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B. You wouldn’t like me to set it to music I suppose?

O.J. Not — likely, ’cos I should get all the checking to do.

B. Go on then.

O.J. Tell ’em it’s gorgeous, ’andsome, smart. Tell ’em it’s fab! Tell ’em they ’aven’t lived until they’ve read it!

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THE UNIT TO BE DESCRIBED PROVIDES A SIMPLE, compact, and relatively cheap method of converting any sine wave voltage between wide amplitude and frequency limits into a square waveform having an extremely fast rise time and variable amplitude output. This useful piece of apparatus may be made as a separate unit or built into an existing sine wave audio signal generator, both methods of construction being described. The unit uses six transistors, and all the components are easily obtainable, no close tolerance or special types being required.

To anyone engaged in serious amplifier work, whether audio or wide band, this device should prove most useful as the extremely square waveform obtained, together with the very fast rise time, quickly shows up any design faults such as incorrect or badly adjusted h.f. or l.f. compensation, etc. The writer has found it indispensable in checking and correctly setting up the amplifiers and attenuators of oscilloscope circuits, particularly the compensation networks in d.c. coupled wide band amplifiers. On the other hand it has also been employed to show that certain “hi-fi” amplifiers were not quite so good as was at first imagined. Some of the uses to which the unit may be put will be discussed later.

Specification
The specification of the converter, the circuit of which is shown in Fig. 1, may be summarised as follows:

Input: any sine wave or near sine wave voltage between 0.5 and 50 volts r.m.s. at any frequency between 20 c/s and 75 kc/s.

Output: square wave with mark-space ratio of 1:1, amplitude variable between 0 and 12 volts peak-to-peak and rise time less than 0.5 μS. These output figures hold good for all frequencies between 20 c/s and 75 kc/s.

Current consumption from the 12 volt supply is 14mA.

Though an upper frequency limit of 75 kc/s is quoted, the actual upper limit is somewhat dependent upon the frequency-gain characteristics of the front-end transistors. By using transistors with a better frequency-gain characteristic, the writer has had the unit working satisfactorily up to 110 kc/s. If an upper frequency limit of 20–25 kc/s would be satisfactory, the three front-end transistors TR1, 2, 3, (OC202, OC200, OC200) can be replaced by three OC71 type transistors without any other circuit changes being necessary. As OC71’s are much cheaper, this reduces the cost of the converter although, as just stated, it also reduces the maximum

Fig. 1. The circuit of the converter
frequency limit to about 20 to 25 kc/s. If it is intended to work only on audio equipment, such a range should be quite satisfactory.

Operation
The action of the converter is relatively straightforward. Referring to Fig. 1, the circuit may be regarded as being composed of four sections: D1, TR1, TR2 and TR3, squarer and amplifier; C2 and R6, differentiating and trigger circuit; TR4 and TR5, bi-stable multivibrator circuit; and TR6, emitter follower output.

The sine wave input is applied to the base of TR1 via the limiting resistor R1, the positive and negative peaks being clipped off this waveform by diode D1 and the base-emitter diode of TR1. The base of TR1 is biased by means of R2 to ensure that this clipping action is symmetrical, so that a 1:1 mark-space ratio is obtained. The capacitor C1 provides d.c. isolation between the sine wave source and TR1. An amplified version of this clipped waveform is developed across the load resistor R3, this being applied to the cascaded amplifier pair TR2 and TR3. The advantage of using a pair of transistors in this type of cascade connection is that an extremely high overall gain is achieved, the signal swing developed across the output load resistor R5 being between the fully cut off and fully bottomed positions, i.e. a signal swing of almost the full 12 volts. This circuit is for all practical purposes independent of transistor gain characteristics and transistor tolerance spreads.

Components List (Fig. 1)

Resistors
(All fixed resistors 10% 1 watt)
R1 10kΩ
R2 1MΩ
R3 220kΩ
R4 3.3kΩ
R5 2.2kΩ
R6 100kΩ
R7 2.2kΩ
R8, 9 33kΩ
R10 2.2kΩ
R11 1kΩ
VR1 1kΩ potentiometer, linear

Capacitors
C1 0.01μF paper, 150V wkg.
C2 0.002μF paper, 150V wkg.
C3 0.1μF paper, 150V wkg.
C4 0.002μF paper, 150V wkg.

Transistors
TR1 OC202 or OC71 (see text)
TR2, 3 OC200 or OC71 (see text)
TR4, 5 OC44
TR6 OC200

Diode
D1 OA81

Miscellaneous
1 toggle switch (s.p.s.t.)
2 coaxial sockets
2 O-Z sockets and plugs (Belling-Lee)
1 pointer knob

Fig. 2. The waveforms appearing at the various stages in the converter

R4 is a limiting resistor to prevent the possibility of damage to TR2 and, as far as circuit function is concerned, can be ignored. The output from TR3 is, therefore, a 12 volt peak-to-peak square wave having quite a sharp rise time.

It may be mentioned at this point that only the first stage is in any way critical, though even here a fair degree of tolerance is permissible. This is because the correct bias setting on this stage does ensure an exact 1:1 mark-space ratio. Should the base of TR1 be over or under biased, non-symmetrical clipping takes place, resulting in a non-symmetrical output. If an oscilloscope is available, the mark-space ratio can be checked and R2 adjusted if necessary. However, no adjustment should be required if TR1 has average gain characteristics. For most practical purposes an exact 1:1 mark space ratio is not in any case entirely necessary, so that no setting up procedure should generally be necessary. Typical waveforms throughout the circuit are shown in Fig. 2.

The output at the collector of TR3 is applied to the differentiating network C2, R6. This changes the positive and negative-going edges of the square wave.
wave into a series of sharp positive and negative-going spikes. The time constant of this circuit was carefully chosen to ensure that with low frequencies the spike was not so sharp that it failed to trigger the following circuit and that, with high frequencies, the spike was not so slow that the trigger point was uncertain, thus resulting in an erratic output. A compromise between these two extremes was therefore chosen.

The output spike from the differentiating circuit is applied to the base of TR4 in the bi-stable circuit. The coupling capacitor C3 provides d.c. isolation between the two circuits and has negligible effect on the differentiated waveform, its reactance being very much larger than the reactance of C2.

TR4 and TR5 comprise the bi-stable multivibrator circuit, i.e. a circuit which has two stable conditions. If TR5 is cut off TR4 will be bottomed. Under these conditions a positive-going spike applied to TR4 base will switch the circuit to its other stable condition, with TR5 on and TR4 off. The application of a negative-going spike to TR4 base will then cause the circuit to revert to its original condition, with TR4 on and TR5 off. These transistors are, therefore, alternately driven between fully cut off and fully bottomed at a rate dependent upon the time duration between the alternate positive and negative-going spikes from C3. When the spikes are originally derived from a sine wave, as in this instance, it follows that the bi-stable circuit will be switched between its on and off positions at the same frequency as the sine wave. Also, if the spikes derived from this sine wave are of 1:1 mark-space ratio, the bi-stable circuit (assuming that it has symmetrical components, as shown) will similarly have a 1:1 mark-space ratio. Thus, the output obtainable at either TR4 or TR5 collector is a square wave. Also, since the bi-stable circuit is d.c. coupled by means of R8 and R9, the rise time of this square wave will be extremely fast, since it approaches the switching time of the transistors themselves. Compensating capacitors C4 and C5 help to speed up this switching time. As TR4 and TR5 are switched or driven between their extreme conditions, they may simply be regarded as switches with a very rapid change-over mechanism, and not as amplifiers.
in the normal acceptance of the word.

The principal advantage of this circuit is that the output is completely independent of the input, and the rise time and amplitude of the output waveform will remain constant regardless of the input amplitude or frequency within the very wide limits quoted. Another advantage of the circuit is that it is independent of changes or spread in transistor characteristics, as the transistors are not used as conventional amplifiers but as switches.

The final section of the circuit, TR₆, is an emitter follower d.c. coupled to the bi-stable output via the limiting resistor R₁₁. A variable resistor VR₁, in the emitter circuit of this stage, allows the output amplitude to be varied between zero and almost 12 volts. The advantage of the emitter follower circuit is twofold: it gives isolation between the bi-stable circuit and the output, the loading effect being negligible, and a low impedance output is obtained. In consequence, the output can be loaded to quite a considerable extent before any noticeable damping effects occur. The output impedance of this circuit is in the order of 75Ω, thus matching standard coaxial cable. By using d.c. coupling in the final stage the rise time and squareness of the waveform is maintained.

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**Fig. 4 (a). The layout of components on the Paxolin board**

(b). Side view, showing the assembly with the transistors wired into position
Actual waveforms illustrating the performance of the converter. In each instance the sine wave is shown above the corresponding square wave output. The top pair of waveforms illustrates operation at 1 kc/s, the centre pair operation at 10 kc/s and the lower pair operation at 25 kc/s.

Construction

The construction of the unit offers no difficulties and no special layout is required. The method followed by the writer is described here, though any other forms of construction which are more suitable to the needs of the individual user or which fit in with existing test arrangements may be adopted instead. It should be mentioned, however, that one of the benefits of the unit is that it can be constructed in an extremely compact form. Any type of construction which occupies a large amount of space is obviously not taking full advantage of this point. In the writer's unit coaxial sockets are used for both input and output. The 12 volt battery supply was external to the unit.

The construction and layout of the converter are shown in Figs. 3 and 4 together with relevant dimensions. The transistors and other components are mounted between turret tags set in a Paxolin base board. This is fixed to the aluminium chassis or frame by means of impact adhesive, a thin wafer of similar insulating material being fixed with the same adhesive between the bottom of the base board and the aluminium. This method of assembly obviates the possibility of the tags short-circuiting on the aluminium. As is shown in Fig. 4, an extremely compact form of construction is achieved.

After the tags have been mounted on the board, the interconnecting wires are first connected in, next the resistors and capacitors, and finally the transistors. These are mounted by their leads in an upright position, a piece of sleeving over the leads preventing any accidental short-circuits. When soldering the transistors in place it is advisable to use a heat sink, particularly with the OC44's and OC71's, if used, as these are germanium types. The silicon types are not so susceptible to heat.

The frame, or chassis, is simply a piece of 18 s.w.g. aluminium bent into the shape shown, the necessary holes being drilled before bending. Two rods of metal or fibre are used as strengtheners between the two upper corners of the chassis, these being cut to length and the ends drilled and tapped 6BA for fixing. Finally a small wood or aluminium cover can be made if desired, though this is a matter of choice.

The method of construction just described is for use when the converter is to be employed as an individual unit. It can, alternatively, be easily fitted into an existing sine wave audio generator, thus converting the latter into a sine wave-square wave generator. Here the circuit is wired up on the board as shown in Fig. 4 but, instead of fitting it into an aluminium frame, it is fitted into any convenient space inside the sine wave generator. As the unit

Fig. 5. Installing the converter into an existing sine wave generator
in this form only occupies a space of $4 \times 2.5 \times 1.4$ in, no difficulty should be found fitting it in. The unit is then connected up as illustrated in Fig. 5, extra holes having to be drilled for one output coaxial socket, two Belling-Lee O-Z sockets (for the 12 volt supply), potentiometer VR₁, and a d.p.s.t. toggle switch. These holes can be drilled in the front panel or, if insufficient panel space is available, the O-Z sockets can be mounted with the toggle switch at the rear of the generator.

Checking

Before connecting any supplies to the converter, the wiring should be carefully checked, paying particular attention to see that the diode and transistors are connected correctly. To check the waveform for rise time and mark-space ratio an oscilloscope is required.

To test the converter, connect a sine wave supply to the input (a 6.3 volt 50 c/s heater supply being quite adequate), set VR₁ to its maximum output position, and switch on the 12 volt d.c. supply. The output is taken to the Y₁ input on the oscilloscope, which should be set to a sensitivity of about 3 volts/cm with a sweep speed of about 10 ms/cm. If the c.r.o. has a d.c. coupled amplifier the waveform should appear as in Fig. 6 (a). An a.c. coupled c.r.o. amplifier will give a waveform like that shown in Fig. 6 (b), the slope being due to the l.f. response of the amplifier. The mark-space ratio should be 1:1 and, as previously stated, a slight adjustment in the value of R₂ will correct any error here though this should not generally be necessary. If it is required to check the rise time a sweep speed of at least 2 μS/cm is required, rise time being measured as shown in Fig. 6 (c). Lastly, check the amplitude of the square wave and ensure that it falls linearly as VR₁ is reduced from maximum to minimum.

Practical Applications

Finally, a few points will be mentioned on some practical applications of the converter. The first and obvious use to which the unit can be put is in the testing of high quality a.f. amplifiers. The test circuit can be set up as shown in Fig. 7, 1 kc/s being the usual standard frequency used. Fig. 8 shows some of the common waveforms likely to be met, as compared with the ideal waveshape. VR₁ should be adjusted so as to avoid overloading the amplifier under test and the waveforms checked through the amplifier a stage at a time. Faulty compensation networks will be immediately apparent and adjustments can be made to obtain optimum square wave response. The frequency of the test supply can then be reduced to a low value, say 30 c/s, and then up to say 5 or 10 kc/s, the output

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Fig. 6. Testing the converter with a 50 c/s input. The square wave which should be displayed by a d.c. coupled oscilloscope amplifier is shown in (a), whilst (b) illustrates a typical response if the amplifier is a.c. coupled. The rise time of the waveform may be checked as shown in (c).
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Fig. 7. Checking the response of an amplifier
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Fig. 8 (a). An ideal output waveform from the amplifier under test
(b). A good practical response
(c). A response indicating poor low frequency response
(d). The result of poor high frequency response
(e). High frequency peaking resulting in parasitic oscillation
(f). The effect given by inductive bass boost with high frequency fall-off
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Fig. 9. One section of a typical simple c.r.o. attenuator.

waveshapes being checked at each frequency. This is an excellent method of checking the effectiveness (or lack of effectiveness) of bass and treble tone circuits. It will be found with experience that amplifiers which had previously been known to have quite a good response to a sine wave signal have a completely different response to a square wave. In the opinion of the writer this is the only method of finding the true response characteristic of a quality amplifier and for the correct assessment of the efficiency of compensation and tone control networks.

The testing of wide band oscilloscope amplifiers is carried out in a similar manner except that the

frequency range is extended. As most amplifiers of this type have a compensated attenuator at the front end this can in many cases be disconnected from the amplifier and set up separately. The trimming capacitors on the attenuator (see Fig. 9) are set to give minimum overshoot without undershoot at the highest square wave frequency available. Overshoot and undershoot are shown in Fig. 10. For the correct alignment of wide band oscilloscope amplifiers a square wave source of relatively high frequency with a fast rise time is essential.

The above is but a brief mention of a few of the basic uses to which a good square wave source can be put, and the writer has found the converter described in this article of considerable help in a number of practical applications, particularly in experimental pulse circuits.

CAN ANYONE HELP?

Requests for information are inserted in this feature free of charge, subject to space being available. Users of this service undertake to acknowledge all letters, etc., received and to reimburse all reasonable expenses incurred by correspondents. Circuits, manuals, service sheets, etc., lent by readers must be returned in good condition within a reasonable period of time.

Ace Model TR62.—A. Currie, c/o Hunter, 3c Sunnyside, Saint Nintang, Stirling, Scotland—circuit of this transistor radio.

* * *

CRT 3FP7.—B. P. Bradley, 63 The Lowe, Chigwell, Essex—pin connections of this American tube.

* * *

62H Receiver Unit AP61357.—W. E. Newman, 108 The Drive, Hounslow, Middx.—any information (all will be returned).

* * *

Peto Scott Receiver Type HE72.—C. Taylor, 73 Wellington Street, Matlock, Derbyshire—service sheet or manual on loan.

* * *

Control Unit 704, Indicator Type 230.—A. A. Stuttard, "Burwood", Lostock, Bolton, Lancs.—any information and circuits. The latter unit contains Wavemeter W1646.

Oscilloscope No. 11.—R. Yates, 36 Milkingstile Lane, Lancaster—circuit and any information for extending the timebase of this unit (AA Predictor Mk. I OS 18799A).

* * *

Hallicrafter 5-10 Receiver.—Simmons, 19 Gt. Bounds Drive, Southborough, Tunbridge Wells, Kent—circuit, loan or purchase.

* * *

R220 Receiver Mk. II.—J. Anderson, 6 Arley Close, Macclesfield, Cheshire—circuit, technical manual or details of conversion for variable tuning. Material on loan will be photo-copied and returned.

* * *

Transmitter Type LMR61.—P. Debono, Mt. Sinai House, New Str., St. Catherine Str., Zejtun, Malta G.C.—any information on this and the following units, receiver type IMR60M; transmitter type T10A; transmitter type LMR83, D.F. type LMR72 and units type AL/27; E7AA; AKU; R19 I/P27A/S B85/1.
A technique commonly employed to improve the efficiency of amateur phone transmitters is provided by speech clipping. A speech clipping circuit is included in the modulation amplifier, and it clips the speech signals at a level which corresponds to 100% modulation. If the circuit is correctly set up, it then becomes impossible to overmodulate the transmitter regardless of the sound intensity at the microphone input.

A second, and more useful, advantage conferred by speech clipping is that it allows a higher average level of a.f. power to modulate the transmitter, with a consequent increase in sideband power. Quite high levels of clipping, up to some 20dB, are feasible before loss of intelligibility becomes significant. As is to be expected, the distortion resulting from such heavy clipping impairs the naturalness of the speech. Lower levels of clipping cause less distortion, and still enable a worthwhile increase in sideband power to be achieved.

Since the audio signals clipped take up what is very nearly a square wave form, the process results in the production of a large number of high frequency harmonics, and these have to be suppressed before modulation takes place. Such suppression may be achieved by a low pass filter following the clipping circuit, this allowing a band of frequencies up to about 3 kc/s only to be passed on to subsequent stages.

