95051.

Circle 435 on Inquiry card.



What's New?

MISCELLANEOUS

TRS-80 Printer Controller

The Printer Timer works with the TRS-80 and the Centronics 779 line printer by automatically turning the printer on and off using signals relayed over the printer cable. The device does not require software or hardware modification other than the soldering of three wires and the mounting of the timer inside the printer cabinet. The timer reduces motor wear and excess noise. It is available for \$95 from National Software Marketing Inc, 4701 McKinley St, Hollywood FL 33021.

Circle 436 on inquiry card.

Voice Terminal for the Exidy Sorcerer Talks and Listens

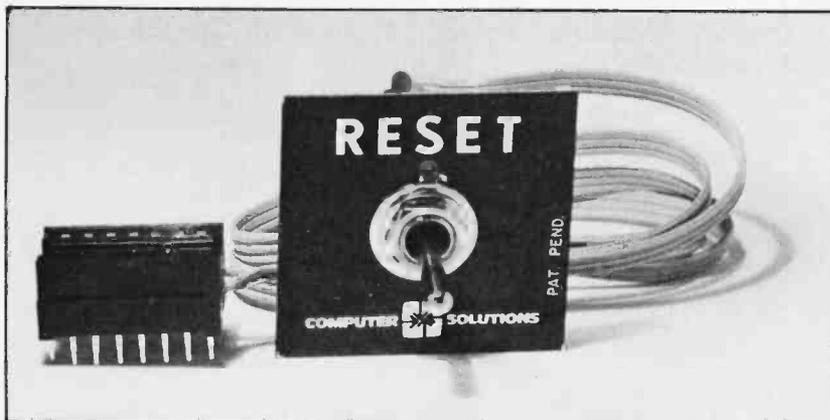
Cognivox plugs into the Sorcerer and offers a sixteen-word recognition vocabulary plus voice response with up to sixteen words or phrases. Recognition accuracies of up to 98% are possible. The unit includes a microphone and amplifier and speaker, making it a complete voice terminal. A software library is provided with Cognivox. It includes Voicetrap, a voice-operated video game, and Vothello, a voice input version of the game Othello. A talking calculator program allows using the Sorcerer as a four-function calculator, and a vocal memory dump program can read its memory out loud. Cognivox is priced at \$149 from Voicetek, POB 388, Goleta CA 93017.

Circle 437 on inquiry card.

Anti-Glare Device for Video Screens

The product is a black woven nylon mesh stretched on a flexible plastic frame. It is designed to be sandwiched behind the video bezel and to conform against the surface of the tube. This device performs by blocking and absorbing ambient light with a honeycombing effect. The contrast is enhanced by the black matrix effect of the fabric background, while the display characters are transmitted undistorted through the pores in the material. The filters are available in 120 sizes, and each size can be equipped with different optically-graded fabrics to vary the intensity of the video display. The filters improve the image, lower maintenance, and reduce eye strain and related stress. For more information, contact Sun-Flex Co Inc, 3020 Kerner Blvd, San Rafael CA 94901.

Circle 438 on inquiry card.



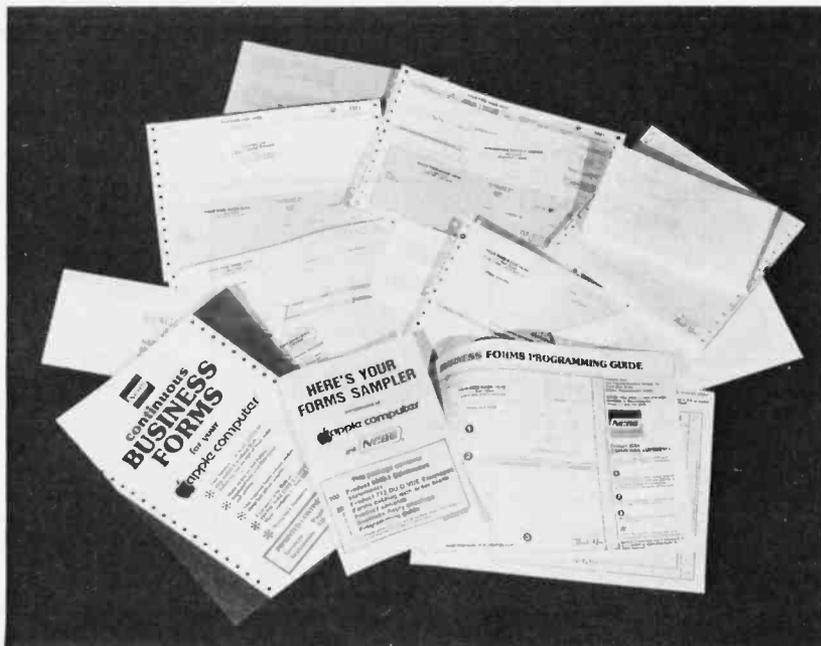
Reset Option for the Apple

Model B is a three-position switch giving the user the option of completely disabling or enabling the reset key on the keyboard. It is easily installed between the keyboard plug and the Apple's board. When the switch is in the down position, the keyboard is functional. With the switch in the middle

position, the reset key on the keyboard is disabled, and the user must flip the switch up to reset the computer. The switch automatically returns to the middle position when released from the up position.

It is available from Computer Solutions, 5135 Fredericksburg Rd, San Antonio TX, 78229, for \$29.95.

Circle 439 on inquiry card.



Standardized Computer Forms

New England Business Service (NEBS) is offering a line of continuous-form computer checks, statements, and invoices. The forms are available with the name of the firm, address and phone number in six quantities from 500 to 6000 forms. Prices start at \$14.95 for 500 statements; \$32.50 for 500 two-part

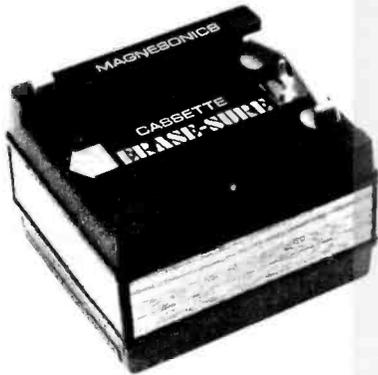
invoices and \$29.95 for 500 of either the payroll or all-purpose checks. At 6000-piece order levels, prices per thousand drop to \$12.50, \$33 and \$22.50 respectively. The firm also offers custom personal checks for home computer systems users. For ordering information and free samples write to the New England Business Service Inc, N Main St, Groton MA 01450.

Circle 440 on inquiry card.

What's New?

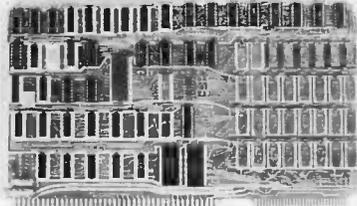
MISCELLANEOUS

Simple Machines for Erasing and Winding Cassettes



Two battery-powered machines offer longer life for cassettes and reduced wear on standard cassette players. The Erase-Sure passes the cassette through a rotating magnetic field that erases the tape and leaves an extremely low residual noise level. The user slides the cassette through the unit once. This

Prototyping Kit for High-Resolution Graphics



The SVB-80P prototyping kit is a dual-board system with stand-alone capability in an Intel multibus configura-

tion. The graphics package features displays of 640 by 409 or 576 by 455 pixels, alphanumeric characters displayed over 80 by 40 or 72 by 44 lines, and intermixable characters with graphics. It interfaces with other multibus-compatible products. The SVB-90 Soft Video Board and the MIB-85 Memory Intensive Board can also be used individually in computer graphics, text editing, scientific applications, and industrial environments. The price for the SVB-80P is approximately \$1600. Contact DOSC Inc, 175 I U Willets Rd, Albertson NY 11507. Circle 446 on Inquiry card.

single pass completely erases the tape. The Rapid Rewind stabilizes cassette tape tension, eliminates tape binding, helps control wow and flutter, and winds a 60-minute tape in approximately 30 seconds. Both units permit the use of a 115 V AC adapter to reduce battery costs. The machines are available from Magnesonics Sales and Manufacturing Co, POB 758, Ventura CA 93001. They cost \$24.50 each. Circle 445 on Inquiry card.

Computer Cables for the TRS-80

Matchless Systems, 18444 Broadway, Gardena CA 90248, manufactures cables for floppy disk and tape drives, printers and other peripherals for the TRS-80 computer. The price for the two-drive cable is \$24.50 and the four-drive cable is \$34.50. The cable for the MS-204 printer or any other Centronics-compatible printer, sells for \$34.50. Circle 447 on Inquiry card.



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ATARI software, Roms, Cassettes \$ CALL
ATARI Expansion Memory: \$ CALL
8K Module or 16K Module \$ CALL
CALL for our lowest prices ever.

ZENITH DATA SYSTEMS: Smart Video Terminal



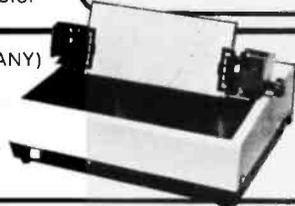
Z-19 has a Z80 Microprocessor, Numeric Keypad and 8 function key \$895.00



Z-89 Computer System: includes: Z19 Display, a built in 5 1/4" Floppy Disk, 2 serial ports, and 16K of memory. 2295.00
48K Memory version 2595.00

EPSON (A SEIKO COMPANY)

TX-80 Printer with 64 graphics characters
7x5 dot matrix (7x6 in graphics) Double width characters



Tractor Feed Model \$745.00
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Our full Disk Extended BASIC and DOS, assembler and editor software comes complete, too. On its own diskette, ready to go. Software from Micropolls includes a DOS and Disk Extended Basic designed for 8080/Z80-based microcomputers.

DOS is a complete package, including an assembler, editor, file management functions and utilities, which provides total support for 8080 programming. BASIC is a self-contained package which provides a powerful set of tools for developing, testing, executing, and maintaining BASIC programs.

BASIC is designed for microcomputers with at least 24K bytes of RAM and a Micropolls MetaFloppy disk system. DOS can be used alone in a 16K bytes memory system.

Activating the built-in Auto load ROM brings up the system under control of the DOS executive. BASIC can be accessed by issuing a simple DOS command.

The 1053 MOD II Subsystem is designed for flexible, efficient programming. 8080 programs created under DOS can be loaded and accessed from BASIC. Data files created under BASIC can be processed by user written application programs running under the DOS.

At Micropolls, complete means COMPLETE.

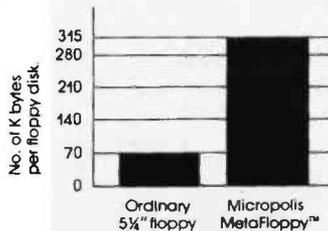
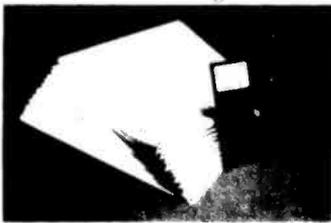
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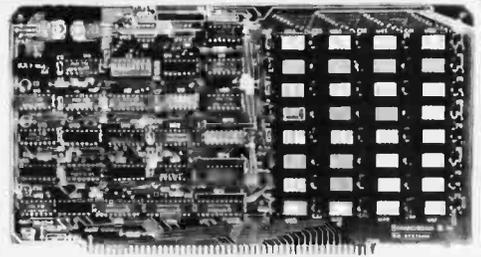
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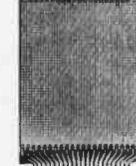
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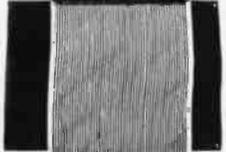
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Card Extender has 100 contacts 50 per side on .125 centers-Attached connector is compatible with S-100 Bus Systems. ... \$25.83

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- G10 epoxy glass board with 2 ounce copper, solder plated and 038 diam. vias for leads
- Solder mask with solder windows on critical circuits to avoid accidental short circuits
- Mounts 11 receptacles with 100 contacts (2 rows) on 125 centers with 250 row spacing. Vector part number N681-2, or mounts 10 receptacles plus interconnections to upgrade mother board for expansion
- Includes etched circuit and instructions for option of active, pull-up, or floating terminations
- Large buses: +5V and GND (10 AMP'S), ±12V or 16V (1 AMP'S). Current ratings as per MIL-S10-275 with 100% wire
- Fits in Vector rack enclosures
- Fits in IMSAI 8080 microcomputer as expansion board.