Symmetrical Clipping

There are several ways in which speech clipping can be achieved, and a particularly popular method amongst amateur transmitter enthusiasts makes use of a symmetrical clipping technique. The symmetrical clipper limits both positive and negative excursions of the a.f. signal (as opposed to the asymmetrical clipper, which clips only on peaks of one polarity), and it is interposed between two stages in the modulation amplifier. Symmetrical clipping is provided, typically, by two diodes, each having a fixed voltage delay. In a series clipping circuit the diodes become non-conductive for signal voltages above the delay voltage, whilst in a shunt clipping circuit the diodes become conductive when the signal voltage reaches the delay voltage. Clipping level in circuits of this nature is usually of the order of 3 to 5 volts peak-to-peak.

These clipping circuits are quite simple, but they can be made simpler still by taking advantage of the characteristics of the zener diode. Two suggested methods in which a zener diode may be employed for symmetrical shunt clipping will now be discussed, and they form the basis of this article.

Fig. 1 shows a clipping circuit comprising two zener diodes, these appearing between two stages of a modulation a.f. amplifier. In the absence of signal the voltage across the diodes with respect to chassis is zero, due to the presence of potentiometer R2.

Let us now see what happens during a half-cycle of signal voltage which causes the anode of V1 to go positive. This positive anode excursion then appears (slightly reduced in amplitude because of the potential divider R1(R2) across the diodes. However, the diodes have no effect on circuit operation until the positive voltage of the "cathode" of D1 reaches the zener voltage for this diode. D1 then assumes the low slope resistance characteristic of a zener diode, whilst D2 conducts in the same way as does an ordinary diode. The combination of D1 functioning as a zener diode and D2 as an ordinary diode limits any further positive excursion on the "cathode" of D1. Increased positive excursions at the anode of V1 merely become dropped across R1.

Negative excursions on the anode of V1 have the same effect, except that limiting occurs when the zener voltage of D2 is reached. D2 then functions as a zener diode whilst D1...
functions as an ordinary diode.

Summing up, it may be seen that the a.f. signal is limited in the positive direction by the zener voltage of D1 and in the negative direction by the zener voltage of D2. If both diodes have the same zener voltage, symmetrical clipping takes place.

An interesting point is that there is no necessity for a d.c. blocking capacitor between the diodes and R2, because the grid input signal at the upper end of R2 swings positive and negative of chassis in just the same way as would occur if the diodes were not in circuit.

In the explanation just given it was stated that the diodes conducted as soon as the zener voltage of one diode was reached, the other then functioning as an ordinary diode. This does not give a complete picture of circuit operation, however, because the assumption is made that the second diode commences to conduct at virtually zero forward voltage. In practice, silicon diodes of the type employed for zener operation normally become conductive at forward voltages of the order of 0.6. So, the limiting voltage across the diodes is given by the zener voltage of the one which functions as a zener diode plus the forward voltage required for conduction in the other.

Limiting Levels

Limiting levels at around 9 volts peak-to-peak can be achieved with the circuit of Fig. 1 using readily available zener diodes. The OA220, for instance, offers a typical zener voltage of 3.9 at 0.1mA, with a tolerance ranging from 3.6 to 4.2 volts at this current. If the 0.6 volts required for forward conduction is added, two OA220's would clip for either polarity at, typically, some 4.5 volts. A swing of 4.5 volts positive and negative of chassis will, normally, be too large for the valve employed in the V2 position, and it is reduced by the pre-set potentiometer R2. This potentiometer may then be the control which sets clipping level to correspond with 100% modulation.

If, assuming OA220's are used, one of the two diodes is on bottom tolerance, with a zener voltage of 3.6, and the other is on top tolerance, at 4.2 zener volts, excursions in one direction will be clipped at about 4.2 volts (3.6 + 0.6) and in the other direction at about 4.8 volts (4.2 + 0.6). The resultant lack of symmetry, which corresponds to the worst combination of OA220's, should not have any serious consequences in practice.

The "hardness" of clipping (i.e., the speed of transition in the diodes from the non-conductive condition to the low-resistance condition as voltage increases) which is given by the circuit of Fig. 1 will be about half that given by a normal shunt clipping circuit using semiconductor diodes, and should be adequate for all normal purposes. The "hardness" of clipping can be increased, if desired, by reducing the value of R1, so that the forward-plus-zener current in the diodes is increased when clipping occurs and, if necessary, arranging the V1 stage so that the necessary increased signal current is provided.

Single Diode Circuit

A circuit employing a single zener diode is shown in Fig. 2. In this diagram the "cathode" of the zener diode is returned to a point in the cathode bias resistor circuit of V2 which offers half the zener voltage above chassis. The resistors employed in the cathode circuit of V2 will have low values compared with R1, and the voltage provided at the junction of R3 and R4 can be considered, for the purposes of the circuit, as being fixed.

In the absence of signal from V1, the upper electrode of the zener diode is held negative of the diode "cathode" by R3, R5 and R4. Since the voltage across the diode is half the zener voltage it does not then conduct in either mode.

Let us now apply a signal; and we shall assume for the moment that the diode conducts as an ordinary diode at zero forward voltage. When the signal voltage on the upper electrode of the diode goes positive of chassis by half the zener voltage, the diode commences to conduct as an ordinary diode. This is because its "cathode" is similarly positive of chassis by the same potential. When the signal applied to the diode goes negative of chassis by half the zener voltage, the diode commences to conduct as a zener diode. This is because its "cathode" is half the zener voltage positive of chassis, whereupon the whole zener voltage becomes applied across the diode. Thus, the signal is clipped, in either direction, by half the zener voltage, and the peak-to-peak amplitude is the zener voltage itself.

We have, however, ignored the
forward voltage needed to cause the diode to conduct. When this forward voltage is taken into consideration we then find that the peak-to-peak clipped amplitude increases to the zener voltage plus the forward voltage. Also, to achieve symmetrical clipping the voltage at the junction of R3 and R4 has to be changed so that it becomes half the zener voltage less half the forward voltage. This is shown in Fig. 3 as 0.5VZ — 0.5VF, where VZ is the zener voltage and VF is the forward voltage. On positive signal excursions, the zener diode of Fig. 3 will conduct at (0.5VZ — 0.5VF) + VF = 0.5(VZ + VF). On negative signal excursions the zener diode will conduct at (0.5VZ — 0.5VF) — VZ = —0.5(VZ + VF). Thus, symmetry is achieved.

The single diode circuit enables a low peak-to-peak clipped amplitude to be obtained. With the OAZ200, for instance, the peak-to-peak amplitude can be of the order of 4.5 volts. If desired, and if a suitable valve is employed in the V2 position, this signal could be fed direct to the grid of V2, as in Fig. 4, whereupon the clipper level control can be placed at a later point in the amplifier chain.

To find the values needed in R3 and R4 to give 0.5VZ — 0.5VF at their junction, it will be necessary to find VZ and VF at a current of around 0.1mA for the particular zener diode employed. However, little serious error should be introduced with, say, a 5% zener diode if it is assumed that V2 is the typical zener voltage at about 0.1mA quoted in the manufacturer's literature, and VF is 0.6 volts. An alternative approach would consist of temporarily fitting a potentiometer in the R3R4 position, connecting its slider to the diode and adjusting this until symmetrical clipping is given, as shown by an oscilloscope. The potentiometer could then be replaced by fixed resistors of the appropriate value.

It is, of course, necessary for the cathode voltage of V2 to be greater than 0.5VZ — 0.5VF, but this requirement may be readily met when low voltage zener diodes such as the OAZ200 are used.

The “hardness” of clipping offered by the single diode circuit will be of the same order as a normal shunt circuit using semiconductor diodes. As with the circuit of Fig. 1, the “hardness” of clipping may be increased by reducing the value of R1 and, if necessary, arranging the V1 stage to offer the increased signal current required.

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**Club Events**

**Northern Heights Amateur Radio Society**  
Hon. Sec. A. Robinson, G3MDW, Candy Cabin, Ogden, Halifax.  
- October 13th—Setting up Scout Jamboree Station.  
- October 16th—Scout Jamboree on the air (also 17th).  
- October 27th—Visit to Baird Television Works, Bradford.  
- October 30th—Visit to the International Radio Communications Exhibition, (London).

**Derby and District Amateur Radio Society**  
Hon. Sec. F. C. Ward, 5 Uplands Avenue, Littleover, Derby.  
- October 3rd—Contest for President's D.F. Trophy.

**The Slade Radio Society**  
Hon. Sec. D. Wilson, 177 Dower Road, Sutton Coldfield.  
- October 2nd—Television Spectacular '65.  
- October 9th—Double Midnight D.F. Test.  
- October 23rd—Annual Dinner, Market Hotel.

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**Electronic Counting with Dekatrons**

We regret that Part 2 of this series has been held over until the next issue.
A Quality Multimeter

By W. KEMP

Part Two

In this concluding article our contributor discusses overload protection devices, then carries on to the complete circuit of the 30-range testmeter.

Overload Protection

Some kind of automatic overload protection is almost essential on any general purpose meter, as the inadvertent use of the instrument on too low a range can result in severe damage to the basic movement. While it is true that most meters can withstand a considerable overload (as much as 100 times f.s.d. with some of the better quality types), there is no doubt that, even if the overload may cause no great harm, it most certainly won't do the meter any good!

Several methods of obtaining overload protection are available, each with its own particular advantages and applications. A few of these will now be described.

Germanium Diode Protection

Fig. 11 shows a simple overload protection device that has applications in a number of special circuits where linearity of meter readings is not essential. As can be seen, the circuit consists simply of the meter and a resistor, $R_1$, in series, with a germanium diode wired across the combination in the forward direction. The diode is a non-linear device, the forward resistance of which varies with applied voltage. At very low voltages, in the order of millivolts, the forward resistance may be some hundreds of kilohms; at higher voltages, of perhaps half a volt, the forward resistance may fall to several hundred ohms or so. By wiring the diode into the circuit as shown it is made to act as a variable shunt across the meter, so that whilst an input current of perhaps $5\mu A$ may cause the meter pointer to move to one-tenth of f.s.d., a current of $1mA$, or 200 times $5\mu A$ may be needed to read f.s.d. These figures relate to a $50\mu A$ movement.

Such a circuit gives a roughly log scale reading and the precise working points of the diode, and thus the total input current for f.s.d. can be varied by choosing different values of $R_1$. A circuit of this type is of particular use as an indicator in bridges.

Silicon Diode

If the germanium diode of the above circuit is replaced by a silicon diode, a completely different meter scale characteristic is obtained, although the principle of operation is exactly the same as already outlined.

In the case of the silicon diode the forward resistance is still quite high at very low voltage levels, but it is found that as the voltage is increased, perhaps to the order of well over 200 millivolts in some cases, very little decrease in forward resistance takes place. Then, quite sharply, at perhaps half a volt input, the forward resistance begins to fall. If a silicon diode characteristics graph is studied, it will be observed that a sharp knee occurs at this point on the current/voltage curve.

If the silicon diode is used in the circuit of Fig. 11, it will be found that, when a suitable value of $R_1$ is chosen such that the “knee” occurs at three or four times the f.s.d. voltage, then almost no shunting at all will take place over the working range of the meter and the scale will be reasonably linear. On the other hand, when an overload input current of, for example, one hundred times f.s.d. is applied to the circuit, the meter current will be only five or six times that of f.s.d., and no damage will occur.

Such a circuit has applications in low-cost general purpose multimeters.

Protection By Time Constant

Whenever an overload current is applied to a meter the operator has an indication of the fact by
the way in which the needle flashes across the meter dial at high speed. Unfortunately, the speed of movement in such cases is so high that the operator has no time in which to take advantage of the warning. If, however, a large capacitor is wired in parallel with the meter a time constant is obtained, determined by the value of the meter resistance and the capacitor. The time constant in seconds is given approximately by the formula \( T = RC \), so that when a meter with an internal resistance of 1,000 \( \Omega \) is wired in parallel with a capacitor of 1,000 \( \mu F \) a time constant of about 1 second is obtained. If sufficient voltage is now applied to the input of the circuit to give an f.s.d. reading, it will be found that the actual meter current will slowly rise from zero until some time after 1 second, the f.s.d. reading is obtained. Should an overload of ten times f.s.d. be applied instead, however, f.s.d. will be reached in one tenth of the time. Although this is a fairly short time it is still sufficient for the operator to react, and to disconnect the input and prevent damage to the meter. While it is not possible to make wonderful claims for so simple a device, it does at least give some degree of protection against damage, and that is far better than none at all.

It should be noted that the above system is best suited for a d.c. instrument. On a.c. the capacitor may act as a shunt, the value of which varies with frequency.*

**Alternative Overload Protection Devices**

All of the circuits mentioned so far have distinct disadvantages when applied to accurate multimeters and are far from being foolproof. This latter point is due to the fact that none of the devices are positive in action. For full protection a device that gives a very positive action is essential. When the f.s.d. current of the meter is exceeded the device should cause the input to be automatically removed completely from the circuit until a “re-set” order is given by the operator. A number of systems may be used to meet the above requirement but only a few of them will be discussed here, and all of these, except that used on the instrument to be described, mentioned briefly only.

The systems may be operated by either current values, voltage values, or both. In the former case, a sensitive moving coil relay may be wired in series with the meter circuit so that, when an overload current flows, the relay operates and cut the input to the meter. The relay must be self-latching, and this can be arranged by causing the moving coil relay to feed a second, battery-operated relay. The moving coil relay need not be as sensitive as the basic meter, and may operate at, say, ten times f.s.d. current, but the meter manufacturer’s literature should be consulted first before settling on this figure.

Voltage operated safety circuits may use the voltage developed across a series resistor or the meter itself to feed a transistor-operated relay. In such a case the transistor circuit should have a fairly high input impedance, otherwise non-linearity in readings may be obtained due to varying shunt effects.

The system employed with the meter that forms the basis of this article uses the basic meter movement itself to act as the overload device, and takes advantage of the fact that, when the f.s.d. value of the basic meter is exceeded, the pointer presses against the end stop. This end stop is flexible and moves back under the pressure of the pointer. Behind the stop is a fixed arm or contact, and when sufficient pressure is exerted on the stop it bends back and presses against the fixed arm, causing a

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*If the capacitor were to immediately follow the meter rectifier it could also act as a reservoir.—Editor.
short-circuit between the two. The assembly thus acts as a make and break switch, operated when an overload current flows. The two “contacts” of this “switch” are connected in series with a battery operated self-latching relay, the contacts of which are in series with the multimeter input. A sketch of the mechanical arrangement is shown in Fig. 12 (a), which is self-explanatory (in conjunction with its caption) so far as constructional details are concerned. The electrical circuit diagram of the complete automatic overload protection circuit is shown in Fig. 12 (b).

General Notes on Moving Coil Meters

Articles sometimes appear in the pages of the amateur radio magazines in which the contributors tend to become rather carried away with their own enthusiasm and as a result have made rather wild claims for the equipment they describe. This is particularly so in the case of multimeter articles and is due to the fact that certain simple, elementary facts of life are overlooked. The author is thinking, in particular, of the relationship between the accuracy with which a meter may be read and its physical size.

When using a meter, it is very unlikely that the operator will be able to “read” it to an accuracy of better than 10 thousandths of an inch (0.01 inch), due to the thickness of the pointer, parallax errors, and so on. In most cases, in fact, two different operators may “see” readings that are as much as 0.02 inches different under normal conditions, i.e. when only “normal” care is taken in obtaining the reading. If a 2 inch diameter meter is used, therefore, and the reading is taken at f.s.d., an “error” of as much as 1% may be incurred. If the reading is taken at half f.s.d., the error will be 2%, and will become progressively higher as the pointer becomes removed from f.s.d. If, however, a 6 inch meter is used under these conditions, the errors would be only 0.3% and 0.6% respectively. It can be seen, then, that for accurate readings a large diameter meter is essential, and should preferably have a mirror scale.

If the reader has a steady hand and a great deal of patience, he will find it possible to convert a small diameter meter to a larger diameter one, such as, for example, from 2 1/4 to 4 inches. It must be emphasised that the conversion process should only be attempted by those who have the requisite skill and are competent to carry it out, as it is easily possible to ruin a good instrument if great care is not taken. The conversion may be made in the following manner, the work being carried out in a clean dust-free room.

Remove the meter from its case, and carefully remove the scale. Make up a new scale of the required size from thin aluminium, suitably marked, and secure this in place of the old one. The old meter case will now have to be either considerably modified or a new one made up, preferably from glass fibre, to take the enlarged meter assembly.

When the above has been completed and care taken to ensure that a good fit is obtained, the movement has to be modified. Lengthen the pointer, using either fine aluminium wire or special pointer wire (obtainable from instrument dealers), securing the extension to the old pointer with a touch of varnish. Next, and this is the most difficult part of the whole procedure, the pointer assembly must be re-balanced. It will be found that the pointer assembly has the form of a cross, the three short arms being nearest to the pivot. Balancing is carried out by adding, by trial and error, suitable weights to these cross pieces. The weights may consist simply of dabs of varnish, or wire secured with varnish. When correctly balanced, the pointer will remain in the same relative position regardless of the position of the movement, vertical or horizontal.

Finally, when all this work has been carried out, the f.s.d. current should be checked against a standard meter. If any error has appeared the magnetic shunt, a small piece of metal screwed to one of the poles of the moving coil magnet and fitted on all moving coil instruments, should be adjusted until the correct reading is obtained.

It must be stressed again that this procedure must not be tackled by the ham-fisted or impatient types, and in any case, the system should be tried first on a “not-very-expensive” meter, before proceeding to the better type; a basic mistake will then be less expensive. (The author damaged three meters before he finally got the hang of things!)