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CND-DE9S	9 Pin Female	2.25	2.00	1.90
CND-DE9C	9 Pin Cover	1.50	1.35	1.20
CND-DA15P	15 Pin Male	2.35	2.15	2.00
CND-DA15S	15 Pin Female	3.25	3.10	2.90
CND-DA15C	15 Pin Cover	1.60	1.45	1.30
CND-DB25P	25 Pin Male	2.80	2.60	2.40
CND-DB25S	25 Pin Female	3.80	3.40	3.20
CND-DB51212-1	1 pc Grey Hood	1.50	1.30	1.10
CND-DB11063-3	2 pc Grey Hood	1.75	1.50	1.35
CND-DB1228-1A	2 pc Black Hood	1.90	1.65	1.45
CND-DC37P	37 Pin Male	4.20	4.00	3.70
CND-DC37S	37 Pin Female	6.00	5.75	5.50
CND-DC37C	37 Pin Cover	2.25	2.00	1.75
CND-DD50P	50 Pin Male	5.50	5.10	4.75
CND-DD50S	50 Pin Female	8.40	8.00	8.00
CND-DD50C	50 Pin Cover	2.40	2.20	2.00
D2041B-S	Hardware Set 2 pr.	1.00	.80	.70
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VCT84P44	4.5x8.5"	\$2.21	\$1.99
VCT169P44	4.5x17"	\$4.52	\$4.07
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RNS-14WWG	14	.50	.39	.37	.35	.32
RNS-16WWG	16	.55	.42	.40	.37	.34
RNS-18WWG	18	.75	.65	.60	.55	.50
RNS-20WWG	20	.90	.80	.70	.65	.62
RNS-22WWG	22	1.00	.90	.85	.80	.75
RNS-24WWG	24	1.00	.90	.85	.80	.75
RNS-28WWG	28	1.40	1.30	1.25	1.10	1.00
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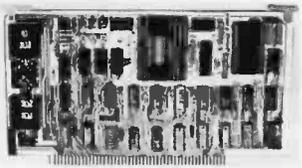
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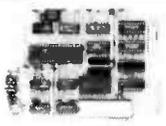
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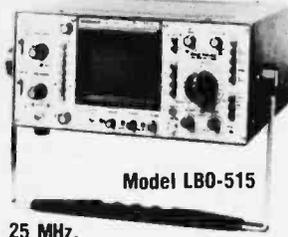
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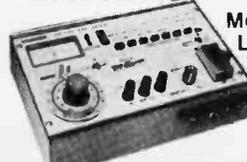
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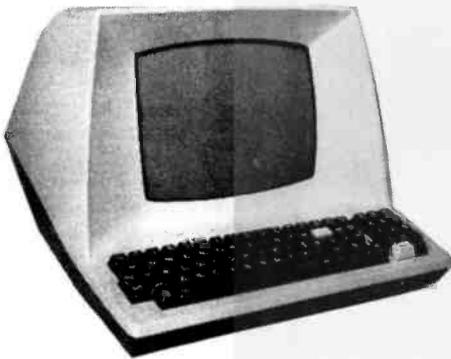
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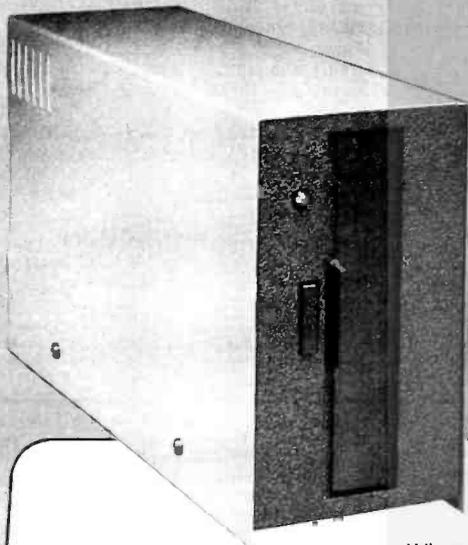
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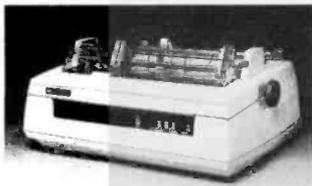
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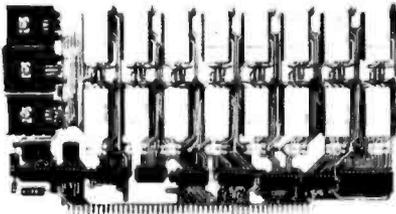
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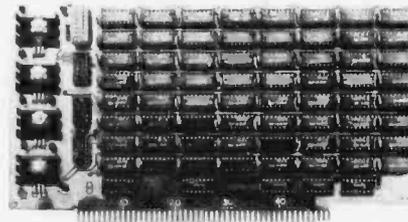
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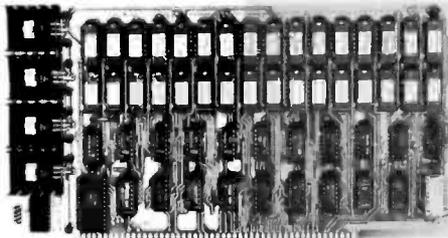
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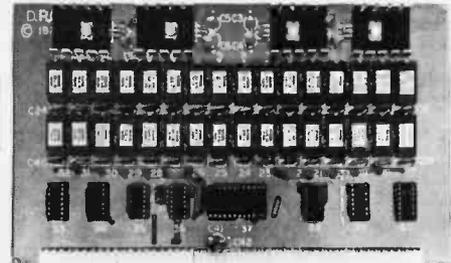
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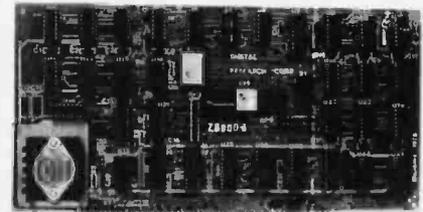
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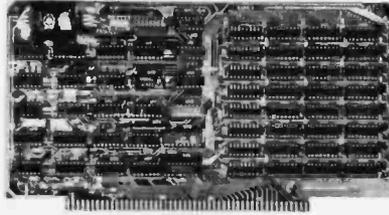
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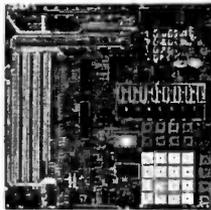
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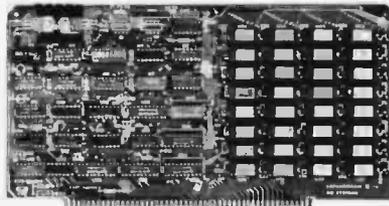
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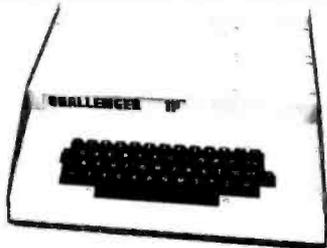
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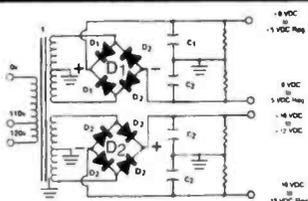
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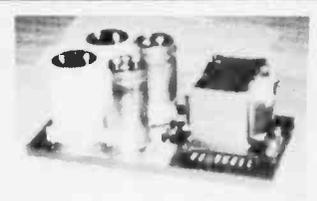
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7473N	LM340T-348	1.25	CD4053	1.42
7474N	LM340T-354	1.25	CD4053	1.42
7475N	LM340T-360	1.25	CD4053	1.42
7476N	LM340T-366	1.25	CD4053	1.42
7477N	LM340T-372	1.25	CD4053	1.42
7478N	LM340T-378	1.25	CD4053	1.42
7479N	LM340T-384	1.25	CD4053	1.42
7480N	LM340T-390	1.25	CD4053	1.42
7481N	LM340T-396	1.25	CD4053	1.42
7482N	LM340T-402	1.25	CD4053	1.42
7483N	LM340T-408	1.25	CD4053	1.42
7484N	LM340T-414	1.25	CD4053	1.42
7485N	LM340T-420	1.25	CD4053	1.42
7486N	LM340T-426	1.25	CD4053	1.42
7487N	LM340T-432	1.25	CD4053	1.42
7488N	LM340T-438	1.25	CD4053	1.42
7489N	LM340T-444	1.25	CD4053	1.42
7490N	LM340T-450	1.25	CD4053	1.42
7491N	LM340T-456	1.25	CD4053	1.42
7492N	LM340T-462	1.25	CD4053	1.42
7493N	LM340T-468	1.25	CD4053	1.42
7494N	LM340T-474	1.25	CD4053	1.42
7495N	LM340T-480	1.25	CD4053	1.42
7496N	LM340T-486	1.25	CD4053	1.42
7497N	LM340T-492	1.25	CD4053	1.42
7498N	LM340T-498	1.25	CD4053	1.42
7499N	LM340T-504	1.25	CD4053	1.42
7500N	LM340T-510	1.25	CD4053	1.42

7400TL	LM323K-5	99	CD4021	1.25
7400N	LM323K-12	1.50	CD4022	1.10
7402N	LM320T-15	1.50	CD4023	2.8
7404N	LM320T-5	1.60	CD4024	75
7409N	LM320T-8	1.60	CD4025	28
7410N	LM320T-12	1.50	CD4026	2.00
7414N	LM320T-15	1.60	CD4027	66
7420N	LM323N	1.15	CD4028	65
7427N	LM323N	1.55	CD4029	1.02
7430N	LM340K-5	1.35	CD4030	45
7432N	LM340K-8	1.35	CD4031	1.02
7447N	LM340K-12	1.35	CD4040	1.02
7448N	LM340K-15	1.35	CD4042	3.00
7449N	LM340K-24	1.35	CD4043	85
7450N	LM340K-30	1.35	CD4044	85
7414N	LM340T-8	1.25	CD4046	1.67
7415N	LM340T-12	1.25	CD4049	45
7416N	LM340T-15	1.25	CD4051	1.13
7418N	LM340T-18	1.25	CD4051	1.13
7419N	LM340T-24	1.25	CD4052	1.42
7420N	LM340T-30	1.25	CD4052	1.42
7421N	LM340T-36	1.25	CD4053	1.42
7422N	LM340T-42	1.25	CD4053	1.42
7423N	LM340T-48	1.25	CD4053	1.42
7424N	LM340T-54	1.25	CD4053	1.42
7425N	LM340T-60	1.25	CD4053	1.42
7426N	LM340T-66	1.25	CD4053	1.42
7427N	LM340T-72	1.25	CD4053	1.42
7428N	LM340T-78	1.25	CD4053	1.42
7429N	LM340T-84	1.25	CD4053	1.42
7430N	LM340T-90	1.25	CD4053	1.42
7431N	LM340T-96	1.25	CD4053	1.42
7432N	LM340T-102	1.25	CD4053	1.42
7433N	LM340T-108	1.25	CD4053	1.42
7434N	LM340T-114	1.25	CD4053	1.42
7435N	LM340T-120	1.25	CD4053	1.42
7436N	LM340T-126	1.25	CD4053	1.42
7437N	LM340T-132	1.25	CD4053	1.42
7438N	LM340T-138	1.25	CD4053	1.42
7439N	LM340T-144	1.25	CD4053	1.42
7440N	LM340T-150	1.25	CD4053	1.42
7441N	LM340T-156	1.25	CD4053	1.42
7442N	LM340T-162	1.25	CD4053	1.42
7443N	LM340T-168	1.25	CD4053	1.42
7444N	LM340T-174	1.25	CD4053	1.42
7445N	LM340T-180	1.25	CD4053	1.42
7446N	LM340T-186	1.25	CD4053	1.42
7447N	LM340T-192	1.25	CD4053	1.42
7448N	LM340T-198	1.25	CD4053	1.42
7449N	LM340T-204	1.25	CD4053	1.42
7450N	LM340T-210	1.25	CD4053	1.42
7451N	LM340T-216	1.25	CD4053	1.42
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7454N	LM340T-234	1.25	CD4053	1.42
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7456N	LM340T-246	1.25	CD4053	1.42
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7459N	LM340T-264	1.25	CD4053	1.42
7460N	LM340T-270	1.25	CD4053	1.42
7461N	LM340T-276	1.25	CD4053	1.42
7462N	LM340T-282	1.25	CD4053	1.42
7463N	LM340T-288	1.25	CD4053	1.42
7464N	LM340T-294	1.25	CD4053	1.42
7465N	LM340T-300	1.25	CD4053	1.42
7466N	LM340T-306	1.25	CD4053	1.42
7467N	LM340T-312	1.25	CD4053	1.42
7468N	LM340T-318	1.25	CD4053	1.42
7469N	LM340T-324	1.25	CD4053	1.42
7470N	LM340T-330	1.25	CD4053	1.42
7471N	LM340T-336	1.25	CD4053	1.42
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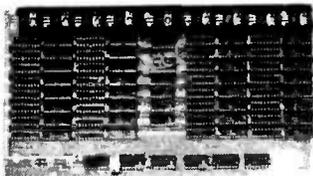
"Power One" Model CP206 Power Supply adequate for at least two drives, 2.8A/24V 2.5A/5V, 0.5A/-5V beautiful quality. **\$99.00**



CABINETS for FDD120 and 801R drives, or CP206 supply. Matte finish in mar resistant black epoxy paint and stacking design **29.95**



DISKETTES
(Mrx, Verbatim, Georgia Magnetics)
8" **\$39.95/10**
5 1/4" **\$34.95/10**



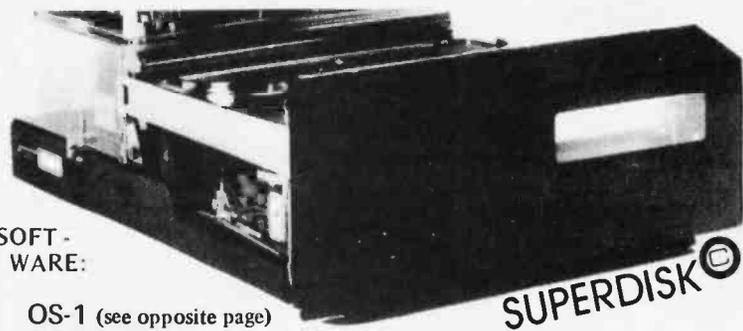
STATIC RAM MEMORY, S-100

32K - \$549.00 16K - \$349.00

"BACK TO SCHOOL" KEYBOARD SPECIAL



CHERRY "PRO" Keyboard \$119.00
Streamlined Custom Enclosure \$34.95
BOTH ONLY \$134.95 !!!!!!!!!