The 30-Range Multimeter

Having dealt with the basic design principles
involved, the practical multimeter which forms the subject of this series can now be considered in detail. The instrument to be described is very comprehensive, having the following ranges:

D.C. Volts: (f.s.d. readings), 3, 10, 30, 100, 300 and 1,000 volts.
A.C. Volts: 3, 10, 30, 100, 300 and 1,000 volts r.m.s. (Sine).
D.C. Current: 100μA, 1, 10, 100mA, 1 and 10 Amp.
A.C. Current: 10, 100 and 300mA, 1, 3 and 10 Amp, r.m.s. (Sine).
Ohms: Basic range with centre scale of 1,000Ω, giving a reasonable indication from 100Ω to 10,000Ω. (Full coverage of basic range is 0 to 100,000Ω, but ends of scale are cramped.) Multipliers of times 0.1, 1, 10 and 100. Full coverage is 1Ω to 10MΩ.

In addition to the above, two more ranges, giving 50μA or 250mV d.c. are available, making up the total to 30 ranges.

When designing a multimeter, the procedure is to deal with the individual range sections first; i.e., d.c. volts, a.c. volts, etc., and when all the values have been worked out, design the required switching arrangements to suit. To help the reader to follow the principles, the full circuits of the individual range sections are given, as well as the circuit of the complete instrument. The individual circuits will now be introduced.

**D.C. Volts Ranges**

The circuit used for the direct voltage ranges is shown in Fig. 13. The first point to note is that a swamp resistor, R₁, has been incorporated. The value of this should be chosen so that the total series resistance of R₁ and the meter is 5,000Ω. The swamp has been included so that any 50μA meter movement may be used in the multimeter, without fear of errors creeping into the readings of the finished job. The swamp is in circuit with all the remaining ranges.

<table>
<thead>
<tr>
<th><strong>S₁ Switch Position</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>1</strong></td>
</tr>
<tr>
<td><strong>DC Volts</strong></td>
</tr>
<tr>
<td>1</td>
</tr>
<tr>
<td>2</td>
</tr>
<tr>
<td>3</td>
</tr>
<tr>
<td>4</td>
</tr>
<tr>
<td>5</td>
</tr>
<tr>
<td>6</td>
</tr>
</tbody>
</table>

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A "ladder type" multiplier system has been used, although this is not essential to general design. The multiplier values used are non-standard, but there is no way round this snag even if the ladder system is not used. When designing the instrument it was decided that ranges of 30, 300, etc., were far more useful than ones of 25, 250, etc., although the latter would have enabled more readily obtainable resistors to be used. More will be said on this matter under "Constructional Notes".

D.C. Current Ranges

See Fig. 14 for the direct current section. The design of this circuit was dealt with in full in Part 1 and no further comments are required at the moment.

A.C. Voltage Ranges

The a.c. voltage ranges are shown in Fig. 15. The meter is shunted to read 1mA f.s.d. by R14. A ladder type chain is again used, the 3 volt range being made up of RV1 and R15 in series. See under "Constructional Notes".

A.C. Current Ranges

Fig. 16 shows the a.c. current ranges. The design procedure has been dealt with in full in Part 1 and no further notes are needed here.

Resistance Ranges

The resistance range section is shown in Fig. 17. The circuit used is that given in Fig. 10 (c) of Part 1 of this series. The extra complication is due to the fact that it was considered desirable to have only one "set zero" control, rather than the three or four that might otherwise be required. Roughly speaking, the basic meter has been shunted by R27 and RV3 so that it reads $67\mu A$, variable to about $-10\%$ to $+20\%$, thus allowing for changes in battery voltage.

To operate, the circuit is required to pass an f.s.d. current that is dictated by the range in use, i.e. by the battery voltage and series resistance. The current (f.s.d.) required by the individual ranges of this particular meter are: times $0.1 = 15mA$, times $1 = 1.5mA$, times $10 = 1.35mA$ and times $100 = 135\mu A$. It was decided, in view of the need for only one "set zero" control, to make the variable shunt meter as it now is, into a multi-range current meter to meet the above requirements. This is accomplished by resistors R28 to R31 inclusive.

When explaining the principles of operation of the circuit in Part 1 of this series, it was mentioned that the series resistor should be made the same value as the required centre scale reading. When working out the value of this series resistor the resistance of the basic meter has also to be taken into account.

Fig. 16. The "A.C. Current" section, shown switched to the 1 amp range

Fig. 17. The resistance measuring section, switched to "X1". The two switch poles are ganged together
into account in some cases, and it may even be necessary to allow for the battery resistance as well if very low ranges are to be used. In the design shown in Fig. 17 the input resistance of the universal shunt has also had to be considered when choosing the values of resistors R32 to R35. Even so, on the lowest range (times 0.1) it has not been possible to allow fully for varying resistance of the 1.5 volt battery, and errors of as much as 3% may creep into the readings with a battery that is not in very good condition.

Shown in Fig. 18 is a typical calibrated ohms scale for use on the finished meter, although it would be preferable to calibrate the individual meter against a standard.

The one calibrated scale will serve for all four ranges.

50μA and 250mV Ranges

These two ranges are made available by connecting the input directly across the meter and swamping resistor terminals.

Constructional Notes

Although only 35 fixed-value resistors (a low figure considering the number of ranges provided) are shown in the complete circuit diagram, the practical instrument will contain considerably more than this figure, as many of the resistance values will have to be made up by connecting two or more resistors in a series or parallel combination.

All of the resistive values shown have been chosen to give an accuracy of better than 0.5%. If, however, this degree of accuracy is not needed, then the values may be altered slightly to allow more readily obtainable components to be used. If, for example, the awkward value of 98.7kΩ shown for R35 were changed for 100kΩ, the latter component would only give an error of 1.3% in readings. Similarly, if R4 and R6 were changed to 390kΩ and 3.9MΩ respectively, errors of only about 1.6% would be expected, and so on.

The circuit of the complete instrument (less the overload circuit) is shown in Fig. 19. Two six-pole six-way switches are required.

For the meter rectifier, either one of the special 1mA instrument types or four germanium diodes may be used.

The first step in construction is to decide on the practical layout to be used, checking that sufficient space is provided for all of the components and bearing in mind that some of the individual resistive values will have to be made up by a combination of two or more resistors. Once the layout has been decided the meter box should be made up, preferably from glass fibre, and the holes for the meter, switches, etc., cut out. Bushes or bolts may be moulded into the glass fibre so that tag boards may be secured inside the box without spoiling the external appearance of the finished instrument. The following notes on the wiring procedure should be observed.

(1) Determine the required value for Rf and solder into place. The correct value for this resistor is 2,000Ω minus the meter internal resistance, r, the latter being determined by the method described in Part 1. A standard meter will have to be used for setting up certain of the multimeter ranges and, as a check that the correct value of Rf has been used, it should be verified that with 250mV connected between the positive terminal and the end of R1, the 50μA meter reads f.s.d.

The use of a standard meter will in some cases be available at the reader's place of work or, failing this, the local technical college may make their instrument available, under supervision. Other possibilities may also occur to the reader's mind.

(2) Before proceeding with the main meter ranges, the overload safety circuit should be wired in place, using the diagram of Fig. 12. The operation of the circuit should be checked, ensuring that the trip and re-set systems work correctly.

(3) When wiring the d.c. voltage range multipliers, it will be necessary to check the calibration of the meter after each resistor is soldered in place, as a fault in one stage will affect the readings of all following stages.

(4) The next stage in construction is the wiring up of the d.c. current ranges. Here the three lowest value resistors will have to be made up from resistance wire, and approximate lengths and s.w.g. figures are included in the Components List. The exact length of resistance wire will have to be determined finally by trial and error, and the following system of construction should be followed.

First, make up a suitable tag board to hold all the resistors required, and then wire the resistors temporarily in place, making sure that R8 is exactly 4.5kΩ and that the total resistance of the chain is 5kΩ within 1%. It should be noted that, at this stage, the exact value of R1, R2 and R3 is not of great importance, as if, for example, R11 is out of tolerance by as much as 100% a total error on the 100μA range of only 0.1% will result. It is the value of R8 and the sum of the rest of the chain that counts at this stage.

Next, the calibration of the 100μA range must be checked against the standard. If any error occurs

![Fig. 18. Resistance range calibration against a linear volts scale](image-url)
it can only be because one of the above points has not been observed or because a dry joint has been made. When the correct calibration has been observed, resistor $R_6$ should be soldered permanently in place and the calibration again checked.

Now check the calibration of the 1mA range, ensuring that $R_9$ is $450\,\Omega$ and that the sum of $R_{10}$, $R_{11}$, $R_{12}$ and $R_{13}$ is $50\,\Omega$. When satisfied, again solder the relevant resistor ($R_6$) permanently in place. Use a similar procedure for the 10mA range.

On the remaining three ranges, the values of the home-made resistors will have to be adjusted on test to bring the calibration within the desired degree of accuracy; i.e. if the meter reads low, the resistance will have to be increased, and vice versa. To increase the resistance of the wire, the length can be either increased or the diameter reduced by filing. To reduce the resistance, either reduce the length or apply solder to a suitable length of the wire.

After the correct value of each resistor has been obtained, the accuracy of the preceding range should be checked, and if an error of greater than about 10% is found, check the stage before that as well and correct the errors. It should be noticed that an error of a given magnitude in one stage
Components List
(Fig. 19)

Resistors
(All resistors listed hereunder should be high stability types with a tolerance of 1% or better—see text)

<table>
<thead>
<tr>
<th>Resistor</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>R₁</td>
<td>5kΩ</td>
</tr>
<tr>
<td>R₂</td>
<td>55kΩ</td>
</tr>
<tr>
<td>R₃</td>
<td>140kΩ</td>
</tr>
<tr>
<td>R₄</td>
<td>400kΩ</td>
</tr>
<tr>
<td>R₅</td>
<td>1.4MΩ</td>
</tr>
<tr>
<td>R₆</td>
<td>4MΩ</td>
</tr>
<tr>
<td>R₇</td>
<td>14MΩ</td>
</tr>
<tr>
<td>R₈</td>
<td>4.5kΩ</td>
</tr>
<tr>
<td>R₉</td>
<td>450Ω</td>
</tr>
<tr>
<td>R₁₀</td>
<td>45Ω</td>
</tr>
<tr>
<td>R₁₁</td>
<td>263Ω</td>
</tr>
<tr>
<td>R₁₂</td>
<td>1kΩ</td>
</tr>
<tr>
<td>R₁₃</td>
<td>6,300Ω</td>
</tr>
<tr>
<td>R₁₄</td>
<td>18kΩ</td>
</tr>
<tr>
<td>R₁₅</td>
<td>63kΩ</td>
</tr>
<tr>
<td>R₁₆</td>
<td>180kΩ</td>
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<tr>
<td>R₁₇</td>
<td>630kΩ</td>
</tr>
<tr>
<td>R₁₈</td>
<td>90.1Ω</td>
</tr>
<tr>
<td>R₁₉</td>
<td>3.9kΩ</td>
</tr>
<tr>
<td>R₂₀</td>
<td>23.2Ω</td>
</tr>
<tr>
<td>R₂₁</td>
<td>209Ω</td>
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<tr>
<td>R₂₂</td>
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<tr>
<td>R₂₃</td>
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<td>78Ω</td>
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<tr>
<td>R₂₅</td>
<td>775Ω</td>
</tr>
<tr>
<td>R₂₆</td>
<td>9.750Ω</td>
</tr>
<tr>
<td>R₂₇</td>
<td>98.7kΩ</td>
</tr>
</tbody>
</table>

Resistors (Wirewound)
(See text concerning construction of the resistors listed hereunder)

<table>
<thead>
<tr>
<th>Resistor</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>R₁₁</td>
<td>4.5Ω  (32in 30 s.w.g. Eureka)</td>
</tr>
<tr>
<td>R₁₂</td>
<td>0.45Ω (9in 24 s.w.g. Eureka)</td>
</tr>
</tbody>
</table>

shows up as an error reduced by powers of ten in all preceding stages. To take an example, if, when setting up R₁₁ it is necessary to change the resistance value by 10% in order to set the calibration, an error of only 1% will occur in the preceding (10mA) stage, of 0.1% in the 1mA stage and 0.01% in the 100μA stage.

(5) Wire R₁₄ into circuit and check that, with the switching set to the appropriate positions, the meter is shunted to read 1mA f.s.d. Next, connect the bridge rectifier and ensure that it is functioning correctly.

(6) The alternating voltage multipliers are now wired up. First, wire in RV₁ and R₁₅ and adjust RV₁ to give 3 volts f.s.d., from a sine wave (the mains, fed through a suitable transformer), checking against the standard meter. Lock RV₁ in position. Wire in the multipliers for the remaining ranges, proceeding as described in (3) above.

(7) The alternating current ranges come next. Wire the pre-set resistor, RV₂, in circuit with one end to the bridge rectifier input as indicated in the circuit diagram and then, with a low level alternating voltage connected between the free end of RV₂ and the other input of the rectifier, adjust RV₂ to give 1 volt f.s.d., checking against the standard. Lock RV₂.

Make up the universal shunt, as shown in the circuit diagram and consisting of R₂₁ to R₂₆ inclusive, using the method described in (4) above.

(8) Wire R₂₇ and the “set zero” control, RV₃, into circuit as shown and check that, with the switching set to the required positions, the meter reads approximately 67μA, variable by about −10% to +20%. Now wire up the resistance-measuring circuit, and then check that this functions correctly. If it is found to be impossible to set zero on any of the ranges, the action of the universal shunt section, consisting of R₂₈ to R₃₁ inclusive, should be checked as for a multi-range direct current meter, using the figures given in the “Resistance Ranges” section.

When the wiring of the resistance ranges has been completed and it has been checked that the “set zero” control works correctly, check that the centre (continued on page 194)
NEWS AND COMMENT . . .

T.E.P.
T.E.P. stands for Transequatorial Propagation. It is a transmission mode of high frequency radio signals over long distances, which has been discovered mainly through the activities of radio amateurs. The upper layers of the ionosphere tend to be more dense over the equator than over the Polar regions, so that stations situated such that their path of communication passes across the equator are often able to communicate on frequencies far higher than one would expect. Regular recording of signals from amateur operated beacon transmitters, working in the range 29 to 50 Mc/s, over the past few years, has thrown much light on this phenomenon. Readers who would like to know more about this matter should read the article "Transequatorial Radio Propagation during the Years of the Quiet Sun", by R. C. Cracknell, ZE2JV; and R. A. Whiting, ZC4WR, in the June 1965 R.S.G.B. Bulletin. We liked very much the final paragraph of this article which reads:

"...T.E.P. has been mainly an amateur discovery, and the team work which has gone into its development is of the type that should in some measure justify the continued allocation of frequencies for amateur use, and has been, to quote Ed Tilton, V.H.F. Editor of QST, 'One of the finest examples of Amateur Radio's potential for worthwhile contributions to wave-propagation knowledge'."

Car Radio New Use
A car radio that sounds a reminder if a driver forgets to turn off his headlights has been introduced in the United States. It works if the lights are left on after the ignition has been turned off, and gives its signal even if the radio is not turned on.
The warning unit has been produced by the Motrolo Corporation.

Ghana TV
The Ghana television service, the most modern and comprehensive television broadcasting system in the African continent, was officially declared open by President Kwame Nkrumah on July 31st, 1965.

Designed, built and installed by The Marconi Company, in collaboration with the Ghana Broadcasting Corporation, the new service has three television transmitting stations at Accra, Kumasi and Sekondi-Takoradi. These stations cover approximately one quarter of the country including the Atlantic seaboard, the most heavily populated part of Ghana. Each of the three stations is served by a central studio complex in Accra, the capital.
The whole of the new television broadcasting service was a "turnkey" project and was handed over as a fully operational concern. Engineers and technicians from the Ghana Broadcasting Corporation have received extensive training in the techniques of television broadcasting at the Company's headquarters in Chelmsford and have now taken over the running of the new service.
The order, which was the largest single broadcasting contract ever awarded to the Company, also included major extensions to the existing sound broadcasting service. These have considerably improved the coverage of the Ghana Home Service and also of the external broadcasting services.

This order is another step in the close association of The Marconi Company with the development of broadcasting in Ghana. The Company built the first station there in 1935 and have since been responsible for a number of other projects, including the ultra-modern external broadcasting station at Tema, opened by President Nkrumah in 1961.

TV by Gramophone
A gramophone record that plays television still pictures has been developed in the United States. Along with the pictures, sound comes from the same long-playing disc. The system has been named Phonovid.
Both sound and pictures are represented in the grooves of the record, and both are picked up by the gramophone needle. Up to 400 pictures and 40 minutes of voice and music can be recorded on the two sides of a 12-in recording that turns at 33 1/2 revolutions per minute.
The recording is played on an ordinary turntable. Any part of the recording can be held, skipped or repeated by manually lifting the tone arm.
Standard sound and television equipment can be used. But a specially developed scan converter, must be used to link the conventional record player and television set.
Information from the record is stored in the scan converter's special electronic storage tubes. Every six seconds, a complete picture is built up in the tubes and flashed on the screen. While this picture is displayed, the next picture is being formed in the tube from information supplied from the grooves in the recording.

"Do not adjust your set, the breakdown is only temporary!"
Infra-Red Ray Alarm System

By E. V. KING

The device described in this article will give faultless warning of any object passing a narrow invisible beam and will function equally well as a Burglar Alarm, Fog Alarm, Smoke Alarm or Customer Alarm. A phototransistor with a d.c. amplifier transistor is used to operate a relay circuit and an electric, battery operated, bell. Light incident on the transistor prevents the bell working, darkness causes it to ring.

No great knowledge of electronics is required and successful operation is sure from the start.

There are three versions of the alarm, these differing only in the relay circuits required.