10MByte DRIVE \$3300

S-100 DMA CONTROL

POWER UNIT \$395.00

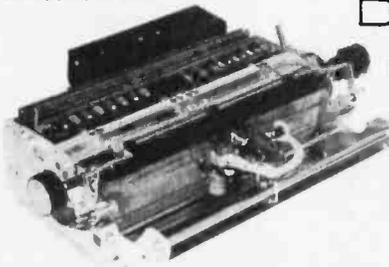
SOFTWARE:

OS-1 (see opposite page)
Call for up to the minute pricing on S-100 DMA controller, LSI-11 controller, cabinetry, etc.

PS: OS-1 runs on the TRS-80, and can transform it from a toy computer to a real business machine !!!

SUPERDISK

For the first time in something like 10 years, a new STANDARD in removable media has evolved. Selected by Datapoint, and others who have not yet announced, this drive is beautifully simple and easy, if not trivial to maintain. 920kBy/sec. transfer rate, 3600 RPM 39 lbs and only 125 Watts.



Daisy Wheel Printers

Qume Sprint 3/45

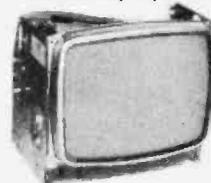
- PRINTER (factory warr.) **\$1499.00**
- POWER SUPPLY (Boschert) **349.00**
(shown mounted on rear of printer)
- COMBINATION SPECIAL **\$1699.00**
- Cases available **200.00**
- S-100 interface card **149.00**

DATA DISPLAY MONITORS

Used 12" Sylvania monitors. Composite Video, 15 MHz, 120VAC. Rebuilt with NEW P39 anti-glare tube \$119.00 New P4, 109.00, used P4 79.00. U-fix model, 10/\$300.00



"OEM STYLE" as above, will fit any case. (Both versions serviced by qualified tech). Identical to above but subtract \$12.00



Televideo 912B (\$860.00) **Televideo 920C (\$1020.00)**

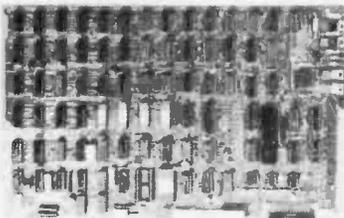
Electrolabs

POB 6721, Stanford, CA 94305

415-321-5601 800-227-8266

Telex: 345567 (Electrolab Pla)

Visa MC Am. Exp.

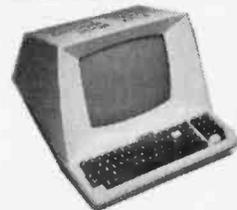


ESAT 200B

BI-LINGUAL 80x24 COMMUNICATING TERMINAL

Scrolling, full cursor, bell, 8x8 matrix, 110 - 19,200 baud, Dual Font Applications. Arabic & Hebrew, Multilingual Data Entry Forms Drawing, Music, & Switchyards. **\$349.00**

New!



TELEVIDEO 912B

- Upper & lower case
- Adjustable baud rate
- 80 x 24
- Editing capabilities
- Printer port
- Second page memory & much much more

TELEVIDEO 920C

- Same features as 912B PLUS
- Line & character insert/delete
- Special function keys

SOCKET SPECIAL



"Won't Let Go"

Low Profile

Solder Tail

1 CENT/ Pin !! (0.75/1000's)

8 14 16 18 20 22 24 28 40

ESAT 200B BILINGUAL COMMUNICATING TERMINAL

IF YOU THINK THAT THIS FUNCTION IS ACCURATE, YOU ARE WRONG !!

Let you will get a 25% discount on your ESAT 200B purchase if you send us the correct solution to this puzzle.

What the key is an example of a graphics application of the BILINGUAL ESAT 200B terminal. The key is a dual language system. There are two keys: one for Arabic and one for Hebrew. The key is a dual language system.

CP/M* Source Code - FREE! when you purchase "OS-1"
 Electrolabs' new operating system for the Z-80 designed to have exactly the appearance of UNIX**, including virtual I/O, "set TTY", a tree and a shell, filters and pipes PLUS total compatibility with CP/M software!

OS-1[®] FEATURES

(Because OS-1 is truly a comprehensive "OS", and not merely a file handling "DOS", we have changed the name from "Superdos" to "OS-1")

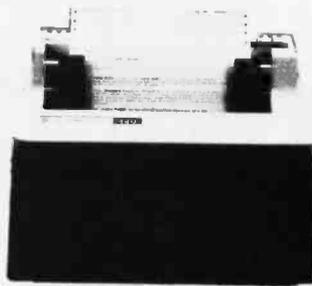
- VIRTUAL I/O** - copy with a single command between floppy and hard disk, or from TTY to printer to tape to disk... etc., etc.
 No messy I/O routines to write, & no awkward transfers.
- SECURITY** - 9 modes of file protection, user and login protection.
- MULTI-USER** - up to 256 passwords. (non-simultaneous users)
- 16MBy FILE SIZE** - but no limit to no. of directories per device, thus allowing EASY implementation of gigantic storage devices.
- "SET TTY"** - for printer or crt: tabs, page width, buffer, cursor, UC/LC, fonts, formfeed, arbitrary control characters etc., etc.
- "LOGIN"** - automatically executes user selected programs and "set TTY".
- OCCUPIES 12KBy** - only 50% larger than CP/M, but 500% more features.
- CP/M & CDOS COMPATIBLE** - your library is guaranteed to run!

* (Naturally, we are not giving away the version of CP/M written by Digital Research, Please pardon our pun, but they might object. What we ARE giving you is a greatly enhanced version of CP/M which resides on OS-1, and allows the user of OS-1 to run any and all of his programs, packages or system utilities which are already running on CP/M. We give you the source code at no charge so that you may modify any part of the CP/M to suit your own system requirements. At no charge, you also receive the enhancement allowing 4MBy files instead of 256K.)

OS-1 (with debugger, linker and screen oriented editor)	\$199.00
Update service, per year	29.00
Symbolic Debugger	150.00
MACRO-Assembler (Creates relocatable code)	150.00
"C" Compiler	660.00
FORTRAN Compiler	100.00
BASIC Compiler (very fast)	350.00

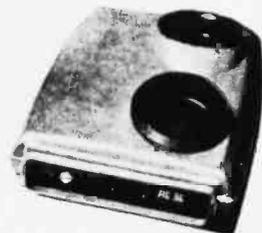
PAPER TIGER

- IDS MODEL 440**
- 8 Software Selectable Character Sizes
 - Parallel & Serial Interface
 - 98 ASCII Character set, upper & Lower case
 - Forms length control
 - Tractor Feed \$949.00
 - Graphics option with 2K CRT screen buffer add \$199.00



DYNAMIC DEVICES MODEM

- Acoustically coupled modem assembly set
- Asynchronous 0-300 Baud
- Switchable originate or answer modes
- Operates full or half duplex mode
- 15 minute assembly \$149.95



SPRINGTIME IC SPECTACULAR

(While Supply Lasts)	4116 (set of 8, 16K, mem-)	2732	95.00
MEMORY & EPROM	ory expansion for TRS-80,	8748-8	49.00
		8755-8	49.00
2114	\$ 5.99 Apple, Exidy)	CPU	
2114-2	6.99 2708	6502	6.25
pd 411	2.50 2716	Z-80	9.95
2107	2.00 2516	Z-80A	12.05
		8080A	8.99
		8085	22.00
		8741	79.00

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 POB 6721 Stanford, CA 94305
 415-321-5601 800-227-8266
 Telex: 345567 (Electrolab Pla)

FLOPPY CONTROLLERS

1771	\$26.95
1791	37.95
Pd372	39.00

MISCELLANEOUS (CALL US!!)

Graphics

High Resolution 480 x 512 for B&W and Color Imaging and Graphics

Light pen, A-D, D-A, TV synchro (needs no time base correction or adjustment with anything between random interface & NTSC commercial standard). T, V, single frame grabber ("snapshot"). Up to 1 Byte of attributions per pixel.

LSI-100 & S-100 applied to:

Graphic Presentation - such as computer generated animation & other graphic displays up to 256 colors & up to 256 b&w gray scales. **Image Analysis** - using built-in FRAME GRABBER, for medical image enhancement, contour analysis, & pattern recognition. **Commercial TV Tilting & Advertising** - using synchronization capability. **Interactive graphics** - using light pen accessory.

BASIC CONFIGURATION -

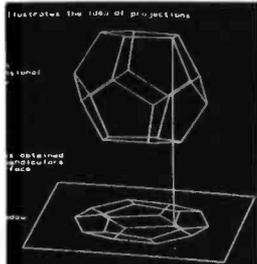
LSI-11 \$1995. S-100 \$1265.
 For TRS-80/Exidy Add \$595.00
 Includes: Data Board - 32K (480 x 512 x 1 pixel) D-A 16 level video generator. Video Synchronization Circuitry. Address Control & Timing Board.

FEATURES - High speed. DMA or 2KBy window memory mapped interface. Full NTSC commercial color capability. Low power consumption. Excellent Software **Options - Accessories - Software**
 Options include: light pen, auxiliary outputs, text mode, memory and much more. Accessories include: b&w and color cameras and monitors. Software: "Plot" 2D or 3D, "Tilting", "Contour", "Image Enhancement", "Vector Curve Generation".

Call for price and details

*CPM and **UNIX trademarks of Digital Research and Western Electric respectively.

Circle 272 on inquiry card.

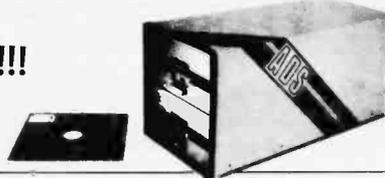


MATCHMAKER TECHNOLOGY

TURNKEY DISK SUBSYSTEMS

DISK IS IN!!!

For those who wish to avoid the aggravation, fussing, irritation, annoyance etc., of assembling your own subsystem, plug in and GO!!!



- ✓ SORCERER
- ✓ TRS-80
- ✓ APPLE
- ✓ HP1B
- ✓ PET

APPLE

- FEATURES:**
- 2 8" Floppy DISK DRIVES (Single Sided)
 - Color Coordinated Cabinet with Power Supply
 - Expanded version of APPLE-DOS
 - Single Density Disk Controller
 - Full Cabling, Connectors + Documentation
 - Assembled and Tested
 - Plug In and GO!!! \$1695.00

- OPTIONS:**
- 2 8" Double Sided Drives (In place of Single Sided) \$2395.00
 - 16K Internal Memory Expansion Kit 69.00

PET

Prices and specifications same as for APPLE except PET Operates via PET-DOS

TRS-80

Prices and specifications same as for SORCERER with following exceptions:

- Expansion Interface necessary
- Space for up to 48K plug-in dynamic memory on Controller Card
- Software package as above \$ 995.00

SORCERER

- FEATURES:**
- 2 8" Single Sided Floppy Disk Drives
 - Single and/or Double Density
 - Color Coordinated Cabinet with Power Supply
 - Full RS-232 Interface
 - OS-1 Disk Operating System (Fully CP/M compatible) CP/M is a registered trademark of Digital Research
 - Full Cabling, Connectors + Documentation
 - Assembled and Tested
 - One S-100 Slot available for Memory Expansion
 - Plug In and GO!!! \$2195.00

- OPTIONS:**
- 2 8" Double Sided Drives (In place of Single Sided) \$2845.00
 - 32K Dynamic RAM Memory Board, Assembled and Tested \$ 299.00
 - 16K Dynamic RAM Internal Memory Expansion Kit \$ 69.00

- Deluxe Business Software package includes:
 C BASIC
 WORD PROCESSING SOFTWARE
 INTERACTIVE "Big 4":
 General Ledger, Accts. Payable, Accts. Rec. and Payroll \$ 695.00
 - 10 MBY Removeable Hard Disk - Call for Details

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 Outside Cal: 800-227-8266

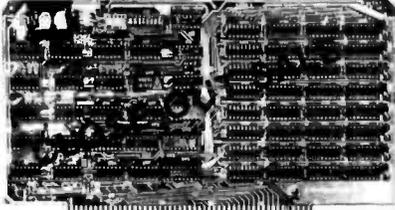
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Worldwide:
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OUR BEST SELLING MEMORY EXPANDORAM

EXPANDABLE TO 64K USING 4116 RAMS



Interfaces with most popular S-100 boards
Bank selectable: PHANTOM provision
Draws only 5 watts fully populated
Designed to work with Z-80, 8080, and 8085 systems
No wait states required
16K boundaries & protect via dip switches
Kits come with sockets for full 64K
Invisible refresh

MEM-16130K (16K KIT)	\$239.95
MEM-16130A (16K A&T)	\$289.95
MEM-32131K (32K KIT)	\$309.95
MEM-32131A (32K A&T)	\$359.95
MEM-48132K (48K KIT)	\$379.95
MEM-48132A (48K A&T)	\$429.95
MEM-64133K (64K KIT)	\$449.95
MEM-64133A (64K A&T)	\$499.95

SOLID STATE MUSIC PB-1

EPROM PROGRAMMER FOR 2708 OR 2716

MEM-99510K(KIT)	\$125.00
MEM-99510A(A & T)	\$175.00

VECTOR GRAPHICS HI-RES GRAPHICS

256X240 S-100 HI-RES GRAPHICS BOARD

IOV-1070K(KIT)	\$150.00
IOV-1070A(A & T)	\$199.95

LIMITED TO STOCK ON HAND

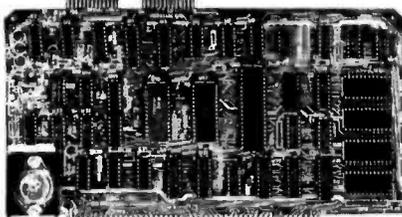
SOLID STATE MUSIC I/O-4

2 SERIAL & 2 PARALLEL I/O PORTS

IOI-1010K(JADE KIT)	\$149.95
IOI-1010A(A & T)	\$199.95

S D SYSTEMS SBC-100/200

2 OR 4 MHz SINGLE BOARD COMPUTER



S-100 bus compatible Z-80 CPU
1K of on-board RAM
4 EPROM sockets accommodates 2708, 2716, or 2732
One parallel and one serial I/O port
4-channel counter timer chip (Z-80 CTC)
Software programmable serial baud rates

CPC-30100K (2 MHz KIT)	\$249.95
CPC-30100A (2 MHz A&T)	\$299.95
CPC-30200K (4 MHz KIT)	\$289.95
CPC-30200A (4 MHz A&T)	\$339.95

GET THE INSIDE TRACK JADE DOUBLE-D DOUBLE DENSITY DISK CONTROLLER

Read/write single or double density, 8" or 5 1/4" drives
On board Z-80 insures reliable operation
CP/M compatible in either single or double density
Density is software selectable
Up to 4 single or double sided, single or double density drives may be mixed on the same system
EIA level serial printer interface on board-up to 9600 baud (perfect for despooling operations)
All the hard work of disk access is done by the on board Z-80A and 2K memory, leaving your host CPU free for its normal duties
Uses IBM standard formats for proven reliability
THIS BOARD REALLY WORKS !!!!!
IOD-1200K (DOUBLE-D KIT)

\$285.00

IOD-1200A (DOUBLE-D A&T)

\$349.00

IOD-1200D (MANUAL ONLY)

\$15.00

S D SYSTEMS VERSAFLOPPY II DOUBLE DENSITY DISK CONTROLLER

Single or double density floppy disk controller
985600 bytes on 8" double sided diskettes
259840 bytes on double sided 5 1/4" diskettes
S-100 bus (IEEE) standard compatible
IBM 3740 format in single density
8" and 5 1/4" drives controlled simultaneously
Operates with Z-80, 8080, and 8085 CPU's
Controls up to 4 drives
Vectored Interrupt operation optional
IOD-1160K (KIT)

\$335.95

IOD-1169A (A&T)

\$385.95

S D SYSTEMS VERSAFLOPPY

VERSATILE FLOPPY DISK CONTROLLER
IBM 3740 soft sectored format
S-100 Z-80 or 8080 compatible
Controls up to 4 single or double sided drives
Compatible with all popular disk drives
CP/M compatible
Listings for control software included
IOD-1150K (KIT)

\$189.95

IOD-1150A (A&T)

\$239.95

NEW DISK OPERATING SYSTEM SDOS IS HERE

WE THINK IT'S SUPERIOR

SDOS is a CP/M compatible operating system designed for the S.D. Sales Versafloppy I or II. It requires the SBC-100/Versafloppy board set and functions as a superset of CP/M, giving 19 additional functions including file attributes, disk label, and read/write logical blocks. It provides additional protection features, and is expandable to a multi-user real-time system.
SDOS sells for \$200.00

CALL FOR SALE PRICES !!! 32K STATIC RAM EXPANDABLE 8K/32K, 2/4MHz, KIT/A&T

NEW 2 OR 4 MHz REV. C BOARD THE JADE BIG Z

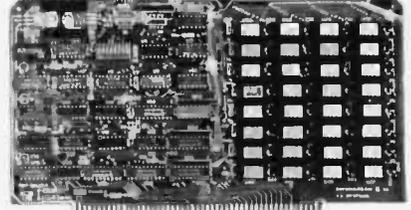
Z-80 CPU BOARD WITH SERIAL I/O PORT
2 or 4 MHz switchable, on-board 2708, 2716, or 2732 EPROM useable in SHADOW mode (full 64K RAM)
Automatic MWRITE generation if no front panel
On-board USART for sync or async RS232
CPU-30201K (KIT)

\$159.00

CPU-30201A (A & T)

\$209.00

S D SYSTEMS EXPANDORAM II 4 MHz RAM BOARD EXPANDABLE TO 256K



S-100 bus compatible, up to 4 MHz operation
Expandable memory from 16K to 256K
Dip switch selectable boundaries
Page-mode allows up to 8 boards on the same bus
Invisible refresh; PHANTOM output disable
Designed to operate in Z-80 based systems
MEM-16631K (16K KIT)

\$295.95

MEM-16631A (16K A&T)

\$345.95

MEM-32632K (32K KIT)

\$369.95

MEM-32632A (32K A&T)

\$419.95

MEM-48632K (48K KIT)

\$444.95

MEM-48632A (48K A&T)

\$494.95

MEM-64632K (64K KIT)

\$519.95

MEM-64632A (64K A&T)

\$569.95

VECTOR GRAPHICS 12K PROM/RAM 1K OF STATIC RAM AND 12 2708 SOCKETS MEM-12340A(A & T, NO PROMS)

\$135.00

BEST BUY RATED TV-1 ONLY \$7.95 OUR BEST SELLING R. F. MODULATOR

GET YOUR "ROCKS" OFF..THE SHELF CRYSTAL SALE WE STOCK 40 STANDARD FREQ. 3 FOR \$12

TIMELY SPECIAL 60 Hz TIME BASE CRYSTAL CONTROLLED KIT ONLY \$4.95

COMING SOON NEW JADE P/S I/O

PARALLEL/SERIAL/INTERRUPT BOARD
Z-80 SIO/PIO, 2 CTCs, expands to 2 SIOs, 4 CTCs
4 serial ports (async, sync, bisync, SDLC/HDLC)
2 parallel ports with full handshake
Software baud rate generators, interval timers, counters, and generates 32 vectored interrupts
Designed especially for MP/M multi-user multi-tasking operating systems. For use with Z-80 only
IOI-1045B (BARE BOARD)

\$45.00

IOI-1045K (KIT)

\$169.95

IOI-1045A (A & T)

\$224.95

SALE SALE SALE SALE SALE EPROMS BUY NOW AND SAVE

1702A	\$4.95
2708	\$8.95
2516	\$34.95
2716(T.I.)	\$4.95
2716(5 VOLT)	\$34.95
2758	\$34.95
2532	\$74.95
2732	\$74.95

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PRICES SLASHED FOR MARCH ! CALL TOLL-FREE AND SAVE

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TERMINAL SALE ADDS REGENT OUR FINEST LINE OF TERMINALS

ADDS REGENT 20	\$795.00
ADDS REGENT 25	\$850.00
ADDS REGENT 40	\$1195.00
ADDS REGENT 60	\$1495.00

SPECIAL PACKAGE PRICE RS-232 SET \$6.50

1 MALE DB-25, 1 FEMALE DB-25, 1 COVER

MICRO WORKS 2708 PROGRAMER

FITS STANDARD SWPT 6800 I/O SLOT
LIMITED SUPPLY(A & T) \$75.00

VECTOR GRAPHICS S-100 CARD CAGE

17" RACK WITH 18 SLOT MOTHERBOARD
ENC-118100(A & T) \$210.00

SPECIAL CLEARANCE SALE 4K EPROM BOARD

HOLDS UP TO 16 INEXPENSIVE 1702A's
MEM-04220K(KIT NO PROMS) \$45.00
MEM-04220A(A & T NO PROMS) \$79.95

CP/M 2.0

Digital Research has done it again! This new release of their industry standard disk operating system is bound to be an even bigger hit than the original version. All of the fundamental file-size restrictions of release 1 have been eliminated, while maintaining full compatibility with the earlier versions. This new release can be field-configured by the user for a single mini-disk up through a multiple drive hard-disk system with 128 megabyte capacity. Field configuration can be accomplished easily through use of the Macro Library (DISKDEF) provided with CP/M 2.0.

A powerful operating system for only ... \$150.00

JADE'S NEW MOTHERBOARDS THE ISO-BUS

WE'RE PROUD OF OUR MOTHER !
6-SLOT

BARE BOARD	\$24.95
KIT	\$49.95
ASSEMBLED & TESTED	\$59.95

BARE BOARD	\$39.95
KIT	\$89.95
ASSEMBLED & TESTED	\$99.95

BARE BOARD	\$59.95
KIT	\$129.95
ASSEMBLED & TESTED	\$149.95

SPECIAL PACKAGE PRICE ROCKWELL AIM-65

THE HEAD-START IN MICROCOMPUTERS

KIM-1 compatible
On-board printer
Full ACSII keyboard

AIM-65 w/1K RAM..\$375.00

AIM-65 w/4K RAM..\$450.00

8K BASIC ROM..\$100.00

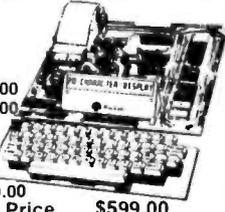
POWER SUPPLY..\$59.95

CASE for AIM-65..\$49.95

4K Assembler/Editor..\$80.00

Special Package Price \$599.00

4K AIM-65, 8K BASIC ROM, Power Supply, and Case.



JADE MEMORY EXPANSION KITS FOR TRS-80 APPLE EXIDY

Everything you need to add 16K of memory to your computer. Your kit comes neatly packaged with easy to follow instructions. In just minutes your computer is ready to tackle more advanced software.

\$69.00

SALE SALE SALE SALE SALE TRANSISTORS

LOOK UP THE SPECS AND STOCK UP

2N456A	10/\$1.00
2N718	10/\$1.00
2N2222A	5/\$1.00
2N3392	10/\$1.00
2N3741	2/\$3.00
2N3904	8/\$1.00
2N4013	20/\$1.00
2N4348	3/\$5.00
2N5088	5/\$2.00
2N5434	5/\$1.00
2N5449	5/\$1.00
2N6569	4/\$1.00
3N81	5/\$1.00

MICROPROCESSORS		6800 PRODUCT	
F8	\$16.95	6821P	\$5.25
Z80 (2MHz)	\$10.95	6828P	\$12.00
Z80A (4MHz)	\$14.95	6834P	\$16.95
CDP1802CD	\$24.95	6850P	\$4.80
6502	\$11.95	6852P	\$7.50
6800	\$12.50	6860P	\$9.25
6802	\$20.00	6862P	\$12.00
8008-1	\$15.95	6875L	\$7.30
8035	\$24.00	6880P	\$2.50
8035-B	\$24.00	CHARACTER GENERATORS	
8080-A	\$10.00	2513 Upper	\$7.95
8085	\$23.00	2513 Lower	\$6.75
TMS9900TL	\$49.95	2513 Upper (5 volt)	9.75
8080A SUPPORT DEVICES		2513 Lower (5 volt)	\$13.00
B212	\$5.00	MCM6571 up scan	\$13.00
B214	\$4.65	MCM6571A down scan	\$10.95
B216	\$2.95	PROMS	
B224 (2MHz)	\$4.30	1702A	\$5.00
B226	\$2.75	2708	\$8.95
B228	\$6.40	2716	\$39.95
B238	\$6.40	2716 (5v)	\$39.95
B243	\$8.00	2758 (5v)	\$30.00
B251	\$7.50	DYNAMIC RAMS	
B253	\$20.00	4116/416D	8 tor \$74.95
B255	\$6.40	2104/4096	\$4.75
B257	\$19.95	2107B-4	\$3.95
B259	\$19.95	TMS4027/4096	\$4.75
B275	\$69.95	STATIC RAMS	
B279	\$17.70	21L02 (450ns)	\$1.50
USRT		21L02 (250ns)	\$1.75
S2350	\$10.95	2101-1	\$2.95
UARTS		2111-1	\$3.25
AY5-1013A	\$5.25	2112-1	\$2.95
AY5-1014A	\$8.25	2114L (450ns)	\$5.75
TR1602B	\$5.25	2114L (300ns)	\$5.95
TMS6011	\$5.95	TMS4044 (450ns)	\$8.00
IM6403	\$8.00	TMS4044 (300ns)	\$9.95
BAUD RATE GENERATORS		410D (200ns)	\$9.95
MC14411	\$10.00	4200A (200ns)	\$9.95

INTEGRAL DATA SYSTEMS THE PAPER TIGER

132 COLUMN DOT MATRIX PRINTER

Up to 198 CPS
1.75 to 9.5 inch adjustable tractor and friction feed.
Parallel and serial interface.