The Circuits

The simplest of the three circuits is illustrated in Fig. 1. In this diagram an OCP71, TR1, is illuminated by an infra-red beam, whereupon it conducts. This causes a relatively heavy current to flow through R2, and allows only a small amount of base current to pass to TR2. TR2 collector current is, therefore, also small, and the relay remains de-energised. If the infra-red beam is interrupted, the current drawn by TR1 reduces considerably, allowing a greater bias current to flow through R2 to TR2. The consequently increased collector current in TR2 flows through the relay, which then energises. The 150Ω resistor, R1, limits transistor current.1

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1 R1 was fitted in the author's prototype, but it could in practice be omitted, if desired, without upsetting circuit operation unduly. —EDITOR.

The relay employed is a Siemens 1000 + 1000Ω high speed type, with the two coils in series. Its contacts are not heavy enough to switch such loads as an electric bell more than about 50 times without cleaning. Whilst it could, therefore, be employed to control a bell for occasional use, more frequent usage requires that a second relay be incorporated in the circuit. The circuit of Fig. 1 will, of course, switch low currents other than that needed for a bell.

The second relay may be a P.O. type 3000 unit with a 200Ω coil, and it is connected into circuit as shown in Fig. 2. When the Siemens relay contacts close, the P.O. relay is energised. Its contacts then close and cause the bell to ring. It is assumed, in Fig. 2, that the 9–12 volt supply will also be applied to the bell. If the bell is designed to run from a lower voltage it may be necessary to insert a resistor in series for correct operation. A suitable resistor, as employed by the writer, is a 12 volt 3 watt lamp.

The third circuit is shown in Fig. 3. This is a development from Fig. 2 and includes a lock-in facility. When the P.O. relay energises, a second set of contacts short-circuit the Siemens relay contacts, causing the P.O. relay to remain permanently energised until the supply is disconnected.

It should be noted that this circuit is of the "fail-safe" type in so far that the alarm is always given if the lamp illuminating the OCP71 fails.

Components

For the prototype, the author obtained the Siemens relay from Service Trading Co., 47-49

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Fig. 1. The simplest version of the alarm

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The cabinet housing the transistors and the relays
High Street, Kingston-on-Thames, Surrey. The P.O. relay was obtained from Messrs. Arthur Sallis, 93 North Road, Brighton, Sussex. TR₁ is an OCP71, but one of the early OC71's with transparent glass cover and transparent internal grease could also be used with the outside paint scraped away. Currently available OC71's are metal cased and cannot be modified in this way. TR₂ is an OC72, and the supply may be provided by a transistor battery or batteries.

It is also necessary to provide the infra-red illumination for the phototransistor and one of the components required here is a focusing torch. An inexpensive focusing torch is available from Messrs. Boots the Chemist. The infra-red filter may be obtained from photographic stores, and it should be capable of being fitted to the torch.²

²The writer states that he has found that a plastic bathroom tile, known as "Polytile S & S", makes an excellent infra-red filter.

—EDITOR.

A further requirement is a focusing lens for the OCP71, and this should be 1½ to 2in in diameter, convex, and with a focal length of 3 to 4in. Lens No. 24 in the catalogue of Messrs. H. W. English, Rayleigh Road, Brentwood, Essex, will suit.

Finally required are a small carpenter's G-clamp, and an adjustable ball joint. The latter may be a photographic ball joint or that employed with a cycle handlebar mirror.

Making The Cabinet

A cabinet for the transistors and relays is required, and this may take up the form in the illustration (on which the bell and a lamp are also mounted). The convex lens is fitted to the circular aperture at the front. The dimensions of the author's unit were 6in long, 3in wide and 3in high. The lens hole is cut exactly to size and the lens glued within using Durofix. A small side aperture is provided as shown in the second photograph.

Fig. 2. Adding a second relay to allow higher currents to be switched. The resistor in series with the bell is discussed in the text.
The components inside the cabinet

This can be opened to enable the position of the phototransistor to be adjusted. The inside of the cabinet should be painted with Berlin Black. The battery is not fitted inside the cabinet in the author's version.

Preliminary Test

Plug in a battery of 9 to 12 volts, being careful to have the polarity correct. In the dark the relay (or relays, if Fig. 2 or Fig. 3 are used) should pull in, and if a match is struck nearby it should release automatically until darkness returns. If the lens is used to focus the filament of a lamp bulb on to the transistor the relay should again fall out. Now connect the bell so that it rings when the match test is applied. Light mutes the bell, darkness causes it to ring.

Next, shine a torch into the lens and adjust the position of the phototransistor to coincide with the image of the filament and then by trial and error find the most sensitive part of the transistor (usually the filament should be on the collector/base junction if this can be distinguished). When an OCP71 is used, follow the maker's instructions regarding positioning relative to the light source. Any future adjustment, which should normally be unnecessary, will have to be made via the side window of the cover.

The infra-red light source and the manner in which it is mounted

A side aperture is provided for final adjustment of the OCP71

The Light Source

This is best hidden under stairs, etc., and it is made in such a way that the fitting is virtually universal. The focusing torch is fitted with a dummy battery made from a piece of broom stick or dowel on which are fixed dummy brass screw contacts at top and bottom. Wires to these pass through grommets fitted into the side of the torch. A tube of metal or card is painted with Berlin Black and fixed over the glass of the torch by soldering or making a flange.

It is easier to use the torch if it is fitted with Terry clips on a piece of wood as shown in the appropriate illustration, this in turn being held in a ball joint attached to a carpenter's clamp. The leads are taken to a 12 volt heater transformer and a small wattage 12 volt lamp fitted in the torch. If desired the voltage may later be reduced to 8 watts or so to prolong bulb life.

The whole apparatus is now tested with a white light source (i.e. no filter) the torch being directed at the lens in front of the OCP71. A piece of infra red filter material is then cut to the same size as the glass of the torch and is fitted in lieu of the glass.

The transistor will now be almost as sensitive to the invisible rays, but since these cannot be seen, initial adjustment is tricky. If the bell is allowed to ring it will cease when the beam is correctly aiming at the lens. If the circuit of Fig. 3 is used, it will be helpful to disconnect the locking contacts of the P.O. relay during this operation.

How to fix up the alarm

When made and tested the alarm is placed in any position away from heat. For burglar use is should be hidden, say under the stairs with only the "infra-red ray hole" visible and the bell (and/or lamp) wired to any point in the house.

The battery should be in good condition as, if it is run down, the until will tend to go in and out of operation continuously.

When setting up the locking burglar alarm
the light must be put on first or the unit will, of course, automatically sound the alarm. The author has left out a switch, and other testing devices to make the unit as simple as possible.

It should be added that the prototype has been continuously tested for six months and is functioning well.

This month Smithy the Serviceman, aided as always by his able assistant Dick, discusses some of the finer points of design in transistor mixer-oscillator circuits, and deals in particular with typical examples of the Luxembourg tuning circuits fitted in commercial receivers.

REPAIR that?"

Dick pointed a scornful finger at the battered little transistor radio which lay on his bench.

"Yes, of course," said Smithy, puzzled at Dick's reaction. "Why on earth shouldn't we?"

"Look at the state it's in," protested Dick. "It's wrecked before we even get it out of the case!"

Smithy picked up the little radio and examined it carefully.

"It is," he remarked eventually, "rather battered, I must say. Hello, what's this? Someone's scratched something on the case."

The Serviceman peered at the plastic back of the receiver.

"'Jagger for President'," he read out haltingly. "Dear me, what a way to treat a radio. Hello, there's something on the side, too. 'Good old Baillie Vass'."

No Output

"That's what I mean," said Dick. "That set's been so bashed around and badly treated that it isn't even worth the trouble of fixing it."

"Oh, I don't know," replied Smithy. "We've got an hour to kill before packing-up time, and we've cleared out all the other sets in the Workshop."

"All right, then," said Dick resignedly, as he picked up a screwdriver. "But we were meant to do better jobs than this, you know!"

As Dick unscrewed the bolt holding the rear of the case, Smithy walked to his bench and returned with his stool.

"There we are," he said, as he settled himself comfortably alongside his assistant. "It isn't too bad inside after all, is it?"

"I suppose not," agreed Dick grudgingly, as he examined the components which were packed on to the Lilliputian printed board. "Perhaps it's worth having a go at it, after all."

Experimentally, he applied his thumb to the rim of the volume control. There was a click as the on-off switch operated. Dick turned the control to full, but no sound came from the receiver.

"I should check the battery," advised Smithy, "it's amazing how many faulty transistor sets there are which suffer from nothing else but a run-down battery!"

Obediently, Dick adjusted the switch of his testmeter and applied the test prods to the terminals of the battery.

"It's reading," he announced, "about 8.8 volts. No it isn't, it's gone down to 8.4 volts. Wait a minute, though, it's back at 8.8 volts. Now it's back to 8.4 volts again! Blimey, it's wandering around from 8.4 up to 8.8 all the time now!"

Dick stared unbelievingly at the battery.

"I've heard about intermittents," he said incredulously, "but this is ridiculous. Who ever made a battery which gives a variable voltage output?"

Wearily, Smithy reached over and turned the tuning dial of the receiver.

"Try it now," he commanded.

Once more Dick applied his test prods.

"Well, I'm dashed," he said, staring at his meter. "It's dead steady at 8.8 volts now."

"Fair enough," commented Smithy. "We won't have far to look for this particular snag."

"Hey?"

"The trouble is obvious," continued Smithy. "It's almost 100% certain that this set was tuned to a station when you first applied the test prods, and that the output transistors were running on a good strong signal in consequence."

"Oh, I see what you mean," exclaimed Dick, as light broke in.

"The varying battery voltage would be the result of the heavy current drawn by the output transistors, and this current would alter according to the sound being broadcast."

"That's right," agreed Smithy, "and this point is confirmed by the fact that, after I'd moved the tuning capacitor off the station, the battery voltage remained steady. With the set off tune, the output transistors weren't handling any heavy signal."

"If that's the case," said Dick
promptly, "the speaker's gone open-circuit."

Smithy sighed.

"I do wish," he complained, "that you wouldn't keep jumping to these illogical conclusions of yours."

"What's so illogical about that?" queried Dick indignantly. "If the output transistors are handling a large signal and there's no noise coming out of the speaker, something must be wrong in the speaker circuit. What could be more logical than the speaker itself?"

"Plenty of things," replied Smithy patiently. "The flexible connections between the printed circuit board and the speaker for one, and the earphone socket for another. It's very common practice to put the earphone socket in the speaker circuit and give it a contact which breaks the connection to the speaker when the earphone is plugged in. (Fig. 1.) Incidentally, I've often thought that the people who use an earphone with the full whack of the output going into it must have rubber eardrums, but that's another story!"

Whilst Smithy was speaking, Dick had already switched off the receiver and was now examining the socket in question. Picking up a pair of taper-nosed pliers he carefully bent in the right direction.

"That should fix it," he remarked cheerfully. "The connection those contacts made looked a bit dicey, so I've just given the fixed one a wee twist in the right direction."

Dick switched on the receiver once more, whereupon a comforting hiss was immediately audible from the speaker. He swung the tuning dial, to find that both sensitivity and reproduction were satisfactory.

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**Light Programme Switching**

"That's got this one fixed then," he remarked exultantly. "Last job of the day done. Good show!"

"Does it work on both wavebands?"

"Oh yes," replied Dick. "It's one of those sets with contacts on the tuning capacitor which switch over to the long waves around 1500 metres for the Light Programme. And the Light Programme's coming in fine."

"Fair enough," said Smithy. "Seeing that you've been playing around with the earphone socket you'd better test it with an earphone as well, before you finally let the set go."

Dick rummaged around on his bench and unearthed a small earphone with a flexible cord. He plugged this into the receiver, whereupon the speaker became silent and the little earphone rattled away as it reproduced the signal received by the set. Dick unplugged the phone, and the receiver's speaker once more became operative. He switched off the set and pushed it to one side.

"And that," he remarked, "is what I wish they were all as easy."

A thought struck him.

"By the way, Smithy," he asked, "how do those long wave switching circuits work? The ones with the contacts on the tuning capacitor?"

"Oh, those," said Smithy. "Well, all that happens normally is that the contacts just connect extra capacitance across the oscillator tuned circuit and the aerial tuned circuit. If you look at the back of the tuning capacitor you'll see that there are two fixed contacts mounted on it. These connect to a third moving contact when the tuning capacitor is tuned past the low frequency end of the medium wave band, and they cause long waves to be selected. The moving contact is earthed, and so the fixed contacts can then add extra fixed capacitors across the aerial and oscillator tuned circuits."

(Fig. 2.)

"No trimmers?"

"Not normally," replied Smithy. "The tuning capacitor still offers a change of capacitance when the contacts are made, and so its oscillator section can enable you to tune in the Light Programme accurately. The extra aerial tuned circuit capacitance is pretty large and so you get a low L/C ratio, giving this part of the circuit a broad response. Because of this, it's hardly worthwhile using a long wave aerial trimmer."

"Won't the additional capacitance cause the oscillator tuned circuit to have a low L/C ratio as well?"

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**Fig. 1. A typical earphone jack circuit in a transistor receiver.**

Inserting the earphone jack plug breaks the circuit to the loudspeaker.

"Not really," explained Smithy. "The extra capacitance connected across the oscillator tuned circuit is around 170pF only. The extra capacitance across the aerial tuned circuit is normally about 1,300pF."

Dick listened to this information with obvious scepticism.

"That doesn't make sense," he declared. "You're switching both circuits from medium waves to long waves, and yet one of the additional capacitors is nearly ten times as big as the other."

"Who," asked Smithy, "said anything about switching the oscillator tuned circuit to long waves?"

"You must do," stated Dick. "If it isn't switched to long waves, how the heck do you pick up the Light Programme?"

"One of these days," sighed Smithy, "I'll let you into the secret of how a superhet works. In the meantime, please take my word for it that the oscillator frequency is removed from the signal frequency by the intermediate frequency. In most receivers, including broadcast

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**Fig. 2. A simple wave-change switching circuit, as is used when the wave-change contacts are closed by turning the tuning capacitor.**

The values shown for the two fixed capacitors switched into circuit on long waves are representative of commercial practice.
band receivers, it runs above the signal frequency. O.K.?”

“I'm prepared,” said Dick reluctantly, “to accept that.”

“Having established these basic facts,” Smithy went on, “let's now see how things in our medium-long wave switching circuit work out in terms of frequency. To start off with, the tuning capacitor switch comes into action at the low frequency end of the medium waveband, where the signal frequency is round about 600 kc/s. Right?

“That seems,” said Dick, “to be reasonable enough.”

“Good. Now, the oscillator frequency is higher than this by the intermediate frequency. If we say that the i.f. of the receiver is 450 kc/s, then the oscillator frequency will be 600 plus 450 kc/s. Which, to my way of reckoning, comes out at 1,050 kc/s. Agreed?”

“I would,” said Dick condescendingly, “accept that figure.”

Smithy gritted his teeth. Life can be difficult for those who have knowledge to impart.

“Right,” he said shortly. “So now let's add the extra capacitance needed to tune in the Light Programme on long waves, and see how the two frequencies come out. The Light Programme is on 1,500 metres, or 200 kc/s, and so this is our new signal frequency. The new oscillator frequency is 200 plus 450 kc/s, or 650 kc/s. In consequence, switching to the Light Programme results in the signal frequency dropping to a third of its previous value. But the oscillator frequency only drops from 1,050 to 650 kc/s, which isn't even half. Apart from anything else, therefore, you have to add a larger capacitor across the aerial tuned circuit than is needed across the oscillator circuit.”

“Well, blow me,” said Dick.

“That seems,” said Dick, “to be a bit complicated.”

“Of course it is,” replied Smithy. “Well, blow me,” said Dick.

“Probably,” replied Smithy, “but the circuit complications might not be acceptable in a very small low-cost receiver, and it would be difficult to switch in an extra coil with the two contacts that are given by the tuning capacitor switch. If the set has a separate wave-change switch this can provide one or two more switching poles, and the switching circuit will then almost always bring in a long wave coil on the ferrite rod. This occurs even if the receiver is of the type which offers a limited long wave range on either side of the Light Programme.”

“Talking about wave-change switches,” volunteered Dick, “reminds me that some of these transistor wave-change switching circuits aren't half complicated.”

“How d'you mean?”

“Well,” said Dick, “you open up the service sheet to look at the circuit, and you find a whole jungle of switches and components around the oscillator-mixer transistor. Dead complicated, some of them are.”

“Don't tell me,” said Smithy, surprised, “that you've actually started looking at service sheets.”

“Of course I look at them,” replied Dick, indignantly. “Mind you, I don't believe in getting out the service sheets as soon as I get a set on the bench. I like to have a little prod around first.”

“So,” remarked Smithy, “I have noticed. I'd hate to have to add up the hours you've spent in proddling around when the service sheets are available to give you all the gen you want.”

“What I was saying,” said Dick, ignoring Smithy's criticism, “is that some of these transistor wave-change switching circuits are jolly complicated.”

“A few of them do tend to give that impression,” conceded Smithy.

“The trouble is that a lot of transistor receivers use push button wave-change switches in which the depressed button springs out when a new one is pressed, and the circuit diagrams become a wee bit harder to follow than in the cases where normal switches and normal switch symbols are used. If you've got a really complicated wave-change circuit, it's a good plan to find your landmarks first.”

“How d'you mean?”

“You want to find,” explained Smithy, “the easily recognisable components. The first of these are the two sections of the tuning capacitor, identifiable by the dashed line that joins them; and the readily recognisable pattern (b) of the mixer-oscillator transistor and its oscillator coil, with the occasionally-met variant shown in (c). Of the winding arrangements tend to vary from set to set but the car aerial coupling circuit is almost always that shown in (d).
(d.) If, with an unfamiliar and complicated mixer-oscillator circuit, you first identify and place the component you've just mentioned, you can save yourself quite a bit of time. This is particularly true if the wave-change switching circuit has lots of trimmers and fixed capacitors in it. "Some wave-change circuits," said Dick, "bring in resistors as well. The wave-change switch connects a resistor across the oscillator tuned winding on medium waves."