98 character ASCII set.
80 to 132 columns.
6 or 8 lines per inch.
Eight software selectable character sizes.

110, 300, 600, or 1200 baud.

PRM-33440 \$950.00
PRM-33441(GRAPHICS & 2K BUFFER) . \$1050.00



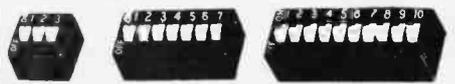
SPECIAL SALE PRICE

GUARANTEED PREMIUM QUALITY JADE DISKETTES

MAGNIFICENT MAGNETIC MEDIA !

5 1/4" single sided, single density, box of 10	
MMD-5110103 (SOFT SECTOR)	\$29.95
MMD-5111003 (10 SECTOR)	\$29.95
MMD-5111603 (16 SECTOR)	\$29.95
5 1/4" double sided, double density, box of 10	
MMD-5220103 (SOFT SECTOR)	\$39.95
8" single sided, single density, box of 10	
MMD-8110103 (SOFT SECTOR)	\$34.95
8" single sided, double density, box of 10	
MMD-8120103 (SOFT SECTOR)	\$55.95
8" double sided, double density, box of 10	
MMD-8220103 (SOFT SECTOR)	\$57.95

SPST DIP SWITCHES



PART NUMBER	NUMBER OF SWITCHES	PRICE
SWD-103	3	\$1.00 \$1.18
SWD-104	4	\$1.05 \$1.20
SWD-105	5	\$1.10 \$1.24
SWD-106	6	\$1.15 \$1.28
SWD-107	7	\$1.20 \$1.30
SWD-108	8	\$1.25 \$1.34
SWD-109	9	\$1.30 \$1.38
SWD-110	10	\$1.35 \$1.38

SALE



TEXT TOOL ZIP* DIP II SOCKETS

16 PIN ZIP* DIP II	\$5.50
24 PIN ZIP* DIP II	\$7.50
40 PIN ZIP* DIP II	\$10.25

* ZERO INSERTION PRESSURE

SPECIAL PRICE FOR MARCH NOVATION CAT

ACOUSTIC COUPLER/MODEM

\$157.50



Let your computer talk to other computers !
Bell Systems 103 compatible
300 baud, answer or originate
IOM-5200A (SALE PRICED) \$157.50

JADE Computer Products

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213-679-3313

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INSIDE CALIFORNIA CONTINENTAL U.S.

WRITE FOR OUR FREE 1980 CATALOG
FOR CUSTOMER SERVICE OR TECHNICAL INQUIRIES
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TERMS OF SALE: Cash, checks, money orders, and credit cards accepted. Minimum order \$10.00. California residents add 6% sales tax. Minimum shipping and handling charge \$2.50. Prices are for U.S. and Canadian delivery only and are subject to change without notice. For export prices and information send for a JADE INTERNATIONAL CATALOG.



RN IDH Series - Headers

PC Mounting



Pins	Straight	Right Angle	1-9	10-24	25-99
10	IDH-10S	IDH-10SR	.95	.72	.70
20	IDH-20S	IDH-20SR	1.30	1.15	1.10
26	IDH-26S	IDH-26SR	1.75	1.50	1.35
34	IDH-34S	IDH-34SR	2.25	1.95	1.75
40	IDH-40S	IDH-40SR	2.55	2.35	2.15
50	IDH-50S	IDH-50SR	3.25	2.95	2.75

Wire Wrap

Pins	Straight	Right Angle	1-9	10-24	25-99
10	IDH-10W	IDH-10WR	1.95	1.65	1.55
20	IDH-20W	IDH-20WR	2.75	2.50	2.40
26	IDH-26W	IDH-26WR	3.50	3.25	3.15
34	IDH-34W	IDH-34WR	4.25	3.95	3.75
40	IDH-40W	IDH-40WR	4.75	4.50	4.25
50	IDH-50W	IDH-50WR	5.95	5.60	5.40

Ejector Ears for above. 4/\$1.00 20/\$3.00 100/\$10.00

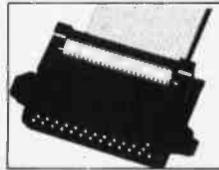
- Header is permanently mounted on PCB and accepts IDS socket connectors.
- Straight or right angle mounting options available for both solder and wrap pin terminations.

- Solder termination length for either .062" or .125" PCB.
- Ejector/Latch available, latches IDS socket in place when closed, serves as ejector when open.

IDC Card Edge Connectors

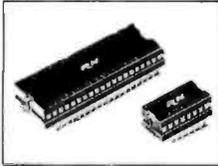
Pins	1-9	10-24	25-99
20	4.15	3.75	3.30
26	4.75	4.30	3.80
34	5.70	5.10	4.50
40	6.50	5.80	5.25
50	7.00	6.30	5.40

25 Pin 'D' Subminiature



	1-9	10-24	25-99
Plug	6.00	5.25	4.70
Socket	6.35	5.60	5.00

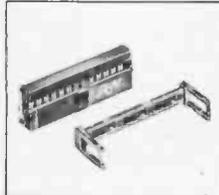
RN Cable Plugs



Pins	1-9	10-24	25-99	100
14	1.30	1.25	1.10	.95
16	1.50	1.40	1.25	1.10
24	2.25	2.15	2.00	1.75
40	3.75	3.50	3.25	2.95

- Provides pluggable termination of cable to PCB thru IDP plugs and standard DIP sockets such as RN ICN series DIP sockets.
- Single piece design for easy handling and assembly.
- Cover latch allows cover swivel for easy cable insertion.
- Tapered pin tip permits easy insertion into IC sockets.
- Strong leads for multiple insertions without damage.

RN Insulation Displacement Sockets



Pins	Socket Connector	1-9	10-24	25-99	Strain Relief
10	IDS10	1.40	1.20	1.10	.25
20	IDS20	2.00	1.85	1.75	.25
26	IDS26	2.50	2.40	2.30	.25
34	IDS34	3.25	3.10	2.95	.25
40	IDS40	3.95	3.70	3.55	.25
50	IDS50	5.00	4.60	4.40	.25

- Provides pluggable termination of cable to PCB thru IDS sockets and IDH headers.
- Single piece body construction for easy assembly, strain relief attached after assembly.
- Rugged cover latch and optional strain relief for dependability.
- Strain relief can be purchased separately.
- Molded orientation tab.

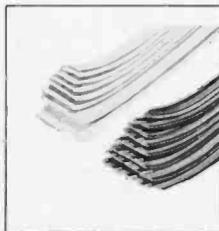
RN Transition Connectors



	1-9	10-24	25-99
10	1.50	1.35	1.25
20	1.75	1.60	1.50
26	2.25	2.00	1.75
34	2.50	2.40	2.30
40	3.00	2.80	2.60
50	3.60	3.45	3.15

- Connector used to permanently attach cable to PCB.
- Lead length options for .062" and .125" thick PCB.
- Rugged single piece design for easy assembly and dependability.
- Cable can be attached before or after soldering connector to PCB.

RN Cable



Conductors	Solid Color		Color Coded	
	10 ft.	100 ft.	10 ft.	100 ft.
10	2.90	17.00	4.00	30.00
14	3.40	23.80	5.00	42.00
16	3.70	27.20	5.60	48.00
20	4.40	34.00	7.00	60.00
24	5.00	40.80	8.00	72.00
26	5.40	44.20	8.60	78.00
34	6.80	57.80	11.00	102.00
40	7.80	68.00	13.00	120.00
50	9.50	85.00	16.00	150.00

- Compatible with all RN IDC products.
- Wire spacing .050" ± .002", 28 ga stranded.
- 10 thru 50 Conductor Laminated Cable Solid Color (with wire one mark) or Color Coded.
- Available in 100 foot rolls, or 10 foot lengths.
- Meets UL FR-1 Vertical Flame Test.

Note: Custom crimping available on all products for proto-type quantities at 50¢/connection.

Gold: All parts on this page except Cable are gold plated. Because of the volatility of gold pricing, orders may be subject to a gold surcharge.

California Digital

Post Office Box 3097 B • Torrance, California 90503

FREE Paper Tiger

With Purchase of The INTEGRAL DATA 440

Your Choice, \$200 Value

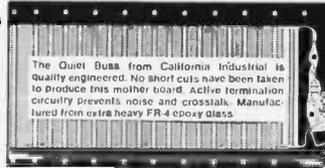
- 1) Graphics Option Package
 - 2) Interface for APPLE II
 - 3) TRS-80 Printer Interface
- California Digital has recently researched the complete low cost printer market. It is our opinion that the IDS440 Paper Tiger is, without doubt, the most versatile and offers the best value of any printer costing under \$1,000.

This quality dot matrix printer incorporates such features as software selectable character size to allow print densities upto 132 characters per line. Full forms handling capabilities and tractor feed mechanism adjustable to 9.5". The Paper Tiger is engineered to accept either parallel or RS232 serial ASCII. 110/220V.50/60Hz. ***** \$995.00 plus shipping *****

S-100 Mother Board

Quiet Buss

\$2995
8803-18
18 slot
IMSAI



The Quiet Buss from California Industrial is quality engineered. No short cuts have been taken to produce this mother board. Active termination circuitry prevents noise and crosstalk. Manufactured from extra heavy FR-4 epoxy glass.

TELETYPE MODEL 43

4320 KEYBOARD
TTL AAA \$1050
RS232... AAK 1150
Friction... AA 1100 plus shipping
183 Modem AAB 1575



Minidisk Drive for TRS-80

your choice \$388.
Lobo or Vista Includes Interface Cable



It is not often that California Digital ventures into the distribution of consumer products, but we have recently come across a product that appears so unique that we had to add it to our product line. This is the System X-10 manufactured by the IBM turntable company. This space age system will remotely control any light or appliance in your home or office. Command signals are transmitted from the command console over your existing wiring. From your bed or easy chair you can control up to 16 different electrical devices inside and outside your home. Use the System X-10 to control your stereo, television or any light fixture of the premises.

The mobility system is available in the following components:
Ultrasonic Master Control Console \$34.95
Battery Operated Ultrasonic Controller 10.00
Appliance Module, Lamp Module or Wall Switch 13.95

FREE PLASTIC LIBRARY CASE with purchase of each box of Verbatim mini-diskettes. \$5 value.

\$24.95 BOX of 10 DISKETTES

CONNECTORS

your choice DB25P male plug & hood or DB25S female \$325

Qty.	fe. male	hd.
10	3.05	1.95 1.15
25	2.95	1.75 1.05
100	2.65	1.67 .95
500	2.25	1.60 .85
1K	1.97	1.37 .73

Edge Connectors

GOLD 100 PIN IMSAI/ALTAIR

Imsal solder .125x.250	\$2.95	3/7.50
Imsal w/.125 centers	\$4.95	3/13.00
Altair solder tail .140row	\$5.95	3/15.00

SPECIALS

22.44 Kim eyelet .156"	\$1.95	3/5.00
25/50 solder tab .156"	\$1.09	3/2.00
36/72 wide post w/.156	\$1.95	3/5.00

SYSTEM X-10

It is not often that California Digital ventures into the distribution of consumer products, but we have recently come across a product that appears so unique that we had to add it to our product line. This is the System X-10 manufactured by the IBM turntable company. This space age system will remotely control any light or appliance in your home or office. Command signals are transmitted from the command console over your existing wiring. From your bed or easy chair you can control up to 16 different electrical devices inside and outside your home. Use the System X-10 to control your stereo, television or any light fixture of the premises.