"That's quite a common practice," agreed Smithy. "These resistors usually range from around 50kΩ up to 250kΩ, and they damp the oscillator coil down a bit on medium waves, where there is less tuning capacitance than on long waves. The result is that oscillation amplitude is at more nearly the same level on the two wavebands than would occur if the resistor weren't fitted." Smithy stopped and looked at his watch.

"Dash it all," he said, "there's still half an hour to go yet. I want to get away dead on packing-up time tonight, too, because I've got a bit of a night on at the club."

"So," said Dick, "have I."

"At the club? You aren't even a member."

"Of course I'm not," replied Dick. "I'm going down to Joe's Caff."

Smithy's eyebrows shot up. "Joe's Caff?" he repeated in surprise. "I thought you'd given that place up ages ago."

"We keep on keeping away," explained Dick. "But, somehow or other, everyone seems to drift back again after a while."

"Isn't Joe the bloke who's always changing the place around and giving it different names?"

"That's right," said Dick. "He used to follow all the raves, like the Merseyside bit and being satirical and all that, but there just aren't any decent raves going these days. So he's now called his place 'The Mandarin's Nosher' and changed it to a Chinese restaurant."

"Sounds charming," commented Smithy. "And does he dish up the real Chinese food?"

A look of uncertainty crept over Dick's face.

"Well, he keeps on saying it is," he replied hesitantly, "but we're all beginning to get extremely suspicious. If we say anything, though, he just says that it's exactly the same food as the Chinese eat out in Hong Kong. Since none of us have got a clue as to what the Chinese do eat out in Hong Kong we just have to take his word for it."

"I think I can understand the problem," said Smithy sympathetically. "You've got a nasty feeling that he's dishing you in some way, but you just can't put your finger on it."

"That's exactly it," said Dick, pleased at Smithy's understanding of the situation. "I couldn't have put it better myself."

"What," asked Smithy, "are some of the meals he serves?"

"Well," said Dick, a little doubtfully, "to start off with, there's Phoo Sten Lung."

"And what's that consist of?"

"Egg and chips."

Smithy swallowed. "Any more?" he asked.

"Oh yes," replied Dick. "There's Sung Tan Choy."

"And what's that?"

"Sausage and chips."

"Any others?"

"There's Chow Hung Choo."

"What?"

"Beans and chips."

"What," asked Smithy gently, "is your favourite one?"

"Ah," said Dick enthusiastically, momentarily forgetting his suspicions of unscrupulous trading on the part of Joe, "that's the old Clong Choo Phoey."

"Ye gods," breathed Smithy, "and what does that comprise?"

"Pie and chips," replied Dick appreciatively. "And if you want a real super version of it, you can't beat the Clong Choo Phoey Chop-Chop!"

"But," protested Smithy, "that's the same as the last one with Chop-Chop added."

"Exactly," said Dick. "It's meat pie and chips with two splodges of chop sauce on the side of the plate!"

"Well," commented Smithy, "you certainly seem to be enjoying your Chinese food at any rate."

"I suppose I'll get used to it in time," replied Dick. "But it's very difficult at first."

"How's that?"

"Have you," asked Dick, "ever tried eating meat pie and chips with chop-sticks? How those Chinese out in Hong Kong manage it boggles me completely."

He stared moodily at the wall behind his bench.

"I suppose," he added gloomily, "it's what you're brought up to, and that's all there is to it."

"Lux" Tuning

Smithy decided that a change of topic might well be profitable.

"Is there anything else," he enquired, "that you want to know concerning transistor tuning circuits before we pack up?"

"Oh yes," said Dick, wrenching his mind away from the inscrutable customs of the Orient when dealing with pie and chips. "What about these medium wave bandspread tuning circuits that are fitted to so many sets these days?"

"You mean," queried Smithy, "the Luxembourg tuning circuits?"

"That's right."

"Well, most of these," said Smithy, "are intended to give easier tuning around the high frequency end of the medium waveband. This end tends to get a little cramped with the tuning circuits you get in these little transistor sets, and the lack of a high ratio tuning drive makes the selection of stations even more difficult. Also, the two major pop stations, Luxembourg and Caroline, appear at the high frequency end. These are liable to fade a bit, which further increases the difficulty of tuning. All these points make bandspread tuning over the high frequency end of the medium waveband an attractive proposition, and a common approach consists of having the bandspread range cover about 185 to 215 metres."

"Radio Luxembourg," remarked Dick, "comes up on 208 metres. What's the wavelength of Radio Caroline?"

"The last I heard," said Smithy, "was that, of the two Caroline ships, Caroline North comes up on 199 metres and Caroline South on 201 metres. This assumes that nobody's thrown any grappling irons on to them yet. So, both the Caroline stations come within the bandspread range I've just mentioned."

"What about the other pirate stations?"

"Well," said Smithy, "Radio King is on 236 or 238 metres, Radio London is on 266, Invicta is on 306 and Radio City is on 275 metres. I'm again assuming that no boarding parties have been in operation, or that conditions haven't caused them to shift frequency. All these fall outside the normal bandspread range, although they do, of course, appear at points on the ordinary medium wave range where tuning is easier. I should add, by the way, that the nominal function of the bandspread circuits we're talking about now is to ease the tuning in of Radio Luxembourg only, and they are usually referred to as the 'Lux' or 'Luxembourg' circuits. These bandspread circuits inevitably make the high frequency end of the 'Lux' range the same as on the standard medium wave range, and so Radio Caroline, at least, manages to come up on bandspread as well."

"How is the bandspreading done?"
"The simplest arrangement," said Smithy, "consists of inserting capacitance in series with the tuning capacitor sections. You'll encounter this on quite a few receivers." Smithy drew out a pen and sketched a circuit on Dick's notepad. (Fig. 4 (a.).) "This," he remarked, "is a rather simplified circuit because I've omitted the switching for long waves. All that happens is that, when you select 'Lux', you insert a fixed capacitor in series with the oscillator tuning capacitor and its padding capacitor, and a trimmer in series with the aerial tuning capacitor. The fixed capacitor normally has a value around 22pF, and the trimmer a range of about 5 to 50pF."

"Why not have fixed capacitors in both positions?"

"Because," replied Smithy, "the ferrite rod medium wave coil peaks pretty sharply at the high frequency end of the band and it is better to use a trimmer which can take up small variations in circuit and stray capacitances than to rely on the results given by two close-tolerance fixed capacitors. Another point is that, in the oscillator circuit, the most critical variable component, so far as the bandspread range is concerned, is the trimmer across the oscillator tuned circuit. This will have a considerable effect on the position of stations on the dial when you're switched to 'Lux'. The usual approach, when aligning a set of this nature, is to get the oscillator trimmer adjusted correctly with the 'Lux' band selected, because this is where the high frequency end of the medium waveband is opened out and where errors in dial calibration become most noticeable. The next step is to adjust the medium wave aerial trimmer when switched to medium waves. The final operation then consists of selecting 'Lux' again, tuning in Luxembourg or the output of a signal generator set to 208 metres, and peaking up the series aerial trimmer which is brought into circuit on the 'Lux' range. Do all these operations and the set works perfectly well on medium waves, and it's spot-on for Radio Luxembourg."

"I can see now," said Dick, "what you meant when you said that the 'Lux' range must inevitably start at the top end of the medium wave range. Since you're inserting series capacitance into the two tuned circuits, you're only reducing the maximum tuning capacitance. The minimum tuning capacitance is pretty well the same as before."

"Actually," Smithy pointed out, "it's a tiny bit reduced on 'Lux', because the tuning capacitor will still have a small capacitance even when its vanes are fully open. So the extra series capacitance introduced on 'Lux' enables a slightly higher resonant frequency to be given. The high frequency end of the 'Lux' band then becomes a metre or two less than the high frequency end of the medium waveband. However, that's only a minor point."
"Are there any other methods of getting 'Lux' bandspreading?"

"Oh yes," said Smithy. "Another approach, which you'll bump into with some receivers, is a variation on the one I've just mentioned. In this case, however, the tuning is intended to cover only a small range on either side of Radio Luxembourg."

Once more Smithy scribbled out a circuit on Dick's notepad. (Fig. 4 (b).)

"Here," said Smithy, "is the basic idea. Let's tackle the oscillator switching circuit first. Once again, I've omitted any other wave-change switching which may be present, and am only concentrating on the medium wave—'Lux' switching. When the two switches S2 and S3 are in the 'position I've marked 'M', medium waves is selected. The tuning capacitor and its parallel trimmer are then applied, in series with the padding capacitor, C2, to the tuned winding of the oscillator coil. The result is that the medium waveband is tuned in normal manner. The padding capacitor, incidentally, will have a value of the order of 250pF or so. When you switch S2 and S3 to position 'L' you enter 'Lux'-land. What happens now is that trimmer C3 has the major tuning capacitor. You usually align a circuit of this type by first of all doing all the trimming and padding needed for medium and long waves. You then switch to 'Lux', set the main tuning capacitor to a point on the scale as specified by the makers of the set, and adjust C3 to bring in Radio Luxembourg."

"That's what my uncle says." Smithy sighed. One of the major complaints he held against the Fates, was that, out of Dick's multitudinous array of aunts and uncles, one of the uncles was the steward at his club. He always felt that his actions at the club were like those of a servo motor, the inhibiting feedback path being the verbal link from Dick's uncle to Dick."

"Let's," he said hastily, "get back to those Luxembourg tuning circuits."

"Righty-ho," said Dick obligingly. "What's the next one?"

"This one is a pre-set tuning circuit," replied Smithy, once more scribbling on Dick's pad. "And in it's really pre-set. When you press the 'Lux' button in receivers employing this circuit, you get Luxembourg spot on the nose, and the receiver tuning capacitor has no control over tuning at all."

"That's a funny looking arrangement," said Dick critically, as he gazed at the circuit Smithy was sketching out. "This time you switch in a coil as well as a capacitor."

"That's right," agreed Smithy, putting the final touches to the circuit. (Fig. 4 (c).) "Now this shows, once more, the basic idea, and let's start off again with the oscillator section. When switch S2 is set to 'M' you get medium wave tuning in the normal manner by way of the receiver tuning capacitor, a padding capacitor and a trimmer."

Pre-Set Tuning

Smithy paused for a moment, as a thought suddenly struck him. "What's up?"

"It's something that's been niggling away at the back of my mind," said Smithy, "ever since we did that little transistor set on your bench."

"We fixed it O.K., didn't we?"

"Oh yes," replied Smithy. "That's all right. It's just that I'm trying to place this Bailie Vass character. The name seems familiar, but I can't remember where I've seen it."

"In a newspaper?"

"No," said Smithy, frowning thoughtfully. "A magazine, then?"

"That's probably it," replied Smithy, his face clearing. "The only time I get to look at magazines these days is down at the club, so I must have seen that name in one of the mags they leave out for members."

"That club of yours seems to be well organised."

"We pride ourselves," said Smithy proudly, "on catering for most tastes."

"That's what my uncle says." Smithy sighed. One of the major complaints he held against the Fates, was that, out of Dick's multitudinous array of aunts and uncles, one of the uncles was the steward at his club. He always felt that his actions at the club were like those of a servo motor, the inhibiting feedback path being the verbal link from Dick's uncle to Dick.

"I still," said Dick, "don't get it! Why introduce the complication of an extra coil?"

"Because," explained Smithy, "if you want an adjustable tuned circuit to stay exactly on frequency over a long period of time without using expensive components, the best course consists of making the frequency adjustment by means of an iron dust core in a coil rather than by means of a trimmer. I don't suppose you'll remember the old press-button medium and long wave sets which were on the market many years ago, and in which you selected your station by pressing a button. In the oscillator section of these sets, the buttons switched in different iron-cored inductors to vary the oscillator frequency, whereas they switched in different trimming capacitors in the aerial circuit. Trimming capacitors had a long-period stability which was good enough for the aerial circuits, but which was certainly not good enough for the oscillator circuits. The latter used inductors with adjustable iron dust cores, because these cores would stay reliably in position over very long periods of time. I should add, for the sake of completeness, that you would sometimes find the oscillator frequency controlled by trimming capacitors as well, but this was only on the button circuits which selected stations at the low frequency end of the band concerned. At the low frequency end, shifts in oscillator tuning capacitance had less detuning effect, and the trimmers could be low-capacitance components shunted by high value fixed capacitors of high stability."
"Is that," asked Dick, "why the 'Lux' circuit we're looking at now has the 100pF capacitor across the tuned circuit?"

"To a limited extent, yes," said Smithy. "Using the additional coil to tune in Radio Luxembourg confers two advantages. First of all, it enables the pre-set tuning to be carried out by an adjustable iron dust core, with its attendant long-term stability. And secondly, because it reduces the overall oscillator tuning inductance, it enables you to put a reasonably large fixed capacitor across it to swamp out the small self-capacitances which exist in the circuit. These self-capacitances can shift with time, but they don't cause any serious detuning because they are swamped out by the 100pF capacitor."

An Additional Point

"That's neat," said Dick, approvingly. "A most knobby arrangement!"

"It's a very good idea," agreed Smithy. "In the previous circuit we looked at, Luxembourg tuning was achieved with a trimming capacitor, but it was still possible to do some fine tuning with the main tuning capacitor in the receiver. The latter enabled you to get exactly on correct frequency, even if the trimmer circuit drifted a wee bit with time. The present idea has a very high long term stability which means that there's no need to bring in the tuning capacitor at all. Incidentally, when you're setting up circuits of this nature it's always very advisable to do the final trimming on Radio Luxembourg itself. If you finally set up the circuit against a signal generator, you may find that calibration error in the generator causes the adjustment to be a wee bit off the actual station itself."

"What," asked Dick, "about the aerial circuit?"

"It's the same as with the previous arrangement," replied Smithy. "When you go on to 'Lux' you simply disconnect the tuning capacitor and connect a trimmer across the medium wave ferrite rod tuned coil. There may be a small fixed capacitor across this trimmer to give increased long term stability. The trimmer is, of course, adjusted for optimum strength of Radio Luxembourg."

"I see," said Dick. "Incidentally, is it packing up time now?"

"Just on it," replied Smithy, grave consulting his watch.

"Fine," said Dick, rising from his stool. "Then I'm off!"

"Hang on a jiff," said Smithy, "there's a final point I want to clear up.

"But I'll be late," protested Dick, "for our get-together down at Joe's."

"This," said Smithy soothingly, "won't take a moment. You remember I said earlier on that, in some receivers, a fairly high value resistor was switched across the oscillator tuned coil on medium waves to damp it down a bit."

"Yes," said Dick impatiently.

"Well," continued Smithy, "on some sets you'll find a little circuit dodge which combines this resistor with the long wave switching."

Smithy sketched out a further circuit on Dick's pad (Fig. 5), whilst his assistant looked on restlessly.

"This," went on Smithy, "is a very neat circuit and it saves switching contacts. When the switch is set to long waves, the resistor is shorted out, and you have the additional capacitance across the oscillator tuned coil which is needed to cause it to work on long waves. This switching circuit doesn't, by the way, apply only to sets with limited long wave coverage around the Light Programme. It can also be found in sets which have full long wave coverage."

"What happens," interjected Dick hurriedly, "if you switch over to medium waves?"

"When," said Smithy, "you go over to medium waves, you take the short off the resistor. The parallel capacitance switched in on long waves will have a value of the order of 250pF or so and its reactance, at medium wave oscillator frequencies, is then in the region of hundreds of ohms only. This is very much lower than the value of the damping resistor, with the result that the two, in series, apply an impedance across the oscillator tuned coil which is almost entirely resistive. The result is that you get the required damping on medium waves, as would be given by a resistor on its own, without any further switching than is needed, in the first place, to select medium and long waves."

Final Words

"That's a good idea," commented Dick, forgetting his hurry for the moment. "You know, Smithy, there aren't half some crafty schemes stowed away in these little transistor sets."

"There are indeed," agreed Smithy, getting up, "and all we've covered during this little session have been a few facets of the mixer-oscillator stage in the simpler type of receiver. We haven't looked at all at what happens, for instance, with transistor sets which cover the short wavebands or, even more interesting, transistor sets which cover v.h.f./f.m. in addition to the a.m. broadcast bands."

Dick suddenly remembered that valuable time was passing by.

"Take it easy," he chuckled, as he hastily got ready to leave, "you're beginning to get all complicated now!"

"Not at all," replied Smithy, turning off the Workshop switches and holding the door open for his assistant. "All these sets are dead easy when you start examining them in detail. It's only when you try to tackle a complex circuit all at once, instead of in little bits, that you're liable to start getting confused."

With which words, Smithy passed through the door, closed and locked it, and fell in step beside his assistant. And the Workshop fell into silence as the two departed, onto to sample the reckless joys of his club under the eagle eye of the other's uncle, and the second to embark on the even headier delights of exotic Eastern dishes as concocted by the proprietor of Britain's most reactionary Chinese Restaurant.
The Story of the Valve

Part 2

C. H. Gardner

In this second article of his 4-part series, C. H. Gardner outlines the development of the valve from the early battery triode to the all-mains indirectly heated valve.

From the early 1920’s onwards, valve development may, as we saw last month, be considered as progressing along three distinct but complementary lines. Valves had to have improved performance, intensive engineering research was needed for high quantity production, and valves had to be made more reliable and have longer life.

The valve manufacturer thus found it necessary to establish a number of ancillary departments which included laboratories to meet these research requirements. Further departments were devoted to experimental work connected with valve application and laboratories dealing with the control of quality.

Receiver Conditions

The valve manufacturer had to endeavour to visualise the changes in design which would be necessary to deal with the conditions under which receivers might have to operate several years ahead. Some considerable foresight was necessary here, as a lengthy period between drawing board and production was unavoidable. Normally, a few sample prototypes would be made and tried out in the applications laboratory. If results showed promise a trial run of a few hundred would be made to establish that the type could be manufactured in quantity within the required tolerances, and at a cost which would allow of its adoption within the “standard” range. Samples would be provided for equipment manufacturers and these would be accompanied by very full reports from the applications laboratory regarding suitable associated circuitry and component design. Modification of the original design might be called for at any stage of the proceedings, whereupon a further journey through the various steps would be needed before quantity production could proceed.

Even apparently minor modifications to a valve are not such a simple matter as may appear at first sight. The valve is a complex device dependent for its successful operation on a number of factors including mechanical construction, electronics and chemistry. A minor change in any single factor may produce unexpected difficulties in one or more of the others. For instance, a change in the metal from which the grid is made could well change the contact potential between cathode and grid, with a consequent alteration in the valve’s characteristics.

Although quite astonishing performances were being obtained in the early 1920’s by the use of simple triode valves as radio frequency amplifiers their limitations were already being recognised. At that time it was quite common to find a combination of five triodes in a broadcast receiver, the first two operating as r.f. amplifiers, the third as a detector and the final two as audio frequency amplifiers. In many cases the r.f. valves were coupled by tuned (but not ganged) circuits, stability being obtained at the expense of some loss of amplification. There were also a number of “suitcase” portable receivers with frame aerials in the lid of the case, and in which all five valves were resistance-capacitance coupled, their functions being determined by suitably chosen values of components and the bias applied to the valve grids. One was inclined to a suspicion that, as the batteries ran down, the valves did not always continue to function in the intended manner and, instead of having a 2 r.f., detector and 2 a.f. receiver, one had a detector and 4 a.f. set.

A major factor influenced the design of receivers of that period and, in fact, continued so to do for some years following. The public were inclined to judge a
The story of the continual search for cathode materials which could provide both efficiency and long life is one which will be dealt with more fully next month.

The Screen Grid Valve

The inability of the triode valve to provide high amplification of radio frequencies was due to the capacitance between grid and anode, causing an undesirable coupling between the input and output circuits. The first tetrode appeared in 1924, the extra grid operating as a screen, but it was appreciably later than 1924 before the screen grid valve began to appear in any quantity in broadcast receivers. It is interesting to note that two well-known home-constructor kits made available by valve manufacturers in 1928, the Mullard "Master Three" and the Cossor "Melody Maker", specified battery triodes.

With the appearance of the loudspeaker the "power" valve became available. These "power" valves were low impedance triodes with longer grid bases and a rather more heavy anode consumption than other valves. A typical 2 volt power valve would have an anode impedance of 20000Ω, an amplification factor in the region of 7 or 8, and would consume about 10 to 15mA at 100 or 150 volts. Being rather expensive so far as h.t. battery replacement was concerned, they became more popular when the so-called "battery eliminator" appeared on the scene, as this allowed the h.t. supply to be obtained from the electric light mains.

A competitor to the "power" valve arrived in the form of the pentode, this having an extra grid, connected to cathode, between the screening grid and the anode. The extra grid overcame an undesirable feature of the screen grid valve by suppressing secondary emission from the anode.

Pentode valves were designed in two types, one for r.f. amplification and the other for use as an output valve. The output pentodes had a much shorter grid base than the triode output valves but gave a much higher degree of amplification. The "quality" enthusiast of that time was apt to suggest that "quality" could be obtained only by the use of triodes in the output stage, a fact which may come as rather a shock to the user of modern hi-fi equipment. But then there were also those who maintained that real "quality" could be obtained only from a crystal detector and a pair of headphones and, at a later period, those who affirmed that only a battery set could provide good reception, mains-driven sets being useless for high "quality"!

The "All-Mains" Valve

Mention must next be made of the indirectly heated "all-mains" valves which made their appearance in the 1928–1930 period. In the early versions of these valves the heater was a spiral of wire inserted in an insulating tube which, in turn, was inserted in a nickel cathode tube sprayed with an emissive powder. They were made to operate at 4 volts, 1 amp, the heater supply being taken from a suitable winding on the mains transformer which also provided the necessary h.t. supply. The rigid cathode made it possible to reduce the clearance between cathode and grid, and thus materially improve the performance of the valve. As the h.t. supply was also taken from the mains, higher anode currents and voltages could be used. This, in turn, required reconsideration of cathode efficiency in order to obtain the requisite...
emission without unduly high heater wattage.

Thus, a whole new series of problems arose, a great many of which were concerned with the design of the heater and cathode assembly. The use of indirectly heated valves provided opportunity for numerous developments in circuit design and many such developments, in turn, made more stringent demands on the valves. This is a "battle" which has carried on for more than 30 years and which still continues. Some of the major difficulties encountered in this battle of progress will be the subject of the next article.

(to be continued)

Cover Feature

This article describes a simple design for the 160 metre band which combines efficient operation with low cost. Many of the components are non-critical and may already be on hand, and the author fully discusses suitable types and alternatives. For this reason, such components are not specified by make and type number in the Components List. The design includes a modulation amplifier suitable for use with a carbon microphone or, by employing an external pre-amplifier, a crystal microphone. A further alternative is a separate modulation amplifier, for which details will appear in next month's issue.

Readers are reminded that this transmitter must, of course, be operated without the requisite Post Office licence.

VFO Top Band Phone Transmitter

FREDERICK SAYERS

Anode current is shown by the 100mA meter and, with 250V reaching the p.a., 40mA corresponds to the maximum permitted input of 10 watts. L3, in conjunction with VC2 and the 2-gang capacitor VC3, forms the customary pi-output circuit, which will load directly into many aerials. For Top Band, an end-fed wire is often used.

The modulator is extremely simple, and was adopted after some experiments with other circuits. The 6CH6, V3, has very high gain, and was found to give adequate results on its own. The bias developed across Re is about 4.5V, and this was suitable for the carbon mike employed, and should suit most carbon microphone inserts. T1 is a 50:1 or similar carbon microphone transformer.

It will be clear that the r.f. section can be used with a more elaborate modulator, if wanted. Notes on the use of a crystal microphone are given later, and a push-pull modulator will be described in next month's issue.

Choke modulation is used, the inductor LFC1 being a mains pentode type output transformer, with the speaker secondary unused. With this type of circuit, overmodulation which would break the carrier is impossible, and this was felt to be an advantage. Reports on speech quality and modulation depth are good. If an attempt is made to use...
too much audio, this causes distortion, but not overmodulation which would break the carrier.

Transmit/Receive switching is included, and is provided by the 4-pole 2-way switch, S1. Section S1(a) transfers the aerial from the transmitter pi tank to the receiver aerial socket. Section S1(b) short-circuits the receiver aerial circuit to chassis in the Transmit position, to avoid overloading the receiver. H.T. is applied to the v.f.o., modulator and p.a. by switch sections S1(c) and S1(d). The "Net" switch, S2, applies h.t. to the v.f.o. only, so that the transmitter can be adjusted to the receiver frequency, or netted on an incoming signal. Resistor R10 is included to obviate the slight sparking at the switch which would otherwise occur when applying h.t. to C6.

Power Supply
The h.t. secondary of the mains transformer, T2, is best rated at 100mA to avoid undue drop in voltage. An h.t. secondary giving 250V, 275V or 300V may be used. There is some loss of voltage in the rectifier, in R8, and in LFC1, causing a reduction in p.a. anode voltage. The d.c. resistance of the speaker transformer primary, LFC1, was 300Ω, dropping over 25V when passing the anode current of the 6CH6 and the anode and screen currents of the 6BW6. In tests with a 250–0–250V transformer, the p.a. received 200V, corresponding to an input of 8W at 40mA. Loading to 50mA at 200V, for 10W input, gave virtually no increase in r.f. output. Good results were obtained with the 8W input. Nevertheless, it is better to have a more adequate voltage available, so a 300–0–300V transformer is preferred. Should a better component, with less d.c. resistance, be to hand for LFC1, this will avoid some of the drop in voltage. R8 can also be replaced by a smoothing choke of lower d.c. resistance, if available, and this will allow a little more voltage on the p.a. So if a 250V 100mA mains transformer is to hand, it
Components List

Resistors
(All fixed values ½ watt 10% unless otherwise stated)

| R1 | 56kΩ |
| R2 | 3.3kΩ |
| R3 | 100kΩ |
| R4 | 100Ω |
| R5 | 20kΩ |
| R6 | 100Ω |
| R7 | 5.6kΩ 1 watt |
| R8 | 100Ω 2 watts |
| R9 | 100kΩ 1 watt |
| R10| 27Ω |

Capacitors

| C1 | 40pF 2% silver mica |
| C2 | 1,000pF 2% silver mica |
| C3 | 1,000pF 2% silver mica |
| C4 | 0.05μF ceramic |
| C5 | 0.01μF ceramic |
| C6 | 200pF silver mica |
| C7 | 0.01μF ceramic |
| C8 | 200pF silver mica |
| C9 | 2,000pF ceramic |
| C10| 5,000pF 1kV wkg. mica |
| C11| 0.01μF ceramic |
| C12| 5,000pF ceramic |
| C13| 50μF 12V wkg. electrolytic |
| C14| 16μF 450V wkg. electrolytic |
| C15| 8μF 450V wkg. electrolytic |
| C16| 32μF 450V wkg. electrolytic |
| VC1| 75pF variable |
| VC2| 500pF variable |
| VC3| 500+500pF variable, two-gang |

Inductors

| L1, L2, L3 | See text |
| RFC1,2 | 2.5mH chokes |
| RFC3 | 2.5mH choke (60mA) |
| LFC1 | mains pentode power transformer primary |
| T1 | 50:1 (or similar) carbon mic. transformer |
| T2 | Mains transformer; secondaries: 300-0-300V 100mA, 6.3V 1.5A (minimum), 5V 2A (minimum). See text |

Valves

| V1 | 12AT7 |
| V2 | 6BW6 |
| V3 | 6CH6 |
| V4 | SR4GY |

Switches

| S1 | 4-pole 2-way rotary (Transmit-Receive) |
| S2 | s.p.s.t. rotary or toggle (Net) |
| S3 | s.p.s.t. rotary or toggle (Mains on-off) |

Valveholders

| 1 B9A holder with skirt and 2in screen |
| 2 B9A holders, skirts optional |
| 1 octal holder |

Meter

| 1 moving-coil meter, 100mA |

Miscellaneous

| 8 x 3in “Universal Chassis” runner (Home Radio (Mitcham) Ltd.) |
| Aluminium sheet for chassis |
| Aluminium sheet or hardboard for panel |
| Stand-off insulator |
| Knobs, as required, including large knob or dial for v.f.o. |

is 1000pF in all, this being obtained by wiring both sections of a 500pF 2-gang tuning capacitor in parallel. A 3-gang capacitor is equally satisfactory, and may in some cases be an advantage. These capacitors are bolted to the panel, and grounded to the chassis by short leads to soldering tags.

A meter reading 100mA full-scale is convenient, but a more sensitive meter can easily be shunted, if to hand. Leads from the meter pass through the chassis to RFC3 and LFC1. It is not necessary to read grid current, once this has been checked when first testing the transmitter.

The tank coil L3 was wound on a ribbed former, and fixed to VC3 by a bracket. See Fig. 2. It is 1¼in in diameter, and has 55 turns of 24 s.w.g. wire. A 1¾in diameter smooth former would be perfectly satisfactory, also with 55 turns. If a somewhat similar coil is to hand, it will probably prove suitable.

V.F.O. Box

The v.f.o. box is 2¼ x 3¼ x 3in high. It is very easily made by purchasing a “Universal Chassis”
runner 8in x 3in (Home Radio, Mitcham) and cutting two 90° sections from the flanges, 2¼in from each end. Two right-angle bends can then be made, to obtain the two sides and rear of the box. After wiring, the box is bolted to the chassis and panel, and closed on top by a piece of aluminium, 2¼ x 3½in, held in place with four self-tapping screws. This forms a rigid assembly. If the panel is not metal, do not forget the screen between panel and box, as mentioned.

The v.f.o. box is not attached to the panel and chassis until the 12AT7 valveholder has been wired. Colour coded leads pass down through a ¾in hole in the chassis, and are taken to the appropriate points under the chassis when the box is finally bolted in position. One lead is from tag 6 (V₁(a) anode) and another from tag 1 (V₁(b) anode).

The final lead is from tag 9 (heater). The dotted line in Fig. 1 shows which components are in the v.f.o. box.

Fig. 3 illustrates the v.f.o. wiring. Connections are short, as movement or vibration will tend to cause shifts in frequency. Various chokes were tried for RFC₁, and a miniature transistor type choke (2.5mH) was finally adopted. The usual type of 2.5mH short wave choke having 4 or 5 sections is equally satisfactory. A small “all-wave” r.f. choke was also found suitable. The choke must be effective at 1.8–2 Mc/s, and without resonances in this band. This is not a very difficult requirement to meet.

Various coils were tried for L₁, and eventually a surplus medium wave coil, with some turns removed, was chosen. No pre-set capacitor is needed in the v.f.o. Final calibration is only made when the transmitter is finished, and has been left running for at least fifteen minutes.

V.F.O. Calibration
V.F.O. calibration can be done with the aid of a receiver and 100 kc/s crystal marker. The v.f.o. signal is coupled into the receiver by placing the receiver aerial lead near C₃. With VC₁ closed, the signal will probably be heard fairly near the bottom of the medium wave band, if a medium wave coil has been connected. The slug of L₁ should be adjusted to a mid-way position, so that subsequent fine changes to inductance can be made. Turns are then removed from L₁ until the v.f.o. signal is heard near 1.8 Mc/s. The coil can then be properly wired, and the v.f.o. box cover may be screwed on.

The receiver is then tuned to the 100 kc/s crystal harmonic which corresponds to 1.8 Mc/s, and the core of L₁ is rotated until the v.f.o. signal gives zero beat with the harmonic, with VC₁ nearly
closed.* The v.f.o. dial or scale is then marked for 1.8 Mc/s. The receiver is next tuned to 1.9 Mc/s by reference to the 100 kc/s crystal, and the v.f.o. tuned again to zero beat, and calibrated for 1.9 Mc/s. This is repeated for 2 Mc/s. Not quite the full 180-degrees rotation of VC1 will be employed.

For the 0.05 Mc/s marks, tune the receiver to the crystal harmonic which falls on 3.7 Mc/s, and adjust the v.f.o. to 1.85 Mc/s, so that its second harmonic is at zero beat with the crystal. Mark the scale, and repeat for 1.95 Mc/s. The 0.01 Mc/s marks between 1.8 Mc/s and 1.85 Mc/s can be estimated with sufficient accuracy, as can those up to 2 Mc/s.

If a friend has a calibrated v.f.o., this may be used to calibrate the Top Band transmitter v.f.o., by comparing signals with a receiver. An accurate heterodyne frequency meter, or similar apparatus will also be satisfactory.

For a home-wound v.f.o. coil, 95 turns of 34 s.w.g. enamelled wire, side by side on a ¼in diameter cored former, can be used. Turns must be sealed to prevent movement.

A large knob was found satisfactory for VC1, but a small reduction drive could be added. This capacitor should be free from wobble, and of good construction.

Under the Chassis
Fig. 4 shows the under-chassis wiring. Heater and h.t. circuits are run close to the chassis. For the “Net” and mains circuits, on/off toggle switches are equally satisfactory instead of the rotary types shown.

Leads to C9 and RFC3 are clear of the chassis, and well removed from C10. With the layout shown, the p.a. is perfectly stable. Wiring should be reasonably short and direct.

When the 6BW6 holder has been wired, a check can be made for grid current, if wished. Alternatively, this test can be left until all construction is finished. The valve should be in place, but no anode or screen-grid voltage should be present. This will occur if the Transmit/Receive switch is left at “Receive” and the “Net” switch is closed. A meter is then inserted between R5 and the chassis.

In the prototype, L2 was a medium wave coil, broadly resonant with stray capacitance to about 1.9 Mc/s. It is only necessary to set the v.f.o. to about 1.9 Mc/s, and rotate the core of L2 until a slight rise in grid current shows resonance. It was found that grid current remained at about

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* This adjustment may be made via the ¼in hole through which the wires to the v.f.o. pass. Alternatively, a small hole may be provided for this purpose in the cover plate.—Edtorox.
Above chassis view of transmitter

2mA throughout the whole range of the v.f.o.

If grid current is too high (say over 2½-3mA) the resistors at R2 and R3 can be increased in value. Should there be plenty of grid current, RFC2 may be omitted, with no loss of efficiency. If grid current is too low (say under 1½mA) there may be insufficient h.t. applied to the v.f.o. or buffer, or L2 may not have been tuned to the band. Small changes in grid current do not produce any significant change in r.f. output, provided the grid current is around the 2mA mark. This represents 40V bias developed across R5.

Once grid current has been checked, R5 can be connected to the chassis, and the meter removed. When operating, it is only necessary to monitor anode current, with the panel 100mA meter.

Modulator

This is of the simplest possible type, with d.c. for the carbon microphone developed across R6, thereby avoiding any need for a battery. If it is wished to cut top somewhat, a 0.05µF or 0.01µF capacitor may be connected from the 6CH6 anode to chassis. This depends to some extent on the user's voice, and the microphone. The telephone insert type of carbon microphone can provide quite acceptable speech quality.

If a crystal mike is preferred, it will be necessary to provide two stages of amplification between this and the 6CH6. While experimenting with an inexpensive crystal microphone, the circuit in Fig. 5 was found satisfactory. It will be realised that any audio amplifier able to provide some 5 watts or so can be employed as a modulator. The modulator can then run from its own power supply. The speaker output transformer of the audio amplifier must be disconnected, and a modulation transformer substituted. The secondary of the modulation transformer is connected to the points X-X in Fig. 1, and T1, V3, LFC1, and the bias components C13 and R6 taken out of circuit. If the p.a. is loaded to a total input (anode and screen grid) of about 45mA, at 250V, its modulating impedance is about 5,500Ω. A 1:1 ratio transformer will do this when using an audio amplifier with output valves having an optimum load of about 5,000 to 6,000Ω or so. A small 5-watt push-pull amplifier is ideal.