The mobility system is available in the following components:
Ultrasonic Master Control Console \$34.95
Battery Operated Ultrasonic Controller 10.00
Appliance Module, Lamp Module or Wall Switch 13.95

Apple II

16K MEMORY COLOR • GRAPHICS • SOUND \$988 PLUS SHIPPING

MINIATURE SWITCHES

your choice \$1.29

10	25	100	1B
ea.	\$1.19	1.09	.97 .83

Specify 4 for 8 Pos.

Authorized Distributor



IBM soft form at \$39.00
Double density 33.00
Double/Double 70.00
8" Hard sector 39.90
5 1/4" mini 39.00

Library case for any above: Add \$3.00

831 A Data Cassette 5.30
D/C 100 Mini Cartridge 16.00
D/C 300 Data Cartridge 20.00
920C Disk Cartridge 39.90

Shugart Associates

SA800-R Floppy Disk Drive The most cost effective way to store data processing information, when random recall is a prime factor. The SA800 is fully compatible with the IBM 3740 format. Write protect circuitry, low maintenance & Shugart quality. \$449.50

XEROX 800 WORD PROCESSING KEYBOARD

ASCII ENCODED \$499.00

This 77 key word processing keyboard was manufactured by Xerox for use in the Xerox 800 word processing system. The keyboard outputs a seven bit ASCII code along with an eighth bit that allows most keys to shift and double function as special characters. Extra large "Tab & Return" keys are designed into the layout of the keyboard to simulate the IBM Selectric. It illuminated keys agree for special word processing codes. The keyboard is equipped with two thumbwheel switches for defining line width.

Original Xerox acquisition over \$400.00 California Digital USD price only \$49.00 Excellent cond. Documentation included.

MEMORY

TRS-80 \$65
APPLE II 16k memory (8) 4116's

Installation is simple. Anyone who has ever changed a spark plug should be able to up-grade his microcomputer. How can California Digital offer these memory up-grade sets at 25% below our competition? Simple, we buy in volume, wholesale to dealers and sell the balance directly to owners of personal micro-systems. These 16K dynamic memory circuits are factory prime and unconditionally guaranteed for one full year. NOW, before you change your mind, pick up the telephone and order your up-grade memory from California Digital. Add \$3 for TRS80 jumpers.

STATIC	1-31	32-99	100-5C	999	1K+
21L02 450nS.	1.19	.99	.95	.90	.85
21L02 250nS.	1.49	1.39	1.25	*	*
2114 1Kx1 450	5.95	5.50	5.25	4.75	4.50
2114 1Kx1 300	8.95	8.50	8.00	*	*
4014 4Kx1 450	9.95	5.50	5.25	*	*
4014 4Kx1 250	9.95	9.50	9.00	*	*
4043 1Kx4 450	8.95	8.50	8.00	*	*
4043 1Kx4 250	9.95	9.50	9.00	*	*
5257 low pow.	5.95	5.50	5.00	4.80	4.60

SPECIAL CIRCUITS

Z80A 4MHz.	24.95	A55-1013A UART	4.95
8940A CPU	9.95	Floppy Disc Controllers	
8095	22.50	WD 1771 single D.	39.95
1086 Intel 16 bits	85.00	WD 1781 Double D.	65.00
FMS 9900 16 bits	49.95	WD 1791 16 D 3740 *	

E PROMS 1-15 16-63 64+

1702A 2K	4.95	1.50	4.00
2708 8K	9.95	9.50	9.00
2716 5V 16K	29.95	27.50	*
2716 1I	24.88	20.00	*
2532	85.00	*	*



TOUCH TONE Speaker Phone \$49 Factory Liquidation

ACOUSTIC MODEM \$89 USED

The Unique model 701 Modem connects the RS-232 aerial port of your computer or peripheral device acoustically to your telephone line. Place the telephone handset into cradle of the modem. Instantly your computer system has access to the world of digital information. Half and full duplex ability.

The Voicecaster simply plugs into your existing phone wall jack. The twelve button pad creates standard Touch Tone frequencies. Unique electronic circuitry eliminates that hollow sound that you have heard on other systems. Original retail price \$295. Please consult your local telephone company to determine if a line protection device is required in your community. Dial units also available.

Regent 25 \$129

Through years of progress the Altis Corporation has evolved a new maintenance-free, variable CRT terminal capable of withstanding an average 31 hour duty cycle. The Regent 25 features Intel 8085 microprocessor controls a capability along with the Cherry Sixteen line-dot equalizer keyboard. 38 key cursor and numeric pad facilities to allow for user-definable special functions. Two descending lower case characters along with a fully adjustable cursor moves the Regent 25 the ideal word processing terminal. 16 character alphanumeric screen is capable of displaying 96 upper and lower case ASCII characters and 23 control codes. This terminal is switch-selectable to display six languages. At \$129 (plus shipping) the Regent 25 offers the best value in today's CRT terminal market. Additional data upon request.

MINIATURE SWITCHES \$1.29

10	25	100	1B
ea.	\$1.19	1.09	.97 .83

Specify 4 for 8 Pos.

DIP Switch \$1.29

10	25	100	1B
ea.	\$1.19	1.09	.97 .83

Specify 4 for 8 Pos.

PORTABLE DATA ENTRY SYSTEM \$139.50

These used data terminals were originally designed for chain store inventory control and order entry systems. The operator enters the inventory control number, merchandise on hand and the unit price. After all pertinent data has been entered into the recorder, the main warehouse is telephoned. The handset is placed in the acoustic coupler and all the recorded information is transmitted back to the master computer. With a little imagination and one of these portable entry systems, you should be able to exchange programs and computer information with associates across the country. All units were removed from service in working condition. Original cost \$2,300. Each system comes complete with:

- Portable Cassette Drive Unit
- "Flow Gould" D' NICs
- "DH25 Cable"
- Acoustical Coupler
- Shoulder strap
- "Batterly Charger"
- Full Documentation

DISCOUNT Wire Wrap Center

IC SOCKETS

pin	wire wrap ea.	low profile ea.	25 profile ea.
8		17: 16 15	
16	37: 36 35	18 17 16	
16	38 37 36	19 18 17	
24	99 93 85	36 35 34	
40	169 155 139	63 60 58	

50ft. KYNAR WIRE WRAP \$98

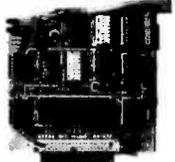
500	1,000	11,000
\$9.	\$15.	\$105.

BATTERY WIRE WRAP \$29.95

OK HOBBY WRAP-30 wire wrap & strip tool \$5.45

TRS-80 E.S. SERIAL I/O

- Can input into basic
- Can use LLIST and LPRINT to output, or output continuously
- RS-232 compatible
- Can be used with or without the expansion bus
- On board switch selectable baud rates of 110, 150, 300, 600, 1200, 2400, parity or no parity odd or even, 5 to 8 data bits, and 1 or 2 stop bits. D.T.R. line
- Requires +5, -12 VDC
- Board only \$19.95 Part No. 8010, with parts \$59.95 Part No. 8010A, assembled \$79.95 Part No. 8010 C. No connectors provided, see below.



EIA/RS-232 connector Part No. 0825P \$6.00 with 5' 8 conductor cable \$10.95 Part No. 0825P9.

3' ribbon cable with attached connectors to fit TRS-80 and our serial board \$19.95 Part No. 3CAB40.

MODEM

- Type 103
- Full or half duplex
- Works up to 300 baud
- Originate or Answer
- No coils, only low cost components
- TTL input and output-serial
- Connect 8 Ω speaker and crystal mic. directly to board
- Uses XR FSK modulator
- Requires +5 volts
- Board only \$7.60 Part No. 109, with parts \$29.95 Part No. 109A



DISKETTES



Box of 10, 5" \$29.95, 8" \$39.95. Plastic box, holds 10 diskettes, 5" - \$4.50, 8" - \$6.50.

APPLE II** SERIAL I/O INTERFACE



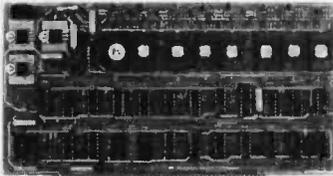
Baud rate is continuously adjustable from 0 to 30,000

- Plugs into any peripheral connector
- Low current drain. RS-232 input and output
- On board switch selectable 5 to 8 data bits, 1 or 2 stop bits, and parity or no parity either odd or even
- Jumper selectable address
- SOFTWARE
- Input and Output routine from monitor or BASIC to teletype or other serial printer
- Program for using an Apple II for a video or an intelligent terminal. Also can output in correspondence code to interface with some selectrics.
- Also watches DTR
- Board only \$15.00 Part No. 2, with parts \$42.00 Part No. 2A, assembled \$62.00 Part No. 2C

8K EPROM PIICEON

Saves programs on PROM permanently (until erased via UV light) up to 8K bytes. Programs may be directly run from the program saver such as fixed routines or assemblers.

- S-100 bus compatible
- Room for 8K bytes of EPROM non-volatile memory (2708's).
- On-board PROM programming
- Address relocation of each 4K of memory to any 4K boundary within 64K
- Power on jump and reset jump option for "turnkey" systems and computers without a front panel
- Program saver software available
- Solder mask both sides
- Full silkscreen for easy assembly. Program saver software in 1 2708 EPROM \$25. Bare board \$35 including custom coil, board with parts but no EPROMS \$139, with 4 EPROMS \$179, with 8 EPROMS \$219.



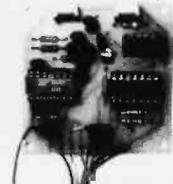
T.V. TYPEWRITER

- Stand alone TVT
- 32 char/line, 16 lines, modifications for 64 char/line included
- Parallel ASCII (TTL) input
- Video output
- 1K on board memory
- Output for computer controlled cursor
- Auto scroll
- Non-destructive cursor
- Cursor inputs: up, down, left, right, home, EOL, EOS
- Scroll up, down
- Requires +5 volts at 1.5 amps, and -12 volts at 30 mA
- All 7400, TTL chips
- Char. gen. 2513
- Upper case only
- Board only \$39.00 Part No. 106, with parts \$145.00 Part No. 106A



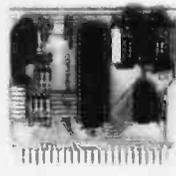
TAPE INTERFACE

- Play and record Kansas City Standard tapes
- Converts a low cost tape recorder to a digital recorder
- Works up to 1200 baud
- Digital in and out are TTL-serial
- Output of board connects to mic. in of recorder
- Earphone of recorder connects to input on board
- No coils
- Requires +5 volts, low power drain
- Board only \$7.60 Part No. 111, with parts \$29.95 Part No. 111A



UART & BAUD RATE GENERATOR

- Converts serial to parallel and parallel to serial
- Low cost on board baud rate generator
- Baud rates: 110, 150, 300, 600, 1200, and 2400
- Low power drain +5 volts and -12 volts required
- TTL compatible
- All characters contain a start bit, 5 to 8 data bits, 1 or 2 stop bits, and either odd or even parity.
- All connections go to a 44 pin gold plated edge connector
- Board only \$12.00 Part No. 101, with parts \$35.00 Part No. 101A, 44 pin edge connector \$4.00 Part No. 44P



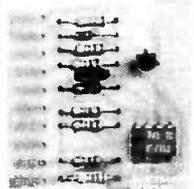
HEX ENCODED KEYBOARD

This HEX keyboard has 19 keys, 16 encoded with 3 user definable. The encoded TTL outputs, 8-4-2-1 and STROBE are debounced and available in true and complement form. Four onboard LEDs indicate the HEX code generated for each key depression. The board requires a single +5 volt supply. Board only \$15.00 Part No. HEX-3, with parts \$49.95 Part No. HEX-3A. 44 pin edge connector \$4.00 Part No. 44P.



RS-232/ TTL INTERFACE

- Converts TTL to RS-232, and converts RS-232 to TTL
- Two separate circuits
- Requires -12 and +12 volts
- All connections go to a 10 pin gold plated edge connector, kit \$ 9.95 Part No. 232A 10 Pin edge connector \$3.00 Part No. 10P.



RS-232/TTY INTERFACE

This board has two active circuits, one converts RS-232 to 20mA, and the other converts 20mA to RS-232. Requires +12 and -12 volts. \$9.95 Part No. 600A Kit.



WAMECO PRODUCTS WITH

ELECTRONIC SYSTEMS PARTS

- FDC-1 FLOPPY CONTROLLER BOARD** will drive shugart, pertek, remex 5" & 8" drives up to 8 drives, on board PROM with power boot up, will operate with CPM (not included). PCBD \$42.95
- FPB-1 Front Panel.** (Finally) IMSAI size hex displays. Byte or instruction single step. PCBD \$42.95
- MEM-1A 8Kx8 fully buffered, S-100, uses 2102 type RAMS.** PCBD \$24.95, \$168 Kit
- GMB-12 MOTHER BOARD, 13 slot, terminated, S-100 board only** \$34.95 \$89.95 Kit
- CPU-1 8080A Processor board S-100 with 8 level vector interrupt PCBD** \$25.95 \$89.95 Kit
- RTC-1 Realtime clock board.** Two independent interrupts. Software programmable. PCBD \$25.95, \$60.95 Kit
- EPM-1 1702A 4K EPROM card PCBD** \$25.95 \$49.95 with parts less EPROMS
- EPM-2 2708/2716 16K/32K EPROM card PCBD** \$24.95 \$49.95 with parts less EPROMS
- GMB-9 MOTHER BOARD.** Short Version of GMB-12. 9 Slots PCBD \$30.95 \$67.95 Kit
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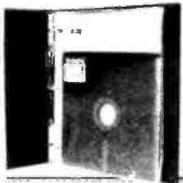
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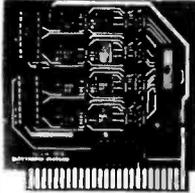
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ASCII KEYBOARD

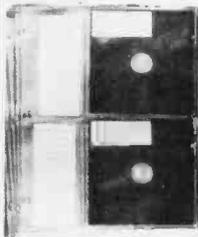
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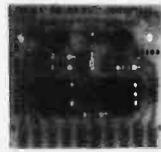
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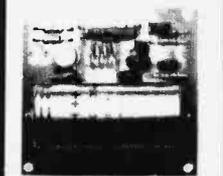
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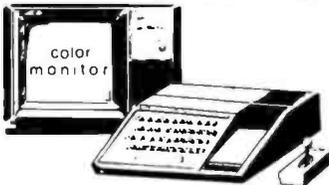


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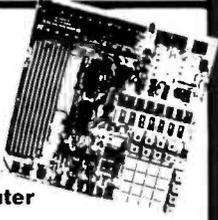
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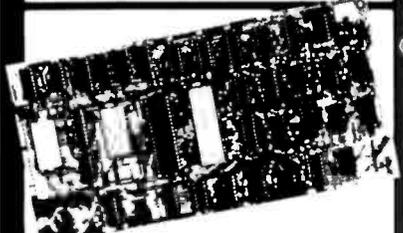
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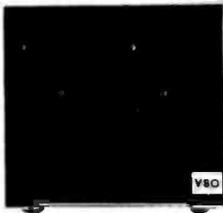
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FOR SALE: RCA Cosmac VIP CDP1802. Fully assembled and working beautifully. Pixe-Verter for television and cassette recorder included. Also, two manuals and one issue of *Viper* magazine. Asking \$200 or best offer. I pay shipping. Jeff Roberts, 1800 Huntington Tpke, Trumbull CT 06611, (203) 375-9430.

FOR SALE: Three 6800 systems at my cost less 50 to 70%. AMI PROTO processor, Davis 16 K random-access-memory boards, MSI/GSI disks, IDS printers. Buy system or components. Send SASE for complete list of components and prices. Phil Reagan, 1557 Jackson St #106, Oakland CA 94612, (415) 839-3409.

FOR SALE: Radio Shack TRS-80, Level II. 16 K. Complete system (processor/keyboard, video monitor, cassette recorder). Plus some programs, assorted books, and many cassettes. One-year-old, used three months. Sacrifice at \$650. Stan Birnbaum, 1610 Hudson St Apt 4, Helena MT 59601, (406) 443-7320.

WANTED: Sanders 708 video display terminal, or equivalent, for X-Y vector displays. Send details, including price and condition. George B Konizer, 2008 N Brailsford Rd, Camden SC 29020.

WANTED: A ZE, ZB, ZC, or ZD erasable read-only memory for Digital Group Z80 board. A Z80 operating system cassette for 1024 TVC, also by Digital, or a good copy of same. You name the price. Fred A Bufanio, 96 Overlook Ter, Bloomfield NJ 07003.

FOR SALE: PerSci dual 8-inch disk drive, double-density rated with cable for direct input/output (I/O), Model #2142; also, controller card for S-100 bus. Both one-year-old and working. Original cost over \$2700; sell for \$2300. Richard Turner, 1420 Balboa Av Apt J-75, Panama City FL 32401, (904) 769-8025 Wednesday and Friday evenings and weekends.

FOR SALE: TRS-80 computer system 16 K Level II, expansion Interface, RS-232 interface, and disk drive with disk operating system disk (all cables included). Excellent condition. Buying larger system. My cost \$1900, will sell for \$1600 or best offer. S Phail, 4900 Bristow Dr, Annandale VA 22003, (703) 941-4075.

WANTED: MITS 88-2SIO input/output (I/O) board. All integrated circuits must be socketed and board must be in working order. R Tsubota, Rt 2 POB 442, Ontario OR 97914.

FOR SALE: Heathkit H8 computer system with 16 K, H8-5 input/output (I/O) cassette interface, H9 video terminal, and HC8-14 cassette software system. All factory tested and running. Includes all manuals, documentation, and software. \$1000 or best offer. (Canadian funds) Will ship. Reason selling: I have two computer systems. Robert Tremblay, 1316 Teillet, Ste-Foy Quebec, CANADA G1W 3C2.

WANTED: Apple II or Apple II Plus. No Apple is too small. If you want to trade up, give a hand to a beginner. Send a description and price. Please include your phone number. Everyone will receive a reply if at all possible. David Hayes, 537 Hall St, Ripon WI 54971.

WANTED: Information about fixes or patches for bugs in TDL-Xitan FORTRAN and/or Disk BASIC. Will pay with money or similar information known to me. Have written FORTRAN program for communication and file transfer between Micro and WYLBUR on 370. Will be happy to share. M Frankel, Dept of Statistics, Baruch College CUNY, 46 E 26 St, NYC NY 10010.

WANTED: Diablo 1650 print mechanism with or without interface. Or Selectric print mechanism with ASCII interface. Dennis Toeppen, 409 S H Lusi, Mount Prospect IL 60056, (312) 255-2255 after 6 PM weekdays.

FOR SALE: Expander Black Box printer. See 11/77 *Kilobaud* for detailed article or 5/79 *Jade* ad for brief description of this compact eighty-column impact printer. Case, parallel interface, cable, connectors, documentation, and shipping included. Cost new is \$470. First \$300 bank check or money order gets mine. Used nine months. Fred Lepow, 1700 Circo del Cielo Dr, El Cajon CA 92020, (714) 440-9310 (nights) or (714) 276-3414 (days).

FOR SALE: Two Friden Flexowriter units. Each has paper-tape read/write on keyboard, a desk/console, and an auxiliary scanning/reader. \$265 each. Also, Tektronix 513 oscilloscope DC to 18 MHz; \$195. Gerald Orman, 7619 Forrest Av, Munster IN 46321, (219) 836-1514 evenings.

FOR SALE: IBM 1050 Data Communication System (RS-232). Consists of control unit, Selectric-based printer-typewriter, paper-tape punch, paper-tape reader. Full documentation. Excellent condition. \$800. SASE would be appreciated. Arkady G Makhlina, 39 Hammer-smith, Danbury CT 06810, (203) 743-9509.

FOR SALE: Two 2315 2.4 M bytes disk cartridges, Hewlett-Packard Model #12869A, in Wright Line Model #5835-20 disk pack carrying case; \$100 or reasonable offer. Fourteen Hewlett-Packard 9162-0050 digital cassettes; \$28 or reasonable offer. James R Schueler, 317 Chilean Av Rear, Palm Beach FL 33480.

FOR SALE: Altos/8000 (Model ACS 8000-1) with two 8-inch drives (1/2 Mb), 64 K main memory, CP/M operating system, Xitan Extended Disk BASIC, Texas Instruments' (Model 810) 150 characters per second (cps) printer with forms length control, Volker Cregl video display with numeric pad, detachable keyboard, and addressable cursor. John Whiffen, (416) 279-1496 (CANADA).

FOR SALE: Intel single-board, computer-based system. Includes: SBC-80/10 (8080A processor card), SBC-104 (4 K random access memory, input/output (I/O), etc), SBC-116 (16 K random access memory, read-only memory, I/O), SBC-310 (high-speed math processor), SBC-534 (four-channel serial I/O), SBC-604 (card cage), SBC-635 (14 A power supply). Also, SBC-80/04 (8085 processor), ultraviolet programmable read-only memory eraser, National Multiplex digital cassette recorder, and DEC LA-36 terminal. Will negotiate price or trade. Jim Mortons, POB 65, Fond du Lac WI 54935.

FOR SALE: PDP-11 boards. Removed from working PDP-11/15. Complete processor. Very powerful. Too many boards to list. One Hex (front panel), four Quad, six Dual, three Single, seven Single small. Twenty-one boards in all. \$60. Take advantage of the low value of the Canadian dollar and buy. Write for complete information. David Lai, 13250 Racine St, Pierrefonds Quebec, CANADA H8Z 1Y7.

FOR SALE: Three IMSAI 4 K random-access-memory boards for S-100 bus with individual 1 K write-protect. \$85 each. One Polymorphic video board with 16 by 64 characters, 48 by 128 graphics, 1 K of on board random access memory, and an 8-bit parallel port for keyboard. Also for S-100 bus. \$160. Everything assembled. Peter Hack, 579 Diamond St, San Francisco CA 94114, (415) 824-4225.

FOR SALE: Commodore PET 2001/8 with full documentation. Assorted software games included. Excellent condition, burned in, and running. \$525. Michael DiMario, 4300 N 92 St Apt 1, Milwaukee WI 53222, (414) 476-8300 ext 720 days, (414) 463-0836 evenings.

FOR SALE OR TRADE: I will design and print a single- or double-sided printed-circuit board from your specifications on my Tektronix graphics computer. Will trade for surplus computer gear. Send SASE for sample of my work. Rex Taylor, 2367 NW Kearney, Portland OR 97210.

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FOR SALE: Two Processor Technology 16 K dynamic programmable memory boards #16KRA for SOL or S-100 system. See January 1977 BYTE, page 10. With manual. 32 K for \$200. Not sold separately. First check or money order takes it. Bob Duke, 13526 Pyramid Dr, Dallas TX 75234, (214) 241-2888.

OLD COMPUTING DEVICES: Do you have or know about planimeters, Integrators, Integrators, mechanical computers, pre-1900 calculators, or other unusual early computing machines? Do you have books, manuals, or other documentation about them? I am buying, studying, and exchanging stories about these things. What's the weirdest computing machine you know of? I'd particularly like to hear about unusual projects, both historical and recent. Dick Rubinstein, 15 Maugus Av, Wellesley MA 02181.

FOR SALE: Digital Group standard mother board, Z80 processor board, input/output (I/O) board, TVC/cassette interface, George Risk keyboard in oak cabinet, TV monitor conversion kit, dual Phi-Deck and controller board, nonstandard power supply and cabinet. All documentation and system programs included. Boards assembled by professional digital technician. System never calibrated or run. \$800 complete or trade for TRS-80 disks or printer. Jim Lewis, POB 22045, Knoxville TN 37922.

WANTED: I need a few odd integrated circuits for repairs to circuit boards made by Intel Corp. Type numbers are: P3404, MC3002, 8267, 8263, NE550, MC3003. Damaged boards with salvageable usable circuits would be satisfactory. Merle Vogt, POB 145, Von Ormy TX 78073.

WANTED: Hewlett-Packard 9830 in excellent working condition, preferably under H-P maintenance. With plasma display, tape cartridge drive, thermal printer, BASIC, and manual. R Kesell, 345 W 88th St, NYC NY 10024, (212) 873-5556.

FOR SALE: Upgrading all TRS-80 Model I equipment to Model II. Must sell like-new expansion interface with 32 K random access memory. Only \$470. Two Shugart disk drives with cable, and four MPI disk drives with cable. Your choice only \$385 per drive. Buy two or more drives and get the cable free. One Centronics printer (call or write for price). Bruce Taylor, 118 S Mill St, Pryor OK 74361, (918) 825-4844, after 6:00 PM (918) 434-5242.