When ample h.t. voltage is available, and a single valve is used as a choke coupled modulator, as in Fig. 1, modulation depth can be increased by introducing a resistor at point Y of Fig. 1. A 2µF capacitor is connected across the resistor. This resistor can normally be between 1kΩ and 2kΩ in value.

Aerial and Loading

A Top Band dipole would be about 246ft long, and is seldom possible. So shorter, end-fed aerials are generally employed. These may often be operated successfully directly from the transmitter, an approach which has the merit of simplicity. In general, the longer the aerial, the better will results be. Aerials actually employed by the writer include 45ft sloping from the operating room to a pole on a chimney; 100ft and 120ft wires in the usual inverted L; and 185ft with a 45ft down-lead. All these gave good results. Signal strength is improved when the wire is reasonably long and well clear of ground, walls, etc. An earth connection should be taken to the transmitter chassis. With relatively short end-fed aerials, the efficiency of the earth has quite a large effect on the strength of the radiated signal.

When the transmitter is to be put on the air, a clear channel should be sought with the receiver. The “Net” switch is then closed, and the v.f.o. tuned to the receiver frequency. There will normally be enough stray coupling to the receiver aerial circuit for this to be done easily. The “Net” switch is then returned to its “Off” position, and is not required for normal transmitting and receiving.

VC3 should be closed, and the equipment
switched to “Transmit”. VC2 is then rotated to find the dip in anode current, as shown by the meter. The dip may be far too low, representing insufficient input to the p.a., so VC3 is opened, VC2 being re-adjusted as necessary. This is continued until the p.a. draws the required anode current. VC2 is always tuned for minimum anode current.

An initial test can be made by loading the transmitter into a 15W domestic lamp (200/250V) which should light with fair brilliance. If the signal is monitored with a receiver having a loudspeaker avoid feedback to the microphone, or howling will arise.

Very short aerials will not present an impedance which will load the transmitter. This problem is best overcome by using one of the usual methods, such as placing a loading coil in series with the aerial, or building a 160 metre tuner, and tuning the aerial against ground. The loading coil is particularly simple to use. It may be 2 to 4in in diameter, and should be wound with 16 s.w.g. or other stout wire, to avoid unnecessary losses.

If an 80 metre dipole, or other co-axial or twin-feeder dipole for a high frequency band is available, this will often work quite well as a Top Band aerial. The two conductors are joined, and the whole worked against ground, as for the end-fed wire. It is also quite easy to try vertical wires, whips, and other aerials electrically resembling those used for mobile work. In some cases where it is wished to work into a low impedance with a minimum of trouble, it may be worth adding extra capacitors in parallel with VC3, or modifying the turns on L3.

It is worth remembering that quite considerable distances are covered by Top Band mobile transmitters, where the type of aerial is severely restricted. An equivalent, or much better, aerial should generally be possible at any fixed location.

Next Month
In next month’s issue, a push-pull modulator suitable for use with this transmitter will be described.

New Edge Contact-Cooled Selenium Rectifiers
A number of new edge contact-cooled selenium rectifiers are now available from Westinghouse Brake and Signal Co. Ltd. They utilise high current density elements which allow improved current ratings. All of these units are fully encapsulated and are ideally suited for electronic or other equipment subject to damp or humid conditions.

Single-phase bridge, centre-tap, voltage-doubler and half-wave units are available. In full-wave circuits maximum current ratings are 180mA and 250mA and in half-wave and voltage-doubler circuits the ratings are 90mA and 125mA.

The following are representative of the range available:
Type EC401, rated at 250 volts 180mA output in single-phase bridge circuit; case size 2½ x 1½ x 3in. Type EC403 rated at 250 volts 250mA output in single-phase bridge; case size 2½ x 1½ x 3in. Type EC402 rated at 250 volts 90mA in half-wave; case size 1½ x 1½ x 3in.
An HFE Tester for Power Transistors

By A. THOMAS

This piece of test equipment enables HFE measurements to be carried out on power transistors at high currents. The parameter HFE is the common emitter large signal current gain of the device, \( H_{FE} = \frac{i_C}{i_B} \).

The normal method of making a HFE measurement is to measure the current required in the base for a given collector current, then \( H_{FE} = \frac{i_C}{i_B} \). To be able to carry out d.c. tests with this method, the transistor under test would have to dissipate a lot of power and, due to heating, would need to be mounted on a heat sink. This is not a convenient method just to test the transistor. When this method is used, therefore, it is carried out with pulses of short duration such that the mean power is low.

The test circuit to be described here uses a modified form of pulse test such that the base is fed with constant current pulses 200 microseconds wide at a repetition rate of 45 pulses per second. The collector current is then measured and displayed on a meter calibrated in units of HFE. This method requires less circuitry than the pulse method described earlier. The mean current under these conditions is:

\[
\frac{\text{Pulse width}}{200 \times 10^6} \times \frac{1}{22 \times 10^3} = 0.9\% \text{ I peak}
\]

Circuit Description

In Fig. 1, transistors TR1 and TR2 form a free running multivibrator giving a square wave output at 45 c/s. The frequency determining components are R3, C1, and R4, C2, and the frequency is given by:

\[ R_3, C_1 = 0.7t, \text{ where } t \text{ is one complete cycle time.} \]

That is, \( t = \frac{f}{45} = 0.022 \), where \( f \) is in c/s, \( t \) is in seconds, \( R \) is in M\( \Omega \), and \( C \) is in \( \mu F \).

The output from the multivibrator is a negative-going square wave, this being fed into the base of an inverter stage TR3. The output from TR3 is differentiated by C4 and R8, and the resultant positive and negative-going spikes are fed to a diode D1, whence the negative-going spike is passed to a monostable trigger given by TR4 and TR5. The positive-going spike is stopped by the diode.

The monostable trigger is normally in the state where TR4 is cut off and TR5 is conducting. The negative-going spike at the base of TR4 causes TR4 to start to conduct. Due to the collector voltage of TR4 falling towards earth, the base of TR5 follows via capacitor C3 and TR5 starts to cut off. Due to TR5 collector rising towards negative, TR4 is driven harder on via the 8.2k\( \Omega \) collector-to-base resistor, R12. The 220k\( \Omega \) emitter resistor, R13, assists in this positive feedback. The circuit will stay in the state of TR4 conducting and TR5 cut off until C3 capacitor charges negative via R14. When the base of TR5 reaches a certain voltage, TR5 will start to conduct and the circuit will rapidly switch to its normal state.

The output from the monostable trigger will be a negative-going pulse at TR collector. The width of the pulse depends on the values of C5 and R14, and is determined as follows: pulse width \( t = 0.7 C_5 R_{14} \), where \( t \) is in seconds, \( C \) is in \( \mu F \) and \( R \) is in M\( \Omega \). The 200\( \mu s \) square pulse at 45 pulses per second is fed from the monostable trigger via the 1\( \mu F \) capacitor C6 to the emitter follower stage, TR6. The pulse amplitude at the emitter of TR4 is 5V, this is fed via the 100\( \Omega \) resistor, R17, to the base of the transistor under test. The input resistance of the transistor under test is low compared with the 100\( \Omega \) resistor, therefore virtually a constant current (50mA) flows, independent of the transistor under test.

The transistor under test has, as a collector load, the 2\( \Omega \) resistor R18. This enables currents up to approximately 5 amps to flow, and the collector voltage drops according to \( E = IR \), where \( R = 2 \) and \( I \) is the collector current. Therefore it can be seen that the collector current is directly proportional to the pulse of voltage appearing at the collector.

The voltage pulse at the collector is fed via the 10\( \mu F \) capacitor C7 to a peak-reading voltmeter, where the 1\( \mu F \) capacitor, C8, charges via the diode to the peak of the voltage pulse. This is displayed

1 For the record, HFE is elsewhere defined as "static forward current gain in common emitter connection."—EDITOR.
Fig. 1. The circuit of the transistor tester

Components List

Resistors
(All resistors 1/2 watt 5% unless otherwise stated)

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<th>R1</th>
<th>R2</th>
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Capacitors

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<th>C7</th>
<th>C8</th>
<th>C9</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.47µF paper</td>
<td>0.1µF paper</td>
<td>0.02µF paper</td>
<td>1µF paper</td>
<td>10µF electrolytic 12V wkg.</td>
<td>1µF paper</td>
<td>2,000µF electrolytic 12V wkg.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Semiconductors

TR1 to TR6, TK28 (Standard Telephones & Cables)

D1,2,3 OA5

Switch

S1 s.p.s.t., push-to-make

Fuse

F1 ½ amp fuse

Meter

M1 0–100µA, moving-coil meter

Battery

B1 10.5 volt battery (may be given by two 4.5 volt batteries and one 1.5 volt cell)

Power Supply

The power supply may be mains driven, but it was found more convenient to use batteries contained in the cabinet of the tester. The normal drain is 0.5 watt from the 10.5 volt batteries, with the test button depressed. It was found more convenient to use batteries contained in the cabinet of the tester. The normal drain is 0.5 watt from the 10.5 volt batteries, with the test button depressed. It was found more convenient to use batteries contained in the cabinet of the tester. The normal drain is 0.5 watt from the 10.5 volt batteries, with the test button depressed.
operated, is 0.017 amp, and \( C_9 \) the 2,000\( \mu F \) capacitor, supplies the high current pulses for 200\( \mu s \). The capacitor \( C_9 \) should be connected as shown in the circuit diagram, that is, directly across \( R_{13} \) and the emitter connection of the transistor under test. The end of life of the batteries occurs when the terminal voltage is down to 9 volts with a load of 0.017 amps. The tester may be used after this point has been reached, but the accuracy is impaired. The battery voltage may be monitored by taking a connection from the junction of \( R_{10} \) and \( D_3 \), via a switch, to the negative terminal of the battery. The meter will then read just over full scale, for a battery voltage of 10.5, when the switch is operated.

Waveforms are shown at points throughout the tester in Fig. 2, and the letters in Fig. 2 refer to the points marked on the circuit diagram.

---

**A QUALITY MULTIMETER (continued from page 171)**

A common, non-linear scale will be needed for alternating current, and a separate non-linear scale for the 3 volt a.c. range. A common scale will serve for all four resistance ranges, which should be checked either against close-tolerance resistors of known value or marked from the scale given in Fig. 18. The 50\( \mu A \)/250mV ranges will need individual scales.

If only a small scale meter is used to make up the multimeter described, it will be found convenient to make up a conversion chart for the individual ranges.

---

**Constructional Details**

The circuit was constructed on an 8 x 4.8in piece of Veroboard with 0.2 x 0.1in hole matrix. The Veroboard was then mounted behind a panel which had the meter, transistor holder and push button switch, mounted on it. The panel was fixed to a pressed steel cabinet with a sloping front. The batteries and \( C_9 \) capacitor were mounted in the cabinet and leads taken to the panel.

**Use of Tester**

The tester is indispensable for the quick testing of power transistors. If a test is required on a transistor already mounted in a piece of apparatus, then three leads may be taken from the tester to the transistor to be tested, ensuring beforehand that any transistor electrode is disconnected if it embarrasses the test in any way. Normally only the collector and base connections need to be disconnected, and in some cases where there is a high value base resistor (greater than 20\( \Omega \)) only the collector.

Carrying out tests in this manner does not give accurate results, but it does check that the transistor is working and may even be used for comparing matched pairs whilst in circuit.

If it is necessary to test transistors with a \( H_{FE} \) greater than 100 then the circuit would have to be modified by reducing the base drive to 25mA (by doubling the value of \( R_{17} \)). This would then give a meter scale of 0–200.

If no reading is shown on the meter and it is known that the tester is working, then the transistor under test must be open-circuit or short-circuit. If it is short-circuit then the fuse should blow.

Low and medium power transistors should not, in general, be tested on this instrument. Nevertheless, the writer has checked a large number of low power transistors, the meter giving results between 5 and 10 (\( H_{FE} \)). As \( H_{FE} \) figures are not generally required for low power transistors, the only reason for testing them on this instrument would be to check that they are working.

The circuit described here has been constructed and in use for two months. No faults have occurred and accurate results have always been given.

---

**Fig. 2. The waveforms appearing at the points identified by letters A to F in Fig. 1**

---

**Scale Resistance Reading of Each Range is as it Should Be.**

(8) Finally, when all of the wiring and setting up has been completed, again check that the calibration of all ranges is correct, and then proceed to mark the full ranges on the scale. Common, linear scales will suffice for the d.c. volts and current ranges, and also for all but the lowest alternating volts range.

---
In last month's issue we continued our examination of the triode by describing how it may be coupled to a loudspeaker by way of a step-down transformer of suitable ratio and primary current rating. We also discussed the few advantages and many disadvantages given by employing a transformer to provide coupling between two a.f. amplifier triodes. We next examined the important point that the alternating voltage at the anode of a triode is 180° out of phase with that applied to the grid, and we finished by seeing how the triode may be used as a cathode follower, as a phase splitter and as a grounded grid amplifier. We shall now turn our attention to several more basic attributes of the triode, including the grid current bias circuit and the grid leak detector.

In a triode the grid and cathode form an effective diode, with the grid functioning as the anode. Because of this, the grid may assume a contact potential in just the same way as does the anode of a diode. The presence of this contact potential may be similarly checked with the aid of a high resistance voltmeter. The contact potential makes it possible to operate some triodes intended for a.f. voltage amplification in the circuit shown in Fig. 316.

At first sight it would appear that the triode in Fig. 316 is operated at zero bias, but it is, in practice, biased by the contact potential on its grid. To ensure that the contact potential remains sufficiently high it is necessary to give the grid resistor a large understanding:

By W. G. Morley

Grid Current Bias

When, in earlier articles, we dealt with the diode we saw that this exhibits a phenomenon which is usually referred to as "contact potential". As was explained in the previous article, contact potential in a diode results in the same effect as would be given by a small internal e.m.f. having a polarity such that anode current still flows when the anode voltage is zero. Anode current only falls to zero when the anode is made slightly negative to counteract the contact potential. The fact that a negative anode voltage results in zero anode current infers that the anode voltage has then become equal to the contact potential and that the anode would therefore, in the absence of external connections, exhibit a potential which is negative of the cathode. This assumption is, in fact, true and it may be demonstrated quite readily in practice by connecting a high resistance voltmeter across the anode and cathode of an indirectly heated diode whose cathode is at emitting temperature. The voltmeter will show that the anode is negative of the cathode, the actual voltage indicated ranging from some 0.1 to 0.6 volts according to the diode type and the resistance of the voltmeter.

In Fig. 316 the triode remains biased by the contact potential for small signal inputs. Since the contact potential causes the grid to be negative of cathode a small current flows through the grid resistor. This is very low in value, being much less than 1µA.

The current in the grid resistor is modified by the input a.f. voltage, and if the latter is made sufficiently high in amplitude the positive peaks of the signal may cause positive grid current to flow, whereupon the grid acts in the same manner as the anode of a rectifier diode. A different method of biasing now takes over and this may be understood by reference to Fig. 317 (a), in which we have an alternating voltage generator, a capacitor and a diode. A different method of biasing now takes over and this may be understood by reference to Fig. 317 (a), in which we have an alternating voltage generator, a capacitor and a diode.

Footnote 2, in "Understanding Radio" in the August 1965 issue, referred briefly to the small currents which could flow in the grid circuit even when the grid is negative of cathode. Such currents are due to the effect we are now discussing.

Footnote 2, in "Understanding Radio", in the August 1965 issue, referred briefly to the small currents which could flow in the grid circuit even when the grid is negative of cathode. Such currents are due to the effect we are now discussing.
Fig. 316. A triode a.f. amplifier with grid current bias. The value of 10MΩ shown for the grid resistor is typical in this type of circuit.

At once be seen that Fig. 317 (a) resembles the half-wave rectifier circuits we have previously examined, and that the capacitor will become charged to the peak value of the alternating voltage. Due to the manner in which the diode is connected, the right hand plate of the charged capacitor will be negative and the left hand plate positive. So far as the voltage on the diode anode, relative to cathode, is concerned, the same result would be given by replacing the capacitor with a battery having the same polarity and voltage, as is shown in Fig. 317 (b). The battery and alternating voltage generator are in series and the voltage at the diode anode relative to cathode will still be the same if we take the further step of transposing the battery and generator, as in Fig. 317 (c).

If we finally replace the diode by the grid and cathode of a triode, as we do in Fig. 317 (d), we may see that, due to the charging of the capacitor, we have obtained the same effect as would be given by inserting a grid bias battery in series with the generator in the normal manner! There is, however, the important difference that the voltage of the “battery” in Fig. 317 (d) is the same as the peak value of the applied alternating voltage, with the consequence that the bias voltage increases when the input alternating voltage increases.

Another way of looking at the circuit of Fig. 316 is to say that the grid-cathode diode conducts on positive half-cycles of the applied alternating voltage, causing the capacitor to charge to peak potential. The average value of the applied alternating voltage then goes sufficiently negative of the diode cathode to ensure that only the positive peaks are at cathode potential, the remainder of the waveform being negative of cathode.

Fig. 316 differs from the diode circuits of Fig. 317 by having a resistor between the grid and cathode. This resistor allows the capacitor to discharge (via the source of alternating voltage) when the amplitude of the alternating voltage decreases. The rate of discharge may, in practical circuits, be quite slow. In a typical a.f. amplifier circuit the capacitor could be a coupling component having a value of 0.01µF, whilst the grid resistor would be of the order of 10MΩ. Ignoring any internal resistance in the
source of alternating voltage, these figures give a
time constant which is as long as 0.1 second.

We may now sum up the biasing action of the
circuit of Fig. 316. For low input voltages, the
triode is biased by contact potential. As input
voltage increases, the rectifying action of Fig. 317 (a)
takes over, whereupon bias varies according to the
amplitude of the input signal. Small changes in bias
voltage do not have any serious effect on the
amplification provided by the valve, and so this
method of working gives quite acceptable results
provided the input signal amplitude is not excessive.
The method of bias under discussion is described
as grid current bias, or grid leak bias. A grid leak,
it may be added, is a grid resistor which, by allowing
a current to "leak" through it, enables a grid bias
voltage to be provided.