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Inquiry No.	Page No.	Inquiry No.	Page No.	Inquiry No.	Page No.	Inquiry No.	Page No.
106	Aardvark Software 167	209	DATABANK 240	*	Micro Diversions (Scion Corp.) 5	259	Quest 271
244	AB Computers 266	127	Data Discount Center 188	133	Micro Innovations Corp 191	200	RACET Computes 233
277	Advanced Computer Prod 284, 285	186	Datadisk Sys 224	170	Micro Integration 217	246	Radio Hut 267
132	AL Industries 191	197	Datasouth Computers 231	176	Micromall 219	80	Radio Shack 131
255	ALL Electronics 268	48	DATASPEED 83	130	Micro Management Systems 190	154	Raygam 205
68	Altos 106, 107	73	Delta Products 117	247	Micro Mart 268	*	RBB 226
218	American Square Computers 258	264	DES-MAR Electronics 272	23	Micro Mikes 177	96	RCA Solid State 152
267	Ampero Software 272	141	DG Electronics 195	151	Micro Music 202	*	Reliable Cash Register 241
44	Anadex Inc 79	85	Digital Pathways 137	193	Micropolis 228, 229	8	RITAM International Corp 18
114	Anderson Jacobson 176	243	Digital Research: Computers 265	231	Micro Products Unlimited 262	204	RNB Enterprises 236
79	Andicom Technical Products 127	84	Digital Research Corp (CA) 136	52	Micro Pro International 88, 89	74	Robotics Age 119
125	Apparat 187	42	Digital Technology Inc 77	288	Microsette 199	167	S-100, Inc 215
4	Apple Insert	12	Digitus 25	220	Microsette 258	101	Howard W. Sams Company 159
195	Appled Computer Systems 229	165	Disc/3 Mart Inc 214	69	Microsoft 109	121	Sara Tech 185
266	Aristo/Polks 272	169	Dr Dobb's Journal 216	21	Microtek 47	159	SCDP 211
138	Artex Electronics 194	123	Dynacomp 186	184	MICROWARE 223	98	Scelbi 154, 155
152	Artex Electronics 203	212	Dynamic Microprocessor Assoc. 241	188	Microware Associates 225	71	Scientific American 113
270	ASAP Computer Products 273	229	Eaton LRC 26, 29	102	The Micro Works 160	58	SciTronics 94
4	Atari 13	272	Electrolabs 261	140	Micro World 166	32	Seattle Computer Products 69
217	ATV Research 258	60	Electronic Control Technology 96	241	Midwest Computer Peripherals 195	99	Seattle Computer Products 235
92	Automated Simulations 145	276	Electronic Systems 282, 283	131	Mini Computer Suppliers 190	99	Shugart 6, 7
17	Avionic Enterprises (A.E.I.) 219	224	Electronic Technicians 258	117	Mini Micro Mart Inc 181	187	Sigma International 224
13	AXIOM Corp 27	171	Escon 217	155	Mini Micro Mart Inc 206	282	Sirius Systems 78
250	B & W Energy Management Sys 268	177	Essex Publishing 220	25	Morrow/Thinker Toys 55	108	Small Business
203	Balantline Books 235	118	Exidy 182, 183	70	Mountain Hardware 207	108	Applications 169
295	BASF 175	249	Faragher & Assoc 268	157	Mountain Hardware 207	194	Ed Smith's Software Works 229
271	Becklan 273	206	Farnsworth Computer 239	324	Multi Business Computer Sys 258	7	Smoke Signal Broadcasting 53
223	John Bell 258	252	Faith Software 268	144	National Artificial Intelligence Lab (NAI) 197	24	Smoke Signal Broadcasting (Dealers) 53
146	Biotech Electronics 198	62	Financial Planning Associates 98	226	NCE/CompuMart 259	50	Softage Inc 86
156	Bishop Graphics 207	183	Fly Stones Software 223	77	NEECO 115, 124, 125	192	Softage 227
107	BIZCOMP 169, 268	227	Fordham Radio Supply 260	86	Netronics 138	120	Softech 185
75	The Bottom Shelf 121	233	Frederick Computer Products 262	283	Netronics 179	89	The Software Exchange 141
113	BYTE Books 59	30	Freeland Intl Computer Shows 65	284	Netronics 179	230	The Software Farm 262
213	BYTE Seminar 243	237	Fuller Software 262	261	New England Recruiters 272	54	The Soft Warehouse 90
87	Byte Shop East 139	137	Futureworld 193	14	North Star 31	242	Solid State Sales 264
*	BYTE Subscriber 239	260	Glmix 272	232	Northwest Computer Services 262	262	Sorrento Valley Associates 272
134	C & S Electronics Mart 192	173	Global Parameters 218	110	Novation 172	279	Southwest Tech Prod Corp CII
5	California Computer Systems 14, 15	90	Godbout Electronics 143	*	NRI Schools 161	3	SSM 11
221	California Data Corp 258	158	GR Electronics 208	281	Ohio Scientific Instrument CIV	205	The Stackworks 237
274	California Digital 279	97	H & E Computronics 153	67	OK Machine and Tool 105	104	Strategic Simulations, Inc. 165
207	California Software 239	17	Hamilton/Avnet 39	129	OK Machine & Tool 189	91	SubLOGIC 144
139	Cambridge Development Labs 195	88	Hardside 140	268	The Old Association 272	258	Sunny International 270
263	CAP Electronics 272	257	Hobby World 270	55	Olivetti 91	94	Supersoft 149
81	Central Data 133	292	Houston Instruments 51	*	onComputing 33	*	Supersoft 209
265	Chaffitz, Inc 272	293	Houston Instrument 51	*	Onyx Sys., Inc. 42, 43	41	Sybox 75
112	Chrislin Industries 174	11	Industrial Micro Systems 23	211	Optimal Technology 241	65	Sybox 100
116	Chrislin Industries 180	61	Infosoftware Systems Inc 97	66	Oregon Software 103	49	Synchro Sound 85
256	Cleveland Consumer Computer & Components 269	26	Intecolor 57	109	Osborne/McGraw-Hill 171	46	Tab Books 81
64	Compas Micro Systems 100	179	Integrand 221	*	Owens Associates 213	76	Tarbell Electronics 123
9	CompuCorp Corp 19	160	International Data Sciences 211	43	Face Inc 78	51	Tech Sys Consultants (TSC) 87
29	CompuServe (microNET) 63	83	International Data Systems (IDS) 135	286	Pacific Exchanges 199	10	Tec-Mar 158
240	Computer City 263	28	Interfac Data Systems 61	326	Page Digital 278	16	Televideo 21
251	Computer and Control Affiliates 268	2	Ithaca Intersystems 9	166	PAIA 214	235	Theta Labs Inc 262
*	The Computer Factory (NY) 170	16	Ithaca Intersystems 36	180	Pan American Elec (A Radio Shack Auth. Sales Ctr.) 221	189	3 G Company Inc 225
142	Computer Furniture & Accessories 196	273	Jade Company 276, 277	31	Per Com Data 67	*	Robert Tinney Graphics CVIII
*	Computer Hardware 200	275	Jameco 280, 281	33	Per Com Data 71	126	TransNet 188
47	Computer Mart of NJ 82	150	JRT Systems Inc 201	33	Per Com Data 72	*	United Software of America 76
210	Computer Service Center 240	6	Konan Corp 16	34	Per Com Data 72	20	Universal Data Systems 45
238	Computer Shopper 262	*	Lifboat Associates 101, 134, 189	35	Per Com Data 72	185	US Robotics 223
161	Computer Specialties 211	93	Macrotronics 146	36	Per Com Data 72	222	Vantage Data Products 258
172	Computer Transceiver Sys (CTS) 217	182	Macrotronics 222	37	Per Com Data 73	148	Vector Electronic Co 200
201	Computers Wholesale 235	*	McGraw-Hill Book Company 128, 129	38	Per Com Data 73	115	Vertec 178
163	Computer World 213	39	Measurement Sys & Controls 41	39	Per Com Data 73	299	Vista Computer Company 286
153	Computex 204	59	Measurement Sys & Controls 199	40	Per Com Data 73	245	VR Data 266
199	Corporate Computer Systems Inc 233	253	Metaresearch 268	57	Personal Software 93	228	Wameco 260
56	Corvus Systems 92	190	MICAH 227	59	Personal Software 95	111	Western I/O 173
122	Cover Craft 185	15	Micro Age Computer Stores 35	143	Pickles & Trout 197	*	Whitesmith's Ltd 151
128	CP Products 189	72	Microamerica Dist 115, 124, 125	178	Pickles & Trout 221	100	John Wiley & Sons, Inc 173
1	Cromemco 1, 2	162	Micro Applications Group 213	248	Potter's Programs 268	214	John Wiley & Sons, Inc. 244
119	CT microCOMPUTER, Inc 184	219	Micro Architect 258	45	Power One 80	236	Wintek 262
135	CT microCOMPUTER, Inc 192	278	Micro Business World 254	215	Priority One 255	208	Worldwide Electronics 240
174	Cybernetics Inc 219	124	Microcomputer Technology Inc 187	216	Priority One 256, 257	168	Z _s Systems 215
234	DAR Sales 262	22	MicroDaSys 49	191	The Q Kit (Div J R Conwell) 227		
136	DataArt, Inc 193	63	Micro Data Base Systems Inc 99	198	Quality Software 233		

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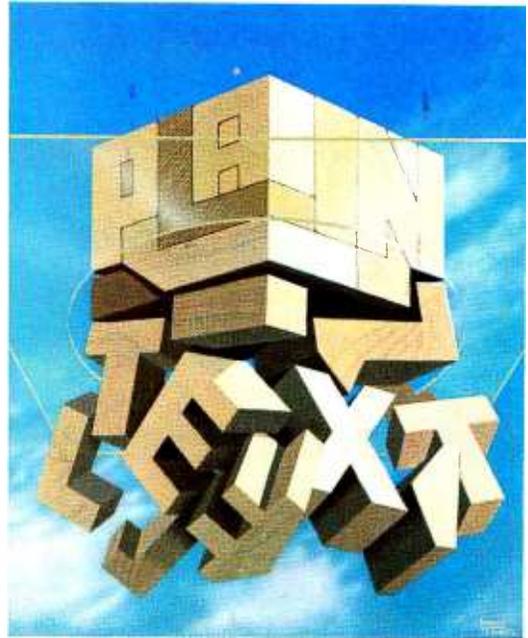
Article #	Page	Article	Author
1	17	Ease into 16-Bit Computing: Get 16-Bit Performance from an 8-Bit Computer	Ciarcia
2	34	Electron Behavior in a Chemical Bond	Liebl
3	60	Hewlett-Packard's New Personal Computer, The HP-85	Morgan
4	74	Solving Problems Involving Variable Terrain, Part 2: Special Cases, Including Hexagonal Grids	Jones
5	84	TRS-80 Performance, Evaluation by Program Timing	Lewis
6	114	Electronic Planimetry	Santil, et al
7	126	A Power-Line Protection Circuit	Schneider, Erickson
8	130	Landing Module Simulation with Random Surface	Houng
9	142	The Dirt-Cheap Bootstrap, More Notes on Bringing Up a Microcomputer	Woodhull
10	156	Hydrocarbon Molecule Constructor	Matthews
11	194	Operation Codes for 8080, 8085, and Z80 Processors	Harrell
12	230	To Err Is Human	McGregor
13	232	Super TIC	Roehrig

December BOMB Numerical Analysis

"Add Nonvolatile Memory to Your Computer" by Steve Ciarcia (page 36) proved to be the most popular among those readers who voted. Second place in the BOMB voting went to James L Peterson for "Text Compression" (page 106). These two authors receive the \$100 first-place and \$50 second-place prizes. Third place was shared by F R Ruckdeschel ("Frequency Analysis of Data Using a Microcomputer," page 10) and Christopher O Kern ("A User's Look at Tiny-C," page 196). ■



BREAKING THE SOUND BARRIER



THE TRAP DOOR

September 1977

March 1979

Byte Cover Prints -- Limited Editions.

The September '77 and March '79 covers of BYTE are now each available as a limited edition art print, personally signed and numbered by the artist, Robert Tinney.

These prints are strictly limited to a quantity of 750 for each cover, and no other editions, of any size, will ever be published. Each print is 18" x 22", printed on quality, coated stock, and signed and numbered in pencil at bottom.

The price of each print is \$25. This includes 1) a signed and numbered print; 2) a Certificate of Authenticity, also signed personally by the artist and witnessed, attesting to the number of the edition (750), and the destruction of the printing plates; and 3) first class shipment in a heavy-duty mailing tube.

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Business Applications

The C8P DF utilizes full size 8" floppy disks and is compatible with Ohio Scientific's advanced small business operating system, OS-65U and two types of information management systems, OS-MDMS and OS-DMS.

The computer system comes standard with a high-speed printer interface and a modem interface. It features a full 53-key ASCII keyboard as well as 2048 character display with upper and lower case for business and word processing applications.

Home Control

The C8P DF has the most advanced home monitoring and control capabilities ever offered in a computer system. It incorporates a real time clock and a unique FOREGROUND/BACKGROUND operating system which allows the computer to function with normal BASIC programs at the same time it is monitoring external devices. The C8P DF comes standard with an AC remote control interface which allows it to control a wide range of AC appliances and lights remotely without wiring and an interface for home security systems which monitors fire, intrusion, car theft, water levels and freezer temperature, all without messy wiring. In addition, the C8P DF can accept Ohio Scientific's Votrax voice I/O board and/or Ohio Scientific's new universal telephone interface (UTI). The telephone interface connects the computer to any touch-tone or rotary dial telephone line. The computer system is able to answer calls, initiate calls and communicate via touch-tone signals, voice output or 300 baud modem signals. It can accept and decode touch-tone signals, 300 baud modem signals and record incoming voice messages. These features collectively give the C8P DF capabilities to monitor and control home functions with almost human-like capabilities.

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The C8P DF incorporates a real time clock, FOREGROUND/BACKGROUND operation and 16 parallel I/O lines. Additionally a universal

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Computers come with keyboards and floppies where specified. Other equipment shown is optional.

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