Grid current bias should only be used with valves
when the maker's technical literature sanctions this
method of operation, and it is usually preferable to
keep input voltage amplitude below about 1 volt
peak to avoid excessive distortion.

A.M. Detector Amplifier

In two preceding articles in this series we
examined typical amplitude modulation detector
circuits employing diodes. We shall next turn our
attention to the manner in which an a.f. voltage
amplifier valve may be coupled to the output of
such detectors.

Fig. 318 (a) illustrates a diode detector circuit
which was described in one of the previous articles,
and which would be capable of operating on the
medium or long wave bands. Its functioning may
be briefly summed up in the following manner.
Resistor R1 is the diode load, whilst R2 and C2
form a low pass filter to attenuate the radio
frequencies present in the detected output from the
diode. Looking upon the diode as though it were
a half-wave rectifier, C1 functions in the same way
as a reservoir capacitor, the average a.f. voltage
across this component being nearly equal to the
peak value of the applied r.f. signal. Capacitor C3
has a low reactance at audio frequencies, and its
function is to prevent the direct voltage which
appears across the diode load from appearing in the
output. At the same time, resistor R3 ensures that
the average voltage on the right-hand plate of C3
is at chassis potential, so that the a.f. signal appearing
on that plate swings positive and negative of chassis
by equal amounts.

A triode amplifier valve may be added as shown
in Fig. 318 (b). In this diagram R3 now serves also
as grid resistor for the triode, and the valve is biased
by a conventional cathode bias circuit. An amplified
version of the detected signal appears at the anode
of the triode.

An alternative method of biasing the triode is
shown in Fig. 318 (c). In this instance a bias
battery (or other source of bias voltage) is interposed
between R3 and chassis. R3 serves once more as

3 In the May and June, 1965, issues.
4 This circuit appeared, as Fig. 283 (c), on page 744 of the June
1965 issue.

---

grid resistor and it ensures that the signal on the
right-hand plate of C2 swings positive and negative
of the bias voltage.

A variation on the diode circuit of Fig. 318 (a)
is that shown in Fig. 319 (a). This is typical of
the detector circuit appearing after the last inter-
mediate frequency transformer in a superhet, and a
triode amplifier may be coupled up to it in the
manner shown in Fig. 319 (b). As will be seen R3
is, once again, the grid resistor for the triode. The
alternative bias arrangement shown in Fig. 318 (c)
may similarly be used.

The triode could also employ grid current bias,
as in Fig. 316 of the present article. In this instance
the circuit would be the same as Figs. 318 (b) and
319 (b), but with the cathode bias components

5 This circuit appeared, as Fig. 285 (a), on page 745 of the June
1965 issue.
removed and the triode cathode connected directly to chassis. \( R_3 \) would, this time, have the high value associated with grid current biasing.

Either \( R_1 \) or \( R_3 \) in any of the circuits shown may be made a volume control, as described previously. If the triode has grid current bias, only \( R_1 \) can be made a volume control. \( R_3 \) cannot be a volume control with grid current bias because of the necessity of maintaining a high resistance between the grid and cathode of the triode.

The Grid Leak Detector

An interesting and frequently encountered detector circuit employs a single triode. This is commonly described as the grid leak detector and it takes advantage of the fact that the grid and cathode of a triode function also as a diode.

The basic grid leak detector circuit is shown in Fig. 320 (a). In this diagram, the modulated radio frequency voltage developed across a tuned circuit is applied, via a capacitor and parallel resistor, \( C_1 \) and \( R_1 \), to the grid of the triode. If the grid and cathode are looked upon as forming a diode, a diode detector circuit is given by this diode, \( R_1 \), and the tuned circuit. \( R_1 \) and \( C_1 \) have the same values as would apply in a normal diode detector circuit, whereupon \( R_1 \) becomes the diode load resistor, with \( C_1 \) as the “reservoir capacitor”, and the detected a.f. voltage appears across these two components. The coil in the tuned circuit offers negligible impedance at audio frequencies, whereupon the detected a.f. voltage becomes applied to the grid and cathode of the triode, and an amplified version appears at the anode. Thus, the single triode has performed both the functions of diode detector and triode a.f. amplifier.

Whilst the triode of Fig. 320 (a) amplifies the detected a.f. signal presented to its grid, it also amplifies the radio frequency appearing across the load resistor. It is normally undesirable to allow this r.f. to be passed on to subsequent amplifier stages and it may be removed by inserting a low pass filter in the anode circuit, as given by \( R_3 \), \( C_2 \), and \( C_3 \) in Fig. 320 (b). Other forms of filter using a choke having a high impedance to radio frequencies and a low impedance to audio frequencies may also be used.

Most grid leak detectors have resistor \( R_1 \) connected between grid and chassis, as in Fig. 320 (c) instead of across \( C_1 \). This causes no significant change in operation, and the resistor still carries out its function of discharging \( C_1 \) between r.f. peaks. This time, however, the discharge current flows through the coil in the tuned circuit. A grid leak detector may have the grid resistor either in the position shown in Fig. 320 (a) or in that shown in Fig. 320 (c); but it is usually a little more convenient to have it in the latter position, and this is the circuit arrangement which is more frequently encountered.

An interesting feature of the grid leak detector is that the direct voltage developed across \( C_1 \) is applied direct to the grid of the triode. In consequence, there is no necessity to consider a.c. and d.c. load values, as occurred with the diode detectors we have previously examined.

The grid circuit of Fig. 320 (c) is identical with that in Fig. 316 which, as we saw earlier, provides grid current bias. The circuits do, in fact, work in similar manner, although the end results are rather different.

We illustrated the action of the current bias circuit by replacing the coupling capacitor with a battery charged to the same voltage. This treatment was permissible because it showed how the charging of the capacitor resulted in the same effect as would be given by a bias battery, the voltage of the “battery” changing in sympathy with the amplitude of the applied a.f. The same approach could be used with the grid leak detector if we wished to study its operation further, but it is much simpler to work from the waveform appearing on the grid of the detector relative to the cathode.

The grid waveform is shown in Fig. 321, and it is the result of an amplitude modulated r.f. signal appearing across the tuned circuit of Fig. 320 (a) or (c). The grid and cathode of the triode function...
as a diode, whereupon these two electrodes offer a low impedance for voltages causing the grid to go positive of the cathode. Thus, positive r.f. peaks go only slightly positive of the cathode and the grid capacitor becomes charged in consequence. Between each positive peak the grid capacitor discharges into the grid resistor, with the result that the succeeding positive peak similarly encounters the low impedance offered by the grid and cathode. The modulated r.f. waveform then takes up the distorted shape shown in the diagram.

This waveform has an average value, shown in dashed line, which varies in sympathy with the a.f. modulation of the r.f. signal. Detection has therefore taken place, and the detected signal can be amplified, as an audio frequency, by the triode. Also present at the grid is an average direct voltage. If a current reading meter is inserted in series with the anode load of the grid leak detector, this will indicate a drop in anode current when a signal is tuned in, because the average direct voltage has the effect of applying negative bias to the grid. (In practice, however, a relatively strong signal is required for a noticeable drop in anode current to be given. Signals given by an aerial and tuned circuit without any amplification will normally be too weak to cause any significant change in meter reading, although they will still be detected by the grid leak detector.)

A disadvantage with the grid leak detector is that it can be overloaded by high amplitude signals. Because of the diode action between grid and cathode the positive peaks of the r.f. signal are all held slightly positive of cathode, with the result that, when r.f. signal strength increases, the average a.f. voltage goes more negative of the cathode. Too high an r.f. signal amplitude will cause part, or all, of the average a.f. voltage to approach or go beyond the valve’s cut-off voltage, with the result that the amplified signal at the triode anode becomes distorted. Thus, the amplitude at which the grid leak detector commences to overload is governed, not by the ability of the grid and cathode to function as a diode, but by the ability of the triode to function as an a.f. amplifier. The fact that a grid leak detector can be overloaded makes it useful as a detector of low level signals only. There are, however, many applications in which it can be so employed.

Fig. 321. The waveform at the grid of the grid leak detector, relative to cathode. (The waveform is shown in slightly idealised form, since it depicts all positive peaks as terminating at the same level above cathode potential. In practice the positive peaks for the high amplitude section will rise a little higher above cathode potential than the positive peaks of the low amplitude section.)
The main advantage conferred by the grid leak detector is that it combines two valves in one. Another advantage, which we shall examine in a later article, is that it lends itself particularly well to circuits in which feedback from the anode to the grid is provided. Such feedback can increase sensitivity to an extremely high level.

The grid leak detector we have discussed here employs a triode. Valves with more complicated electrode structures may be put into service as grid leak detectors just as readily, the main proviso being that they are capable of operating as a.f. voltage amplifiers.

The grid leak detector has been in use for many years and has acquired several other names which will also be encountered in radio work. The most commonly encountered alternatives are leaky-grid detector, cumulative grid detector or, simply, grid detector.

The similarity between the grid leak detector circuit and the grid current bias circuit of Fig. 316 may be a little confusing to the beginner, because the two circuits appear to do different things. This is not entirely true, however. With the current bias circuit, the function of the grid capacitor and resistor is to cause the grid to be negatively biased (for input signals overcoming the contact potential). It may be said that the same is true for the grid leak detector circuit except that, in this case, the grid is caused to go more negative or less negative (according to the instantaneous amplitude of the modulated r.f. signal) at an audio frequency, whereupon the detected audio frequency becomes available at the anode. At the same time, the grid leak circuit resembles the grid current bias circuit in that the average direct voltage on the grid increases with input signal strength, resulting in the drop of anode current as measured by a meter (which does not respond to r.f. or a.f.) noted earlier. A further point is that contact potential is not so high in the grid leak detector as in the current bias circuit because the grid resistor of the former normally has a lower value. To give a complete picture, it should be added, nevertheless, that contact potential is still of some importance with the grid leak detector, and that it prevents the grid-cathode diode from functioning as an “ideal” rectifier on very low-level signals. Such signals are still detected, but they may suffer some distortion in the process. The same point also applies, incidentally, to valve diode detectors.

Next Month
In next month’s issue we shall discuss another type of detector, the infinite impedance detector, after which we shall carry on to triode characteristics.

ONE GREAT ADVANTAGE ABOUT

being in the Services during and shortly after the last war
was that you met so many amiable nuts. I was reminded of this the other day when a friend, who maintains the electronic control equipment at an aluminium processing plant, described a little bitterly his experiences on being shifted to a section he had never worked in before. The burden of his complaint was that the chaps who were already there knew the equipment inside-out, but they wouldn’t pass on any information to him.

It was at this moment that I recalled the Signals Warrant Officer at one large R.A.F. station in the later 1940s. The telephone wiring around this station was a haphazard tangle of pre-war and hurried wartime installations, with junction box outlets popping up all round the perimeter track and in many other widely dispersed places. The wiring was, of course, used for d.f. homer stations, remote control of v.h.f. transmitters and similar purposes, in addition to its more mundane function of providing telephone links. There was only one set of plans covering all the wiring on the unit, and a normal person would have thought that the obvious thing to do was to get a few copies run off at the earliest opportunity. But this Signals Warrant Officer thought otherwise, and he carried this single set of plans around with him wherever he went. On the occasions when it was necessary to take advantage of the existing wiring to run some new equipment he had, then, always to be called in, because he was the only person with the essential (and jealously guarded) information.

Hugging Information
I wonder why it is that people delight in hugging to themselves information which should be generally known. Most of us have had the same experience, on starting at a new place of work, as did my friend on the electronic control equipment. I've certainly bumped into it myself. At one place, indeed, I've even had to ask a second person where the lavatory was because the first person I asked couldn't bring himself to part with this precious bit of intelligence! A typical instance of what you encounter at a new establishment can consist of spending several hours' work with, say, a signal generator, only to find that the particular generator you've chosen is 5% off calibration. Everyone around you knows that the generator you've picked to work with is 5% out, but they've been quite happy to let you press on without warning you about it. After you've found your feet at a place of work it is, of course, always possible to have a chuckle at the initial lack of co-operation you first encountered. But it still seems to me to be a pity that the new initiate has, so often, to put up with people who are not prepared to pass on a little information. A typical instance of what I think I've applied that last adjective to the wrong noun. In cases like this, it isn't the newcomer who's ignorant. THE RADIO CONSTRUCTOR

RADIO TOPICS . . .

by Recorder

THE RADIO CONSTRUCTOR
Buried H.T.
Talk of those Service days reminds me, also, of a time during the war when a crowd of R.A.F. wireless mechanics, in company with myself, spent a period in tented accommodation alongside the happily-named Sweet Water Canal in Egypt. These characters managed to scrounge enough parts to knock up a radio, but the only sources of supply they could lay their hands on were a 6 volt accumulator for the heaters and a small 6 to 200 volt motor-generator for h.t. There was, of course, no such thing as a mains supply available.

The only snag with the motor-generator was that it created a considerable amount of r.f. interference, but this was cured by the very simple process of burying it in the sand about thirty feet away from the tent with the connecting wires similarly buried.

Which meant that the inhabitants of the tent could lean back and enjoy the delights of radio reception without interference. But it was very disturbing for the wanderers over the desert who happened to walk near the hidden generator, as it busily whirred away under the sands of ancient Egypt.

Smithy Rides Again

But that's enough about the past. Let's move forward now to December of last year, in which issue of The Radio Constructor Smithy the Service-man made one of those little telling points of his.

Talking about transistorised u.h.f. TV tuners, Smithy stated that the base voltage pre-set potentiometers fitted to these would be disappearing in the future as manufacturers gained more experience, and would be replaced by ordinary fixed resistors. And I now see that this is exactly what's happening. The new Thorn 950 television chassis has a transistorised u.h.f. tuner, and its base voltage potentiometers have been replaced by fixed resistor circuits.

Dead with it and switched-on is our Smithy.

The First Transistor

How did you get on with the "20 Semiconductor Questions" we published in the July issue? Most people seem to have got through the quiz fairly easily. However, Question No. 4 has raised a point which deserves a little further consideration.

Question No. 4 asked which was the first type of transistor to be invented, and our answer was that it was the point contact type. Whereupon, two of our readers wrote in to say that this was not so, since the first transistor to be invented was the junction type. Not only was this the case but, also, the junction transistor in question was patented in Canada in 1925 and in the United States in 1930!

Our readers stated that their source of information was an article, "The Twenty Lost Years of Solid-State Physics" by Theodore L. Thomas, which appeared in Analog Science Fiction/Science Fact magazine for March 1965. (Analog, I should add, is published in America but may be obtained in Britain through any newsagent.) Naturally, we examined the details referred to by our readers.

In his Analog article, Theodore L. Thomas gives some intriguing details of the early invention, this being for an amplifying device which could nowadays be described as a transistor. The inventor was Dr. Julius Edgar Lilienfeld, previously a professor at the University of Leipzig in Poland. The patents covering his amplifying device were filed in Canada on 22nd October, 1925, and in the U.S., on 28th January, 1930. Patents for later developments were filed, in the U.S., on 13th September, 1932, and 7th March, 1933. The March 1933 patent gives a facsimile reproduction of the 1930 patent application, this being No. 1,745,175 at the United States Patent Office.

The amplifying device described in the patent application comprises materials deposited on a small rectangular base of insulating material, such as glass. The glass is cracked across its width at approximately the centre, the two pieces being joined together again with a piece of 0.001 in. aluminium foil sandwiched between the upper end of the foil being flush with the upper surface of the glass. Deposited on the upper glass surface, on either side of the aluminium foil, are two thin layers of conductive material such as copper. The inside edges of these layers closely approach the aluminium foil. Finally deposited over the metal, glass and aluminium is a thin film of a compound of copper and sulphur, which Mr. Thomas identifies, in his article, as cuprous sulphide.

Thus, starting from one end of the glass base, we have a layer of deposited metal, such as copper. This terminates just before the flush edge of the aluminium foil interposed in the crack in the glass. Just after the aluminium foil the second layer of conductive material starts, this continuing to the other end of the glass base. And, over the lot, is deposited the thin film of the compound of copper and sulphur.

In the patent application, this device is shown connected up in exactly the same way as an enlarged emitter n.p.n. transistor. Using present-day terms, one of the layers of conductive material could be referred to as the emitter, the other as the collector, and the aluminium foil, which appears in between, as the base. The input signal is applied to this "base" via a source of positive bias, and the amplified output signal is taken from the "collector" via a transformer primary coupled to a higher positive potential.

Full acknowledgements are due to Theodore L. Thomas and Analog magazine for unearthing and publishing these fascinating facts. There seems little doubt that this early device provided amplification, whereupon it would seem that it must surely be the world's first transistor.

Our thanks, also, to the readers who brought this interesting information to our attention.

Best Buy

Just to demonstrate one of the little social pitfalls that wait, these days, for the unwary, let me finish by recounting a cautionary tale which has to do with that excellent journal Which? and domestic electric equipment.

Our household recently required a new vacuum cleaner and, being pushed for time, I made no investigation of different makes and models but simply went straight out and bought the cleaner recommended in Which? as Best Buy. And a very good purchase it has turned out to be, too.

Mentioning the episode to a friend I said that the Which? report had not been entirely complimentary with one particular model, which I shall refer to here by the fictitious name of Alpha "Super Sucker". I noticed that the conversation palled somewhat after this point, and it wasn't until later that I discovered that my friend had just bought an Alpha "Super Sucker".

Failing to profit from this experience, I described this last discourse to another friend, referring with some amusement to the palling of the conversation after I'd got to the Alpha "Super Sucker" bit. Whereupon, this conversation palled.

My second friend had just bought an Alpha "Super Sucker", too.
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• BASIC COMPUTER CIRCUIT
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